

CHAPTER 27

Lecture No. 27

27.1 The Inner Product

If \mathbf{u} and \mathbf{v} are vectors in \mathbb{R}^n , then we regard \mathbf{u} and \mathbf{u} as $n \times 1$ matrices.

The transpose \mathbf{u}^T is a $1 \times n$ matrix, and the matrix product $\mathbf{u}^T \mathbf{v}$ is a 1×1 matrix, which we write as a single real number (a scalar) without brackets.

The number $\mathbf{u}^T \mathbf{v}$ is called the inner product of \mathbf{u} and \mathbf{v} , and often it is written as $\mathbf{u} \cdot \mathbf{v}$.

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \cdot \\ \cdot \\ u_n \end{bmatrix} \quad \text{and} \quad \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \cdot \\ \cdot \\ v_n \end{bmatrix}$$

then the inner product of \mathbf{u} and \mathbf{v} is

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + \dots + u_n v_n.$$

Example: Compute $\mathbf{u} \cdot \mathbf{v}$ and $\mathbf{v} \cdot \mathbf{u}$ for \mathbf{u} and \mathbf{v} for $\mathbf{u} = \begin{bmatrix} 2 \\ -5 \\ -1 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} 3 \\ 2 \\ -3 \end{bmatrix}$.

Theorem: Let \mathbf{u} , \mathbf{v} , and \mathbf{w} be vectors in \mathbb{R}^n , and let c be a scalar. Then

1. $\mathbf{v} \cdot \mathbf{u} = \mathbf{u} \cdot \mathbf{v}$
2. $(\mathbf{v} + \mathbf{u}) \cdot \mathbf{w} = \mathbf{v} \cdot \mathbf{w} + \mathbf{u} \cdot \mathbf{w}$
3. $(c\mathbf{u}) \cdot \mathbf{v} = \mathbf{u} \cdot (c\mathbf{v}) = c(\mathbf{v} \cdot \mathbf{u})$
4. $\mathbf{u} \cdot \mathbf{u} \geq 0$, and $\mathbf{u} \cdot \mathbf{u} = 0$ if and only if $\mathbf{u} = \mathbf{0}$

The Length of a Vector: The length (or norm) of \mathbf{v} is the nonnegative scalar $\|\mathbf{v}\|$ defined by

$$\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2} = \mathbf{v} \cdot \mathbf{v}, \quad \text{and} \quad \|\mathbf{v}\|^2 = \mathbf{v} \cdot \mathbf{v}$$

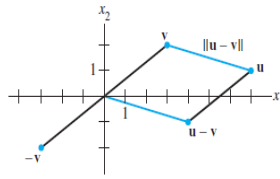
Example: Let $\mathbf{v} = (1, -2, 2, 0)$. Find a unit vector \mathbf{u} in the direction of \mathbf{v} .

Solution: the unit vector is $\frac{\mathbf{v}}{\sqrt{\mathbf{v} \cdot \mathbf{v}}}$.

Example: Let W be the subspace of \mathbb{R}^2 spanned by $\mathbf{x} = (2/3, 1)$. Find a unit vector \mathbf{z} that is a basis for W .

Distance in \mathbb{R}^n : For \mathbf{u} and \mathbf{v} in \mathbb{R}^n , the distance between \mathbf{u} and \mathbf{v} , written as $\text{dist}(\mathbf{u}, \mathbf{v})$, is the length of the vector $\mathbf{u} - \mathbf{v}$. That is

$$\text{dist}(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|.$$



Example: Compute the distance between the vectors $\mathbf{u} = (2, -1, 2, 1)$, $\mathbf{v} = (1, -2, 2, 0)$.

Example: Compute the distance between the vectors $\mathbf{u} = (u_1, u_2, u_3)$, $\mathbf{v} = (v_1, v_2, v_3)$.

27.2 Orthogonal Vectors

Two vectors \mathbf{u} and \mathbf{v} are orthogonal (to each other) if $\mathbf{u} \cdot \mathbf{v} = 0$.

