

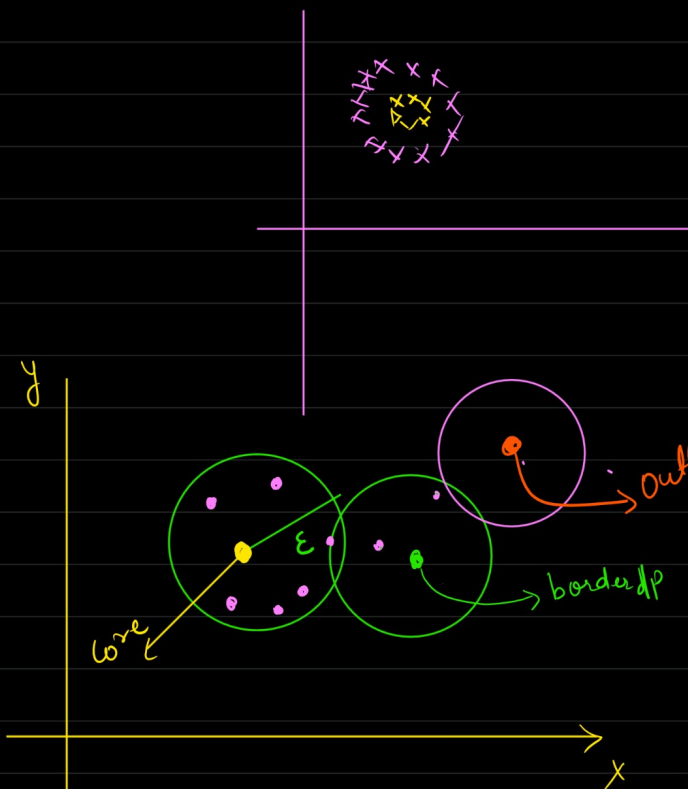
DBSCAN (density based spatial clustering of Application with noise)

* Characteristics of DBSCAN

- Finds groups / pattern
- Finds outliers / noise

if already we had kmean / hierarchical, then why DBSCAN?

* Distance based Algorithm
Such as K means & hierarchical
can not be used here (non linear data / non linear clustering)



- → core data point
- → border data point
- → outlier dp.

* minimum no of dp — 4
* radius (ϵ) — 1 m

* Core dp :-



← The dp's which hv at least minimum no. of dp in its radius ϵ (4)

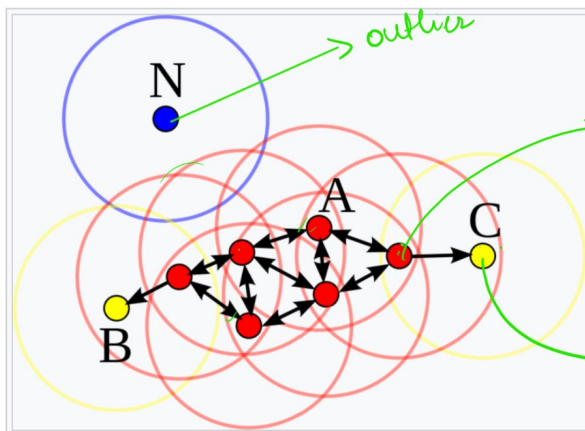


← * Border dp → no. of dp within its boundary (ϵ) will be less than minimum

* Outlier (Noise) dp



→ No dp in radius ϵ



In this diagram, $\text{minPts} = 4$. Point A and the other red points are core points, because the area surrounding these points in an ϵ radius contain at least 4 points (including the point itself). Because they are all reachable from one another, they form a single cluster. Points B and C are not core points, but are reachable from A (via other core points) and thus belong to the cluster as well. Point N is a noise point that is neither a core point nor directly-reachable.

* Some Examples of DBSCAN working very well with non linear data.

