

Assignment 5: MEDIA ADVISOR Expert System using PROLOG/CLISP

Concept of Media Advisor

A decision-support system called MEDIA ADVISOR provides advice on selecting a medium for delivering a training program based on the trainee's job. For example, if a trainee is a mechanical technician responsible for maintaining hydraulic systems, an appropriate medium might be a workshop, where the trainee could learn how basic hydraulic components operate, how to troubleshoot hydraulics problems and how to make simple repairs to hydraulic systems. On the other hand, if a trainee is a clerk assessing insurance applications, a training program might include lectures on specific problems of the task, as well as tutorials where the trainee could evaluate real applications. For complex tasks, where trainees are likely to make mistakes, a training program should also include feedback on the trainee's performance.

Knowledge base

Rule: 1

if the environment is papers
or the environment is manuals
or the environment is documents
or the environment is textbooks
then the stimulus_situation is verbal

Rule: 2

if the environment is pictures
or the environment is illustrations
or the environment is photographs
or the environment is diagrams
then the stimulus_situation is visual

Rule: 3

if the environment is machines
or the environment is buildings
or the environment is tools
then the stimulus_situation is 'physical object'

Rule: 4

if the environment is numbers
or the environment is formulas
or the environment is 'computer programs'
then the stimulus_situation is symbolic

Knowledge base

Rule: 5

if the job is lecturing
or the job is advising
or the job is counselling
then the stimulus_response is oral

Rule: 6

if the job is building
or the job is repairing
or the job is troubleshooting
then the stimulus_response is 'hands-on'

Rule: 7

if the job is writing
or the job is typing
or the job is drawing
then the stimulus_response is documented

Rule: 8

if the job is evaluating
or the job is reasoning
or the job is investigating
then the stimulus_response is analytical

Rule: 9

if the stimulus_situation is 'physical object'
and the stimulus_response is 'hands-on'
and feedback is required
then medium is workshop

Rule: 10

if the stimulus_situation is symbolic
and the stimulus_response is analytical
and feedback is required
then medium is 'lecture – tutorial'

Rule: 11

if the stimulus_situation is visual
and the stimulus_response is documented
and feedback is not required
then medium is videocassette

Rule: 12

if the stimulus_situation is visual
and the stimulus_response is oral
and feedback is required
then medium is 'lecture – tutorial'

Knowledge base

Rule: 13

if the stimulus_situation is verbal
and the stimulus_response is analytical
and feedback is required
then medium is 'lecture – tutorial'

Rule: 14

if the stimulus_situation is verbal
and the stimulus_response is oral
and feedback is required
then medium is 'role-play exercises'

/* The SEEK directive sets up the goal of the rule set

seek medium

All facts are placed in the database

Object	Allowed values	Object	Allowed values
<i>environment</i>	<i>papers</i> <i>manuals</i> <i>documents</i> <i>textbooks</i> <i>pictures</i> <i>illustrations</i> <i>photographs</i> <i>diagrams</i> <i>machines</i> <i>buildings</i> <i>tools</i> <i>numbers</i> <i>formulas</i> <i>computer programs</i>	<i>job</i>	<i>lecturing</i> <i>advising</i> <i>counselling</i> <i>building</i> <i>repairing</i> <i>troubleshooting</i> <i>writing</i> <i>typing</i> <i>drawing</i> <i>evaluating</i> <i>reasoning</i> <i>investigating</i>
<i>stimulus_situation</i>	<i>verbal</i> <i>visual</i> <i>physical object</i> <i>symbolic</i>	<i>stimulus_ response</i>	<i>oral</i> <i>hands-on</i> <i>documented</i> <i>analytical</i>
		<i>feedback</i>	<i>required</i> <i>not required</i>

Goal

- The final goal of the rule-based expert system is to produce a solution to the problem based on input data. In MEDIA ADVISOR, the solution is a medium selected from the list of four options:

medium is workshop

medium is 'lecture – tutorial'

medium is videocassette

medium is 'role-play exercises'

Dialogue

- In the dialogue shown below, the expert system asks the user to input the data Needed to solve the problem (the environment, the job and feedback). Based on the answers supplied by the user (answers are indicated by arrows), the expert system applies rules from its knowledge base to infer that the stimulus_situation is physical object, and the stimulus_response is hands-on. Rule 9 then selects one of the allowed values of medium.

What sort of environment is a trainee dealing with on the job?

⇒ **machines**

Rule: 3

if the environment is machines
or the environment is buildings
or the environment is tools
then the stimulus_situation is 'physical object'

In what way is a trainee expected to act or respond on the job?

⇒ **repairing**

Rule: 6

if the job is building
or the job is repairing
or the job is troubleshooting
then the stimulus_response is 'hands-on'

Is feedback on the trainee's progress required during training?

⇒ **required**

Rule: 9

if the stimulus_situation is 'physical object'
and the stimulus_response is 'hands-on'
and feedback is required
then medium is workshop

medium is workshop

Inference techniques

- The standard inference technique in Leonardo is backward chaining with opportunistic forward chaining, which is the most efficient way to deal with the available information. However, Leonardo also enables the user to turn off either backward or forward chaining, and thus allows us to study each inference technique separately. Forward chaining is data-driven reasoning, so we need first to provide some data. Assume that

Forward Chaining

the environment is **machines**

‘environment’ instantiated by user input to ‘machines’

the job is **repairing**

‘job’ instantiated by user input to ‘repairing’

feedback is **required**

‘feedback’ instantiated by user input to ‘required’

The following process will then happen:

Rule: 3 fires ‘stimulus_situation’ instantiated by Rule: 3 to ‘physical object’

Rule: 6 fires ‘stimulus_response’ instantiated by Rule: 6 to ‘hands-on’

Rule: 9 fires ‘medium’ instantiated by Rule: 9 to ‘workshop’

No rules fire stop

Backward chaining

'medium' is 'workshop'

Pass 1

Trying Rule: 9

Rule: 9 stacked

Need to find object '**stimulus_situation**'

Object '**stimulus_situation**' sought as '**physical object**'

Pass 2

Trying Rule: 3

Rule: 3 stacked

Need to find object '**environment**'

Object '**environment**' sought as '**machines**'

ask environment

⇒**machines**

'**environment**' instantiated by user input to
'**machines**'

Trying Rule: 3

'**stimulus_situation**' instantiated by Rule: 3 to
'**physical object**'

Pass 3

Trying Rule: 9

Rule: 9 stacked

Need to find object '**stimulus_response**'

Object '**stimulus_response**' sought as '**hands-on**'

Backward chaining

Pass 4

Trying Rule: 6

Rule: 6 stacked

ask job

⇒ **repairing**

Trying Rule: 6

Need to find object '**job**'

Object '**job**' sought as '**building**'

'**job**' instantiated by user input to '**repairing**'

'**stimulus_response**' instantiated by Rule: 6 to
'**hands-on**'

Pass 5

Trying Rule: 9

Rule: 9 stacked

ask feedback

⇒ **required**

Trying Rule: 9

Need to find object '**feedback**'

Object '**feedback**' sought as '**required**'

'**feedback**' instantiated by user input to '**required**'

'**medium**' instantiated by Rule: 9 to '**workshop**'

medium is workshop

Tree diagram for the rule-based expert system MEDIA ADVISOR

