

# Scalable Safety Verification of Statechart-*like* Programs

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Nov. 26

CMI, Chennai, India

Thanks

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# Scalability issues

- ▶ concurrency (Statecharts)
- ▶ loops (C programs)
- ▶ compositionality in safety refutations (C programs)
- ▶ inter-procedural  $k$ -induction proofs (C programs)

# Outline of this talk

- ▶ state the problems, and our results
- ▶ discuss two problems in details
  - ▶ concurrency in Statecharts
  - ▶ compositionality in safety refutations (C programs)
- ▶ conclusion and prospects

# Concurrency in Statecharts

- ▶ state-transition diagrams: hierarchical & concurrent (sync)
- ▶ **problem**: is a particular configuration reachable?
- ▶ widely used in the industry (e.g., in designing vehicle ECUs)
- ▶ **existing approaches**: scheduler (sequential); busy-wait (async)
- ▶ **our contribution**<sup>1</sup>: effective encoding of the interleavings, in the lazy abstraction framework<sup>2</sup>
- ▶ **result**: an order of magnitude speed-up over existing approaches

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<sup>1</sup>appeared in DATE 2015, Grenoble, France

<sup>2</sup>Ken McMillan, CAV 2006

# Loops in C programs

- ▶ loops pose a challenge in automated program analysis
- ▶ **problem:** does *acceleration*<sup>3</sup> (transitive-closure computation) help existing safety verification tools?
- ▶ **existing approaches:** several techniques that tackle loops; could be used in conjunction
- ▶ **our contribution**<sup>4</sup>: extensive experimental evaluation to quantify the benefits in off-the-shelf analysis tools

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<sup>3</sup>by Kroening et al., FM 2015 & CAV 2013

<sup>4</sup>appeared in FMCAD 2015, Texas, US

# Compositional Safety Refutation

- ▶ monolithic approach (inlining) does not scale
- ▶ **problem**: can safety refutations be arrived at in a modular (inter-procedural) way?
- ▶ decomposition is useful, if the results may be composed
- ▶ **existing approaches**: assume-guarantee, function summaries
- ▶ **our contribution**<sup>5</sup>: developed a framework; implemented and compared three instantiations with different degrees of completeness

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<sup>5</sup>appeared in ATVA 2017, Pune, India

## Inter-procedural $k$ -induction

- ▶ **problem:** can modular refutation help in doing  $k$ -induction<sup>6</sup> inter-procedurally?
- ▶ the monolithic approach suffers from scalability issues
- ▶ **existing approaches:** using abstractions and invariants, assume-guarantee
- ▶ **our contribution:** a sound algorithmic framework for inter-procedural  $k$ -induction with *selective* refinement

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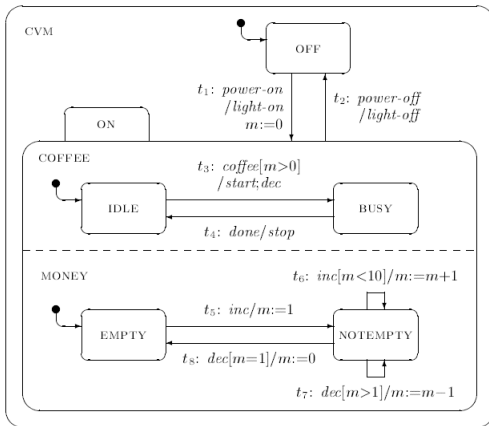
<sup>6</sup>Brain et al., SAS 2015



# Concurrency in Statecharts

# Statecharts

- ▶ states: basic, and, or
- ▶ labeled transitions ( $e[c]/a$ ); “delayed” actions
- ▶ synchronous behaviour
- ▶ write-write races are possible
- ▶ no read-write races



## The context

- ▶ **Problem:** Whether a configuration (set of states) is reachable or not?
- ▶ The popular approaches include:
  - ▶ flattening into a global transition system
  - ▶ implementing a scheduler to analyze different interleavings (e.g. Scoot)
- ▶ use an analysis tool for asynchronously composed processes (e.g. Impara) by *busy-waiting*

## Our approach

- ▶ translate Statecharts to multi-threaded C programs
  - ▶ to leverage existing tools for analyzing C programs
- ▶ extends Lazy Abstraction with Interpolants (LAWI) with support for synchronous concurrency

