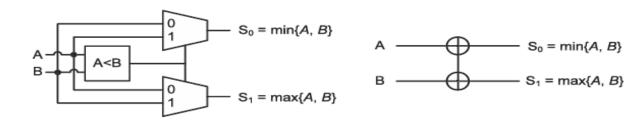


Compare & Exchange Blocks (CAE blocks):-

1) Ascending Compare-and-Swap

```
module compare_swap_asc (
    input signed [15:0] a,
    input signed [15:0] b,
    output signed [15:0] s0,
    output signed [15:0] s1
);
    assign s0 = (a < b) ? a : b; // min
    assign s1 = (a < b) ? b : a; // max
endmodule</pre>
```

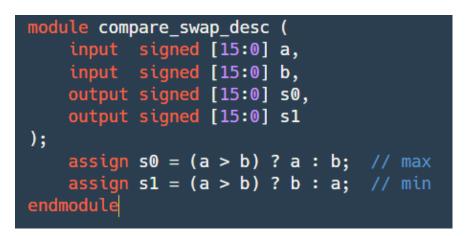


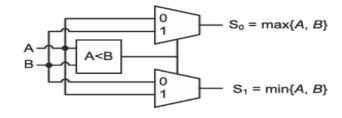


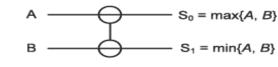
> OUTPUTS:

- •s0: Smaller of a and b
- •s1: Larger of a and b
- > Sorts two inputs in **ascending order** (top = max, bottom = min)

2) Descending Compare-and-Swap







\rightarrow

OUTPUTS:

- •s0: Larger of a and b
- •s1: Smaller of a and b
- Sorts two inputs in descending order (top = min, bottom = max)

MAX_K module :-

Overview:

The MAX-K unit processes K inputs obtained from two Bitonic Merge (BM) units.

Each BM unit provides K/2 inputs:

- One set is ascendingly sorted
- The other set is **descendingly sorted**

Step 1: MAX-K Processing

The MAX-K unit selects the **top** K/2 **maximum values** from the combined K inputs.

The output is not fully sorted but follows a specific pattern:

- The top K/4 elements are in ascending order.
- The bottom K/4 elements are in descending order.

Step 2: Final Sorting using BM-K/2

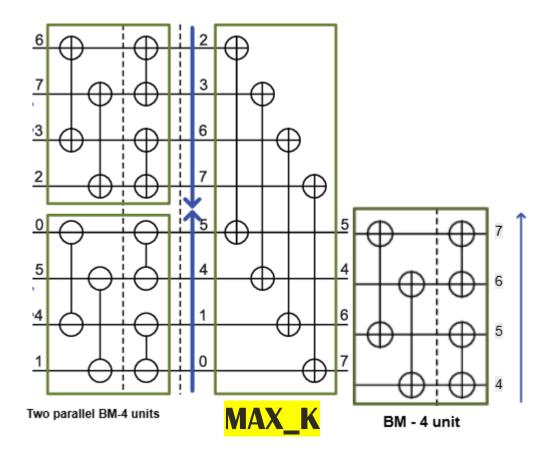
To sort the K/2 selected elements in **descending order**, the output of the MAX-K unit is fed into the **BM-**K/2 unit.

Since the input follows a **bitonic sequence** (K/4 ascending followed by K/4 descending), BM-K/2 efficiently sorts them.

