Lecture 6: Convex sets and convex functions



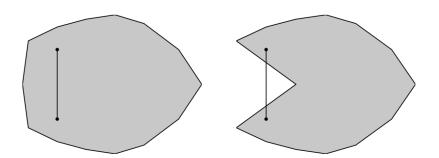
School of Mathematical Sciences, Xiamen University

1. Convex sets

• A set $C \in \mathbb{R}^n$ is a *convex set* if the straight line segment connecting any two points in C lies entirely inside C. Formally,

$$\forall \mathbf{x}, \mathbf{y} \in \mathcal{C}, \ \alpha \in [0, 1] : \quad \alpha \mathbf{x} + (1 - \alpha) \mathbf{y} \in \mathcal{C}.$$

Example: A convex set (left) and a non-convex set (right).



1.1 Basic properties of convex sets

• If $\alpha \in \mathbb{R}$ and \mathcal{C} is convex, then

$$\alpha \mathcal{C} := \{ \alpha \mathbf{x} : \mathbf{x} \in \mathcal{C} \}$$

is convex.

• If all C_i , i = 1 : m, are convex. Then the Cartesian product

$$C_1 \times C_2 \times \cdots \times C_m := \{(\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_m) : \mathbf{x}_i \in C_i\}$$

is convex.

• The convex hull of a set of points $\mathbf{x}_1, \dots, \mathbf{x}_m \in \mathbb{R}^n$, defined by

$$\operatorname{conv}\{\mathbf{x}_1,\cdots,\mathbf{x}_m\} := \left\{ \sum_{i=1}^m \lambda_i \mathbf{x}_i : \lambda_i \ge 0, \sum_{i=1}^m \lambda_i = 1 \right\},\,$$

is convex. Let $S \subseteq \mathbb{R}^n$. Then

$$conv(\mathcal{S}) = \left\{ \sum_{i=1}^{k} \lambda_i \mathbf{x}_i : \lambda_i \ge 0, \mathbf{x}_i \in \mathcal{S}, \sum_{i=1}^{k} \lambda_i = 1, k \in \mathbb{N} \right\}$$

is the "smallest" convex set containing S.

• If $\alpha_i \in \mathbb{R}$ and all C_i are convex, then

$$C = \sum_{i=1}^{m} \alpha_i C_i := \left\{ \sum_{i=1}^{m} \alpha_i \mathbf{x}_i : \mathbf{x}_i \in C_i \right\}$$

is convex.

• Let $C \subseteq \mathbb{R}^n$ be a convex set and let $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $\mathbf{B} \in \mathbb{R}^{n \times m}$. Then the sets

$$\mathbf{A}(\mathcal{C}) := {\mathbf{A}\mathbf{x} : \mathbf{x} \in \mathcal{C}}, \quad \mathbf{B}^{-1}(\mathcal{C}) := {\mathbf{y} \in \mathbb{R}^m : \mathbf{B}\mathbf{y} \in \mathcal{C}}$$

are both convex.

• If C_{α} are convex sets for each $\alpha \in A$, where A is an arbitrary index set (possibly infinite), then the intersection

$$\mathcal{C} = \bigcap_{\alpha \in \mathcal{A}} \mathcal{C}_{\alpha}$$

is convex.

Theorem 1 (Projection onto closed convex sets)

Let C be a closed convex set and $\mathbf{x} \in \mathbb{R}^n$. Then there is a unique point $\pi_{C}(\mathbf{x})$, called the projection of \mathbf{x} onto C, such that

$$\|\mathbf{x} - \pi_{\mathcal{C}}(\mathbf{x})\|_2 = \inf_{\mathbf{y} \in \mathcal{C}} \|\mathbf{y} - \mathbf{x}\|_2,$$

that is,

$$\pi_{\mathcal{C}}(\mathbf{x}) = \underset{\mathbf{y} \in \mathcal{C}}{\operatorname{argmin}} \|\mathbf{y} - \mathbf{x}\|_{2}.$$