## Statecharts to multi-threaded C programs

- ▶ each component is modeled as a separate thread
- ▶ program labels for states; transitions are encoded using `goto` jumps from one label to another
- ▶ *primed* variables to model delayed writes
- ▶ an *environment* process flushes the writes and generates triggers randomly if the system is inactive

## An example

```
void coffee()
    idle:

    if(coffee && (m>0))
        start' = 1;
        dec' = 1;
        cState' = busy;
        goto busy;

    else
        inactive = 1;
        cState' = idle;
        goto idle;

    busy:
    ...
```

```
void environment()

    start = start';
    dec = dec';

    assert(!((cState == busy) &&
(mState == empty)));

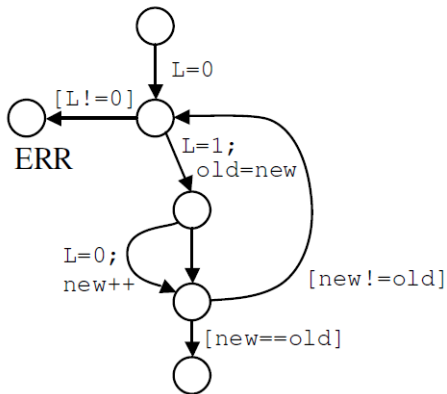
    if(system is inactive)
        coffee = *;
```

## Our approach

- ▶ translate Statecharts to multi-threaded C programs
- ▶ extends LAWI to support synchronous concurrency
  - ▶ incrementally constructs an abstract reachability tree
  - ▶ labels nodes (program points) with interpolants to argue unreachability
  - ▶ does not explore states that are already *covered*
  - ▶ when the algorithm terminates, the labels are the invariants at those program points

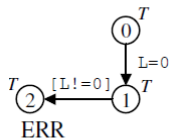
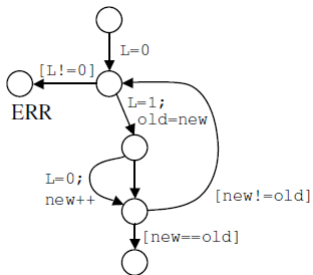
## LAWI algorithm

```
L = 0;  
  
do  
    assert(L == 0);  
  
    L = 1;    // lock  
    old = new;  
  
    if(*)  
        L = 0;    // unlock  
        new++;  
  
while(new != old)
```

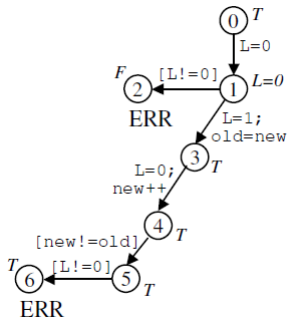
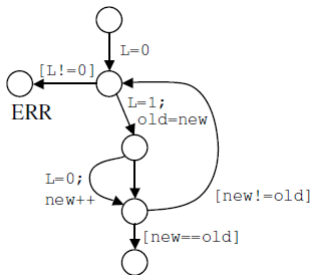




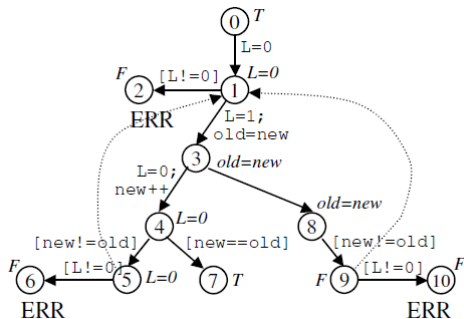
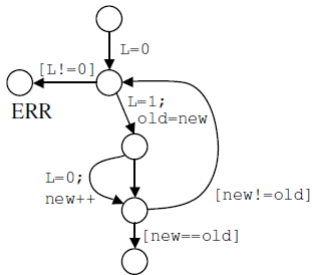
## LAWI algorithm: potential error path



## LAWI algorithm: potential error path



# LAWI algorithm: cover



## SYMPARA & Concurrent SSAs

- ▶ encodes the non-determinism of the schedule into the SSA (static single assignment)
- ▶ conditional assignments of the form  $\underline{x = b?v : v'}$
- ▶ *concurrent SSA* allows checking for races (eagerly)
- ▶ proposed a modified check for *cover*

