Deadlock

Shareable vs Non-shareable resources

► Sharable resources

- can be used by multiple processes during their execution.
- ► e.g., CPU, I/O bus.

▶ Non-sharable resources

- cannot be used by multiple processes during their execution.
- e.g., printer

Static vs. Dynamic resource allocation

- ► **Static**: Allocate all the required resources prior to the execution of the process.
- ▶ Dynamic: Allocate only the initially required resources to start up the process; additional resources will be allocated dynamically.

Static	Dynamic
 Simpler to implement Process is guaranteed to complete in definite time 	Comparatively complexNo certainty about the process completion
Resource utilization lessDeadlock will never occur	Better resource utilizationMay lead to deadlock

Deadlock

- ▶ Deadlock is a situation where a set of processes are blocked.
- ► Each process in the set waits for some event from some other process in the same set.
- ► Example #1
 - ► A system has 2 disk drives
 - \triangleright P_1 and P_2 each hold one disk drive and each needs the other one
- Example #2
 - ► Semaphores *A* and *B*, initialized to 1

P_0	P_{1}
wait (A);	wait(B)
wait (B);	wait(A)



Deadlock Characterization

Deadlock can arise if <u>four</u> conditions hold simultaneously.

- ▶ Mutual exclusion: only one process at a time can use a resource
- ► Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes
- ► **No preemption:** a resource can be released only voluntarily by the process holding it after that process has completed its task
- ▶ **Circular wait:** there exists a set $\{P_0, P_1, ..., P_n\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1 , P_1 is waiting for a resource that is held by P_2 , ..., P_{n-1} is waiting for a resource that is held by P_n , and P_n is waiting for a resource that is held by P_0

Methods for Handling Deadlocks

Prevention

▶ Ensure that the system will never enter a deadlock state

Avoidance

► Ensure that the system will never enter an unsafe state

Detection

► Allow the system to enter a deadlock state and then recover

Deadlock Prevention

Restrain at least one of the causes of deadlock

- ► Mutual Exclusion The mutual-exclusion condition must hold for non-sharable resources.
- ► Hold and Wait we must guarantee that whenever a process requests a resource, it does not hold any other resources
 - ► There is no guarantee that a file that is released by a process will be in the same state when it will get for the next time.

Deadlock Prevention

▶ No Preemption

- ▶ If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are preempted.
- ▶ Preempted resources are added to the list of available resources.
- ▶ A process will be restarted only when it can regain its old resources, and the new ones that it is requesting

Deadlock Prevention

Circular Wait

- ▶ impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration. For example:
 - 1. R1
 - 2. R2
 - 3. R3
 - 4. R4

If P_i holds R3 and requests for R2 then it has release R3 first and re-request for R2 then R3

What if R3 is a file!!

Deadlock Avoidance and Safe State

- ▶ When a process requests an available resource, the system must decide if immediate allocation leaves the system in a *safe state*
- ► A system is in a safe state only if there exists a *safe sequence of execution*
- Total number of resources=12

Process	Max Needs	Allocated	Current Needs
P0	10	5	5
P1	4	2	2
P2	7	3	4

- ▶ P0 requests one more resource dynamically. Can it be granted?
 - ► <P1,P2,P0> is a safe sequence of execution

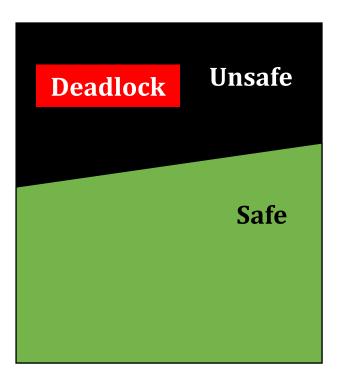
Safe State (continued)

▶ If a system is in <u>safe</u> state \Rightarrow no deadlocks

▶ If a system is in <u>unsafe</u> state \Rightarrow possibility of deadlock

► Avoidance ⇒ ensure that a system will <u>never</u> enter an <u>unsafe</u> state

Safe, Unsafe, Deadlock State



Avoidance algorithms

► For a <u>single</u> instance of a resource type, use a *resource-allocation graph (RAG)*

► For <u>multiple</u> instances of a resource type, use the *banker's algorithm*

- ightharpoonup G = (V, E)
- V: Processes and Resources
- E: Request edge, Allocation edge, Claim edge

Process:

 P_i

Claim edge:

$$P_i \longrightarrow R_j$$

Resource:

