Lecture 5: LU factorization, Cholesky factorization, Gaussian elimination with pivoting



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1. LU factorization

• Definition: Given $\mathbf{A} \in \mathbb{C}^{m \times m}$, an LU factorization (if it exists) of \mathbf{A} is a factorization

$$A = LU$$

where $\mathbf{L} \in \mathbb{C}^{m \times m}$ is unit lower-triangular and $\mathbf{U} \in \mathbb{C}^{m \times m}$ is upper-triangular.

ullet An approach: find a sequence of unit lower-triangular matrices ${f L}_k$ such that

$$\mathbf{L}_{m-1}\cdots\mathbf{L}_2\mathbf{L}_1\mathbf{A}=\mathbf{U}$$

and set

$$\mathbf{L} = \mathbf{L}_1^{-1} \mathbf{L}_2^{-1} \cdots \mathbf{L}_{m-1}^{-1}.$$

• A 4×4 example

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 1 & 0 \\ 4 & 3 & 3 & 1 \\ 8 & 7 & 9 & 5 \\ 6 & 7 & 9 & 8 \end{bmatrix}$$

$$\mathbf{L}_{1}\mathbf{A} = \begin{bmatrix} 1 & & & \\ -2 & 1 & & \\ -4 & & 1 & \\ -3 & & & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 & 0 \\ 4 & 3 & 3 & 1 \\ 8 & 7 & 9 & 5 \\ 6 & 7 & 9 & 8 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 & 0 \\ 1 & 1 & 1 \\ 3 & 5 & 5 \\ 4 & 6 & 8 \end{bmatrix}$$

$$\mathbf{L}_{2}\mathbf{L}_{1}\mathbf{A} = \begin{bmatrix} 1 & & & \\ & 1 & & \\ & -3 & 1 & \\ & -4 & & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 & 0 \\ & 1 & 1 & 1 \\ & 3 & 5 & 5 \\ & 4 & 6 & 8 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 & 0 \\ & 1 & 1 & 1 \\ & & 2 & 2 \\ & & 2 & 4 \end{bmatrix}$$

$$\mathbf{L}_{3}\mathbf{L}_{2}\mathbf{L}_{1}\mathbf{A} = \begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 & 0 \\ & 1 & 1 & 1 \\ & & 2 & 2 \\ & & 2 & 4 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 & 0 \\ & 1 & 1 & 1 \\ & & 2 & 2 \\ & & & 2 \end{bmatrix} = \mathbf{U}.$$

$$\begin{bmatrix} 1 & & & \\ -2 & 1 & & \\ -4 & & 1 & \\ -3 & & & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & & & \\ 2 & 1 & & \\ 4 & & 1 & \\ 3 & & & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & 1 & 0 \\ 4 & 3 & 3 & 1 \\ 8 & 7 & 9 & 5 \\ 6 & 7 & 9 & 8 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 & 1 \\ 4 & 3 & 1 \\ 3 & 4 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 2 & 2 & 2 & 2 \end{bmatrix}$$

1.1. General formulas for LU factorization

- Let \mathbf{x}_k denote the kth column of the matrix at the beginning of step k (which matrix? $\mathbf{L}_{k-1} \cdots \mathbf{L}_2 \mathbf{L}_1 \mathbf{A}$).
- The purpose is to eliminate the entries below x_{kk} . To do this we construct the matrix \mathbf{L}_k :

where the *multiplier*

$$\ell_{jk} = \frac{x_{jk}}{x_{kk}}, \quad k+1 \le j \le m.$$

Proposition 1

The matrix \mathbf{L}_k can be inverted by negating its subdiagonal entries. We have

$$\mathbf{L}_k^{-1} = egin{bmatrix} 1 & & & & & & \\ & & 1 & & & & \\ & & \ell_{k+1,k} & 1 & & \\ & & \vdots & & \ddots & \\ & & \ell_{mk} & & & 1 \end{bmatrix} = egin{bmatrix} \mathbf{I}_{k-1} & \mathbf{0} & \mathbf{0} & \\ \mathbf{0} & 1 & \mathbf{0} & \\ \mathbf{0} & - \bigstar & \mathbf{I}_{m-k} \end{bmatrix}.$$

Proof. Define the vector

$$\boldsymbol{\ell}_k = \begin{bmatrix} 0 & \cdots & 0 & \ell_{k+1,k} & \cdots & \ell_{mk} \end{bmatrix}^\top$$
.