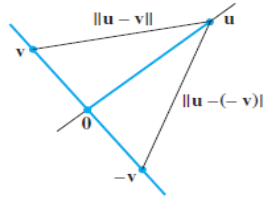


Figure 27.1: Orthogonal vectors

Theorem: Two vectors \mathbf{u} and \mathbf{v} are orthogonal if and only if $\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$.

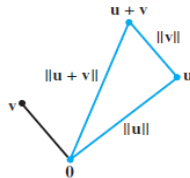
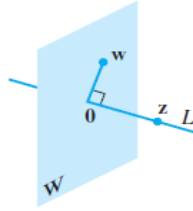


Figure 27.2: Orthogonal vectors

Orthogonal Complements: If a vector \mathbf{z} is orthogonal to every vector in a subspace W of \mathbb{R}^n , then \mathbf{z} is said to be orthogonal to W . The set of all vectors \mathbf{z} that

are orthogonal to W is called the orthogonal complement of W and is denoted by W^\perp .

Example: Let W be a plane through the origin in \mathbb{R}^3 , and let L be the line through the origin and perpendicular to W . If \mathbf{z} and \mathbf{w} are nonzero, \mathbf{z} is on L , and \mathbf{w} is in W then the line segment from $\mathbf{0}$ to \mathbf{z} is perpendicular to the line segment from $\mathbf{0}$ to \mathbf{w} ; that is, $\mathbf{z} \cdot \mathbf{w} = 0$.



So each vector on L is orthogonal to every w in W .

In fact, L consists of all vectors that are orthogonal to the w 's in W , and W consists of all vectors orthogonal to the z 's in L . That is,

$$L = W^\perp \quad \text{and} \quad W = L^\perp.$$

Orthogonal Complements:

1. A vector \mathbf{x} is in W^\perp if and only if \mathbf{x} is orthogonal to every vector in a set that spans W .
2. W is a subspace of \mathbb{R}^n .

Theorem: Let A be an $m \times n$ matrix. The orthogonal complement of the row space of A is the null space of A , and the orthogonal complement of the column space of A is the null space of A^T :

$$(\text{Row } A)^\perp = \text{Nul } A \quad \text{and} \quad (\text{Col } A)^\perp = \text{Nul } A^T.$$

Orthogonal Sets: A set of vectors $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ in \mathbb{R}^n is said to be an orthogonal set if each pair of distinct vectors from the set is orthogonal, that is, if $\mathbf{u}_i \cdot \mathbf{u}_j = 0$ whenever $i \neq j$.

Example: Show that $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal set, where

$$\mathbf{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \quad \mathbf{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}$$

Theorem: If $S = \{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an orthogonal set of nonzero vectors in \mathbb{R}^n , then S is linearly independent and hence is a basis for the subspace spanned by S .

Orthogonal Basis: An orthogonal basis for a subspace W of \mathbb{R}^n is a basis for W that is also an orthogonal set.

Theorem: If $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ be an orthogonal basis for a subspace W of \mathbb{R}^n , For each \mathbf{y} in W , the weights in the linear combination

$$\mathbf{y} = c_1 \mathbf{u}_1 + \dots + c_p \mathbf{u}_p$$

are given by

$$c_j = \frac{\mathbf{y} \cdot \mathbf{u}_j}{\mathbf{u}_j \cdot \mathbf{u}_j}, \quad (j = 1, \dots, p).$$

Example: The set $S = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal basis for \mathbb{R}^3 where

$$\mathbf{u}_1 = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \quad \mathbf{u}_3 = \begin{bmatrix} -1/2 \\ -2 \\ 7/2 \end{bmatrix}.$$

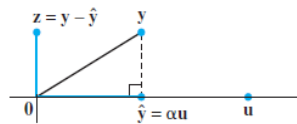
Express the vector $\mathbf{y} = \begin{bmatrix} 6 \\ 1 \\ -8 \end{bmatrix}$ as a linear combination of the vectors in S .