Result:

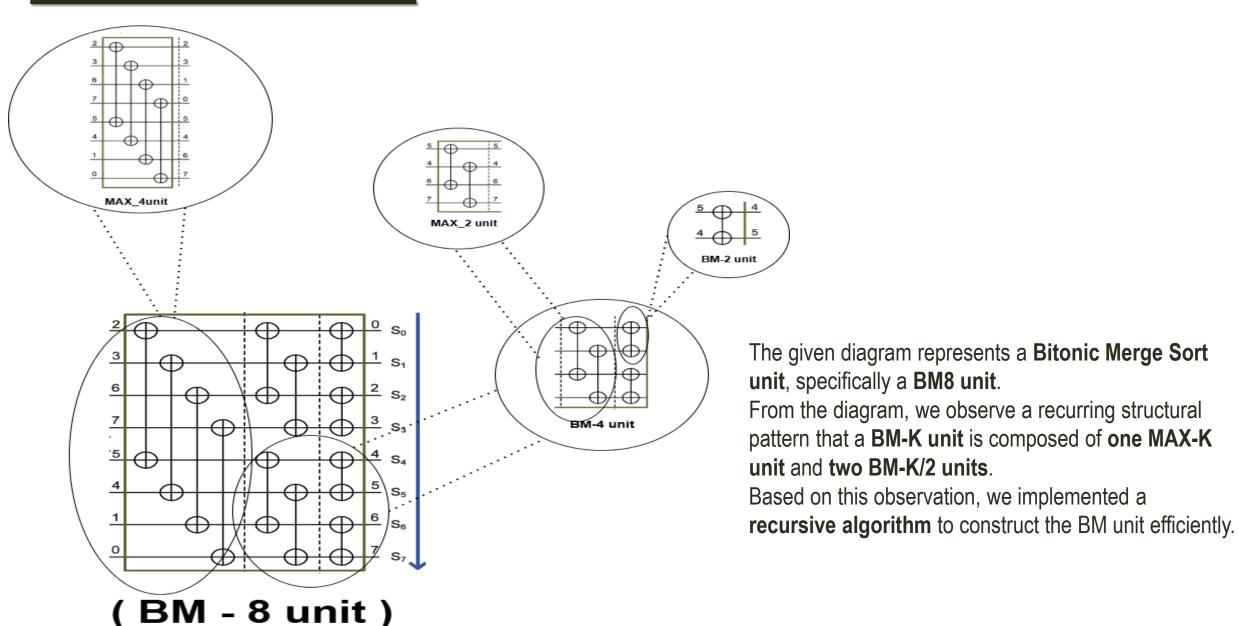
The final output consists of the K/2 largest elements in strict descending order.

This output is ready for the next processing stage or for final use.

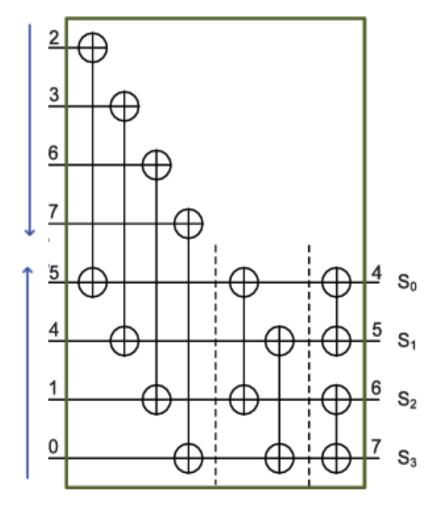


[Fig: Example of max_4, where the max_selector takes inputs from BM-4 (asc.) and BM-4 (desc.)]

BM - K module :-



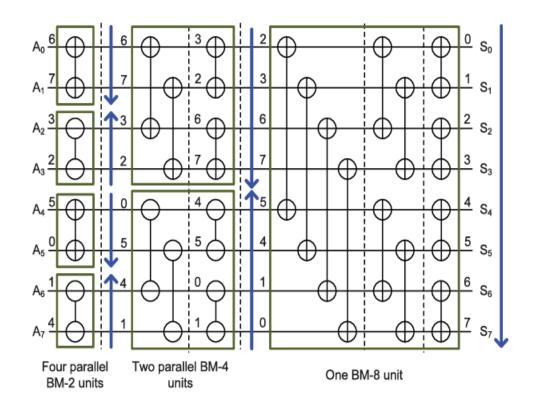
MAXNBY2 module:-



[Fig :- example (MAX8/2 unit)]

