

Lecture 2: Singular value decomposition (SVD)



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1. Singular value decomposition

- **Definition:** Let m and n be arbitrary positive integers ($m \geq n$ or $m < n$). Given $\mathbf{A} \in \mathbb{C}^{m \times n}$, not necessarily of full rank, a *singular value decomposition (SVD)* of \mathbf{A} is a factorization

$$\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^*,$$

where $\mathbf{U} \in \mathbb{C}^{m \times m}$ is unitary, $\mathbf{V} \in \mathbb{C}^{n \times n}$ is unitary, and $\mathbf{\Sigma} \in \mathbb{R}^{m \times n}$ is diagonal. In addition, it is assumed that the diagonal entries σ_i of $\mathbf{\Sigma}$ are nonnegative and in nonincreasing order; that is

$$\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_p \geq 0,$$

where $p = \min\{m, n\}$.

Theorem 1 (Existence of SVD)

Every matrix $\mathbf{A} \in \mathbb{C}^{m \times n}$ has a singular value decomposition.

Proof. Assume $\mathbf{A} \neq \mathbf{0}$; otherwise we can take $\mathbf{\Sigma} = \mathbf{0}$ and let \mathbf{U} and \mathbf{V} be arbitrary unitary matrices. Next, we use induction on m and n to prove the existence of SVD for the case $m \geq n$ (consider \mathbf{A}^* if $m < n$): Assume that an SVD exists for any $(m-1) \times (n-1)$ matrix and prove it for any $m \times n$ matrix.

(i) The basic step: $m \geq n = 1$.

Write $\mathbf{A} = \mathbf{u}_1 \mathbf{\Sigma}_1 \mathbf{V}^*$ with $\mathbf{u}_1 = \mathbf{A} / \|\mathbf{A}\|_2$, $\mathbf{\Sigma}_1 = \|\mathbf{A}\|_2$ and $\mathbf{V} = 1$.

Choose $\hat{\mathbf{U}}$ such that $\mathbf{U} = \begin{bmatrix} \mathbf{u}_1 & \hat{\mathbf{U}} \end{bmatrix} \in \mathbb{C}^{m \times m}$ is unitary. Let

$\mathbf{\Sigma} = \begin{bmatrix} \mathbf{\Sigma}_1 & \mathbf{0} \end{bmatrix}^\top \in \mathbb{R}^{m \times 1}$. Then \mathbf{A} has an SVD $\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^*$.

(ii) The induction step: $m \geq n > 1$.

Let $\mathbf{v}_1 \in \mathbb{C}^n$ be a unit (i.e., $\|\mathbf{v}_1\|_2 = 1$) eigenvector corresponding to the eigenvalue $\lambda_{\max}(\mathbf{A}^* \mathbf{A})$. Then we have $\|\mathbf{A} \mathbf{v}_1\|_2 = \|\mathbf{A}\|_2 > 0$.

Let $\mathbf{u}_1 = \mathbf{A} \mathbf{v}_1 / \|\mathbf{A} \mathbf{v}_1\|_2$, which is a unit vector. Choose $\hat{\mathbf{U}}$ and $\hat{\mathbf{V}}$ such that $\tilde{\mathbf{U}} = \begin{bmatrix} \mathbf{u}_1 & \hat{\mathbf{U}} \end{bmatrix} \in \mathbb{C}^{m \times m}$ and $\tilde{\mathbf{V}} = \begin{bmatrix} \mathbf{v}_1 & \hat{\mathbf{V}} \end{bmatrix} \in \mathbb{C}^{n \times n}$ are unitary.