An Orthogonal Projection: Given a nonzero vector \mathbf{u} in \mathbb{R}^n , consider the problem of decomposing a vector \mathbf{y} in \mathbb{R}^n into the sum of two vectors, one a multiple of \mathbf{u} and the other orthogonal to \mathbf{u} . We wish to write

$$\mathbf{y} = \hat{\mathbf{y}} + \mathbf{z}$$

where $\hat{\mathbf{y}} = \alpha \mathbf{u}$ for some scalar α and \mathbf{z} is some vector orthogonal to \mathbf{u} .

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u}.$$



Example: Let $\mathbf{y} = \begin{bmatrix} 7 \\ 2 \end{bmatrix}$ and $\mathbf{u} = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$. Find the orthogonal projection of \mathbf{y} onto \mathbf{u} . Then write \mathbf{y} as the sum of two orthogonal vectors, one in $\text{Span}\{\mathbf{u}\}$ and one orthogonal to \mathbf{u} .

Solution: Compute

$$\mathbf{y} \cdot \mathbf{u} = \begin{bmatrix} 7 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 2 \end{bmatrix} = 40, \quad \mathbf{u} \cdot \mathbf{u} = \begin{bmatrix} 4 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 2 \end{bmatrix} = 20.$$

The orthogonal projection is

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} = \frac{40}{20} \mathbf{u} = \begin{bmatrix} 8 \\ 4 \end{bmatrix}.$$

27.3 Orthonormal Sets

A set of vectors $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ in \mathbb{R}^n is said to be an orthogonal set if each pair of distinct vectors from the set is orthogonal, that is, if $\mathbf{u}_i \cdot \mathbf{u}_j = 0$ whenever $i \neq j$ and $\mathbf{u}_i \cdot \mathbf{u}_i = 1$.

Example: Show that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthonormal basis in \mathbb{R}^3 , where

$$\mathbf{v}_1 = \begin{bmatrix} 3/\sqrt{11} \\ 1/\sqrt{11} \\ 1/\sqrt{11} \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -1/\sqrt{6} \\ 2/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} -1/\sqrt{66} \\ -4/\sqrt{66} \\ 7/\sqrt{66} \end{bmatrix}.$$

Theorem: An $m \times n$ matrix U has orthonormal columns if and only if $U^T U = I$.

Theorem: Let U be an $m \times n$ matrix with orthonormal columns, and let \mathbf{x} and \mathbf{y} be in \mathbb{R}^n . Then

1. $\|U\mathbf{x}\| = \|\mathbf{x}\|$
2. $(U\mathbf{x}) \cdot (U\mathbf{y}) = \mathbf{x} \cdot \mathbf{y}$
3. $(U\mathbf{x}) \cdot (U\mathbf{y}) = 0$ if and only if $\mathbf{x} \cdot \mathbf{y} = 0$.

Example: Let $U = \begin{bmatrix} 1/\sqrt{2} & 2/3 \\ 1/\sqrt{2} & -2/3 \\ 0 & 1/3 \end{bmatrix}$, and $\mathbf{x} = \begin{bmatrix} \sqrt{2} \\ 3 \end{bmatrix}$. Show that U has orthonormal columns and verify that $\|U\mathbf{x}\| = \|\mathbf{x}\|$.

The matrix

$$U = \begin{bmatrix} 3/\sqrt{11} & -1/\sqrt{6} & -1/\sqrt{66} \\ 1/\sqrt{11} & 2/\sqrt{6} & -4/\sqrt{66} \\ 1/\sqrt{11} & 1/\sqrt{6} & 7/\sqrt{66} \end{bmatrix}$$

is an orthogonal matrix because it is square and because its columns are orthonormal. Verify that the rows are orthonormal, too.

27.4 Some Practice Problems

Question: Determine which set of vectors are orthogonal

$$\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -5 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -5 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 6 \end{bmatrix}.$$

Question: Compute orthogonal projection of $\begin{bmatrix} 1 \\ 7 \end{bmatrix}$ onto the line passing through $\begin{bmatrix} -4 \\ 2 \end{bmatrix}$ and the origin.

Question: Suppose W is a subspace of \mathbb{R}^n spanned by n nonzero orthogonal vectors. Explain why $W = \mathbb{R}^n$.