- The unit shown beside is an example of MaxN/2 unit, which performs partial sorting to reduce the number of compare-and-swap operations. This approach results in lower area usage and fewer hardware components.
- > This block takes **N** inputs, where:
 - The first N/2 elements are in ascending order
 - The remaining N/2 elements are in descending order
- ➤ It outputs the **top N/2 maximum elements**, which are fully sorted. Structurally, this unit is composed of two well-known blocks:
 - A MAX-N unit, followed by
 - o A BM-N/2 unit
- Thus, we implement the MaxN/2 unit by combining a **MAX-N** unit with a **BM-N/2 unit**.
- ➢ If we instead use descending compare-and-swap operations in BM-N/2, the output will be in descending order, forming a descending MaxN/2 unit (e.g., Max8/2).

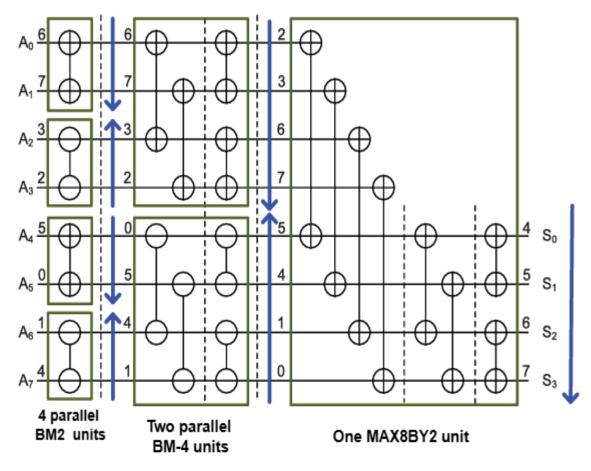
Complete Bitonic Merge (BM) Sorting Unit:-



[Fig : - example of complete BM unit in which random unordered 8-inputs are getting sorted in ascending order]

- ➤ In the complete **Bitonic Sorting** process, we utilize the previously described units to construct the full sorting block.
- As shown in the image, the system takes 8 random input numbers and produces 8 sorted output numbers.
- > The structure includes:
 - Four BM2 units (4 × 2 = 8), arranged in alternating ascending and descending order
 - Two BM4 units (2 × 4 = 8), also used in an alternating ascending/descending configuration
 - One BM8 unit $(1 \times 8 = 8)$, which operates in ascending order
- Following this observed pattern, we developed a **general recursive implementation** for the Bitonic Sorting algorithm.