The matrix $\mathbf{L}_k = \mathbf{I} - \boldsymbol{\ell}_k \mathbf{e}_k^*$, where \mathbf{e}_k is the kth column of the identity matrix \mathbf{I} . Obviously, $\mathbf{e}_k^* \boldsymbol{\ell}_k = 0$. Therefore, the statement follows from

$$(\mathbf{I} - \boldsymbol{\ell}_k \mathbf{e}_k^*)(\mathbf{I} + \boldsymbol{\ell}_k \mathbf{e}_k^*) = \mathbf{I} - \boldsymbol{\ell}_k \mathbf{e}_k^* \boldsymbol{\ell}_k \mathbf{e}_k^* = \mathbf{I}.$$

Proposition 2

The product $\mathbf{L}_1^{-1}\mathbf{L}_2^{-1}\cdots\mathbf{L}_{m-1}^{-1}$, i.e., the L factor **L**, can be formed by collecting the entries ℓ_{jk} in the appropriate places. We have

$$\mathbf{L} = \begin{bmatrix} 1 & & & & \\ \ell_{21} & 1 & & & \\ \ell_{31} & \ell_{32} & 1 & & \\ \vdots & \vdots & \ddots & \ddots & \\ \ell_{m1} & \ell_{m2} & \cdots & \ell_{m,m-1} & 1 \end{bmatrix}.$$

Proof. It follows from $\mathbf{L}_k^{-1} = \mathbf{I} + \boldsymbol{\ell}_k \mathbf{e}_k^*$ and $\mathbf{e}_k^* \boldsymbol{\ell}_j = 0 \ (\forall j \geq k)$ that

$$\mathbf{L}_k^{-1}\mathbf{L}_{k+1}^{-1} = \mathbf{I} + \boldsymbol{\ell}_k\mathbf{e}_k^* + \boldsymbol{\ell}_{k+1}\mathbf{e}_{k+1}^*.$$

Therefore,

$$\mathbf{L} = \mathbf{L}_1^{-1} \mathbf{L}_2^{-1} \cdots \mathbf{L}_{m-1}^{-1} = \mathbf{I} + \ell_1 \mathbf{e}_1^* + \ell_2 \mathbf{e}_2^* + \cdots + \ell_{m-1} \mathbf{e}_{m-1}^*.$$

Remark 3

- The matrices \mathbf{L}_k^{-1} are never formed and multiplied explicitly.
- The multipliers ℓ_{jk} are computed and stored directly into **L**.

1.2. LU factorization algorithm

Algorithm: LU factorization
$$\mathbf{A} = \mathbf{L}\mathbf{U}$$

$$\mathbf{U} = \mathbf{A}, \quad \mathbf{L} = \mathbf{I}$$
for $k = 1$ to $m - 1$
for $j = k + 1$ to m

$$\ell_{jk} = u_{jk}/u_{kk}$$

$$u_{j,k:m} = u_{j,k:m} - \ell_{jk}u_{k,k:m}$$
end
end

- 1.3. Gaussian elimination for Ax = b
 - $\bullet \mathbf{A} = \mathbf{L}\mathbf{U}, \quad \mathbf{L}\mathbf{y} = \mathbf{b}, \quad \mathbf{U}\mathbf{x} = \mathbf{y}$

Algorithm: Forward substitution solving Ly = b

for k = 1 to m

$$y_k = \left(b_k - \sum_{j=1}^{k-1} \ell_{kj} y_j\right) / \ell_{kk}$$

end

Algorithm: Back substitution solving $\mathbf{U}\mathbf{x} = \mathbf{y}$

for k = m downto 1

$$x_k = \left(y_k - \sum_{j=k+1}^m u_{kj} x_j\right) / u_{kk}$$

end

2. Cholesky factorization

• Every Hermitian positive definite matrix **A** has a factorization

$$A = LDL^*$$

where **L** is the unit lower-triangular matrix in its LU factorization $\mathbf{A} = \mathbf{L}\mathbf{U}$ and **D** is a diagonal matrix with diagonal entries $d_{ii} > 0$.