Question: Let U be a square matrix with orthonormal columns. Explain why U is invertible.

Question: Let U be an $n \times n$ orthogonal matrix. how that the rows of U form an orthonormal basis of \mathbb{R}^n .

CHAPTER 28

Lecture No. 28

Question: Suppose W is a subspace of \mathbb{R}^n spanned by n nonzero orthogonal vectors. Explain why $W = \mathbb{R}^n$.

Solution: We know that an orthogonal set of vectors is linearly independent. Hence form a basis for the space W . Consequently, dimension of W is n and $W = \mathbb{R}^n$.

28.1 Orthogonal Projections

The orthogonal projection of a point in \mathbb{R}^2 onto a line through the origin has an important analogue in \mathbb{R}^n .

Given a vector \mathbf{y} and a subspace W in \mathbb{R}^n , there is a vector $\hat{\mathbf{y}}$ in W such that

(1) $\hat{\mathbf{y}}$ is the unique vector in W for which $\mathbf{y} - \hat{\mathbf{y}}$ is orthogonal to W , and

(2) $\hat{\mathbf{y}}$ is the unique vector in W closest to \mathbf{y} .

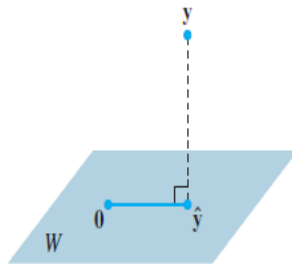


Figure 28.1: Shortest distance

These two properties of $\hat{\mathbf{y}}$ provide the key to finding least-squares solutions of linear systems

Example: Let $\{\mathbf{u}_1, \dots, \mathbf{u}_5\}$ be an orthonormal basis for \mathbb{R}^5 and let

$$\mathbf{y} = c_1\mathbf{u}_1 + \dots + c_5\mathbf{u}_5.$$

Consider the subspace $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$, and write \mathbf{y} as the sum of a vector \mathbf{z}_1 in W and a vector \mathbf{z}_2 in W^\perp .

Solution: Write $\mathbf{y} = c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + \dots + c_5\mathbf{u}_5$

where $\mathbf{z}_1 = c_1\mathbf{u}_1 + c_2\mathbf{u}_2$ is in $\text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$ and $\mathbf{z}_2 = c_3\mathbf{u}_3 + c_4\mathbf{u}_4 + c_5\mathbf{u}_5$ is in $\text{Span}\{\mathbf{u}_3, \mathbf{u}_4, \mathbf{u}_5\}$.

Theorem: The Orthogonal Decomposition Theorem

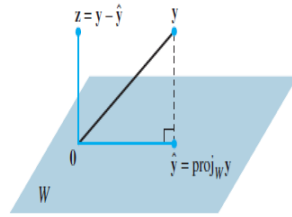
Let W be a subspace of \mathbb{R}^n . Then each \mathbf{y} in \mathbb{R}^n can be written uniquely in the form

$$\mathbf{y} = \hat{\mathbf{y}} + \mathbf{z}$$

where $\hat{\mathbf{y}}$ is in W and \mathbf{z} is in W^\perp .

In fact, if $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is any orthogonal basis of W , then

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \dots + \frac{\mathbf{y} \cdot \mathbf{u}_p}{\mathbf{u}_p \cdot \mathbf{u}_p} \mathbf{u}_p.$$



The vector $\hat{\mathbf{y}}$ is called the orthogonal projection of \mathbf{y} onto W and is often is written $\text{proj}_W \mathbf{y}$.

Example: Let $\mathbf{u}_1 = \begin{bmatrix} 2 \\ 5 \\ -1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$, and $\mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$. Observe that $\{\mathbf{u}_1, \mathbf{u}_2\}$ is an orthogonal basis for $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$. Write \mathbf{y} as the sum of a vector in W and a vector orthogonal to W .