# Experiments

- ▶ compare SYMPARA with CBMC (with  $k$ -induction) and IMPARA
- ▶ encode each example in three different ways, to suit each tool
- ▶ the executables and examples are available at <http://www.cmi.ac.in/~madhukar/sympara/>

## Comparing the time taken..

| No. | Example   | Property        | Tools   |         |                       |
|-----|-----------|-----------------|---|---------|-----------------------|
|     |           |                 | SYMPARA   | IMPARA  | CBMC + $k$ -Induction |
|     |           |                 | <i>time taken (in seconds); timeout = 900 seconds</i> |         |                       |
| 1.  | mutex     | correctness     | 5.77  | timeout | timeout               |
| 2.  | mutex     | stability       | 8.02  | timeout | timeout               |
| 3.  | vw_alarm  | non-determinism | 1.80  | timeout | timeout               |
| 4.  | vw_alarm  | stability       | 214.82  | timeout | timeout               |
| 5.  | sc_alarm  | sensitivity     | 1.35  | 8.65    | 2.66                  |
| 6.  | sc_alarm  | independence    | 1.36  | 9.96    | 0.46                  |
| 7.  | dragon    | correctness     | 0.64  | timeout | timeout               |
| 8.  | switch    | correctness     | 0.02  | 0.39    | 0.12                  |
| 9.  | prod_cons | correctness     | 0.03  | timeout | timeout               |

- ▶ examples are representative of real-life instances

## Summarizing this part..

- ▶ a technique tailored for verifying synchronous reactive systems
- ▶ ANSI-C based input offers applicability to a variety of formalisms (e.g. Lustre, Esterel, Stateflow, SCADE)
- ▶ concurrent SSAs encode synchronous concurrency and enable on-the-fly race analysis
- ▶ significant performance advantage over CBMC and IMPARA

# Compositional Safety Refutation



# The context

- ▶ divide & conquer approaches effective in scaling verification algorithms
- ▶ compositional approaches based on contracts and summaries
- ▶ we look at safety refutation in *procedure-modular* decompositions
- ▶ *assumptions*: non-recursive programs; loops unwound a finite number of times

## An example

```
void main(int x)
  if(x < 10)
    x = foo(x);
    x = foo(x);
    bar(x);
```

```
int foo(int y)
  return y+1;
```

```
void bar(int z)
  assert(z > 10);
```

# Entry-exit guards

|   |   |   |
|---|---|---|
| <pre>void main(int x)   if(x &lt; 10)     x = foo(x);     x = foo(x);     bar(x);</pre> | $T_{main}((x_0, g_{main}^{in}), (g_{main}^{out})) \equiv$ | $  \begin{aligned}  &g_{foo_0}^{in} = (g_{main}^{in} \wedge (x_0 < 10)) \wedge \\  &foo_0((x_0, g_{foo_0}^{in}), (x_1, g_{foo_0}^{out})) \wedge \\  &g_{foo_1}^{in} = g_{foo_0}^{out} \wedge \\  &foo_1((x_1, g_{foo_1}^{in}), (x_2, g_{foo_1}^{out})) \wedge \\  &g_{bar}^{in} = g_{foo_1}^{out} \wedge \\  &bar((x_2, g_{bar}^{in}), (g_{bar}^{out})) \wedge \\  &g_{main}^{out} = ((g_{main}^{in} \wedge \neg(x_0 < 10)) \vee g_{bar}^{out})  \end{aligned}  $ |
| <pre>int foo(int y)   return y+1;</pre>   | $Props_{main} \equiv$                                     | $true$  |
|   | $T_{foo}((y, g_{foo}^{in}), (r, g_{foo}^{out})) \equiv$   | $(r = y + 1) \wedge (g_{foo}^{in} = g_{foo}^{out})$   |
|   | $Props_{foo} \equiv$                                      | $true$  |
| <pre>void bar(int z)   assert(z &gt; 10);</pre>   | $T_{bar}((z, g_{bar}^{in}), (g_{bar}^{out})) \equiv$      | $g_{bar}^{out} = (g_{bar}^{in} \wedge (z > 10))$  |
|   | $Props_{bar} \equiv$                                      | $g_{bar}^{in} \Rightarrow (z > 10)$   |