 R_{i}

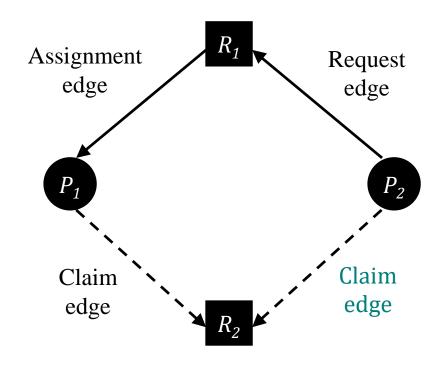
Request edge:

$$P_i \longrightarrow R_j$$

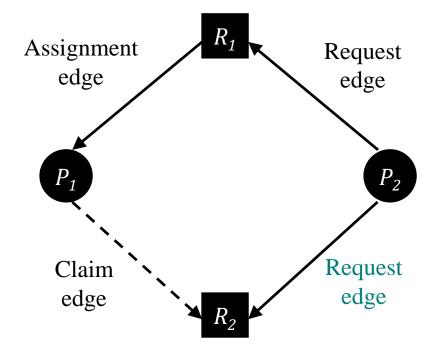
Assignment edge:

$$P_i \longleftarrow R_j$$

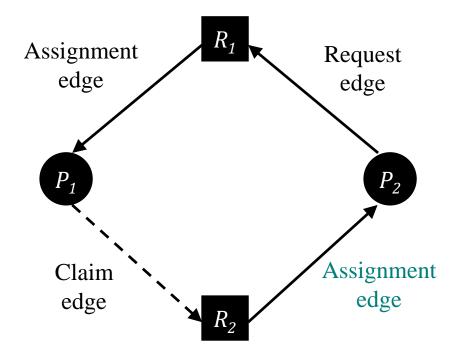
- ► Claim edge $P_i - \rightarrow R_j$ indicates that process P_j may request resource R_j ; which is represented by a dashed line
- ► A <u>claim edge</u> converts to a <u>request edge</u> when a process **requests** a resource
- ► A <u>request edge</u> converts to an <u>assignment edge</u> when the resource is **allocated** to the process







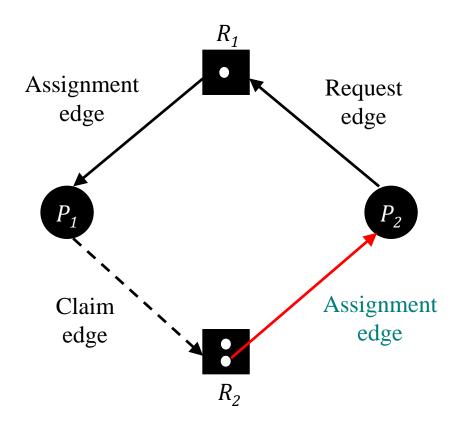
Presence of Cycle in RAG may lead to DEADLOCK



lacktriangle Suppose that process P_i requests a resource R_j

► The request can be granted only if converting the <u>request edge</u> to an <u>assignment edge</u> does not result in the formation of a <u>cycle</u> in the resource allocation graph

► RAG algorithm doesn't work for multiple instances of resources.



Banker's Algorithm

- ► When a process makes a request for a set of resources,
- ► Resource Request Algorithm:
 - assume that the request is granted,
 - Update the system state accordingly,
 - ► Then, determine if the result is a safe state (Safety algo)
 - If so, grant the request
 - if not, block the process until it is safe to grant the request.

Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- ▶ *Available*: Vector of length m. If *Available* [j] = k, there are k instances of resource type R_i available.
- Max: $n \times m$ matrix. If Max[i,j] = k, then process P_i may request at most k instances of resource type R_{i} .
- ▶ *Allocation*: $n \times m$ matrix. If *Allocation*[i,j] = k then P_i is currently allocated k instances of R_i .
- ▶ *Need*: $n \times m$ matrix. If *Need*[*i,j*] = k, then P_i may need k more instances of R_i to complete its task.

```
Need [i,j] = Max[i,j] - Allocation [i,j]
```

Safety Algorithm

- Initialize Work = Available
 Initialize Finish[i] = False, for i = 1,2,3,..n
- 2. Find an i such that:
 Finish[i] == False and Need[i] <= Work</p>
 If no such i exists, go to step 4.
- 3. Work = Work + Allocation[i]Finish[i] = Truegoto step 2
- 4. if Finish[i] == True for all i, then the system is in a safe state.

Initially Available=(10,5,7)

Pro	Al	locatio	n		Need		Available			
cess	A	В	С	A	В	С	A	В	С	
P0	0	1	0	7	4	3	3	3	2	
P1	2	0	0	1	2	2				
P2	3	0	2	6	0	0				
Р3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

Updated State.

