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SUMMARY

 Nearly 5 Years of experiences on Robot and PLC Programming at automobile manufacturing sector.

- Capable of handling KUKA, Fanuc, ABB, Yaskawa, Kawasaki, KUKA IIWA (Sunrise OS/ Collaborative/ JAVA based), Universal Robot (Collaborative/ Python based), Epson Scara robot or any other robot.
- Advance Level certification from KUKA college.
- Currently working as a Project lead for Rhythmsoft Robotics and automation Pvt. Ltd. (www.rhythmsoftindia.com).
- Project Management Installation & Commissioning (Robot based automation) Team Management
- Single handily completed robot installation and commissioning at customer end in Ethiopia, Africa.
- Hands-on experience with all major Robot programming, Robotic Line Commissioning.
- Hands on and experience with Mitsubishi PLC at Honda Cars.
- Hands on and system integration experience with Allan Bradly PLC at Ford Sanand.
- Hands on and system integration experience with Siemens PLC at Ford Chennai.
- Wide Experience of MIG welding Projects with KUKA Robot and Fronius Power source.
- Trained and on site experience with Fanuc Robots in glass glazing application for Honda Cars Tapukara, Rajasthan, India.
- On site experience with KUKA KR-16 Robots for Maruti Suzuki project YL1, YL7, XD, B6, YCA, YSD etc.
- Glass Glazing Application with KUKA KR 16 at Ashok Leyland, Pantnagar.
- Kawasaki Robot (BX-200L) Programming and Training at Ford Sanand, Gujarat.
- Kawasaki Robot (BX-200L) Programming and Training at Ford Chennai.
- Two year Experience with SCA and Graco PU dispensing system.
- Skilled in managing operations involving resource & materials planning, team building and coordination with the internal departments
- Adept in coordinating, planning & implementing changes to technology, machinery, equipment, control systems and reporting procedures
- An effective communicator with good leadership, decision making, planning and team management skills
- Gained significant exposure in working with industrial automation solutions incorporating robotic systems, ideally with associated knowledge of machine tools in the automotive sector
- Expertise in managing all mechanical, electrical, controls and robotic resources including the scheduling of service and installation personnel for on and offsite work
- An effective communicator with honed interpersonal, analytical, problem solving, leadership and motivational skills

EDUCATION

Bachelor of Technology (Electrical and Electronics Engineering) (2009-2013)

TECHNICAL SKILLS

ROBOTS: KUKA, Fanuc, ABB, Yaskawa, Kawasaki, KUKA IIWA (Sunrise OS/Collaborative/JAVA based), Universal Robot (Collaborative/Python based), Epson Scara robot or any other robot.

PLC: Mitsubishi (GX Works 2), AB (RX Logix 5000), Seimens (TIA Portal) etc.

Software Development: C# (.Net), Python, JAVA, C++ and also Capable of implementation in ROS (Robot Operating system) (for info visit www.ros.org)

Other Technical and Managerial Skills:

- Operation of Pneumatic circuits.
- Capable of working in Linux environment (basic Shell scripting).
- Capable of working with windows and Linux environment.
- Over 3 years experience in working with Arduino, Raspberry Pl.
- Machine vision engineering with Open CV and MATLAB.
- Capable of working with NI LabView.
- On-site Team management.
- On-site Resource management.
- Design approval
- Commercial negotiation and Project Buy-off.

PROFESSIONAL EXPERIENCE

Rhythmsoft Robotics and Automation Pvt. Ltd.

Clients – All major automobile and automotive companies in India.

Currently working as a Project lead for Robotics Projects.

ROLES:

- Project Lead and Site in charge for projects.
- Team management on site.
- Entire online robot programming and system administration.
- On-site Training for customer.
- Project management and Buy-off.

PROJECT DETAILS

Project 1

Title : Honda Glass Glazing Cell 2

Client : Honda Cars India ltd., Tapukara Rajasthan

Duration of project : 6 months

End Customer : Honda Tapukara, Rajasthan

Technology Used: Fanuc Robot, Graco Glass Glazing System, Mitsubishi PLC, Mitsubishi Drive,

SEW Drive.

Role & Responsibilities

Full project coordination from design to final commissioning.

Robot, PLC and other hardware selection.

Complete robot teaching and logic development.

Final commissioning and buy off.

Project 2

Title : Ford Sanand, Gujarat Glass Glazing Cell

Client : Ford Sanand, Gujarat Duration

of project : 1 month

End Customer : Ford motors.

Technology Used : Kawasaki Robot, SCA Glass Glazing System, AB PLC, SEW Drive.