• Definition: Given $\mathbf{A} \in \mathbb{C}^{m \times m}$, a Cholesky factorization (if it exists) of \mathbf{A} is a factorization

$$\mathbf{A} = \mathbf{R}^* \mathbf{R}$$

where $\mathbf{R} \in \mathbb{C}^{m \times m}$ is upper-triangular.

Theorem 4

Every Hermitian positive definite matrix $\mathbf{A} \in \mathbb{C}^{m \times m}$ has a unique Cholesky factorization

$$\mathbf{A} = \mathbf{R}^* \mathbf{R}.$$

where $\mathbf{R} \in \mathbb{C}^{m \times m}$ is upper-triangular and $r_{ij} > 0$.

Proof. (By induction on the dimension).

It is easy for the case of dimension 1. Assume it is true for the case of dimension m-1. We prove the case of dimension m. Let $\alpha = \sqrt{a_{11}}$. We have

$$\mathbf{A} = \begin{bmatrix} a_{11} & \mathbf{w}^* \\ \mathbf{w} & \mathbf{K} \end{bmatrix} = \begin{bmatrix} \alpha & \mathbf{0} \\ \mathbf{w}/\alpha & \mathbf{I} \end{bmatrix} \begin{bmatrix} 1 & \mathbf{0} \\ \mathbf{0} & \mathbf{K} - \mathbf{w}\mathbf{w}^*/a_{11} \end{bmatrix} \begin{bmatrix} \alpha & \mathbf{w}^*/\alpha \\ \mathbf{0} & \mathbf{I} \end{bmatrix}$$

$$= \begin{bmatrix} \alpha & \mathbf{0} \\ \mathbf{w}/\alpha & \mathbf{I} \end{bmatrix} \begin{bmatrix} 1 & \mathbf{0} \\ \mathbf{0} & \widehat{\mathbf{R}}^*\widehat{\mathbf{R}} \end{bmatrix} \begin{bmatrix} \alpha & \mathbf{w}^*/\alpha \\ \mathbf{0} & \mathbf{I} \end{bmatrix}$$

$$(\text{by } \mathbf{K} - \mathbf{w}\mathbf{w}^*/a_{11} \text{ is HPD and the induction hypothesis})$$

$$= \begin{bmatrix} \alpha & \mathbf{0} \\ \mathbf{w}/\alpha & \widehat{\mathbf{R}}^* \end{bmatrix} \begin{bmatrix} \alpha & \mathbf{w}^*/\alpha \\ \mathbf{0} & \widehat{\mathbf{R}} \end{bmatrix} = \mathbf{R}^*\mathbf{R}.$$

The first row of **R** is uniquely determined by $r_{11} > 0$ and the factorization itself. The uniqueness of **R** follows from the induction hypothesis that $\hat{\mathbf{R}}$ is unique.

2.1. A 4×4 example:

$$\mathbf{A} = \begin{bmatrix} 4 & 4\mathrm{i} & 6 & 2 \\ -4\mathrm{i} & 5 & -4\mathrm{i} & 5 - 2\mathrm{i} \\ 6 & 4\mathrm{i} & 17 & 3 - 8\mathrm{i} \\ 2 & 5 + 2\mathrm{i} & 3 + 8\mathrm{i} & 36 \end{bmatrix}, \mathbf{w} = \begin{bmatrix} -4\mathrm{i} \\ 6 \\ 2 \end{bmatrix}, \mathbf{K} = \begin{bmatrix} 5 & -4\mathrm{i} & 5 - 2\mathrm{i} \\ 4\mathrm{i} & 17 & 3 - 8\mathrm{i} \\ 5 + 2\mathrm{i} & 3 + 8\mathrm{i} & 36 \end{bmatrix}$$

• Compute the upper triangular matrix **R** row by row

Row 1:
$$\begin{bmatrix} 2 & & & \\ -2i & 1 & & \\ 3 & & 1 \\ 1 & & & 1 \end{bmatrix} \begin{bmatrix} 1 & & & \\ & 1 & 2i & 5 \\ & -2i & 8 & -8i \\ & 5 & 8i & 35 \end{bmatrix} \begin{bmatrix} 2 & 2i & 3 & 1 \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