## To make it easier to read

```
void main(int x)
  if(x < 10)
    x = foo(x);
    x = foo(x);
    bar(x);
```

$$\begin{aligned} T_{main}((x_0, g_0), (g_5)) &\equiv g_1 = (g_0 \wedge (x_0 < 10)) \wedge \\ &\quad foo_0((x_0, g_1), (x_1, g_2)) \wedge \\ &\quad foo_1((x_1, g_2), (x_2, g_3)) \wedge \\ &\quad bar((x_2, g_3), (g_4)) \wedge \\ &\quad g_5 = (g_0 \wedge \neg(x_0 < 10)) \vee g_4 \\ Props_{main} &\equiv true \end{aligned}$$

```
int foo(int y)
  return y+1;
```

$$\begin{aligned} T_{foo}((y, g_6), (r, g_7)) &\equiv (r = y + 1) \wedge (g_6 = g_7) \\ Props_{foo} &\equiv true \end{aligned}$$

```
void bar(int z)
  assert(z > 10);
```

$$\begin{aligned} T_{bar}((z, g_8), (g_9)) &\equiv g_9 = (g_8 \wedge (z > 10)) \\ Props_{bar} &\equiv g_8 \Rightarrow (z > 10) \end{aligned}$$

## Formal definition (monolithic case)

- ▶ inline every procedure call at its call site
- ▶ then to refute safety, we must show that the following is satisfiable:

$$\forall \hat{X} : \bigwedge_{j \in CS} g_{f_{entry}}^{in} \wedge T_{fn(j)}(\vec{x}_j^{in}, \vec{x}_j^{out}) \wedge InlineRec_{fn(j)} \wedge \neg Props_{fn(j)}(\vec{x}_j)$$

- ▶ solving this is often intractable
- ▶ decompose this into smaller subformulae that are faster to solve
  - ▶ usually decomposition is over paths e.g. KLEE, UAutomizer

## Summaries and Calling Contexts

- ▶ approximate the input-output behavior of procedures
- ▶ from the callee's and caller's perspective, resp.
- ▶  $Sum_{foo}((y, g_6), (r, g_7)) = (y < max\_int \Rightarrow r > y)$
- ▶  $CallCtx_{foo_0}((x_0, g_1), (x_1, g_2)) = (g_1 \Rightarrow x_0 < 10)$

## Modular Safety Refutation

- ▶ a summary for each procedure  $f$  – while considering only  $f$  and the summaries for the procedures called in  $f$
- ▶ start with negation of properties
- ▶ compute *maximal* summary and contexts that lead the program to an error state

$$\begin{aligned}
 & \text{for all } j \in CS_f \\
 & \max \text{Sum}_f, \overbrace{\text{CallCtx}_j, \dots}^{\text{for all } j \in CS_f} : \forall X_f : \\
 & \quad \text{Sum}_f(\vec{x}_f^{\text{in}}, \vec{x}_f^{\text{out}}) \wedge \\
 & \quad \bigwedge_{j \in CS_f} \text{CallCtx}_j(\vec{x}_j^{\text{p-in}}, \vec{x}_j^{\text{p-out}}) \implies (\text{CallCtx}_f(\vec{x}_f^{\text{in}}, \vec{x}_f^{\text{out}}) \vee \neg \text{Props}_f) \wedge \\
 & \quad T_f(\vec{x}_f^{\text{in}}, \vec{x}_f^{\text{out}}) \wedge \text{Sums}_f
 \end{aligned} \tag{1}$$