Now we have

$$\tilde{\mathbf{U}}^* \mathbf{A} \tilde{\mathbf{V}} = \begin{bmatrix} \mathbf{u}_1^* \\ \hat{\mathbf{U}}^* \end{bmatrix} \mathbf{A} \begin{bmatrix} \mathbf{v}_1 & \hat{\mathbf{V}} \end{bmatrix} = \begin{bmatrix} \mathbf{u}_1^* \mathbf{A} \mathbf{v}_1 & \mathbf{u}_1^* \mathbf{A} \hat{\mathbf{V}} \\ \hat{\mathbf{U}}^* \mathbf{A} \mathbf{v}_1 & \hat{\mathbf{U}}^* \mathbf{A} \hat{\mathbf{V}} \end{bmatrix}.$$

We note that

$$\mathbf{u}_1^* \mathbf{A} \mathbf{v}_1 = \frac{(\mathbf{A} \mathbf{v}_1)^* (\mathbf{A} \mathbf{v}_1)}{\|\mathbf{A} \mathbf{v}_1\|_2} = \|\mathbf{A} \mathbf{v}_1\|_2 = \|\mathbf{A}\|_2,$$

and

$$\hat{\mathbf{U}}^* \mathbf{A} \mathbf{v}_1 = \hat{\mathbf{U}}^* \mathbf{u}_1 \|\mathbf{A} \mathbf{v}_1\|_2 = \mathbf{0}.$$

We claim $\mathbf{u}_1^* \mathbf{A} \hat{\mathbf{V}} = \mathbf{0}$ too because otherwise

$$\begin{aligned} \sigma_1 &:= \|\mathbf{A}\|_2 = \|\tilde{\mathbf{U}}^* \mathbf{A} \tilde{\mathbf{V}}\|_2 \\ &= \left\| \begin{bmatrix} 1 & 0 & \cdots & 0 \end{bmatrix} \right\|_2 \cdot \|\tilde{\mathbf{U}}^* \mathbf{A} \tilde{\mathbf{V}}\|_2 \\ &\geq \left\| \begin{bmatrix} 1 & 0 & \cdots & 0 \end{bmatrix} \tilde{\mathbf{U}}^* \mathbf{A} \tilde{\mathbf{V}} \right\|_2 = \|[\sigma_1 \ \mathbf{u}_1^* \mathbf{A} \hat{\mathbf{V}}]\|_2 > \sigma_1, \end{aligned}$$

which is a contradiction.

Therefore,

$$\tilde{\mathbf{U}}^* \mathbf{A} \tilde{\mathbf{V}} = \begin{bmatrix} \sigma_1 & \mathbf{0} \\ \mathbf{0} & \hat{\mathbf{U}}^* \mathbf{A} \hat{\mathbf{V}} \end{bmatrix}.$$

By the induction hypothesis, we know that the $(m-1) \times (n-1)$ matrix $\hat{\mathbf{U}}^* \mathbf{A} \hat{\mathbf{V}}$ has an SVD:

$$\hat{\mathbf{U}}^* \mathbf{A} \hat{\mathbf{V}} = \mathbf{U}_0 \boldsymbol{\Sigma}_0 \mathbf{V}_0^*.$$

Then it follows from

$$\tilde{\mathbf{U}}^* \mathbf{A} \tilde{\mathbf{V}} = \begin{bmatrix} \sigma_1 & \mathbf{0} \\ \mathbf{0} & \mathbf{U}_0 \boldsymbol{\Sigma}_0 \mathbf{V}_0^* \end{bmatrix} = \begin{bmatrix} 1 & \mathbf{0} \\ \mathbf{0} & \mathbf{U}_0 \end{bmatrix} \begin{bmatrix} \sigma_1 & \mathbf{0} \\ \mathbf{0} & \boldsymbol{\Sigma}_0 \end{bmatrix} \begin{bmatrix} 1 & \mathbf{0} \\ \mathbf{0} & \mathbf{V}_0 \end{bmatrix}^*$$

that

$$\mathbf{A} = \tilde{\mathbf{U}} \begin{bmatrix} 1 & \mathbf{0} \\ \mathbf{0} & \mathbf{U}_0 \end{bmatrix} \begin{bmatrix} \sigma_1 & \mathbf{0} \\ \mathbf{0} & \boldsymbol{\Sigma}_0 \end{bmatrix} \begin{bmatrix} 1 & \mathbf{0} \\ \mathbf{0} & \mathbf{V}_0 \end{bmatrix}^* \tilde{\mathbf{V}}^* =: \mathbf{U} \begin{bmatrix} \sigma_1 & \mathbf{0} \\ \mathbf{0} & \boldsymbol{\Sigma}_0 \end{bmatrix} \mathbf{V}^*.$$