A point z is the projection of x onto C, i.e.,

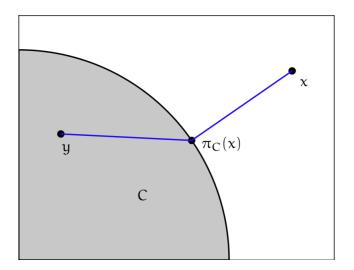
$$\mathbf{z} = \pi_{\mathcal{C}}(\mathbf{x}),$$

if and only if

$$\langle \mathbf{x} - \mathbf{z}, \mathbf{y} - \mathbf{z} \rangle \le 0,$$

for all $y \in C$.

• Projection of the point \mathbf{x} onto the set \mathcal{C} (with projection $\pi_{\mathcal{C}}(\mathbf{x})$), exhibiting $\langle \mathbf{x} - \pi_{\mathcal{C}}(\mathbf{x}), \mathbf{y} - \pi_{\mathcal{C}}(\mathbf{x}) \rangle \leq 0$.



Corollary 2 (Nonexpansiveness)

Projections onto closed convex sets are nonexpansive, in particular,

$$\|\pi_{\mathcal{C}}(\mathbf{x}) - \mathbf{y}\|_2 \le \|\mathbf{x} - \mathbf{y}\|_2$$

for any $\mathbf{x} \in \mathbb{R}^n$ and $\mathbf{y} \in \mathcal{C}$.

Theorem 3 (Strict separation of points)

Let C be a closed convex set. For any $\mathbf{x} \notin C$, the vector

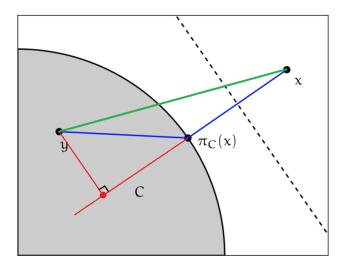
$$\mathbf{v} = \mathbf{x} - \pi_{\mathcal{C}}(\mathbf{x})$$

satisfies

$$\langle \mathbf{v}, \mathbf{x} \rangle \geq \sup_{\mathbf{y} \in \mathcal{C}} \langle \mathbf{v}, \mathbf{y} \rangle + \|\mathbf{v}\|_2^2 > \sup_{\mathbf{y} \in \mathcal{C}} \langle \mathbf{v}, \mathbf{y} \rangle.$$

This means the strict separation of the point $\mathbf{x} \notin \mathcal{C}$ from the closed convex set \mathcal{C} .

• Strict separation of \mathbf{x} from \mathcal{C} by the vector $\mathbf{v} = \mathbf{x} - \pi_{\mathcal{C}}(\mathbf{x})$.



• For nonempty sets S_1 and S_2 satisfying $S_1 \cap S_2 = \emptyset$, if there exist vector $\mathbf{v} \neq \mathbf{0}$ and scalar b such that

$$\langle \mathbf{v}, \mathbf{x} \rangle \geq b$$
 for all $\mathbf{x} \in \mathcal{S}_1$,

and

$$\langle \mathbf{v}, \mathbf{x} \rangle \leq b$$
 for all $\mathbf{x} \in \mathcal{S}_2$,

then

$$\{\mathbf{x} \in \mathbb{R}^n \mid \langle \mathbf{v}, \mathbf{x} \rangle = b\}$$

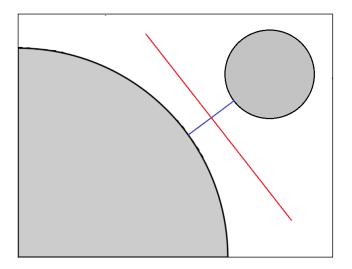
is called a separating hyperplane for nonempty sets S_1 and S_2 .