- ▶ piece-wise calling contexts and summaries are combined disjunctively

## Working on the example

We start with

$$Sum_{main}((x_0, g_0), (g_5)) = \neg g_0,$$

$$Sum_{foo}((y, g_6), (r, g_7)) = \neg g_6,$$

$$Sum_{bar}((z, g_8), (g_9)) = \neg g_8,$$

$$CallCtx_{main}^*((x_0, g_0), (g_5)) = \neg g_5,$$

$$CallCtx_{foo}((y, g_6), (r, g_7)) = false,$$

$$CallCtx_{bar}((z, g_8), (g_9)) = false$$

$$\begin{array}{ll} T_{main}((x_0, g_0), (g_5)) & \equiv g_1=(g_0 \wedge (x_0 < 10)) \wedge \\ & \quad foo_0((x_0, g_1), (x_1, g_2)) \wedge \\ & \quad foo_1((x_1, g_2), (x_2, g_3)) \wedge \\ & \quad bar((x_2, g_3), (g_4)) \wedge \\ & \quad g_5=(g_0 \wedge \neg(x_0 < 10) \vee g_4) \\ Props_{main} & \equiv true \\ T_{foo}((y, g_6), (r, g_7)) & \equiv (r=y+1) \wedge (g_6=g_7) \\ Props_{foo} & \equiv true \\ T_{bar}((z, g_8), (g_9)) & \equiv g_9=(g_8 \wedge (z > 10)) \\ Props_{bar} & \equiv g_8 \Rightarrow (z > 10) \end{array}$$



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$$\begin{array}{ll} T_{main}((x_0, g_0), (g_5)) & \equiv g_1 = (g_0 \wedge (x_0 < 10)) \wedge \\ & \quad foo_0((x_0, g_1), (x_1, g_2)) \wedge \\ & \quad foo_1((x_1, g_2), (x_2, g_3)) \wedge \\ & \quad bar((x_2, g_3), (g_4)) \wedge \\ & \quad g_5 = (g_0 \wedge \neg(x_0 < 10)) \vee g_4 \\ Props_{main} & \equiv true \\ T_{foo}((y, g_6), (r, g_7)) & \equiv (r = y + 1) \wedge (g_6 = g_7) \\ Props_{foo} & \equiv true \\ T_{bar}((z, g_8), (g_9)) & \equiv g_9 = (g_8 \wedge (z > 10)) \\ Props_{bar} & \equiv g_8 \Rightarrow (z > 10) \end{array}$$

The backward traversal begins with *main*. We solve (1):

$$\max Sum_{main}, CallCtx_{foo_0}, CallCtx_{foo_1}, CallCtx_{bar} : \forall X_{main} :$$

$$Sum_{main}((x_0, g_0), (g_5)) \wedge$$

$$CallCtx_{foo_0}((x_0, g_1), (x_1, g_2)) \wedge$$

$$CallCtx_{foo_1}((x_1, g_2), (x_2, g_3)) \wedge$$

$$CallCtx_{bar}((x_2, g_3), (g_4)) \Rightarrow (\neg g_5 \vee \neg true) \wedge$$

$$g_1 = (g_0 \wedge (x_0 < 10)) \wedge$$

$$g_5 = ((g_0 \wedge \neg(x_0 < 10)) \vee g_4) \wedge$$

$$\neg g_1 \wedge \neg g_2 \wedge \neg g_3$$

## Working on the example

$$CallCtx_{bar} = \neg g_4,$$

$$CallCtx_{foo_1} = \neg g_3,$$

$$CallCtx_{foo_0} = \neg g_2,$$

$$Sum_{main} = \neg g_0 \wedge \neg g_5$$

|                               |          |   |
|-------------------------------|----------|---|
| $T_{main}((x_0, g_0), (g_5))$ | $\equiv$ | $g_1 = (g_0 \wedge (x_0 < 10)) \wedge$<br>$foo_0((x_0, g_1), (x_1, g_2)) \wedge$<br>$foo_1((x_1, g_2), (x_2, g_3)) \wedge$<br>$bar((x_2, g_3), (g_4)) \wedge$<br>$g_5 = (g_0 \wedge \neg(x_0 < 10)) \vee g_4$ |
| $Props_{main}$                | $\equiv$ | $true$  |
| $T_{foo}((y, g_6), (r, g_7))$ | $\equiv$ | $(r = y + 1) \wedge (g_6 = g_7)$  |
| $Props_{foo}$                 | $\equiv$ | $true$  |
| $T_{bar}((z, g_8), (g_9))$    | $\equiv$ | $g_9 = (g_8 \wedge (z > 10))$   |
| $Props_{bar}$                 | $\equiv$ | $g_8 \Rightarrow (z > 10)$  |