Solution: The orthogonal projection of \mathbf{y} onto W is

$$\begin{aligned} \hat{\mathbf{y}} &= \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2 \\ &= \frac{9}{30} \begin{bmatrix} 2 \\ 5 \\ -1 \end{bmatrix} + \frac{3}{6} \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} = \frac{9}{30} \begin{bmatrix} 2 \\ 5 \\ -1 \end{bmatrix} + \frac{15}{30} \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -2/5 \\ 2 \\ 1/5 \end{bmatrix}. \end{aligned}$$

Also

$$\mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \begin{bmatrix} -2/5 \\ 2 \\ 1/5 \end{bmatrix} = \begin{bmatrix} 7/5 \\ 0 \\ 14/5 \end{bmatrix}.$$

28.2 A Geometric Interpretation of the Orthogonal Projection

When W is a subspace of \mathbb{R}^3 spanned by \mathbf{u}_1 and \mathbf{u}_2 . Here $\hat{\mathbf{y}}_1$ and $\hat{\mathbf{y}}_2$ denote the projections of \mathbf{y} onto the lines spanned by \mathbf{u}_1 and \mathbf{u}_2 , respectively.

The orthogonal projection $\hat{\mathbf{y}}$ of \mathbf{y} onto W is the sum of the projections of \mathbf{y} onto one-dimensional subspaces that are orthogonal to each other.

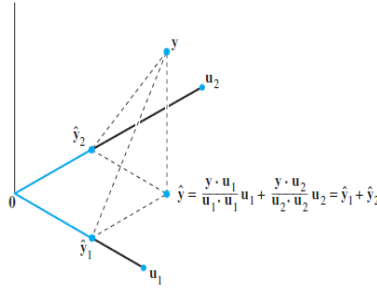


Figure 28.2: Geometric interpretation of orthogonal projection

Properties of Orthogonal Projections:

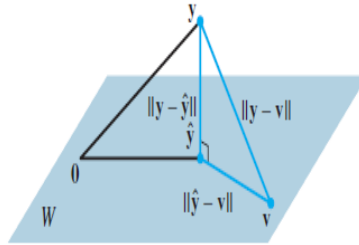
If \mathbf{y} is in $W = \text{Span}\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$, then $\text{proj}_W \mathbf{y} = \mathbf{y}$.

28.3 The Best Approximation Theorem

Let W be a subspace of \mathbb{R}^n , let \mathbf{y} be any vector in \mathbb{R}^n , and let $\hat{\mathbf{b}}$ be the orthogonal projection of \mathbf{y} onto W . Then $\hat{\mathbf{b}}$ is the closest point in W to \mathbf{y} , in the sense that

$$\|\mathbf{y} - \hat{\mathbf{b}}\| < \|\mathbf{y} - \mathbf{v}\|$$

for all \mathbf{v} in W distinct from $\hat{\mathbf{b}}$.



Remark: The vector $\hat{\mathbf{b}}$ is called the best approximation to \mathbf{y} by elements of W .

Example: If $\mathbf{u}_1 = \begin{bmatrix} 2 \\ 5 \\ -1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$, and $\mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, and $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$ then the closest point in W to \mathbf{y} is

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2 = \begin{bmatrix} -2/5 \\ 2 \\ 1/5 \end{bmatrix}.$$

Example: The distance from a point \mathbf{y} in \mathbb{R}^n to a subspace W is defined as the distance from \mathbf{y} to the nearest point in W . Find the distance from \mathbf{y} to $W =$

$\text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$, where $\mathbf{y} = \begin{bmatrix} -1 \\ -5 \\ 10 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 5 \\ -2 \\ 1 \end{bmatrix}$, and $\mathbf{u}_2 = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$.

Solution: By the Best Approximation Theorem, the distance from \mathbf{y} to W is $\|\mathbf{y} - \hat{\mathbf{y}}\|$, where $\hat{\mathbf{y}} = \text{proj}_W \mathbf{y}$. Since $\{\mathbf{u}_1, \mathbf{u}_2\}$ is an orthogonal basis for W ,

$$\begin{aligned}\hat{\mathbf{y}} &= \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2 = \frac{15}{30} \mathbf{u}_1 + \frac{-21}{6} \mathbf{u}_2 \\ &= \frac{1}{2} \begin{bmatrix} 5 \\ -2 \\ 1 \end{bmatrix} - \frac{7}{2} \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} -1 \\ -8 \\ 4 \end{bmatrix}.\end{aligned}$$

