# **SURBHI KUMARI**

#### **Robotics and IoT Enthusiast**

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# **EDUCATION**

# Bharati Vidyapeeth's College of Engineering B.Tech in Electronics and Communication

August 2017 - Present

New Delhi, India

CGPA = 9

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# S.S Mota Singh Model School

#### **High School**

march 2015 - March 2017

New Delhi, India

Perctange= 95.4%

# **SKILLS**

C, C++, Python, Unix, Linux

Arduino, Raspberry pi

IoT, Sensor Networks, Communication

3-D Modelling, Simulation Softwares(V- Rep)

Blender, Unity



# **EXPERIENCES**

# **Embedded Systems Intern**

### Aerogram Pvt. Ltd. (IIT Delhi)

**Aug 2019 - Dec 2019** 

New Delhi, India

Worked on building a network of air pollution monitoring devices including PM sensor modules, wifi, Communication protocols.

#### Vice - Chairperson

#### **Robotics and Automation Society, IEEE**

# July 2019 - Present

New Delhi, India

• Responsible for leading the team, gear up robotics environment in college.

#### Chapter Representative

#### **Robotics and Automation Society, IEEE**

## July 2018 - July 2019

New Delhi, India

 Engage with student and make them aware of robotics field and hold various technical events.

## Trainee

#### **Defence Research and Development Organisation**

**Image:** June 2019 - July 2019

New Delhi, India

 Trainee at Defence Research and Development organisation under Solid state Physics Laboratory studied on Semiconductor and Metal Contacts.

## **ACHIEVEMENTS**

- Winner of Smart India Hackathon Software Edition 2019 conducted by MHRD (Ministry of Human Resource and Development)
- Winner of Smart India Hackathon Hardware Edition 2019 conducted by MHRD (Ministry of Human Resource and Development)
- Winner of Hardware Productathon Conducted by IIT Roorkee
- Finalist(One of the top 5 teams) at E-Yantra Robotics Competition 2019-2020 conducted by IIT Bombay

# **PROJECTS**

#### Rocker Bogie Mechanism Robot

 Rocker Bogie Robot that can traverse on multi terrain surfaces due to its highly stable suspension design.

#### Travel YaAR

 An AR (Augmented Reality) app that shows user the view of various stadiums in AR view so that they select the seats as per their choice enhancing user experience while traveling.

#### **Nurse Joy**

 A Smart ICU Robot to assist nurses in their daily tasks like lifting the patients and giving them bath by mimicking the action of nurses.

#### **Nutty Squirrel**

 A robot mimicking the behaviour of a squirrel. The robot picks the nuts, follows a shortest path algorithm and places it at a position specified. It was one of the themes in E-Yantra Robotics Competition held by IIT Bombay.

#### **Sensor Network for Accident Prevention**

 Built a sensor network to prevent accident using LoRaWAN. A device first detects the factors that lead to accident and then using LoRa protocol, alert is sent to the nearby vehicle drivers as well as the vehicle driver who might get hit.

#### **Biped Patrol**

 A self balanced bot to deliver medicine boxes and first aid kits to victims of natural calamities. LQR control system/algorithm was used to balance the robot to prevent manual tuning required in PID Controller.

#### **Newtons Cradle**

 Simulation of Newton's Cradle in Unity, followed by an AR view of the same. The cradle's model was made in blender.