This is an SVD of \mathbf{A} because $\sigma_1 \geq \|\boldsymbol{\Sigma}_0\|_2$. □

- Full SVD:

$$\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^*$$

- Reduced SVD (the case $m \geq n$):

$$\mathbf{A} = \mathbf{U}_n \mathbf{\Sigma}_n \mathbf{V}^*$$

where

$$\mathbf{U}_n = [\mathbf{u}_1 \quad \mathbf{u}_2 \quad \cdots \quad \mathbf{u}_n],$$

and

$$\mathbf{\Sigma}_n = \text{diag}\{\sigma_1, \sigma_2, \cdots, \sigma_n\}.$$



- Rank SVD or compact SVD or condensed SVD:

$$\mathbf{A} = [\mathbf{U}_r \quad \mathbf{U}_c] \begin{bmatrix} \mathbf{\Sigma}_r & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{V}_r^* \\ \mathbf{V}_c^* \end{bmatrix} = \mathbf{U}_r \mathbf{\Sigma}_r \mathbf{V}_r^* = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^*$$

where $r = \text{rank}(\mathbf{A})$,

$$\mathbf{U}_r = [\mathbf{u}_1 \quad \mathbf{u}_2 \quad \cdots \quad \mathbf{u}_r], \quad \mathbf{U}_c = [\mathbf{u}_{r+1} \quad \mathbf{u}_{r+2} \quad \cdots \quad \mathbf{u}_m],$$

$$\mathbf{V}_r = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \cdots \quad \mathbf{v}_r], \quad \mathbf{V}_c = [\mathbf{v}_{r+1} \quad \mathbf{v}_{r+2} \quad \cdots \quad \mathbf{v}_n],$$

and

$$\mathbf{\Sigma}_r = \text{diag}\{\sigma_1, \sigma_2, \dots, \sigma_r\}.$$

- $\{\sigma_i^2, \mathbf{u}_i\}$ are eigenvalue-eigenvector pairs of $\mathbf{A}\mathbf{A}^*$, and $\{\sigma_i^2, \mathbf{v}_i\}$ are eigenvalue-eigenvector pairs of $\mathbf{A}^*\mathbf{A}$:

$$\mathbf{A}\mathbf{A}^* \mathbf{u}_i = \sigma_i^2 \mathbf{u}_i, \quad \mathbf{A}^* \mathbf{A} \mathbf{v}_i = \sigma_i^2 \mathbf{v}_i, \quad i = 1, 2, \dots, p$$

- $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_p$ are called the *singular values* of \mathbf{A} .

- \mathbf{u}_i is called *left singular vector*, and \mathbf{v}_i is called *right singular vector*: $\mathbf{u}_i^* \mathbf{A} = \sigma_i \mathbf{v}_i^*$, $\mathbf{A} \mathbf{v}_i = \sigma_i \mathbf{u}_i$, $i = 1, 2, \dots, p$

Theorem 2

The set of singular values $\{\sigma_i\}$ is uniquely determined and invariant under unitary multiplication.

Theorem 3

If \mathbf{A} is square and all the σ_i are distinct, the left and right singular vectors are uniquely determined up to complex signs (i.e., complex scalar factors of absolute value 1).

Hint: There exists only one linearly independent eigenvector for each eigenvalue of $\mathbf{A}^* \mathbf{A}$ or $\mathbf{A} \mathbf{A}^*$.

Theorem 4 (Real SVD)

Every matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ has a real singular value decomposition.

1.1. Geometric observation

- The image of the unit sphere (in the 2-norm) of \mathbb{C}^n under any $m \times n$ matrix is a hyperellipse of \mathbb{C}^m .

For example, 2×2 real matrix \mathbf{A}



SVD of a matrix can not be emphasized too much!