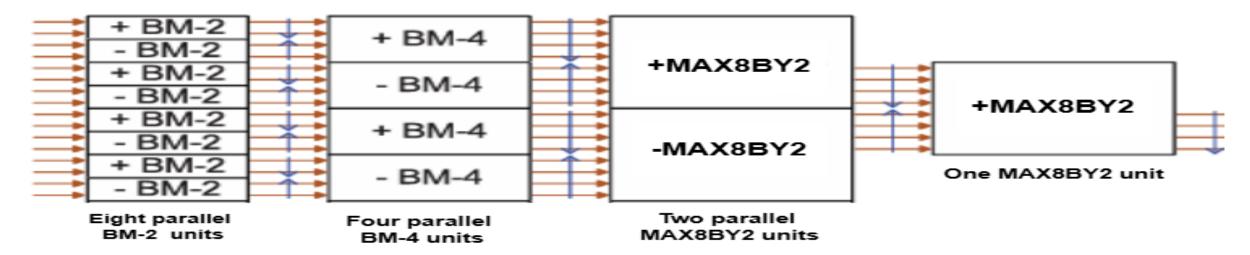
PARTIAL SORTING OF N-to-N/2:-



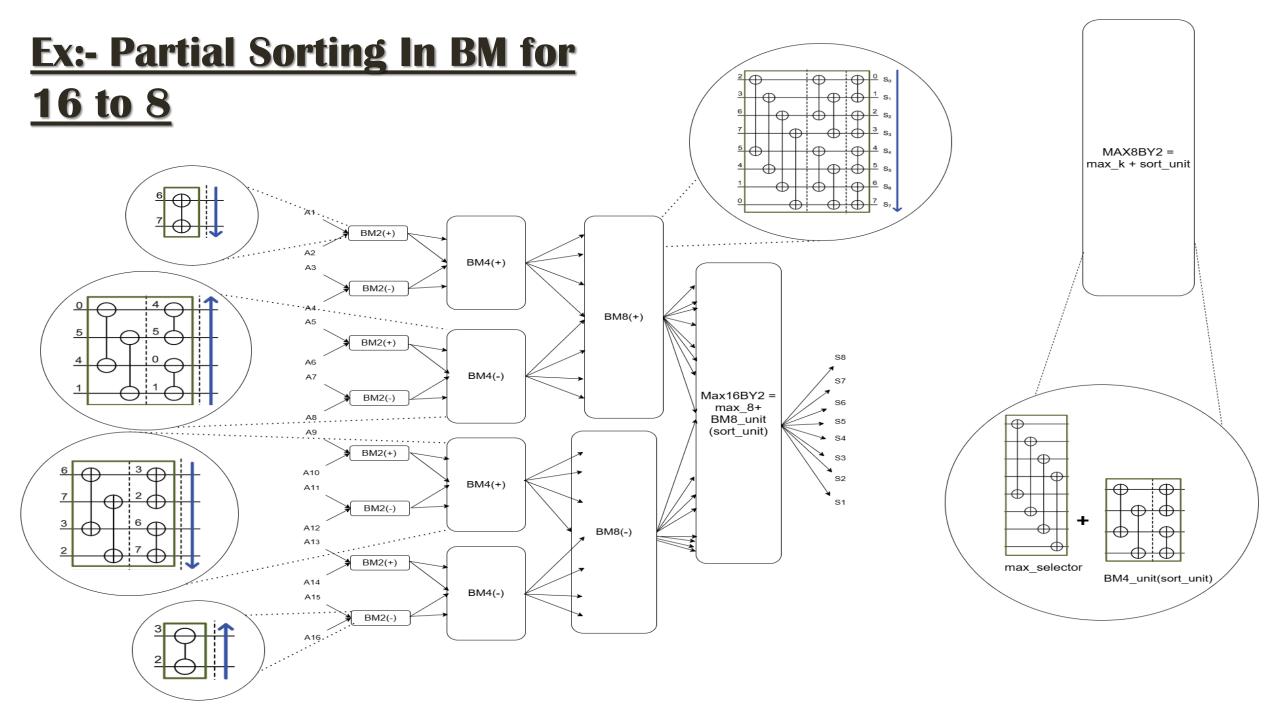
[Fig : - example of partial sorting of of 8-to-4 in which random unordered 8-inputs are getting 4-sorted output in ascending order]

- ➤ The diagram beside illustrates partial sorting from 8 to 4 (example of partial sorting of N-to-N/2).
- > In this structure:
 - We use four BM2 units (4 × 2 = 8), arranged in alternating ascending and descending order.
 - Followed by **two BM4 units** (2 × 4 = 8), also in an **alternating** pattern.
- Finally, we use **one Max8by4 unit**, which outputs the **top 4 elements in ascending order**.
- ➤ This design is similar to the general Bitonic sorting structure; Concept is like when we reach the stage of **BM N/2 units**, After that we have to place it with a **MaxNby2 unit** to obtain the partially sorted output.