$$\|\mathbf{y} - \hat{\mathbf{y}}\|^2 = 0^2 + 3^2 + (-2)^2 = 45.$$

Theorem: If $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ is an orthonormal basis for a subspace W of \mathbb{R}^n , then

$$\text{proj}_W \mathbf{y} = (\mathbf{y} \cdot \mathbf{u}_1) \mathbf{u}_1 + (\mathbf{y} \cdot \mathbf{u}_2) \mathbf{u}_2 + \dots + (\mathbf{y} \cdot \mathbf{u}_p) \mathbf{u}_p.$$

If $U = [\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_p]$ then

$$\text{proj}_W \mathbf{y} = UU^T \mathbf{y} \quad \text{for all } \mathbf{y} \in \mathbb{R}^n.$$

Example: Let $\mathbf{y} = \begin{bmatrix} -9 \\ 1 \\ 6 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix}$, and $\mathbf{u}_2 = \begin{bmatrix} -9 \\ 1 \\ 6 \end{bmatrix}$, and $W = \text{Span}\{\mathbf{u}_1, \mathbf{u}_2\}$. Use this fact that \mathbf{u}_1 and \mathbf{u}_2 are orthogonal to compute $\text{proj}_W \mathbf{y}$.

28.4 Some Practice Problems

Question: Let $\mathbf{x} = \begin{bmatrix} 4 \\ 5 \\ -3 \\ 3 \end{bmatrix}$, $\mathbf{u}_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{u}_2 = \begin{bmatrix} -2 \\ 1 \\ -1 \\ 1 \end{bmatrix}$, $\mathbf{u}_3 = \begin{bmatrix} 1 \\ 1 \\ -2 \\ -1 \end{bmatrix}$, $\mathbf{u}_4 = \begin{bmatrix} -1 \\ 1 \\ 1 \\ -2 \end{bmatrix}$. Write \mathbf{x} as the sum of two vectors, one in $\text{Span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ and the other

in $\text{Span}\{\mathbf{u}_4\}$.

Question: Find the closed point to \mathbf{y} in the subspace W spanned by \mathbf{v}_1 and \mathbf{v}_2

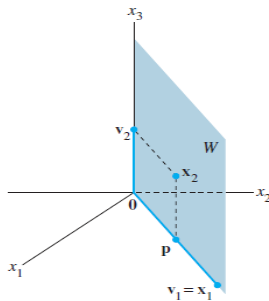
$$\mathbf{y} = \begin{bmatrix} 3 \\ 1 \\ 5 \\ 1 \end{bmatrix}, \quad \mathbf{v}_1 = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}.$$

Question: Find the best approximation to \mathbf{x} by vectors of the form $c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2$ as the vectors in previous example.

Lecture No. 29

29.1 The Gram-Schmidt process

The Gram-Schmidt process is a simple algorithm for producing an orthogonal or orthonormal basis for any nonzero subspace of \mathbb{R}^n .



Example: Let $W = \text{Span}\{\mathbf{x}_1, \mathbf{x}_2\}$, where $\mathbf{x}_1 = \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix}$ and $\mathbf{x}_2 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$. Construct an orthogonal basis $\{\mathbf{v}_1, \mathbf{v}_2\}$ for W .

Solution: Let $\mathbf{v}_1 = \mathbf{x}_1$ and

$$\mathbf{v}_2 = \mathbf{x}_2 - \mathbf{p} = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{x}_1}{\mathbf{x}_1 \cdot \mathbf{x}_1} \mathbf{x}_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} - \frac{15}{45} \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}.$$

Example: Let $W = \text{Span}\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\}$, where $\mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$, $\mathbf{x}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}$, and $\mathbf{x}_3 =$

$\begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$. Construct an orthogonal basis $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ for W which is subspace of \mathbb{R}^4 .

Solution: Step I: Let $\mathbf{v}_1 = \mathbf{x}_1$ and $W_1 = \text{Span}\{\mathbf{x}_1\} = \text{Span}\{\mathbf{v}_1\}$.