## Working on the example

$$\text{CallCtx}_{\text{bar}} = \neg g_4,$$

$$\text{CallCtx}_{\text{foo}_1} = \neg g_3,$$

$$\text{CallCtx}_{\text{foo}_0} = \neg g_2,$$

$$\text{Sum}_{\text{main}} = \neg g_0 \wedge \neg g_5$$

$$\begin{array}{ll} T_{\text{main}}((x_0, g_0), (g_5)) & \equiv g_1 = (g_0 \wedge (x_0 < 10)) \wedge \\ & \text{foo}_0((x_0, g_1), (x_1, g_2)) \wedge \\ & \text{foo}_1((x_1, g_2), (x_2, g_3)) \wedge \\ & \text{bar}((x_2, g_3), (g_4)) \wedge \\ & g_5 = (g_0 \wedge \neg(x_0 < 10)) \vee g_4 \\ \text{Props}_{\text{main}} & \equiv \text{true} \\ T_{\text{foo}}((y, g_6), (r, g_7)) & \equiv (r = y + 1) \wedge (g_6 = g_7) \\ \text{Props}_{\text{foo}} & \equiv \text{true} \\ T_{\text{bar}}((z, g_8), (g_9)) & \equiv g_9 = (g_8 \wedge (z > 10)) \\ \text{Props}_{\text{bar}} & \equiv g_8 \Rightarrow (z > 10) \end{array}$$

Then we recur into *bar* with (1) instantiated as:

$$\begin{array}{l} \max \text{Sum}_{\text{bar}} : \forall z, g_8, g_9 : \\ \text{Sum}_{\text{bar}}((z, g_8), (g_9)) \implies (\neg g_9 \vee \neg(g_8 \Rightarrow z > 10)) \wedge \\ \quad (g_9 = (g_8 \wedge z > 10)) \end{array}$$

## Working on the example

$$\text{CallCtx}_{\text{bar}} = \neg g_4,$$

$$\text{CallCtx}_{\text{foo}_1} = \neg g_3,$$

$$\text{CallCtx}_{\text{foo}_0} = \neg g_2,$$

$$\text{Sum}_{\text{main}} = \neg g_0 \wedge \neg g_5$$

$$\begin{array}{ll} T_{\text{main}}((x_0, g_0), (g_5)) & \equiv g_1 = (g_0 \wedge (x_0 < 10)) \wedge \\ & \text{foo}_0((x_0, g_1), (x_1, g_2)) \wedge \\ & \text{foo}_1((x_1, g_2), (x_2, g_3)) \wedge \\ & \text{bar}((x_2, g_3), (g_4)) \wedge \\ & g_5 = (g_0 \wedge \neg(x_0 < 10)) \vee g_4 \\ \text{Props}_{\text{main}} & \equiv \text{true} \\ T_{\text{foo}}((y, g_6), (r, g_7)) & \equiv (r = y + 1) \wedge (g_6 = g_7) \\ \text{Props}_{\text{foo}} & \equiv \text{true} \\ T_{\text{bar}}((z, g_8), (g_9)) & \equiv g_9 = (g_8 \wedge (z > 10)) \\ \text{Props}_{\text{bar}} & \equiv g_8 \Rightarrow (z > 10) \end{array}$$

Then we recur into *bar* with (1) instantiated as:

$$\begin{array}{l} \max \text{Sum}_{\text{bar}} : \forall z, g_8, g_9 : \\ \text{Sum}_{\text{bar}}((z, g_8), (g_9)) \implies (\neg g_9 \vee \neg(g_8 \Rightarrow z > 10)) \wedge \\ \quad (g_9 = (g_8 \wedge z > 10)) \end{array}$$

Hence, we get for  $\text{Sum}_{\text{bar}}$ :  $(g_8 \Rightarrow \neg(z > 10)) \wedge \neg g_9$

## Working on the example

- ▶ and so on ...
- ▶ we update  $CallCtx_{foo}$ , and compute  $Sum_{foo}$  to be  $(g_6 \Rightarrow \neg(r > 10) \wedge g_7) \wedge (r = y + 1)$
- ▶ and, after another invocation of the composition operator,  $Sum_{main} = (g_0 \Rightarrow \neg(x_0 > 8)) \wedge \neg g_5$
- ▶ hence,  $(x \leq 8)$  is a (maximal) refutation witness