Row 2:
$$\begin{bmatrix} 1 & 2i & 5 \\ -2i & 8 & -8i \\ 5 & 8i & 35 \end{bmatrix} = \begin{bmatrix} 1 \\ -2i & 1 \\ 5 & & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 4 & 2i \\ -2i & 10 \end{bmatrix} \begin{bmatrix} 1 & 2i & 5 \\ 1 \\ & & 1 \end{bmatrix}$$

Row 3:
$$\begin{bmatrix} 4 & 2i \\ -2i & 10 \end{bmatrix} = \begin{bmatrix} 2 \\ -1i & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 9 \end{bmatrix} \begin{bmatrix} 2 & 1i \\ 1 \end{bmatrix}$$

Row 4: $9 = 3 \times 1 \times 3$

• The Cholesky factor
$$\mathbf{R} = \begin{bmatrix} 2 & 2i & 3 & 1 \\ & 1 & 2i & 5 \\ & & 2 & 1i \\ & & & 3 \end{bmatrix}$$
.

2.2. Algorithm for Cholesky factorization

Algorithm: Cholesky factorization R=triu(A) for k = 1 to mfor j = k + 1 to m $r_{j,j:m} = r_{j,j:m} - r_{k,j:m} \overline{r}_{kj} / r_{kk}$ end

 $r_{k,k:m} = r_{k,k:m} / \sqrt{r_{kk}}$

• Exercise: Design an algorithm to compute \mathbb{R}^* column by column.

2.3. Other factorization of HPD matrix

• For any HPD matrix **A**, there exists a unique HPD matrix **B** satisfying

$$\mathbf{A} = \mathbf{B}^2$$
.

B is called the *square root* of **A**. (Proof? HPSD case?)

end

3. Gaussian elimination with partial pivoting (GEPP):

• Only rows are interchanged.

• After m-1 steps, **A** becomes an upper-triangular matrix **U**:

$$\mathbf{L}_{m-1}\mathbf{P}_{m-1}\cdots\mathbf{L}_{2}\mathbf{P}_{2}\mathbf{L}_{1}\mathbf{P}_{1}\mathbf{A}=\mathbf{U},$$

where \mathbf{P}_k is an elementary permutation matrix $(\mathbf{P}_k = \mathbf{P}_k^\top = \mathbf{P}_k^{-1})$.

Remark 5

Absolute values of all the entries of \mathbf{L}_k in GEPP are ≤ 1 due to the property at step k (after pivoting)

$$|x_{kk}| = \max_{k \le j \le m} |x_{jk}|.$$

3.1. A 4×4 Example

• 1: Interchange the first and third rows by P_1

$$\begin{bmatrix} & & 1 \\ & 1 & & \\ 1 & & & \\ & & & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 & 0 \\ 4 & 3 & 3 & 1 \\ 8 & 7 & 9 & 5 \\ 6 & 7 & 9 & 8 \end{bmatrix} = \begin{bmatrix} 8 & 7 & 9 & 5 \\ 4 & 3 & 3 & 1 \\ 2 & 1 & 1 & 0 \\ 6 & 7 & 9 & 8 \end{bmatrix}$$

• 2: First elimination by L_1

$$\begin{bmatrix} 1 & & & \\ -\frac{1}{2} & 1 & & \\ -\frac{1}{4} & & 1 & \\ -\frac{3}{4} & & & 1 \end{bmatrix} \begin{bmatrix} 8 & 7 & 9 & 5 \\ 4 & 3 & 3 & 1 \\ 2 & 1 & 1 & 0 \\ 6 & 7 & 9 & 8 \end{bmatrix} = \begin{bmatrix} 8 & 7 & 9 & 5 \\ -\frac{1}{2} & -\frac{3}{2} & -\frac{3}{2} \\ -\frac{3}{4} & -\frac{5}{4} & -\frac{5}{4} \\ \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \end{bmatrix}$$

• 3: Interchange the second and fourth rows by P_2

$$\begin{bmatrix} 1 & & & & \\ & & & 1 \\ & & & 1 \\ & & 1 & \end{bmatrix} \begin{bmatrix} 8 & 7 & 9 & 5 \\ -\frac{1}{2} & -\frac{3}{2} & -\frac{3}{2} \\ -\frac{3}{4} & -\frac{5}{4} & -\frac{5}{4} \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \end{bmatrix} = \begin{bmatrix} 8 & 7 & 9 & 5 \\ \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ -\frac{3}{4} & -\frac{5}{4} & -\frac{5}{4} \\ -\frac{1}{2} & -\frac{3}{2} & -\frac{3}{2} \end{bmatrix}$$