PARTIAL SORTING OF N-to-N/4:-



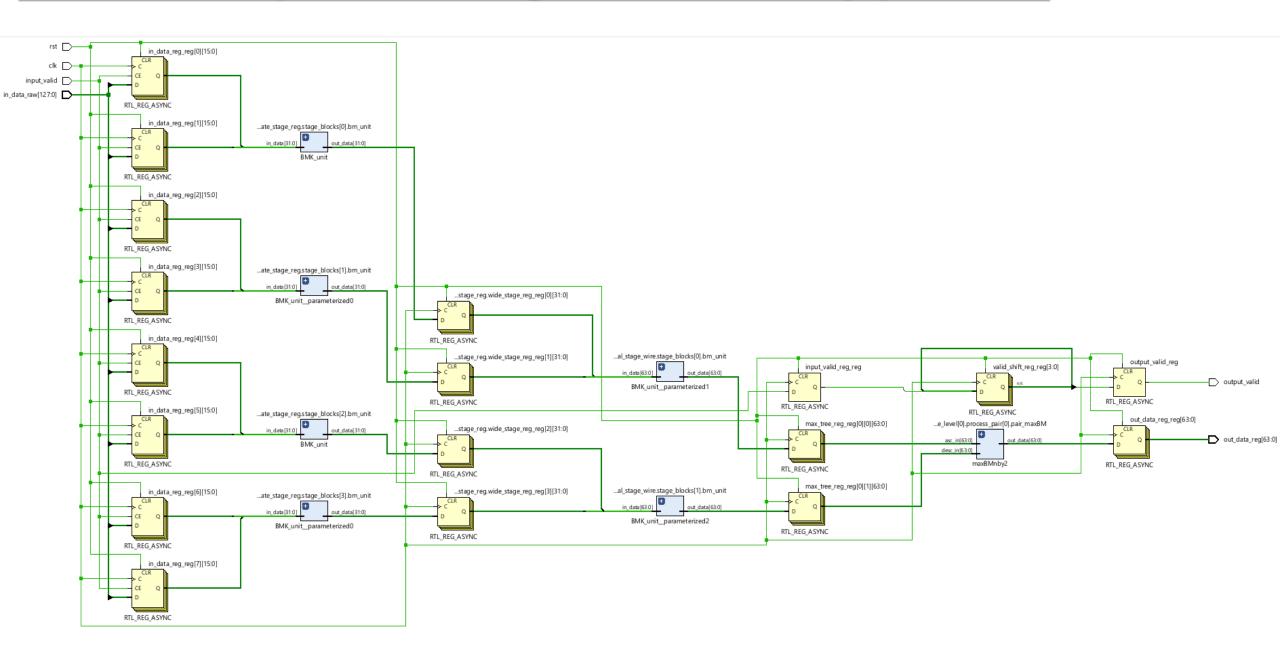
- > The unit shown above demonstrates the implementation of **partial sorting**.
- ➤ It is composed of the following building blocks:
 - \circ Eight BM2 units (8 × 2 = 16), arranged in alternating ascending and descending order
 - \circ Four BM4 units (4 × 4 = 16), also in an alternating pattern
 - o Two Max8by2 units, alternately configured in ascending and descending order
 - Followed by one Max8by2 unit in ascending order
- The pattern observed here closely resembles the structure of a **complete Bitonic sorting unit** for 16 elements. The key difference is introduced after the **BM4 stage**, which corresponds to **N/4** (where N = 16).
 - Instead of continuing with BM units, we insert:
 - Two Max8by2 units (configured alternately)
 - Followed by one Max8by2 unit in ascending order
 - This gives a total of 2 + 1 = 3 Max8by2 units, where 2 = log₂(4) corresponds to the number of additional stages needed for partial sorting after the BM-N/4 level.



Generalised PARTIAL SORTING For 2^m to 2^n (m>n):-

- ▶ By analyzing the patterns in Partial Sorters for sizes N to N/2, N to N/4, and N to N/8, we identified a generalized structure for a Partial Sorter from 2ⁿ to 2^m where m<n</p>
- > The approach follows the structure of the complete **Bitonic Sorter for** 2ⁿ until we reach the level of **BM-**_2^m units.
- ➤ At this point, the structure changes as follows:
 - \circ We use "m" BM- 2^m units, arranged in alternating ascending and descending order
 - \circ Next, we pair the outputs from each **ascending and descending BM-** 2^m **unit**
 - \circ Each pair is then fed into a **Max**2^m by2 unit, which selects the top 2^{m-1} elements
 - \circ These Max units are organized in a **tree structure**, where their outputs are further processed by additional Max2^m BY2 units
 - \circ This continues recursively until only **one final** Max2^m BY2 unit remains
- \succ The final Max unit is configured in **descending order** to produce the **partially sorted top** 2^m **elements** in descending order.

