

## Linear regression for inference

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#### Contents

Regression models

Linear regression

Diagnostics for linear regression

Model selection

#### Where we are

- 1. Define the **research question**
- 2. Get the data
- 3. Explore the data
  - · (Re)format, clean, merge, stratify...
  - Identify trends and outliers
- 4. Model the data
  - Select and build model(s)
  - Evaluate and refine model(s)
- 5. **Summarise** the results
  - · Summarise findings
  - · Describe assumptions and limitations
  - Identify follow-up research questions

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- · a response variable y
- explanatory variables (or predictors)  $x_1, \ldots, x_p$

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Do the  $x_1, ..., x_p$  capture the variability of y?

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#### Aims

- 1. Predict the future (easy)
- 2. Understand the system being modelled (hard)

## Regression modelling steps

- Formulation
  - 1. Error distribution for the response y
  - 2. Combination of predictors
  - 3. Link function
- Estimation of parameters
- Diagnostics (does the model fit the data well?)
- Selection (can we improve the fit?)

## Components of regression models

- (1) A model for the **variability** of the response **y** 
  - y is continuous  $\rightarrow$  normal distribution
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  - $\beta_1 = 2$  and  $\beta_2 = 3$  are regression coefficients
- (3) A link between the two
  - Often depends on the model for the response
  - Linear regression:  $\mathbb{E}[y] = 2x_1 + 3x_2$

### Predictors and response

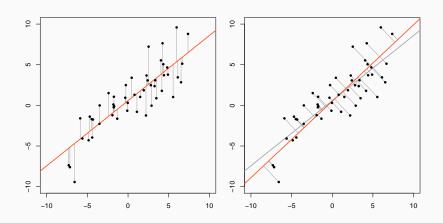
#### **Predictors**

- Viewed as fixed variables
- Assumed not to be affected by measurement error
- → 'Independent' or 'exogenous'

#### Response

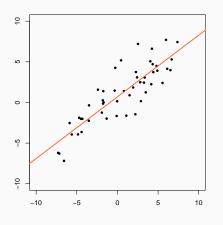
- Variability is modelled (but could also be attributed to other factors)
- → 'Dependent' or 'endogenous'

## Example: estimation of parameters



Linear regression

## Simple linear regression



For the  $i^{th}$  observation:

$$y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$$

 $\beta_0$  Intercept

 $\beta_1$  Slope

 $arepsilon_i$  Individual error term

## Regression coefficients

$$y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$$

**Intercept** Average y when x = 0**Slope** Increase in y for a one-unit increase in x

The regression line passes through:

- The point  $(0, \beta_0)$
- The 'centre' of the data  $(\bar{x},\bar{y})$

#### Error term

$$y_i = \beta_0 + \beta_1 x_i + \mathbf{\varepsilon}_i$$

- · 'Sucks up' unaccounted variation in y
- Model assumptions are mostly on  $\epsilon$  (more later...)

## Multiple linear regression

For the ith observation:

$$y_i = \beta_0 + \sum_j \beta_j x_{ij} + \epsilon_i$$

 $\beta_0$  Intercept

β<sub>j</sub> Slopes

 $\varepsilon_i$  Individual error term

Intercept Average y when all  $x_{.j} = 0$ Slopes Increase in y for a one-unit increase in  $x_{.j}$ all else being equal

## Multiple linear regression

In matrix form:

$$y = X\beta + \epsilon$$

- X Design matrix
- β Regression coefficients
- ε Error term

## Gauss—Markov assumptions

#### If the following holds...

- The relationship between **y** and **X** is linear
- X has full rank (no multicollinearity)
- Exogeneity:  $\mathbb{E}[\mathbf{\epsilon}_i \,|\, \mathbf{X}_i] = 0$
- Homoscedasticity:  $\mathbb{V}[\varepsilon_i \,|\, X_i] = \sigma^2 < \infty$
- Uncorrelated error terms:  $\mathbb{V}\big[\epsilon_i,\epsilon_j\big]=0$ ,  $i\neq j$
- $X_i$  is deterministic and thus uncorrelated with  $\varepsilon_i$ :  $\mathbb{V}[X_i, \varepsilon_i] = \mathbb{E}[X_i \varepsilon_i] - \mathbb{E}[X_i] \mathbb{E}[\varepsilon_i] = X_i \mathbb{E}[\varepsilon_i] - X_i \mathbb{E}[\varepsilon_i] = 0$

## Gauss—Markov assumptions

...then the OLS estimator of  $\beta$  is **BLUE**:

Best Minimal variance

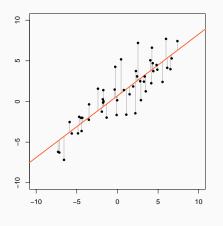
**Linear** Like the relationship between **y** and **X** 

Unbiased  $\mathbb{E}[\beta]$  equals the 'true' values for  $\beta$ 

Estimator

Outside of physics, these assumptions are often violated

## Model fitting: ordinary least squares



For the *i*<sup>th</sup> observation:

$$\hat{\epsilon}_i = y_i - \left(\hat{\beta}_0 + \sum_j \hat{\beta}_j x_{ij}\right)$$