## The example

```
void main(int x)
  if(x < 10)
    x = foo(x);
    x = foo(x);
    bar(x);
```

```
int foo(int y)
  return y+1;
```

```
void bar(int z)
  assert(z > 10);
```

$$\begin{aligned} T_{main}((x_0, g_0), (g_5)) &\equiv g_1 = (g_0 \wedge (x_0 < 10)) \wedge \\ &\quad foo_0((x_0, g_1), (x_1, g_2)) \wedge \\ &\quad foo_1((x_1, g_2), (x_2, g_3)) \wedge \\ &\quad bar((x_2, g_3), (g_4)) \wedge \\ &\quad g_5 = (g_0 \wedge \neg(x_0 < 10)) \vee g_4 \\ Props_{main} &\equiv true \end{aligned}$$

$$\begin{aligned} T_{foo}((y, g_6), (r, g_7)) &\equiv (r = y + 1) \wedge (g_6 = g_7) \\ Props_{foo} &\equiv true \end{aligned}$$

$$\begin{aligned} T_{bar}((z, g_8), (g_9)) &\equiv g_9 = (g_8 \wedge (z > 10)) \\ Props_{bar} &\equiv g_8 \Rightarrow (z > 10) \end{aligned}$$

We prove that

### Theorem

*$Sum_{f_{entry}}$  would be false in modular refutation if and only if the monolithic refutation formula is unsat.*

### Proof.

Induction on the size of call stack



## Examples of Refutation Algorithms

- ▶ three different instantiations of the compositional framework
  - ▶ domain used to propagate summaries and calling contexts
- ▶ *concrete* backward interpretation
  - ▶ a single constant value for each variable

$$\begin{aligned} \max Sum_{bar} : \forall z, g_8, g_9 : \\ Sum_{bar}((z, g_8), (g_9)) \implies & (\neg g_9 \vee \neg(g_8 \Rightarrow z > 10)) \wedge \\ & (g_9 = (g_8 \wedge z > 10)) \end{aligned}$$

$$\begin{aligned} \exists d : \forall z, g_8, g_9 : \\ (g_8 \Rightarrow z=d) \implies & (\neg g_9 \vee \neg(g_8 \Rightarrow (z > 10))) \wedge \\ & (g_9 = (g_8 \wedge z > 10)) \end{aligned}$$



## The example

```
void main(int x)
  if(x < 10)
    x = foo(x);
    x = foo(x);
    bar(x);
```

```
int foo(int y)
  return y+1;
```

```
void bar(int z)
  assert(z > 10);
```

$$\begin{aligned} T_{main}((x_0, g_0), (g_5)) &\equiv g_1 = (g_0 \wedge (x_0 < 10)) \wedge \\ &\quad foo_0((x_0, g_1), (x_1, g_2)) \wedge \\ &\quad foo_1((x_1, g_2), (x_2, g_3)) \wedge \\ &\quad bar((x_2, g_3), (g_4)) \wedge \\ &\quad g_5 = (g_0 \wedge \neg(x_0 < 10)) \vee g_4 \\ Props_{main} &\equiv true \end{aligned}$$

$$\begin{aligned} T_{foo}((y, g_6), (r, g_7)) &\equiv (r = y + 1) \wedge (g_6 = g_7) \\ Props_{foo} &\equiv true \end{aligned}$$

$$\begin{aligned} T_{bar}((z, g_8), (g_9)) &\equiv g_9 = (g_8 \wedge (z > 10)) \\ Props_{bar} &\equiv g_8 \Rightarrow (z > 10) \end{aligned}$$

## Examples of Refutation Algorithms

- ▶ three different instantiations of the compositional framework
  - ▶ domain used to propagate summaries and calling contexts
- ▶ *concrete* backward interpretation
  - ▶ a single constant value for each variable
- ▶ *abstract* backward interpretation
  - ▶ disjunction of intervals for variables

## Examples of Refutation Algorithms

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- ▶ *concrete* backward interpretation
  - ▶ a single constant value for each variable
- ▶ *abstract* backward interpretation
  - ▶ disjunction of intervals for variables
- ▶ *symbolic* backward interpretation (weakest precondition with slicing)
  - ▶ summaries may be as big as the procedures themselves