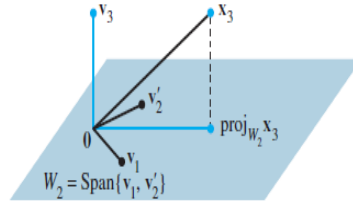
Step II: Let \mathbf{v}_2 be the vector produced by subtracting from \mathbf{x}_2 its projection onto

the subspace W_1 . That is, let

$$\mathbf{v}_2 = \mathbf{x}_2 - \text{proj}_{W_1} \mathbf{x}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{3}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -3/4 \\ 1/4 \\ 1/4 \\ 1/4 \end{bmatrix}.$$

\mathbf{v}_2 is the component of \mathbf{x}_2 orthogonal to \mathbf{x}_1 and $\{\mathbf{v}_1, \mathbf{v}_2\}$ is an orthogonal basis for the subspace W_2 Spanned by \mathbf{x}_1 and \mathbf{x}_2 .

Step II' Optional: Scale \mathbf{v}_2 , we get $\mathbf{v}'_2 = \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix}$.



Step III: Let \mathbf{v}_3 be the vector produced by subtracting from \mathbf{x}_3 its projection onto the subspace W_2 . Use the orthogonal basis $\{\mathbf{v}_1, \mathbf{v}'_2\}$ to compute this projection onto W_2 :

$$\text{proj}_{W_2} \mathbf{x}_3 = \frac{\mathbf{x}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 + \frac{\mathbf{x}_3 \cdot \mathbf{v}'_2}{\mathbf{v}'_2 \cdot \mathbf{v}'_2} \mathbf{v}'_2 = \frac{2}{4} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \frac{2}{12} \begin{bmatrix} -3 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2/3 \\ 2/3 \\ 2/3 \end{bmatrix}$$

Then \mathbf{v}_3 is the component of \mathbf{x}_3 orthogonal to W_2 , namely,

$$\mathbf{v}_3 = \mathbf{x}_3 - \text{proj}_{W_2} \mathbf{x}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 2/3 \\ 2/3 \\ 2/3 \end{bmatrix} = \begin{bmatrix} 0 \\ -2/3 \\ 1/3 \\ 1/3 \end{bmatrix}.$$

Theorem: The Gram-Schmidt Process

Given a basis $\{\mathbf{x}_1, \dots, \mathbf{x}_p\}$ for a nonzero subspace W of \mathbb{R}^n , define

$$\begin{aligned} \mathbf{v}_1 &= \mathbf{x}_1 \\ \mathbf{v}_2 &= \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 \\ \mathbf{v}_3 &= \mathbf{x}_3 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{x}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 \\ &\vdots \\ &\vdots \\ \mathbf{v}_p &= \mathbf{x}_p - \frac{\mathbf{x}_p \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{x}_p \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 - \dots - \frac{\mathbf{x}_p \cdot \mathbf{v}_{p-1}}{\mathbf{v}_{p-1} \cdot \mathbf{v}_{p-1}} \mathbf{v}_{p-1}. \end{aligned}$$

Then $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is an orthogonal basis for W . In addition, we have

$$\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_k\} = \text{Span}\{\mathbf{x}_1, \dots, \mathbf{x}_k\} \quad \text{for } 1 \leq k \leq p.$$

Example: Let $W = \text{Span}\{\mathbf{x}_1, \mathbf{x}_2\}$, where

$$\mathbf{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{x}_2 = \begin{bmatrix} 1/3 \\ 1/3 \\ -2/3 \end{bmatrix}.$$

Construct an orthonormal basis for W .