Ordinary least squares Find  $\hat{\beta}_j$  that minimise the residual sum of squares

RSS = 
$$\sum_{i} \hat{\epsilon}_{i}^{2}$$

## Model fitting: maximum likelihood

$$Y_i \sim \mathcal{N}ig(\mu_i, \sigma^2ig)$$
 where  $\mu_i = eta_0 + \sum_j eta_j x_{ij}$ 

- · Assume that there are **fixed**, 'true' values for the  $\hat{\beta}_i$
- We can write down the **densities** of the Y<sub>i</sub>
- Assuming independence of the Y<sub>i</sub>, we can write down the joint density of the Y<sub>i</sub>
- $\rightarrow f(y | \hat{\beta}_j)$  represents the probability of observing the data given the parameters

## Model fitting: maximum likelihood

$$Y_i \sim \mathcal{N}ig(\mu_i, \sigma^2ig)$$
 where  $\mu_i = eta_0 + \sum_j eta_j x_{ij}$ 

#### Maximum likelihood principle

- Consider instead the likelihood function  $f(\hat{\beta}_j | y)$
- Same as before, but interpreted as the probability of certain parameter values given the data
- ightarrow Can optimise to estimate the  $\hat{oldsymbol{eta}}_i$
- ightarrow Additional assumption:  $arepsilon_i \stackrel{ ext{i.i.d.}}{\sim} \mathcal{N}ig(0, \sigma^2ig)$

## Hypothesis testing for parameters

 $\hat{\beta}_0, \hat{\beta}_1, \ldots$  are **estimated** from the data (they have a hat). How do we know they are not just random fluctuations?

- Define confidence intervals for  $\hat{eta}_j$
- Test  $H_0$  that  $\hat{\beta}_i = 0$



Need sampling distribution of  $\beta_j$ 

## Hypothesis testing for parameters

- Standard deviation of the sampling distribution  $\sqrt{\mathbb{V}\left[\beta_{j}\right]}$  (standard error) is known
- Test statistic is simply  $T_j = \beta_j / \sqrt{\mathbb{V}[\beta_j]}$
- It can be shown that  $T_i$  follows a t-distribution
- $\rightarrow$  Can compute confidence intervals and p-values

## Diagnostics for linear regression

## Violations of linearity or additivity

#### Extremely serious

- · Model is misspecified
- · Inference outside of observed range is misleading

- Predicted  $\hat{\mathbf{y}}$  versus observed  $\mathbf{y}$  values
- · Residuals  $\hat{\mathbf{\epsilon}}$  versus predicted  $\hat{\mathbf{y}}$  values
- · Residuals  $\hat{\pmb{\varepsilon}}$  versus each independent variable  $\pmb{\mathsf{x}}_i$

## Violations of independence

#### Potentially very serious

- Especially if dealing with time series (autocorrelation)
- · Can also result from model misspecification

- · Residuals  $\hat{\epsilon}$  versus time, row number...
- Residual autocorrelation
- Durbin—Watson test for autocorrelation at lag 1

## Violations of homoscedasticity

#### Serious

- · Confidence intervals are too wide or too narrow
- · Data are weighted unequally

- · Residuals  $\hat{\epsilon}$  versus predicted  $\hat{y}$  values
- · Residuals  $\hat{\epsilon}$  versus time, row number...
- · Residuals  $\hat{m{\epsilon}}$  versus each independent variable  $m{x}_j$

## Violations of normality

#### Somewhat serious

- · Often due to a few outliers
- Confidence intervals and *p*-values unreliable

- · Normal quantile plot of the residuals  $\hat{\epsilon}$
- · Statistical tests for normality (e.g. Anderson—Darling)
- · Studentised residuals:

$$\hat{r}_i = \frac{y_i - \hat{y}_i}{\sqrt{\mathbb{V}[\hat{y}_i]}}$$

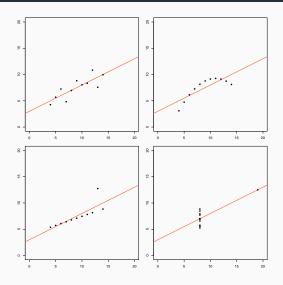
#### **Transformations**

- · Can be applied to predictors and/or response
- Can improve model fit (e.g. when residuals are not normally distributed or homoscedastic)

#### Commonly used transformations

- $\cdot \log y$  and  $\exp y$
- $\sqrt{y}$  and  $y^2$
- · 1/y

## Many datasets, one regression line



## \_\_\_\_\_

Model selection

#### Coefficient of determination

Total sum of squares

$$TSS = \sum_{i} (y_i - \bar{y}_i)^2$$

Residual sum of squares

$$RSS = \sum_{i} \hat{\varepsilon}_{i}^{2} = \sum_{i} (y_{i} - \hat{y}_{i})^{2}$$

Coefficient of determination

$$R^2 = 1 - \frac{RSS}{TSS}$$

#### Coefficient of determination

#### Problem

 $R^2$  increases with the number of predictors

#### Idea

Penalise larger models in the goodness-of-fit metric

- Adjusted R<sup>2</sup>
- Mallows's C<sub>p</sub>
- · AIC and BIC