2. Matrix properties via SVD

- 2-norm

$$\|\mathbf{A}\|_2 = \sigma_1$$

- F-norm

$$\|\mathbf{A}\|_F = \sqrt{\sigma_1^2 + \sigma_2^2 + \cdots + \sigma_r^2}$$

- $\text{range}(\mathbf{A})$: *column space* of \mathbf{A} , spanned by the columns of \mathbf{A}

$$\begin{aligned}\text{range}(\mathbf{A}) : &= \{\mathbf{y} \in \mathbb{C}^m \mid \exists \mathbf{x} \in \mathbb{C}^n \text{ s.t. } \mathbf{y} = \mathbf{Ax}\} \\ &= \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \cdots, \mathbf{u}_r\}\end{aligned}$$

- $\text{null}(\mathbf{A})$: *kernel* or *null space* of \mathbf{A}

$$\begin{aligned}\text{null}(\mathbf{A}) : &= \{\mathbf{x} \in \mathbb{C}^n \mid \mathbf{Ax} = \mathbf{0}\} \\ &= \text{span}\{\mathbf{v}_{r+1}, \mathbf{v}_{r+2}, \cdots, \mathbf{v}_n\}\end{aligned}$$

- Range and null space of \mathbf{A}^* :

$$\text{range}(\mathbf{A}^*) = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\} = \text{null}(\mathbf{A})^\perp$$

$$\text{null}(\mathbf{A}^*) = \text{span}\{\mathbf{u}_{r+1}, \mathbf{u}_{r+2}, \dots, \mathbf{u}_m\} = \text{range}(\mathbf{A})^\perp$$

- Relations between the four subspaces

$$\text{range}(\mathbf{A}^*) \perp \text{null}(\mathbf{A}), \quad \text{range}(\mathbf{A}^*) + \text{null}(\mathbf{A}) = \mathbb{C}^n$$

$$\text{range}(\mathbf{A}) \perp \text{null}(\mathbf{A}^*), \quad \text{range}(\mathbf{A}) + \text{null}(\mathbf{A}^*) = \mathbb{C}^m$$

- If \mathbf{A} is Hermitian, i.e., $\mathbf{A} = \mathbf{A}^*$

singular values are absolute values of eigenvalues

- Determinant of $\mathbf{A} \in \mathbb{C}^{m \times m}$

$$|\det(\mathbf{A})| = \prod_{i=1}^m \sigma_i$$

2.1. Low-rank approximation (LRA)

Theorem 5 (Eckart-Young-Mirski)

For any integer k with $1 \leq k < r = \text{rank}(\mathbf{A})$, define

$$\mathbf{A}_k = \sum_{i=1}^k \sigma_i \mathbf{u}_i \mathbf{v}_i^*.$$

Then

$$\|\mathbf{A} - \mathbf{A}_k\|_2 = \sigma_{k+1} = \min_{\substack{\mathbf{B} \in \mathbb{C}^{m \times n}, \\ \text{rank}(\mathbf{B}) \leq k}} \|\mathbf{A} - \mathbf{B}\|_2,$$

and

$$\|\mathbf{A} - \mathbf{A}_k\|_F = \sqrt{\sigma_{k+1}^2 + \cdots + \sigma_r^2} = \min_{\substack{\mathbf{B} \in \mathbb{C}^{m \times n}, \\ \text{rank}(\mathbf{B}) \leq k}} \|\mathbf{A} - \mathbf{B}\|_F.$$

- **Discussion:** Is the minimizer in Theorem 5 unique?

A random $m \times m$ matrix is “always” nonsingular. Why?

Proof of Theorem 5.

- Suppose there is some $\mathbf{B} \in \mathbb{C}^{m \times n}$ with $\text{rank}(\mathbf{B}) \leq k < r$ such that

$$\|\mathbf{A} - \mathbf{B}\|_2 < \sigma_{k+1}.$$

By $\dim(\text{null}(\mathbf{B})^\perp) = \dim(\text{range}(\mathbf{B}^*)) = \text{rank}(\mathbf{B}^*) = \text{rank}(\mathbf{B}) \leq k$, we have $\dim(\text{null}(\mathbf{B})) = n - \dim(\text{null}(\mathbf{B})^\perp) \geq n - k$. Then there exists an $(n - k)$ -dimensional subspace $\mathcal{W} \subseteq \text{null}(\mathbf{B})$. For any nonzero $\mathbf{x} \in \mathcal{W}$, we have

$$\|\mathbf{A}\mathbf{x}\|_2 = \|(\mathbf{A} - \mathbf{B})\mathbf{x}\|_2 \leq \|\mathbf{A} - \mathbf{B}\|_2 \|\mathbf{x}\|_2 < \sigma_{k+1} \|\mathbf{x}\|_2.$$