Let's check for a safe sequence.

Pro	Al	locatio	n		Need		Available			
cess	A	В	С	A	В	С	A	В	С	
P0	0	1	0	7	4	3	2	3	0	
P1	3	0	2	0	2	0				
P2	3	0	2	6	0	0				
Р3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

P1 can be completed.

Pro	Al	locatio	n		Need		Available			
cess	A	В	С	A	В	С	A	В	С	
P0	0	1	0	7	4	3	5	3	2	
P1	0	0	0	0	0	0				
P2	3	0	2	6	0	0				
Р3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

P3 can be completed.

Pro	Al	locatio	n		Need		A	Available		
cess	A	В	С	A	В	С	A	В	С	
P0	0	1	0	7	4	3	7	4	3	
P1	0	0	0	0	0	0				
P2	3	0	2	6	0	0				
Р3	0	0	0	0	0	0				
P4	0	0	2	4	3	1				

P4 can be completed.

Pro	Al	locatio	n	Need				Available			
cess	A	В	С	A	В	С	ı	A	В	С	
P0	0	1	0	7	4	3		7	4	5	
P1	0	0	0	0	0	0					
P2	3	0	2	6	0	0					
Р3	0	0	0	0	0	0					
P4	0	0	0	0	0	0					

P0 can be completed.

Pro	Al	locatio	n		Need				Available			
cess	A	В	С	ı	A	В	С		A	В	С	
P0	0	0	0		0	0	0		7	5	5	
P1	0	0	0		0	0	0					
P2	3	0	2		6	0	0					
Р3	0	0	0		0	0	0					
P4	0	0	0		0	0	0					

P2 can be completed.

Pro	Al	locatio	n	Need				Available			
cess	A	В	С	A	В	С		A	В	С	
P0	0	0	0	0	0	0		10	5	7	
P1	0	0	0	0	0	0					
P2	0	0	0	0	0	0					
Р3	0	0	0	0	0	0					
P4	0	0	0	0	0	0					

Safe Sequence: <P1,P3,P4,P0,P2>

Pro	Al	locatio	n		Need		Available			
cess	A	В	С	A	В	С	A	В	С	
P0	0	1	0	7	4	3	2	3	0	
P1	3	0	2	0	2	0				
P2	3	0	2	6	0	0				
Р3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

P1 makes $Request_1 = (1,0,2) \longrightarrow GRANTED$

Pro	Al	locatio	n		Need		Available			
cess	A	В	С	A	В	С	A	В	С	
P0	0	1	0	7	4	3	2	3	0	
P1	3	0	2	0	2	0				
P2	3	0	2	6	0	0				
Р3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

Now, P4 makes Request₄ = (3,3,0) --> NOT AVAILABLE

Pro cess	Allocation				Need		Available			
	A	В	С	A	В	С	A	В	С	
P0	0	1	0	7	4	3	2	3	0	
P1	3	0	2	0	2	0				
P2	3	0	2	6	0	0				
Р3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

Now, P0 makes $Request_0 = (0,2,0)$

Updated State.

Let's check for a safe sequence.

Pro cess	Allocation				Need		Available			
	A	В	С	A	В	С	A	В	С	
P0	0	3	0	7	2	3	2	1	0	
P1	3	0	2	0	2	0				
P2	3	0	2	6	0	0				
Р3	2	1	1	0	1	1				
P4	0	0	2	4	3	1				

Now, P0 makes $Request_0 = (0,2,0)$

No process can complete

Pro cess	Allocation				Need		Available		
	A	В	С	A	В	С	A	В	С
P0	0	3	0	7	2	3	2	1	0
P1	3	0	2	0	2	0			
P2	3	0	2	6	0	0			
Р3	2	1	1	0	1	1			
P4	0	0	2	4	3	1			

Now, P0 makes Request₀ = (0,2,0)--> NOT GRANTED

Revert back to previous state

Pro cess	Allocation				Need		Available		
	A	В	С	A	В	С	A	В	С
P0	0	1	0	7	4	3	2	3	0
P1	3	0	2	0	2	0			
P2	3	0	2	6	0	0			
Р3	2	1	1	0	1	1			
P4	0	0	2	4	3	1			

Disadvantage: Time complexity is very high.