Role & Responsibilities

- Full project coordination from design to final commissioning.
- Robot, PLC and other hardware selection.
- Complete robot teaching and logic development.
- Development and commissioning of a .net based pressure sensing software.
- PLC Programming and logic modification onsite.

Project 3

Title : Ford Chennai, Glass Glazing and decking cell.

Client : Ford motors

Duration of project : 1 month

End Customer : Ford motors.

Technology Used : Kawasaki Robot, SCA Glass Glazing System, AB PLC, SEW Drive.

Role & Responsibilities

- Full project coordination from design to final commissioning.
- Robot, PLC and other hardware selection.
- Complete robot teaching and logic development.
- Development and commissioning of a .net based pressure sensing software.

 PLC Programming and logic modification onsite.

Project 4

Title : Honda Glass Glazing Cell 1.

Client : Honda Cars India ltd.

Duration of project : 4 months

End Customer : Honda

Technology Used : Fanuc Robot, SCA Glass Glazing System, Mitsubishi PLC, Mitsubishi Drive.

Role & Responsibilities

· Full project coordination from design to final commissioning.

Robot, PLC and other hardware selection.

Complete robot teaching and logic development.

 Commissioning of a .net based pressure sensing and image processing software developed by Eines, Spain.

PLC Programming and logic modification onsite.

Project 5

Title : Robotic Glass Glazing Ashok Leyland.

Client : Ashok Leyland, Pantnagar

Duration of project : 3 months End Customer : Ashok Leyland

Technology Used : KUKA Robot, SCA Glass Glazing System, Mitsubishi PLC.

Role & Responsibilities

- Full project coordination from design to final commissioning.
- Robot, PLC and other hardware selection.
- Complete robot teaching and logic development.
- PLC Programming and logic modification onsite.

Project 6

Title: Maruti Suzuki MIG welding Application (YL1, YL7, XD a total of 5 robots system)

Client : VeeGee, Faridabad

Duration of project : 6 months

End Customer : Maruti Suzuki

Technology Used : KUKA Robots, Fronius MIG welding power source, Mitsubishi PLC.

Role & Responsibilities

- Full project coordination from design to final commissioning.
- · Robot, PLC and other hardware selection.
- Complete robot teaching and logic development.
- PLC Programming and logic modification onsite.

Project 7

Title : TAL Glass Glazing system

Client : TAL

Duration of project : 3 month

End Customer : Redawa Motors, Ethiopia, Africa

Technology Used: ABB Robots, SCA Glass glazing pump, AB PLC.

Role & Responsibilities

Full project coordination from design to final commissioning.

· Robot, PLC and other hardware selection.

Complete robot teaching and logic development.

PLC Programming and logic modification onsite.

Project8

Title : Direct Glazing equipment with Yaskawa

robot

Client : Maruti Suzuki Manesar

Duration of project : 40 days

End Customer : Maruti Suzuki Manesar

Technology Used : Yaskawa Robot (DX 200), SCA Glass glazing

pump, Mitsubishi PLC.

Role & Responsibilities

- Full project coordination from design to final commissioning.
- Robot, PLC and other hardware selection.
- Complete robot teaching and logic development.
- PLC Programming and logic modification onsite.

Project9

Title : Glass Sub –assy conveyor and Robot

application

Client : Honda Greater noida

Duration of project : 30 days

End Customer : Honda Greater noida

Technology Used : KUKA KR 210, SCA Glass glazing

pump, Mitsubishi PLC.

Role & Responsibilities

· Full project coordination from design to final commissioning.

Robot, PLC and other hardware selection.

Complete robot teaching and logic development.

PLC Programming and logic modification onsite.

Project 10:

Title: Veegee MIG Welding LINE for YCA and YSD models (16

Robots Line).

Client: VEEGEE Industrial Enterprise Faridabad.

Duration: 6 Monthes

End Customer: MSIL Manesar.

Technology used: KUKA KR 16, Fronius TPSI Power source,

KUKA external axis based Turn Table welding fixtures.

Role & Responsibilities

Full project coordination from design to final commissioning.

Robot, PLC and other hardware selection.

Complete robot teaching and logic development.

PLC Programming and logic modification onsite.

Project 11:

Title: KUKA LWR IIWA Demo implementation.

Client : KUKA India Duration : 10 Days

End Customer: KUKA India.

Technology used: KUKA LBR IIWA Robot, KUKA Sunrise OS

(JAVA based).

Role & Responsibilities:

 Program Robot to Open a beer bottle and fill it in glasses and offer to customers.

Programming and proving to customers.