Theorem 4 (Strict separation of closed convex sets)

Let C_1, C_2 be closed convex sets, with C_2 compact and $C_1 \cap C_2 = \emptyset$. Then there is a vector \mathbf{v} such that

$$\inf_{\mathbf{x} \in \mathcal{C}_1} \langle \mathbf{v}, \mathbf{x} \rangle > \sup_{\mathbf{x} \in \mathcal{C}_2} \langle \mathbf{v}, \mathbf{x} \rangle.$$

• Strict separation of closed convex sets.



• For a set S and a boundary point x, i.e.,

$$\mathbf{x} \in \mathrm{bd}\mathcal{S} := \mathrm{cl}\mathcal{S} \setminus \mathrm{int}\mathcal{S},$$

if vector $\mathbf{v} \neq \mathbf{0}$ satisfies

$$\langle \mathbf{v}, \mathbf{x} \rangle \ge \langle \mathbf{v}, \mathbf{y} \rangle$$
 for all $\mathbf{y} \in \mathcal{S}$,

then

$$\{\mathbf{z} \in \mathbb{R}^n \mid \mathbf{v}^\top (\mathbf{z} - \mathbf{x}) = 0\}$$

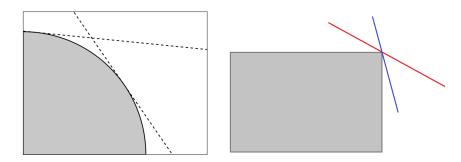
is called a supporting hyperplane supporting S at x.

Theorem 5 (Supporting hyperplane theorem)

For convex set C and any $\mathbf{x} \in \mathrm{bd}C$, theres exists a supporting hyperplane supporting C at \mathbf{x} , i.e., $\exists \ \mathbf{v} \neq \mathbf{0}$ satisfying

$$\langle \mathbf{v}, \mathbf{x} \rangle \ge \langle \mathbf{v}, \mathbf{y} \rangle$$
 for all $\mathbf{y} \in \mathcal{C}$.

• Supporting hyperplanes to a convex set. (unique?)



Theorem 6 (Halfspace intersections)

Let $\mathcal{C} \subset \mathbb{R}^n$ be a closed convex set. Then \mathcal{C} is the intersection of all the halfspaces containing it. Moreover, $\mathcal{C} = \bigcap_{\mathbf{x} \in \mathrm{bd}\mathcal{C}} \mathcal{H}_{\mathbf{x}}$, where $\mathcal{H}_{\mathbf{x}}$ denotes the intersection of the halfspaces contained in the hyperplanes supporting \mathcal{C} at \mathbf{x} .

2. Convex functions

• A function $f: \mathcal{C} \to \mathbb{R}$ defined on a convex set $\mathcal{C} \subseteq \mathbb{R}^n$ is called convex (or convex over \mathcal{C}) if for any $\mathbf{x}, \mathbf{y} \in \mathcal{C}$, $\lambda \in [0, 1]$,

$$f(\lambda \mathbf{x} + (1 - \lambda)\mathbf{y}) \le \lambda f(\mathbf{x}) + (1 - \lambda)f(\mathbf{y}).$$

It is called *strictly convex* if for any $\mathbf{x} \neq \mathbf{y}$, $\lambda \in (0, 1)$,

$$f(\lambda \mathbf{x} + (1 - \lambda)\mathbf{y}) < \lambda f(\mathbf{x}) + (1 - \lambda)f(\mathbf{y}).$$

Examples of convex functions: afines functions, norms.

• Jensen's inequality.

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex function defined on the convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Then for any $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k \in \mathcal{C}$ and $\lambda_i \geq 0, \sum_{i=1}^k \lambda_i = 1$, the following inequality holds:

$$f\left(\sum_{i=1}^k \lambda_i \mathbf{x}_i\right) \le \sum_{i=1}^k \lambda_i f(\mathbf{x}_i).$$

2.1 Characterizations of convex functions

Theorem 7 (the gradient inequality)