• 4: Second elimination by L_2

$$\begin{bmatrix} 1 & & & \\ & 1 & & \\ & \frac{3}{7} & 1 & \\ & \frac{2}{7} & & 1 \end{bmatrix} \begin{bmatrix} 8 & 7 & 9 & 5 \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & -\frac{3}{4} & -\frac{5}{4} & -\frac{5}{4} \\ & -\frac{1}{2} & -\frac{3}{2} & -\frac{3}{2} \end{bmatrix} = \begin{bmatrix} 8 & 7 & 9 & 5 \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & & -\frac{2}{7} & \frac{4}{7} \\ & & -\frac{6}{7} & -\frac{2}{7} \end{bmatrix}$$

• 5: Interchange the third and fourth rows by P_3

$$\begin{bmatrix} 1 & & & \\ & 1 & & \\ & & & 1 \\ & & & 1 \end{bmatrix} \begin{bmatrix} 8 & 7 & 9 & 5 \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & & -\frac{2}{7} & \frac{4}{7} \\ & & -\frac{6}{7} & -\frac{2}{7} \end{bmatrix} = \begin{bmatrix} 8 & 7 & 9 & 5 \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & & -\frac{6}{7} & -\frac{2}{7} \\ & & -\frac{2}{7} & \frac{4}{7} \end{bmatrix}$$

• 6: Final elimination by L_3

$$\begin{bmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & -\frac{1}{3} & 1 \end{bmatrix} \begin{bmatrix} 8 & 7 & 9 & 5 \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & & -\frac{6}{7} & -\frac{2}{7} \\ & & & -\frac{2}{7} & \frac{4}{7} \end{bmatrix} = \begin{bmatrix} 8 & 7 & 9 & 5 \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & & -\frac{6}{7} & -\frac{2}{7} \\ & & & \frac{2}{3} \end{bmatrix}$$

 $\bullet \ \mathbf{A} = \mathbf{P}_1^{-1} \mathbf{L}_1^{-1} \mathbf{P}_2^{-1} \mathbf{L}_2^{-1} \mathbf{P}_3^{-1} \mathbf{L}_3^{-1} \mathbf{U}$

$$\begin{bmatrix} 2 & 1 & 1 & 0 \\ 4 & 3 & 3 & 1 \\ 8 & 7 & 9 & 5 \\ 6 & 7 & 9 & 8 \end{bmatrix} = \begin{bmatrix} \frac{1}{4} & -\frac{3}{7} & \frac{1}{3} & 1 \\ \frac{1}{2} & -\frac{2}{7} & 1 \\ 1 & & & \\ \frac{3}{4} & 1 & \end{bmatrix} \begin{bmatrix} 8 & 7 & 9 & 5 \\ & \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & & -\frac{6}{7} & -\frac{2}{7} \\ & & & \frac{2}{3} \end{bmatrix}$$

 $\bullet \ \mathbf{PA} = \mathbf{LU} \ \mathrm{with} \ \mathbf{P} = \mathbf{P}_3 \mathbf{P}_2 \mathbf{P}_1 \ \mathrm{and} \ \mathbf{L} = \mathbf{P}_3 \mathbf{P}_2 \mathbf{L}_1^{-1} \mathbf{P}_2^{-1} \mathbf{L}_2^{-1} \mathbf{P}_3^{-1} \mathbf{L}_3^{-1}$

$$\begin{bmatrix} & 1 \\ & & 1 \\ 1 \\ 1 & & \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 & 0 \\ 4 & 3 & 3 & 1 \\ 8 & 7 & 9 & 5 \\ 6 & 7 & 9 & 8 \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{3}{4} & 1 \\ \frac{1}{2} & -\frac{2}{7} & 1 \\ \frac{1}{4} & -\frac{3}{7} & \frac{1}{3} & 1 \end{bmatrix} \begin{bmatrix} 8 & 7 & 9 & 5 \\ \frac{7}{4} & \frac{9}{4} & \frac{17}{4} \\ & -\frac{6}{7} & -\frac{2}{7} \\ & & & \frac{2}{3} \end{bmatrix}$$

