## Answer to Q2

## July 15, 2019

```
In [1]: import numpy as np
        print("Jun Qing 1002088, and Shaun Toh 1002012, done in collaboration")
        action0 = np.array([[0.1,0.5,0.4],[0.2,0.2,0.6],[0.8,0.1,0.1]])
        action1 = np.array([[0.3,0.3,0.4],[0.3,0.4,0.3],[0.6,0.2,0.2]])
        a0r=np.array([1,2,4])
        a1r=np.array([0,5,2])
        action0=action0.transpose()
        action1=action1.transpose() # this is transposed to allow for
        #correct multiplication
        actionOmat = actionO*aOr # rewards for actionO and its various states.
        action1mat = action1*a1r # blah
        print("action 0:\n",action0)
        print()
        print("action 1:\n",action1)
        print()
        print("reward for action 0:\n",action0)
        print()
        print("rewards for action 1:\n",action1)
        print()
        print("rewards weighed via probabilities for action 0\n", action0mat)
        print()
        print("rewards weighed via probabilities for action 1\n", action1mat)
        print()
        eff_val_0 = np.sum(action0mat,axis=1)
        eff_val_1 =np.sum(action1mat,axis=1)
        print("In the order of state0, state1, state2...")
        print("effective value of an action 0 given current state:\n",eff_val_0)
        print()
        print("effective value of action 1 given current state:\n",eff_val_1)
        print()
        print("however, we have a set policy already of")
        print("doing action 1 in state 0, and state 2")
        print("while doing action 0 in state 1 only.")
        print("As a result we can ignore the rewards for irrelevant actions,")
        print("obtaining the rewards obtained by the policy per movement.")
        true_eff_val = np.array([eff_val_1[0],eff_val_0[1],eff_val_1[2]])
        print(["s=0","s=1","s=2"])
        print(true_eff_val)
```

```
Jun Qing 1002088, and Shaun Toh 1002012, done in collaboration
action 0:
[[0.1 0.2 0.8]
 [0.5 0.2 0.1]
[0.4 0.6 0.1]]
action 1:
 [[0.3 0.3 0.6]
 [0.3 \ 0.4 \ 0.2]
 [0.4 0.3 0.2]]
reward for action 0:
 [[0.1 0.2 0.8]
 [0.5 0.2 0.1]
 [0.4 0.6 0.1]]
rewards for action 1:
 [[0.3 0.3 0.6]
 [0.3 0.4 0.2]
[0.4 0.3 0.2]]
rewards weighed via probabilities for action 0
 [[0.1 0.4 3.2]
 [0.5 0.4 0.4]
 [0.4 1.2 0.4]]
rewards weighed via probabilities for action 1
 [[0. 1.5 1.2]
[0. 2. 0.4]
[0. 1.5 0.4]]
In the order of state0, state1, state2...
effective value of an action O given current state:
 [3.7 1.3 2.]
effective value of action 1 given current state:
[2.7 2.4 1.9]
however, we have a set policy already of
doing action 1 in state 0, and state 2
while doing action 0 in state 1 only.
As a result we can ignore the rewards for irrelevant actions,
obtaining the rewards obtained by the policy per movement.
['s=0', 's=1', 's=2']
[2.7 1.3 1.9]
In [2]: print("there are hence 3^3 possible policy values depending on the states.")
```

```
val_list1 = []
        val_list2 = [] # tuple output... of real, gamma, gamma square
        val_list3 = []
        states_list =[]
        for i in range(len(true_eff_val)):
            for j in range(len(true_eff_val)):
                for k in range(len(true_eff_val)):
                    print("Landed in State",i, "then State",j,"then State", k)
                    print("k=1 value")
                    val_list1.append((true_eff_val[i],0,0))
                    print("Real Value: ",true_eff_val[j],
                          " Gamma value:",0, "Gamma square value:",0)
                    print("k=2 value")
                    val_list2.append((true_eff_val[j],true_eff_val[i],0))
                    print("Real Value: ",true_eff_val[j],
                          " Gamma value:",true_eff_val[i], "Gamma square value:",0)
                    print("k=3 value")
                    print("Real Value: ",true_eff_val[k],
                          " Gamma value: ",true_eff_val[j], "Gamma square value: ",true_eff_val[i]
                    val_list3.append((true_eff_val[k],true_eff_val[j],true_eff_val[i]))
                    states_list.append((i,j,k))
                    print()
                    print()
there are hence 3<sup>3</sup> possible policy values depending on the states.
Landed in State O then State O then State O
k=1 value
Real Value: 2.7 Gamma value: 0 Gamma square value: 0
k=2 value
Real Value: 2.7 Gamma value: 2.7 Gamma square value: 0
k=3 value
Real Value: 2.7 Gamma value: 2.7 Gamma square value: 2.7
Landed in State O then State O then State 1
k=1 value
Real Value: 2.7 Gamma value: 0 Gamma square value: 0
k=2 value
Real Value: 2.7 Gamma value: 2.7 Gamma square value: 0
k=3 value
Real Value: 1.3 Gamma value: 2.7 Gamma square value: 2.7
```

print("\n")

