# Akshay Kumar

http://kumarakshay324.github.io | akumar5@wpi.edu | +91 7790985755

### **EDUCATION**

# WORCESTER POLYTECHNIC INSTITUTE

MS IN ROBOTICS ENGINEERING Expected May 2019 | Worcester, MA

### **MNIT JAIPUR**

B TECH. IN ELECTRICAL ENGINEERING

May 2017 | Jaipur, Rajasthan Cum. GPA: 8.25/10

### **BALDWIN ACADEMY**

Intermediate | CBSE April 2013 | Patna, India Percentage Aggregate: 93%

### CHRIST CHURCH HIGH SCHOOL

Matriculation | ICSE April 2011 | Patna, India Percentage Aggregate: 95%

### RELEVANT COURSES

### **GRADUATE**

Synergy of Humans and Robot Deep Reinforcement Learning Foundations of Robotics

### **UNDERGRADUATE**

Control System Engineering
Modern Control Theory & Design
Techniques
Computer Architecture and Organisation
Basics Of Mechanical Engineering
Microprocessors

### SKILLS

### **HARDWARE**

Intel Galileo | Sensors | AVR Atmega Micro-controllers

### **PROGRAMMING**

#### Proficient:

C | Python | MATLAB SolidWorks | Proteus | Processing Arduino IDE | Simulink

### Familiar:

Atmel Studio | Assembly Language 8085-86 | MikroC Robot Operating System(ROS)

# **PROJECT WORK**

### LOWER BODY WALKING BIPED ROBOT

August 2016 - April 2017 | ZINE LAB - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Designed and manufactured a 12-DOF(6 DOF in each limb) low cost servo actuated biped robot with custom-designed 3D printed parts
- IMU sensor based joint angle prediction and estimation of the biped's orientation (Sensor Data Fusion using Kalman Filter, Extended Kalman Filter)
- Cubic Spline Interpolation based trajectory planning for the foot, knee and hip motion

### SMART ANIMATRONIC HUMAN FACE

Jan - May 2017 | DEPARTMENT OF ELECTRICAL ENGINEERING - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Designed fabricated complete mechanism with movable parts of the human face like lips, jaw, neck and eyes
- Interactive control of the face through computer vision and speech inputs
- Project Website

# ROBOTIC SETUP FOR POWER TRANSMISSION LINE MAINTENANCE

March – April 2015 | ZINE LAB - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Hardware in the loop based simulation and Live animation setup of the remotely functioning setup for easier controllability by the operator
- Designed DC motor powered robotic system with pulleys for gripping/ungripping mechanism and traversal on the transmission lines in mid-air
- Used Onboard sensors(temperature, magnetic field, IMU, cameras) for health monitoring of the lines and data transmission via internet to the control base

### COST EFFECTIVE EMG SIGNAL EXTRACTION SETUP

January- July 2015 | ZINE LAB - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Developed a low cost 4 channel Electromyography hardware with partial onboard noise attenuation and filtering
- Built an indigenous GUI in Processing IDE, for data logging and its analysis in real time from the hardware

### **GEO-FENCING BASED RAIL ALERT SYSTEM**

September - October 2015 | ZINE LAB - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Built a system capable of establishing a multiple-level virtual perimeter-geofence around unmanned rail-road crossovers to prevent mishaps
- On-board GPS based location tracking and Multi-level warning issue system for vehicles approaching crossovers

# 15 DOF WIRE-STEERED MOTION MIMICKING ANTHROPOMORPHIC ROBOTIC ARM

February - March 2014 | ZINE LAB - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Designed and manufactured a robotic arm capable of replicating the motion of human arm using a sensor powered pair of gloves
- Accurate motion by human hand's and model's proper position mapping (Using flex sensors and two-level closed loop servo motor control)

### **INTERESTS**

Control Systems | Manipulation Sensing | Mechanical Designing Embedded Systems

## CO-CURRICULARS

Senior Member of ZINE - College's Robotics & Research Group

Delivered lectures on Sensors, ICs & MCUs, Ethical Hacking, Processing and MATLAB in Robotics Workshops for the fresher batch of 2014, 15 & 16

Working as Technical Secretary for the Electrical Engineering Society(EES) in the college

# DEVELOPMENT OF CONTROL SYSTEM FOR UNMANNED GROUND VEHICLE(UGV)

April - May 2016 | DEPARTMENT OF ELECTRICAL ENGINEERING - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Designed & simulated the control system of a differential drive robot on MATLAB-Simulink to accomplish motion on pre-planned path
- Derivation of transfer functions via intrinsic features of the DC motor powering the rear wheels of the UGV

#### **ELBOW JOINT REHABILITATION DEVICE**

July – August 2015 | ZINE LAB - MNIT JAIPUR | Mentor: Dr. Rajesh Kumar

- Elbow actuation assistive device for externally powered motion of the elbow joint of the human body
- Indigneously designed and 3D printed model of a worm-gear power transmission based assistive device
- Unique 3D design compliant with optical postion encoders for real time closed loop control of the actuators

# INTERNSHIP | SWAAYATT ROBOTS PVT. LTD

May-July 2016 | Bhopal, India | Mentor: Sanjeev Sharma (Founder) Development of a mobile robotic research platform

- Development of a mobile robot with multiple sensors and a 6-DOF robotic manipulator arm with the ability to learn through kinesthetic teaching
- Facilitated by two level joint angle tracking using inertial sensors feed as well as actuator(servo motor) internal position feedback

### Automation of controls in a Self Driving Vehicles

• Designed the mechanical setups and control system for automation of Accelerator, Clutch, Gear and Brakes of an existing SUV

# **ACHIEVEMENTS**

### **PUBLICATIONS**

- Akshay Kumar, Anshul Mittal, Rajat Arya, Akash Garg, Sharad Garg, Rajesh Kumar. Hardware In The Loop based simulation of a Mechatronics System for real time control and animation of working model - In Press: Presented at IEEE International Conference on Inventive Systems and Control 2017 - Link
- Akshay Kumar, Rahul Ravichandran, Rajesh Kumar. Joint angle measurement for biped robot orientation estimation using MEMs based inertial sensors -Under Review at Elsevier Journal: Robotics and Autonomous Systems

#### **PATENTS**

- Robotic Technology for Transmission Line Inspection in Live Condition Published Link
- Rail Alert Systems- Published Link
- Comprehensive System for Osteoarthritis detection, analysis and rehabilitation based on efficient SEMG signals Published Link

### SCHOLASTIC ACHIEVEMENTS

- Winner at Student Innvoation Pavallion in Gridtech 2015 by PGCIL, Govt. Of India
- Runners Up at Tech Expo, Blitzschalg'14, the Annual Techno-Cultural fest of MNIT Jaipur
- Winner of Cosmology & Physics Quiz Contest 2014 at MNIT Jaipur
- Finalists in Texas instruments India Analog Maker College Level Competition 2015
- Obtained positions of **1/100** and **3/400** in the class X-ICSE and class XII-CBSE board examinations respectively