Schematic of partial sorting for 8-to-4 with pipelined :-



Comparision Table of different sorting units:-

Sorter Unit	DATA arrival Time in ns (Critical Path)	Area in μm^2	Power in mW
Sorter_8 _to_4	9.76	69440.582056	3.5054
Sorter_16_to_4	9.76	161175.697563	7.7992
Sorter_16_to_8	9.91	221422.279062	10.1341
Sorter_32_to_4	9.77	348220.652916	16.5151
Sorter_32_to_8	10.03	507333.673078	22.6277
Sorter_32_to_16	10.82	659107.498189	28.0751
Sorter_64_to_4	9.76	161175.697563	7.7992
Sorter_64_to_8	9.84	1107709.310906	46.8409
Sorter_64_to_16	10.93	1479133.758506	61.1747
Soter_64_to_32	13.72	1714610.439567	67.7443
Sorter_128_to_4	9.77	1499987.714066	71.1501
Sorter_128_to_8	10.01	2270082.935802	100.6285
Sorter_128_to_16	11.99	2968870.937471	125.9072

Continuing...

Sorter Unit	DATA arrival Time in ns (Critical Path)	Area in μm^2	Power in mW
Sorter_128 _to_32	14.73	3638295.210396	147.9505
Sorter_128_to_64	17.51	4327399.255973	168.4183
Sorter_256_to_4	9. 76	3050510.206716	144.9235
Sorter_256_to_8	11.02	4680408.079414	198.2483
Sorter_256_to_16	12.46	6057940.798922	256.0527
Sorter_256_to_32	16.40	7504066.388765	307.0547
Sorter_256_to_64	19.26	9131967.819051	354.1982
Sorter_256_to_128	21.51	1107709.310906	387.6980
Sorter_512_to_64	20.76	18481756.255650	680.7511
Sorter_512_to_128	25.38	22051140.217641	771.6448
Sorter_512_to_256	28.55	25604820.252861	871.6812
Sorter_1024_to_512	33.42	61102975.980396	1.9801e+03

Inference from Synthesis Results

M-Dominant Critical Path:

For fixed M, critical path remains stable even as N increases.

Example: $M=4 \Rightarrow 9.76$ ns for N=64 to 256.

Due to pipelined design; final maxBMnby2 unit dominates delay.

Scalability with M:

Critical path increases with M due to deeper comparison logic.

Example: Sorter_256_to_4: 9.76 ns, Sorter_256_to_32: 16.40 ns.

Resource Utilization:

Area and power increase with both N and M.

For fixed M: scales linearly with N (more comparators).

For fixed N: grows with M (wider data paths, complex logic).

Matches $\mathcal{O}(N \cdot \log^2 M)$ complexity.

FUTURE WORK:-

1. Pipelining within BM-K and MaxNby2 Blocks:

Introduce pipelining inside the BM-K and MaxNby2 units to further reduce the **critical path delay**.

- A. Currently, the critical path depends on the **deepest MaxNby2** or **final BM-K block**.
- B. With pipelining, the critical path will primarily depend only on the **compare-and-swap blocks**, significantly improving performance.

2. Index Tracking:

Attach an **index bit** to each input number to keep track of its **original position**.

This will help identify which index corresponds to the maximum or selected values, which is especially
useful in applications like selection networks or sorting with traceability.

3. Generalized Partial Sorter for Arbitrary N to 2^m (where $N > 2^m$):

Extend the current implementation to support **general partial sorting** from any integer $\bf N$ to $\bf 2^m$, enabling more flexible and scalable designs.

SOFMING THANK YOU