COL750: Foundations of Automatic Verification (Jan-May 2023)

Lectures 07 & 08 (CTL Model Checking and BDDs)

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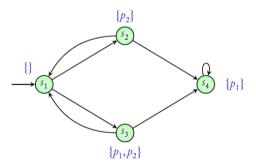
Jan 28th and 30th

Existential Normal Form for CTL

- $\phi := true \mid p_i \mid \phi_1 \wedge \phi_2 \mid \neg \phi \mid EX\phi \mid E(\phi_1 U \phi_2) \mid EG\phi$
- For every CTL formula there exists an equivalent CTL formula in ENF

Algorithms for EX, EU, and E G^1

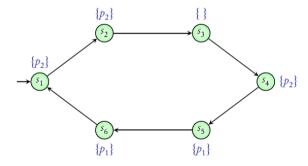
$$\mathbf{E} \mathbf{X} (p_1 \wedge \neg p_2)$$



¹all examples here are sourced from B. Srivathsan's NPTEL course slides on Model Checking

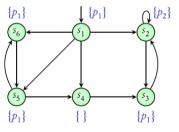
Algorithms for EX, EU, and EG

$$\mathbf{E} (\neg p_1 \mathbf{U} \neg p_2)$$



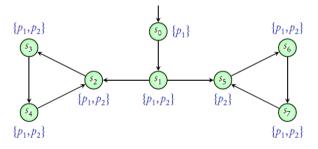
Algorithms for EX, EU, and EG

 $\mathbf{E} \mathbf{G} p_1$



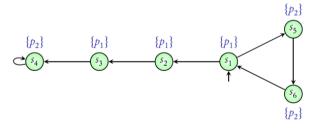
CTL Model Checking – Example 1

 $\mathbf{E} \mathbf{X} \mathbf{E} \mathbf{G} (p_1 \wedge p_2)$



CTL Model Checking – Example 2

 $\mathbf{E} p_1 \mathbf{U} (\mathbf{E} \mathbf{G} p_2)$



EX

```
\begin{array}{l} \textbf{function SAT}_{\textbf{EX}}\left(\phi\right) \\ /^* \ \text{determines the set of states satisfying EX} \ \phi \ ^* / \\ \textbf{local var} \ X, Y \\ \textbf{begin} \\ X := \texttt{SAT}\left(\phi\right); \\ Y := \mathtt{pre}_{\exists}(X); \\ \textbf{return} \ Y \\ \textbf{end} \end{array}
```

EU

```
function SAT<sub>EU</sub> (\phi, \psi)
/* determines the set of states satisfying E[\phi U \psi] */
local var W, X, Y
begin
   W := SAT(\phi);
   X := S;
   Y := SAT(\psi);
   repeat until X = Y
    begin
       X := Y:
       Y := Y \cup (W \cap \operatorname{pre}_{\exists}(Y))
    end
    return Y
end
```

EG

```
function SAT_{EG}(\phi)
/* determines the set of states satisfying EG \phi */
local var X, Y
begin
   Y := SAT(\phi);
   X := \emptyset:
   repeat until X = Y
   begin
       X := Y;
       Y := Y \cap \operatorname{pre}_{\exists}(Y)
   end
   return Y
end
```

State-space Explosion Problem

- Correctness and Termination

Efficiency

Thank you!