Orthonormal Basis: Construct an orthonormal basis for the subspace spanned by the vectors

$$\mathbf{v}_1 = \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}.$$

Example: Find an orthogonal basis for the column space and null space of the matrix

$$\begin{bmatrix} 1 & 3 & 5 \\ -1 & -3 & 1 \\ 0 & 2 & 3 \\ 1 & 5 & 2 \\ 1 & 5 & 8 \end{bmatrix}.$$

29.2 Some Practice Problems

Question: Find an orthogonal basis for the column space and null space of each matrix

$$\begin{bmatrix} 3 & -5 & 1 \\ 1 & 1 & 1 \\ -1 & 5 & -2 \\ 3 & -7 & 8 \end{bmatrix}, \quad \begin{bmatrix} 1 & 3 & 5 & 0 \\ -1 & -3 & 1 & 1 \\ 0 & 2 & 3 & 1 \\ 1 & 5 & 2 & 2 \end{bmatrix}.$$

Question: Mark each statement as true or false

1. If $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthogonal basis for W , then multiplying \mathbf{v}_3 by a scalar c gives a new orthogonal basis $\{\mathbf{v}_1, \mathbf{v}_2, c\mathbf{v}_3\}$.
2. If $W = \text{Span}\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\}$ with $\{\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3\}$ linearly independent, and if $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthogonal set in W , then $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a basis for W .
3. If \mathbf{x} is not in a subspace W , then $\mathbf{x} - \text{proj}_W \mathbf{x}$ is not zero.

Question: Construct an orthogonal basis using Gram-Schmidt process for $\mathbf{v}_1 =$

$$\begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 8 \\ 5 \\ -6 \end{bmatrix}, \quad \mathbf{x}_1 = \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}, \quad \mathbf{x}_2 = \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix}.$$

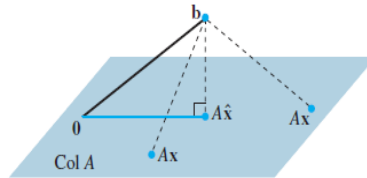
Lecture No. 30

30.1 Least Squares Solutions

If A is $m \times n$ and \mathbf{b} is in \mathbb{R}^m , a least-squares solution of $A\mathbf{x} = \mathbf{b}$ is an $\hat{\mathbf{x}}$ in \mathbb{R}^n such that

$$\|\mathbf{b} - A\hat{\mathbf{x}}\| \leq \|\mathbf{b} - A\mathbf{x}\|$$

for all \mathbf{x} in \mathbb{R}^n .



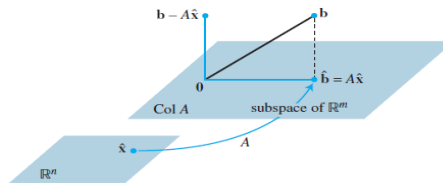
Remark: The most important aspect of the least-squares problem is that no matter what \mathbf{x} we select, the vector $A\mathbf{x}$ will necessarily be in the column space, $\text{Col } A$. So we seek an \mathbf{x} that makes $A\mathbf{x}$ the closest point in $\text{Col } A$ to \mathbf{b} .

Solution of the General Least-Squares Problem: Given A and \mathbf{b} , apply the Best Approximation Theorem to the subspace $\text{Col } A$. Let

$$\hat{\mathbf{b}} = \text{proj}_{\text{Col } A} \mathbf{b}$$

Because $\hat{\mathbf{b}}$ is in the column space of A , the equation $A\mathbf{x} = \hat{\mathbf{b}}$ is consistent, and there is an $\hat{\mathbf{x}}$ in \mathbb{R}^n such that

$$A\hat{\mathbf{x}} = \hat{\mathbf{b}}.$$



Since $\hat{\mathbf{x}}$ is the closest point in $\text{Col } A$ to \mathbf{b} , a vector $\hat{\mathbf{x}}$ is a least-squares solution of $A\mathbf{x} = \mathbf{b}$ if and only if $A\hat{\mathbf{x}} = \hat{\mathbf{b}}$. Suppose $\hat{\mathbf{x}}$ satisfies $A\hat{\mathbf{x}} = \hat{\mathbf{b}}$. By the Orthogonal Decomposition Theorem the projection $\hat{\mathbf{b}}$ has the property that $\mathbf{b} - \hat{\mathbf{b}}$ is orthogonal to $\text{Col } A$, so $\mathbf{b} - A\hat{\mathbf{x}}$ is orthogonal to each column of A .