Let $f: \mathcal{C} \to \mathbb{R}$ be a continuously differentiable function defined on a nonempty convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Then f is convex over \mathcal{C} if and only if

$$f(\mathbf{x}) + \nabla f(\mathbf{x})^{\top} (\mathbf{y} - \mathbf{x}) \le f(\mathbf{y})$$
 for any $\mathbf{x}, \mathbf{y} \in \mathcal{C}$,

and f is strictly convex over C if and only if

$$f(\mathbf{x}) + \nabla f(\mathbf{x})^{\top}(\mathbf{y} - \mathbf{x}) < f(\mathbf{y}) \text{ for any } \mathbf{x}, \mathbf{y} \in \mathcal{C} \text{ satisfying } \mathbf{x} \neq \mathbf{y}.$$

Theorem 8 (monotonicity of the gradient)

Suppose that f is a continuously differentiable function over a nonempty convex set $C \subseteq \mathbb{R}^n$. Then f is convex over C if and only if

$$(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y}))^{\top}(\mathbf{x} - \mathbf{y}) \ge 0$$
 for any $\mathbf{x}, \mathbf{y} \in \mathcal{C}$.

Proposition 9

Let f be a continuously differentiable function which is convex over a convex set $C \subseteq \mathbb{R}^n$.

- (1) Suppose that $\nabla f(\mathbf{x}_{\star}) = \mathbf{0}$ for some $\mathbf{x}_{\star} \in \mathcal{C}$. Then \mathbf{x}_{\star} is a global minimizer of f over \mathcal{C} .
- (2) If $C = \mathbb{R}^n$, then $\nabla f(\mathbf{x}_{\star}) = \mathbf{0}$ if and only if \mathbf{x}_{\star} is a global minimizer of f over \mathbb{R}^n .

Theorem 10 (second order characterization of convex functions)

Let f be a twice continuously differentiable function over a nonempty convex set $C \subseteq \mathbb{R}^n$. Then

- (1) If $\nabla^2 f(\mathbf{x}) \succeq \mathbf{0}$ for any $\mathbf{x} \in \mathcal{C}$, then f is convex over \mathcal{C} .
- (2) If $\nabla^2 f(\mathbf{x}) \succ \mathbf{0}$ for any $\mathbf{x} \in \mathcal{C}$, then f is strictly convex over \mathcal{C} .
- (3) If C is open, then f is convex over C if and only if $\nabla^2 f(\mathbf{x}) \succeq \mathbf{0}$ for any $\mathbf{x} \in C$.

2.2 Operations preserving convexity

Theorem 11 (nonnegative scalar multiplication and summation)

- (1) Let f be a convex function defined over a convex set $\mathcal{C} \subseteq \mathbb{R}^n$ and let $\alpha \geq 0$. Then αf is a convex function over \mathcal{C} .
- (2) Let $f_1, f_2, ..., f_p$ be convex functions over a convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Then the sum function $f_1 + f_2 + \cdots + f_p$ is convex over \mathcal{C} .

Theorem 12 (affine change of variables)

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex function defined on a convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Let $\mathbf{A} \in \mathbb{R}^{n \times m}$ and $\mathbf{b} \in \mathbb{R}^n$. Then the function g defined by

$$g(\mathbf{y}) = f(\mathbf{A}\mathbf{y} + \mathbf{b})$$

is convex over the convex set

$$\mathcal{D} = \{ \mathbf{y} \in \mathbb{R}^m : \mathbf{A}\mathbf{y} + \mathbf{b} \in \mathcal{C} \}.$$

Theorem 13 (composition with a nondecreasing convex function)

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex function over the convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Let $g: \mathcal{I} \to \mathbb{R}$ be a one-dimensional nondecreasing convex function over the interval $\mathcal{I} \subseteq \mathbb{R}$. Assume that the image of \mathcal{C} under f is contained in $\mathcal{I}: f(\mathcal{C}) \subseteq \mathcal{I}$. Then the composition of g with f defined by

$$h(\mathbf{x}) \equiv g(f(\mathbf{x})), \quad \mathbf{x} \in \mathcal{C},$$

is a convex function over C.