## How does compositional refutation help

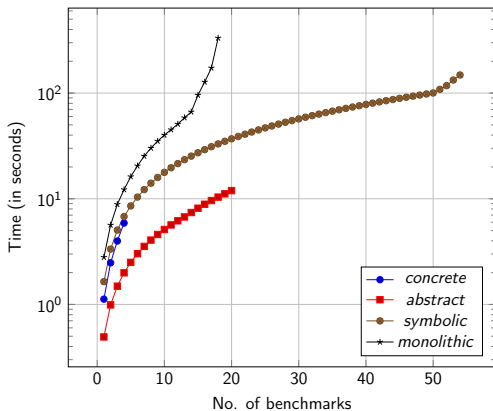
- ▶ spuriousness checks often succeed faster (without having to go all the way up to the entry function)
- ▶ summaries could be cached and reused

## Experiments

- ▶ implemented these techniques in 2LS (a tool built on the CPROVER framework)
- ▶ sources at <https://github.com/kumarmadhukar/2ls/tree/atva17>
- ▶ 265 benchmarks from SV-COMP (*product-lines*)
- ▶ reasonably complex – 83 procedures per benchmark (on avg.)
- ▶ chose an unwinding depth of 5

## Results

- ▶ compositional approaches faster than monolithic
- ▶ more complete techniques solve more examples
- ▶ concrete is slower (but uses SAT; can be made faster)



## Benefits of this approach

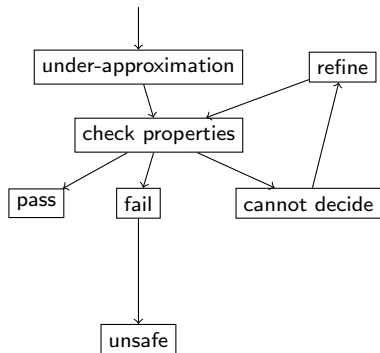
- ▶ spuriousness checks often succeed faster (without having to go all the way up to the entry function)
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## Summarizing this part..

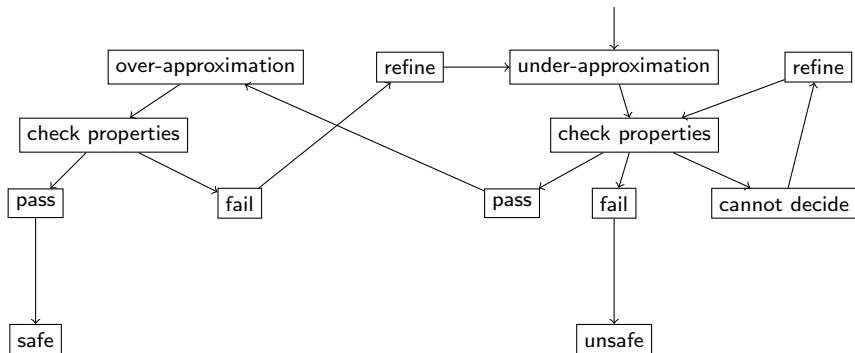
- ▶ compositional refutation in procedure-modular decompositions
- ▶ the abstract technique solves as many benchmarks as the monolithic one, even with only interval domains
- ▶ semantic decompositions – independent of the program's syntactic structure (*future work*)



How this fits in..



## How this fits in..



# Conclusion

- ▶ this thesis looks at techniques that aim at exploiting source-level syntactic and/or semantic structure of the input program
- ▶ opens up some interesting directions of future work
- ▶ for example, in the modular approaches that we have explored, the division is syntactic; it would be interesting to explore semantic decompositions

Thank you!

Questions?

# Appendix

## Acceleration helping invariant generation

- ▶ experimental evidence that proofs are easier to obtain
- ▶ consider, for example, the lazy abstraction with interpolants approach
- ▶ interpolants blocking all the paths in the loops may be obtained at once (due to the accelerated fragment), as compared to iterative strengthening

## Handling multiple and nested loops

- ▶ multiple and nested loops are handled with different unwindings for each loop
- ▶ we may also have a summary (or an invariant) for the inner loop and an unwinding for the outer loop
- ▶ refinement may strengthen the summary, or may add more unwindings to the loops
- ▶ we propose to do this *selectively* – by localizing the problem found during the spuriousness check