$$\mathbf{P} \qquad \mathbf{A} \qquad \mathbf{L} \qquad \mathbf{U}$$

3.2. General formulas for PA = LU

• The matrix $\mathbf{L}_{m-1}\mathbf{P}_{m-1}\cdots\mathbf{L}_{2}\mathbf{P}_{2}\mathbf{L}_{1}\mathbf{P}_{1}$ can be rewritten in the form

$$\mathbf{L}_{m-1}\mathbf{P}_{m-1}\cdots\mathbf{L}_{2}\mathbf{P}_{2}\mathbf{L}_{1}\mathbf{P}_{1}=\widehat{\mathbf{L}}_{m-1}\cdots\widehat{\mathbf{L}}_{2}\widehat{\mathbf{L}}_{1}\mathbf{P}_{m-1}\cdots\mathbf{P}_{2}\mathbf{P}_{1},$$

where
$$\hat{\mathbf{L}}_k = \mathbf{P}_{m-1} \cdots \mathbf{P}_{k+2} \mathbf{P}_{k+1} \mathbf{L}_k \mathbf{P}_{k+1}^{-1} \mathbf{P}_{k+2}^{-1} \cdots \mathbf{P}_{m-1}^{-1}$$
.

Remark 6

The elementary permutation matrix \mathbf{P}_k in GEPP has the form

$$\mathbf{P}_k = egin{bmatrix} \mathbf{I}_{k-1} & \mathbf{0} \\ \mathbf{0} & \widehat{\mathbf{P}}_k \end{bmatrix},$$

where $\widehat{\mathbf{P}}_k \in \mathbb{R}^{(m-k+1)\times(m-k+1)}$ is an elementary permutation matrix.

Remark 7

The unit lower triangular matrix $\hat{\mathbf{L}}_k$ in GEPP has the same sparsity pattern as that of \mathbf{L}_k . The sparsity pattern is

$$egin{bmatrix} \mathbf{I}_{k-1} & \mathbf{0} & \mathbf{0} \ \mathbf{0} & 1 & \mathbf{0} \ \mathbf{0} & \bigstar & \mathbf{I}_{m-k} \end{bmatrix} = egin{bmatrix} \mathbf{0} & \mathbf{0} & \mathbf{0} \ \mathbf{0} & \mathbf{0} & \mathbf{0} \ \mathbf{0} & \bigstar & \mathbf{0} \end{bmatrix} + \mathbf{I}.$$

The matrix $\hat{\mathbf{L}}_k$ is equal to \mathbf{L}_k but with the \bigstar 's entries permuted.

Remark 8

By Proposition 1, $\widehat{\mathbf{L}}_k^{-1}$ has the same sparsity pattern as that of $\widehat{\mathbf{L}}_k$. Thus, the product $\widehat{\mathbf{L}}_1^{-1}\widehat{\mathbf{L}}_2^{-1}\cdots\widehat{\mathbf{L}}_{m-1}^{-1}$ is unit lower triangular.

Remark 9

GEPP has the LU factorization PA = LU where

$$\mathbf{P} = \mathbf{P}_{m-1} \cdots \mathbf{P}_2 \mathbf{P}_1, \quad \mathbf{U} = \mathbf{L}_{m-1} \mathbf{P}_{m-1} \cdots \mathbf{L}_2 \mathbf{P}_2 \mathbf{L}_1 \mathbf{P}_1 \mathbf{A},$$

$$\mathbf{L} = \widehat{\mathbf{L}}_{1}^{-1} \widehat{\mathbf{L}}_{2}^{-1} \cdots \widehat{\mathbf{L}}_{m-1}^{-1} = \mathbf{P}_{m-1} \cdots \mathbf{P}_{3} \mathbf{P}_{2} \mathbf{L}_{1}^{-1} \mathbf{P}_{2}^{-1} \mathbf{L}_{2}^{-1} \mathbf{P}_{3}^{-1} \cdots \mathbf{P}_{m-1}^{-1} \mathbf{L}_{m-1}^{-1}.$$

Remark 10

The matrices $\widehat{\mathbf{L}}_k^{-1}$ are never formed and multiplied explicitly. The multipliers ℓ_{jk} are computed and stored in the appropriate places.