Let $\mathcal{V} = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{k+1}\}$. For any $\mathbf{x} \in \mathcal{V}$, we have

$$\|\mathbf{A}\mathbf{x}\|_2 = \|\mathbf{A}\mathbf{V}_{k+1}\mathbf{y}\|_2 = \|\mathbf{U}_{k+1}\mathbf{\Sigma}_{k+1}\mathbf{y}\|_2 = \|\mathbf{\Sigma}_{k+1}\mathbf{y}\|_2 \geq \sigma_{k+1} \|\mathbf{x}\|_2.$$

Since $\dim \mathcal{W} + \dim \mathcal{V} = (n - k) + (k + 1) > n$, there must be a nonzero vector lying in both, and this is a contradiction.

- Case $\|\cdot\|_F$: **Generalized Inverses: Theory and Applications, 2nd edition, Adi Ben-Israel and Thomas N.E. Greville, Page 213.** □

Application of low-rank approximation: image compression

- An image can be represented as a matrix. For example, typical grayscale images consist of a rectangular array of pixels, m in the vertical direction, n in the horizontal direction. The color of each of those pixels is denoted by a single number, an integer between 0 (black) and 255 (white). (This gives $2^8 = 256$ different shades of gray for each pixel. Color images are represented by three such matrices: one for red, one for green, and one for blue. Thus each pixel in a typical color image takes $(2^8)^3 = 2^{24}$ shades.)
- The objective of image compression is to reduce irrelevance and redundancy of the image data in order to be able to store or transmit data in an efficient form.
- Low-rank SVD approximation is a good candidate. (Note: jpeg compression algorithm uses similar idea, on subimages)

3. Moore–Penrose pseudoinverse

- Let $\mathbf{A} \in \mathbb{C}^{m \times n}$ have an SVD (rank form) $\mathbf{A} = \mathbf{U}_r \mathbf{\Sigma}_r \mathbf{V}_r^*$. The *Moore–Penrose pseudoinverse* of \mathbf{A} , denoted by \mathbf{A}^\dagger :

$$\mathbf{A}^\dagger := \mathbf{V}_r \mathbf{\Sigma}_r^{-1} \mathbf{U}_r^* = \sum_{i=1}^r \frac{1}{\sigma_i} \mathbf{v}_i \mathbf{u}_i^*.$$

- The matrix \mathbf{A}^\dagger is the *unique* matrix satisfying the four equations

$$\mathbf{A} \mathbf{X} \mathbf{A} = \mathbf{A}, \quad \mathbf{X} \mathbf{A} \mathbf{X} = \mathbf{X}, \quad (\mathbf{A} \mathbf{X})^* = \mathbf{A} \mathbf{X}, \quad (\mathbf{X} \mathbf{A})^* = \mathbf{X} \mathbf{A}.$$

For a proof, see Page 122 of [Numerical linear algebra \(in Chinese\) by Zhihao Cao](#).

- If \mathbf{A} has full column rank, then $\mathbf{A}^\dagger = (\mathbf{A}^* \mathbf{A})^{-1} \mathbf{A}^*$.
If \mathbf{A} has full row rank, then $\mathbf{A}^\dagger = \mathbf{A}^* (\mathbf{A} \mathbf{A}^*)^{-1}$.

4. A wonderful reference

- Zhihua Zhang

The singular value decomposition, applications and beyond
arXiv:1510.08532

5. Another proof of Theorem 5

- Holger Wendland

Numerical Linear Algebra An Introduction

Cambridge University Press, 2018.

See Page 295, Theorem 7.41.

6. A computationally more feasible method for LRA

- Adaptive cross approximation (ACA)

See Page 297 of Numerical Linear Algebra An Introduction.