Landed in State O then State O then State 2

k=1 value

Real Value: 2.7 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 2.7 Gamma value: 2.7 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 2.7 Gamma square value: 2.7

Landed in State O then State 1 then State O

k=1 value

Real Value: 1.3 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.3 Gamma value: 2.7 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 1.3 Gamma square value: 2.7

Landed in State O then State 1 then State 1

k=1 value

Real Value: 1.3 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.3 Gamma value: 2.7 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 1.3 Gamma square value: 2.7

Landed in State O then State 1 then State 2

k=1 value

Real Value: 1.3 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.3 Gamma value: 2.7 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 1.3 Gamma square value: 2.7

Landed in State O then State 2 then State O

k=1 value

Real Value: 1.9 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.9 Gamma value: 2.7 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 1.9 Gamma square value: 2.7

Landed in State O then State 2 then State 1

k=1 value

Real Value: 1.9 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.9 Gamma value: 2.7 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 1.9 Gamma square value: 2.7

Landed in State 0 then State 2 then State 2

k=1 value

Real Value: 1.9 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.9 Gamma value: 2.7 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 1.9 Gamma square value: 2.7

Landed in State 1 then State 0 then State 0

k=1 value

Real Value: 2.7 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 2.7 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 2.7 Gamma square value: 1.3

Landed in State 1 then State 0 then State 1  $\,$ 

k=1 value

Real Value: 2.7 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 2.7 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 2.7 Gamma square value: 1.3

Landed in State 1 then State 0 then State 2

k=1 value

Real Value: 2.7 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 2.7 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 2.7 Gamma square value: 1.3

Landed in State 1 then State 1 then State 0

k=1 value

Real Value: 1.3 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.3 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 1.3 Gamma square value: 1.3

Landed in State 1 then State 1 then State 1

k=1 value

Real Value: 1.3 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.3 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 1.3 Gamma square value: 1.3

Landed in State 1 then State 1 then State 2

k=1 value

Real Value: 1.3 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.3 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 1.3 Gamma square value: 1.3

Landed in State 1 then State 2 then State 0

k=1 value

Real Value: 1.9 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.9 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 1.9 Gamma square value: 1.3

Landed in State 1 then State 2 then State 1

k=1 value

Real Value: 1.9 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.9 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 1.9 Gamma square value: 1.3

Landed in State 1 then State 2 then State 2

k=1 value

Real Value: 1.9 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.9 Gamma value: 1.3 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 1.9 Gamma square value: 1.3

Landed in State 2 then State 0 then State 0

k=1 value

Real Value: 2.7 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 2.7 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 2.7 Gamma square value: 1.9

Landed in State 2 then State 0 then State 1

k=1 value

Real Value: 2.7 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 2.7 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 2.7 Gamma square value: 1.9

Landed in State 2 then State 0 then State 2

k=1 value

Real Value: 2.7 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 2.7 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 2.7 Gamma square value: 1.9

Landed in State 2 then State 1 then State 0

k=1 value

Real Value: 1.3 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.3 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 1.3 Gamma square value: 1.9

Landed in State 2 then State 1 then State 1

k=1 value

Real Value: 1.3 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.3 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 1.3 Gamma square value: 1.9

Landed in State 2 then State 1 then State 2

k=1 value

Real Value: 1.3 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.3 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 1.3 Gamma square value: 1.9

Landed in State 2 then State 2 then State 0

k=1 value

Real Value: 1.9 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.9 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 2.7 Gamma value: 1.9 Gamma square value: 1.9

Landed in State 2 then State 2 then State 1

k=1 value

Real Value: 1.9 Gamma value: 0 Gamma square value: 0

k=2 value

Real Value: 1.9 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 1.3 Gamma value: 1.9 Gamma square value: 1.9

Landed in State 2 then State 2 then State 2  $\,$ 

k=1 value

Real Value: 1.9 Gamma value: O Gamma square value: O

k=2 value

Real Value: 1.9 Gamma value: 1.9 Gamma square value: 0

k=3 value

Real Value: 1.9 Gamma value: 1.9 Gamma square value: 1.9