Remark 11

The permutation matrix **P** is not known ahead of time.

3.3. GEPP for Ax = b

 $\bullet \mathbf{PA} = \mathbf{LU}, \quad \mathbf{Ly} = \mathbf{Pb}, \quad \mathbf{Ux} = \mathbf{y}$

Algorithm: LU factorization
$$\mathbf{PA} = \mathbf{LU}$$
 in GEPP $\mathbf{U} = \mathbf{A}, \ \mathbf{L} = \mathbf{I}, \ \mathbf{P} = \mathbf{I}$ for $k = 1$ to $m - 1$ Select $i \geq k$ to maximize $|u_{ik}|$ $u_{k,k:m} \leftrightarrow u_{i,k:m}$ (interchange two rows) $\ell_{k,1:k-1} \leftrightarrow \ell_{i,1:k-1}$ $p_{k,:} \leftrightarrow p_{i,:}$ for $j = k + 1$ to m $\ell_{jk} = u_{jk}/u_{kk}$ $u_{j,k:m} = u_{j,k:m} - \ell_{jk}u_{k,k:m}$ end end

3.4. Growth factor

• Define the growth factor for **A** as the ratio $\rho = \frac{\max_{ij} |u_{ij}|}{\max_{ij} |a_{ij}|}$.

Proposition 12

The growth factor ρ of Gaussian elimination with partial pivoting applied to any matrix $\mathbf{A} \in \mathbb{C}^{m \times m}$ satisfies $\rho \leq 2^{m-1}$.

Proof. Exercise 22.1.

• Worst case of ρ : Consider the 5×5 matrix **A**:

The L and U factors are given by

and

$$\mathbf{U} = \begin{bmatrix} 1 & & & 1 \\ & 1 & & & 2 \\ & & 1 & & 4 \\ & & & 1 & 8 \\ & & & & 16 \end{bmatrix}.$$

The growth factor $\rho = 2^{m-1} = 16$.

4. Gaussian elimination with complete pivoting (GECP):

- Both rows and columns are interchanged
- After m-1 steps, **A** becomes an upper-triangular matrix **U**:

$$\mathbf{L}_{m-1}\mathbf{P}_{m-1}\cdots\mathbf{L}_{2}\mathbf{P}_{2}\mathbf{L}_{1}\mathbf{P}_{1}\mathbf{A}\mathbf{Q}_{1}\mathbf{Q}_{2}\cdots\mathbf{Q}_{m-1}=\mathbf{U}.$$

Remark 13

GE with complete pivoting has the LU factorization

$$PAQ = LU$$
,

where
$$\mathbf{P} = \mathbf{P}_{m-1} \cdots \mathbf{P}_2 \mathbf{P}_1$$
, $\mathbf{Q} = \mathbf{Q}_1 \mathbf{Q}_2 \cdots \mathbf{Q}_{m-1}$, and

$$\mathbf{L} = \widehat{\mathbf{L}}_1^{-1} \widehat{\mathbf{L}}_2^{-1} \cdots \widehat{\mathbf{L}}_{m-1}^{-1} = \mathbf{P}_{m-1} \cdots \mathbf{P}_3 \mathbf{P}_2 \mathbf{L}_1^{-1} \mathbf{P}_2^{-1} \mathbf{L}_2^{-1} \mathbf{P}_3^{-1} \cdots \mathbf{P}_{m-1}^{-1} \mathbf{L}_{m-1}^{-1}.$$

Remark 14

The permutation matrices P and Q are not known ahead of time.

4.1. GECP for Ax = b

 $\bullet \ \mathbf{PAQ} = \mathbf{LU}, \quad \mathbf{Ly} = \mathbf{Pb}, \quad \mathbf{Uz} = \mathbf{y}, \quad \mathbf{x} = \mathbf{Qz}$

Algorithm: LU factorization PAQ = LU in GECP

The details are left as an exercise.

• Discussion:

How to modify the pseudocode of the algorithms in this lecture when memory space (as low as possible) is taken into account?

See Shufang Xu, Li Gao, and Pingwen Zhang's book.