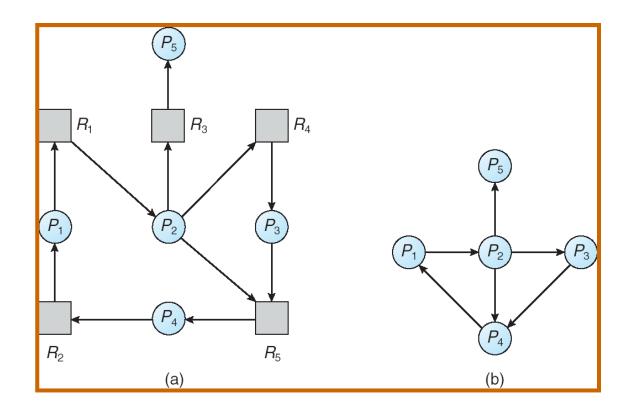
Deadlock Detection and Recovery

- ► An algorithm that examines the state of the system to detect whether a deadlock has occurred
- ► And an algorithm to recover from the deadlock

Deadlock Detection: Single Instance of Each Resource Type

- Requires the creation and maintenance of a <u>wait for</u> graph (WFG)
 - variant of the resource-allocation graph
 - ► The graph is obtained by **removing** the <u>resource</u> nodes from a RAG and **collapsing** the appropriate edges
 - ► Consequently; all nodes are processes
 - $ightharpoonup P_i \rightarrow P_j$ if P_i is waiting for P_j
- Periodically invoke an algorithm that searches for a cycle in the graph
 - ▶ If there is a cycle, there exists a deadlock
 - An algorithm to detect a cycle in a graph requires an <u>order of n^2 </u> operations, where n is the number of vertices in the graph

Deadlock Detection: Single Instance of Each Resource Type



Resource-Allocation Graph

Corresponding wait-for graph

Deadlock Detection: Multiple Instances of Resource Types

Variation of Banker's Algorithm

- Initialize Work = Available
 Initialize Finish[i] = False, for i = 1,2,3,..n
- 2. Find an i such that:
 Finish[i] == False and Request[i] <= Work</pre>
 - If no such i exists, go to step 4.
- 3. Work = Work + Allocation[i]Finish[i] = Truegoto step 2
- 4. if Finish[i] == true for all i, then the system is not in deadlocked state

Deadlock Detection Algorithm: Example

Sequence <P0, P2, P3, P1, P4> results in Finish[i] == true for all i

⇒ System is not in deadlocked state

Pro cess	Allocation				Reques	t	Available		
	A	В	С	A	В	С	A	В	С
P0	0	1	0	0	0	0	0	0	0
P1	2	0	0	2	0	2			
P2	3	0	3	0	0	0			
Р3	2	1	1	1	0	0			
P4	0	0	2	0	0	2			

Deadlock Detection Algorithm: Example

Finish[0] is Ture but **P1**, **P2**, **P3**, **P4** are deadlocked.

Pro cess	Allocation				Reques	t	Available		
	A	В	С	A	В	С	A	В	С
P0	0	1	0	0	0	0	0	0	0
P1	2	0	0	2	0	2			
P2	3	0	3	0	0	1			
Р3	2	1	1	1	0	0			
P4	0	0	2	0	0	2			

Recovery from Deadlock

- ► Two Approaches
 - ▶ Process termination
 - ► Resource preemption

Recovery from Deadlock: Process Termination

- ► Abort all deadlocked processes
 - ► This approach will break the deadlock, but at great expense
- ► Abort one process at a time until the deadlock cycle is eliminated
 - ► This approach incurs considerable overhead, since, after each process is aborted, a deadlock-detection algorithm must be re-invoked to determine whether any processes are still deadlocked
- ► Many factors may affect which process is chosen for termination
 - ▶ What is the priority of the process?
 - ► How long has the process run so far and how much longer will the process need to run before completing its task?
 - ► How many and what type of resources has the process used?
 - ► How many more resources does the process need in order to finish its task?
 - How many processes will need to be terminated?

Recovery from Deadlock: Resource Preemption

- ► With this approach, we successively preempt some resources from processes and give these resources to other processes until the deadlock cycle is broken
- ► When preemption is required to deal with deadlocks, then three issues need to be addressed:
 - ► **Selecting a victim** Which resources and which processes are to be preempted?
 - ► **Rollback** If we preempt a resource from a process, what should be done with that process?
 - ➤ **Starvation** How do we ensure that starvation will not occur? That is, how can we guarantee that resources will not always be preempted from the same process?

Summary

- ► Both deadlock avoidance and deadlock detection and recovery are expensive
- ▶ **Do nothing**: ignore the problem altogether and pretend that deadlocks never occur in the system (used by Windows and Unix)
 - ► System administrator/user will restart the processes