Theorem 14 (pointwise maximum of convex functions)

Let $f_1, \ldots, f_p : \mathcal{C} \to \mathbb{R}$ be p convex functions over the convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Then the maximum function

$$f(\mathbf{x}) = \max_{i=1,\dots,p} f_i(\mathbf{x})$$

is a convex function over C.

Theorem 15 (partial minimization)

Let $f: \mathcal{C} \times \mathcal{D} \to \mathbb{R}$ be a convex function defined over the set $\mathcal{C} \times \mathcal{D}$, where $\mathcal{C} \subseteq \mathbb{R}^m$ and $\mathcal{D} \subseteq \mathbb{R}^n$ are convex sets. Let

$$g(\mathbf{x}) = \min_{\mathbf{y} \in \mathcal{D}} f(\mathbf{x}, \mathbf{y}), \quad \mathbf{x} \in \mathcal{C},$$

where we assume that the minimal value (maybe not attained) in the above definition is finite. Then g is convex over C.

• Let $\mathcal{C} \subseteq \mathbb{R}^n$ be a nonempty convex set and $\|\cdot\|$ an arbitrary norm. The distance function defined by

$$d(\mathbf{x}, \mathcal{C}) = \min_{\mathbf{y} \in \mathcal{C}} \|\mathbf{x} - \mathbf{y}\|$$

is convex since the function $f(\mathbf{x}, \mathbf{y}) = ||\mathbf{x} - \mathbf{y}||$ is convex over $\mathbb{R}^n \times \mathcal{C}$.

2.3 Level sets of convex functions

• Let $f: \mathcal{S} \to \mathbb{R}$ be a function defined over a set $\mathcal{S} \subseteq \mathbb{R}^n$. Then the level set of f with level $\alpha \in \mathbb{R}$ is given by

$$Lev(f, \alpha) = \{ \mathbf{x} \in \mathcal{S} : f(\mathbf{x}) \le \alpha \}.$$

Theorem 16 (level sets of convex functions are convex)

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex function defined over a convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Then for any $\alpha \in \mathbb{R}$ the level set $\text{Lev}(f, \alpha)$ is convex.

- A function $f: \mathcal{C} \to \mathbb{R}$ defined over the convex set $\mathcal{C} \subseteq \mathbb{R}^n$ is called quasi-convex if for any $\alpha \in \mathbb{R}$ the set $\text{Lev}(f, \alpha)$ is convex.
- Quasi-convex functions may be nonconvex. For example, $f(x) = \sqrt{|x|}$ with level sets

$$\operatorname{Lev}(f,\alpha) = \begin{cases} [-\alpha^2,\alpha^2], & \alpha \geq 0, \\ \emptyset, & \alpha < 0. \end{cases}$$

2.4 Continuity and differentiability of convex functions

• Convex functions are always continuous at interior points of their domain. Thus, for example, functions which are convex over \mathbb{R}^n are always continuous. A stronger result is given below.

Theorem 17 (local Lipschitz continuity at interior points)

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex function defined over a convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Let $\mathbf{x}_0 \in \operatorname{int}(\mathcal{C})$. Then there exist $\varepsilon > 0$ and L > 0 such that $\mathcal{B}[\mathbf{x}_0, \varepsilon] \subseteq \mathcal{C}$ and

$$|f(\mathbf{x}) - f(\mathbf{x}_0)| \le L ||\mathbf{x} - \mathbf{x}_0||$$

for all $\mathbf{x} \in \mathcal{B}[\mathbf{x}_0, \varepsilon]$.

Theorem 18 (existence of directional derivatives at interior points)

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex function defined over a convex set $\mathcal{C} \subseteq \mathbb{R}^n$. Let $\mathbf{x} \in \text{int}(\mathcal{C})$. Then for any $\mathbf{d} \neq \mathbf{0}$, the directional derivative $f'(\mathbf{x}; \mathbf{d})$ exists.

2.5 Extended real-valued function

• The effective domain of an extended real-valued function $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ is defined as

$$dom(f) := \{ \mathbf{x} \mid f(\mathbf{x}) < +\infty \}.$$

- An extended real-valued function is called *proper* if there exists at least one $\mathbf{x} \in \mathbb{R}^n$ such that $f(\mathbf{x}) < +\infty$, meaning that $\text{dom}(f) \neq \emptyset$.
- An extended real-valued function f is convex if $\forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and $\alpha \in [0, 1]$ the following inequality holds:

$$f((1-\alpha)\mathbf{x} + \alpha\mathbf{y}) \leq (1-\alpha)f(\mathbf{x}) + \alpha f(\mathbf{y}),$$

where we use the arithmetic with $+\infty$:

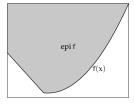
$$a + (+\infty) = +\infty \ (a \in \mathbb{R}), \quad b \cdot (+\infty) = +\infty \ (b > 0),$$

and

$$0 \cdot (+\infty) = 0.$$

- The definition of convexity of extended real-valued functions is equivalent to saying that dom(f) is a convex set and that the restriction of f to its effective domain dom(f) is a convex function.
- The epigraph of $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ is defined by

$$\operatorname{epi}(f) = \{(\mathbf{x}, y) : f(\mathbf{x}) \le y, \mathbf{x} \in \mathbb{R}^n, y \in \mathbb{R}\}.$$





An extended real-valued function f convex " \Leftrightarrow " $\operatorname{epi}(f)$ convex.

Theorem 19

Let $f_i: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ be an extended real-valued convex function for any $i \in \mathcal{I}$ (\mathcal{I} being an arbitrary index set). Then $f(\mathbf{x}) = \max_{i \in \mathcal{I}} f_i(\mathbf{x})$ is an extended real-valued convex function.

2.6 Maxima of convex functions

Theorem 20

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex function which is not constant over the convex set \mathcal{C} . Then f does not attain a maximum at a point in $int(\mathcal{C})$.

• Let $C \subseteq \mathbb{R}^n$ be a convex set. A point $\mathbf{x} \in C$ is called an *extreme* point of C if there do not exist $\mathbf{x}_1, \mathbf{x}_2 \in C, \mathbf{x}_1 \neq \mathbf{x}_2$, and $\lambda \in (0, 1)$ such that $\mathbf{x} = \lambda \mathbf{x}_1 + (1 - \lambda)\mathbf{x}_2$. The set of extreme points is denoted by ext(C).

Theorem 21 (Krein-Milman)

Let $C \subseteq \mathbb{R}^n$ be a compact convex set. Then C = conv(ext(C)).

Theorem 22

Let $f: \mathcal{C} \to \mathbb{R}$ be a convex and continuous function over the nonempty convex and compact set $\mathcal{C} \subseteq \mathbb{R}^n$. Then there exists at least one maximizer of f over \mathcal{C} that is an extreme point of \mathcal{C} .

2.7 Convexity and inequalities

• The arithmetic geometric mean inequality

For any $x_1, \ldots, x_n \geq 0$ and $\lambda \in \Delta_n$ the following inequality holds:

$$\sum_{i=1}^{n} \lambda_i x_i \ge \prod_{i=1}^{n} x_i^{\lambda_i}.$$

• Young's inequality

For any $s,t\geq 0$ and p,q>1 satisfying 1/p+1/q=1 it holds that

$$st \le s^p/p + t^q/q.$$

• Hölder's inequality

For any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and $p, q \in [1, \infty]$ satisfying 1/p + 1/q = 1, it holds that

$$|\mathbf{x}^{\top}\mathbf{y}| \leq ||\mathbf{x}||_p ||\mathbf{y}||_q.$$

• Minkowski's inequality

Let $p \geq 1$. For any $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$, $\|\mathbf{x} + \mathbf{y}\|_p \leq \|\mathbf{x}\|_p + \|\mathbf{y}\|_p$.