

Homework 4

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EEEN 5338 Digital and DSP Based Control

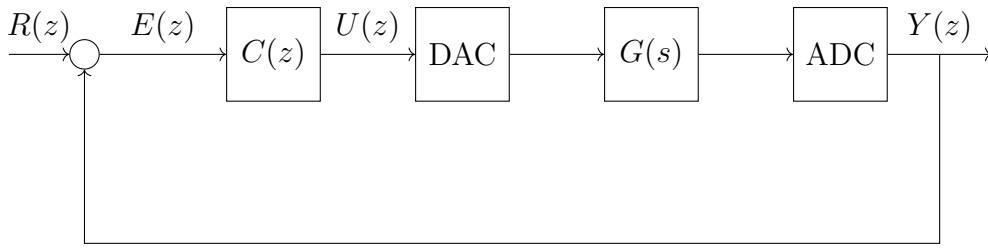
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Problem 1. For the following unity feedback system with

$$G(s) = \frac{s+8}{s+5}$$

which is digitally controlled with a sampling period of 0.02 seconds and a controller transfer function

$$C(z) = \frac{0.35z}{z-1}$$



(a) Find the z -transfer function for the analog subsystem with DAC and ADC.

$$\frac{G(s)}{s} = \frac{s+8}{s(s+5)} = \frac{A}{s} + \frac{B}{s+5} \implies s+8 = (s+5)A + sB$$

$$s=0 \implies 8=5A \implies A = \frac{8}{5} = 1.6$$

$$s=-5 \implies 3=-5B \implies B = -\frac{3}{5} = -0.6$$

$$\implies \frac{G(s)}{s} = \frac{1.6}{s} - \frac{0.6}{s+5}$$

$$G_{ZAS}(z) = (1-z^{-1})\mathcal{Z}\left\{\frac{G(s)}{s}\right\}$$

$$= \frac{z-1}{z} \left(\frac{1.6z}{z-1} - \frac{0.6z}{z-e^{-5(0.02)}} \right)$$

$$= 1.6 - \frac{0.6(z-1)}{z-e^{-0.1}}$$

using Wolfram Alpha to simplify the algebra:

$$G_{ZAS}(z) = \frac{z-0.84774}{z-0.904837}$$

- (b) Find the closed-loop transfer function and characteristic equation.

transfer function:

$$G_{cl}(z) = \frac{C(z)G_{ZAS}(z)}{1 + C(z)G_{ZAS}(z)}$$

$$= \left(\frac{0.35z(z - 0.84774)}{(z - 1)(z - 0.904837)} \right) / \left(1 + \frac{0.35z(z - 0.84774)}{(z - 1)(z - 0.904837)} \right)$$

using Wolfram Alpha to simplify the algebra:

$$G_{cl}(z) = \frac{0.259259(z - 0.84774)z}{z^2 - 1.63077z + 0.67025}$$

characteristic equation:

$$1 + C(z)G_{ZAS}(z) = 0$$

$$z^2 - 1.63077z + 0.67025 = 0$$

- (c) Find the steady-state error due to a sampled unit step and a sampled unit ramp. Comment on the effect of the controller on steady-state error.

$$C(z)G_{ZAS}(z) = L(z)$$

$$\Rightarrow L(z) = \frac{0.35z(z - 0.84774)}{(z - 1)(z - 0.904837)}$$

$$\Rightarrow \text{system is type 1}$$

The steady state error for a sampled unit step is 0 for type 1 and higher.
The steady state error for a sampled unit ramp is:

$$e(\infty) = \frac{T}{(z - 1)L(z)|_{z=1}} = \frac{0.02}{\frac{0.35(1-0.84774)}{1-0.904837}} = 0.035714$$

If the controller has additional pole(s) at unity, the type of the system can be increased to make the steady-state error 0 for the unit ramp.

Problem 2. Use MATLAB for the following system with a sampling period of 0.05 seconds:

$$G(s) = \frac{10(s+2)}{s(s+5)}$$

(a) Obtain the transfer function for the system with sampled input and output.

```
>> g=zpk(-2,[0,-5],10)

g =

    10 (s+2)
    -----
     s (s+5)

Continuous-time zero/pole/gain model.

>> gd=c2d(g,.05,'imp')

gd =

    0.5 z (z-0.9115)
    -----
   (z-1) (z-0.7788)

Sample time: 0.05 seconds
Discrete-time zero/pole/gain model.
```

(b) Obtain the transfer function for the system with DAC and ADC.

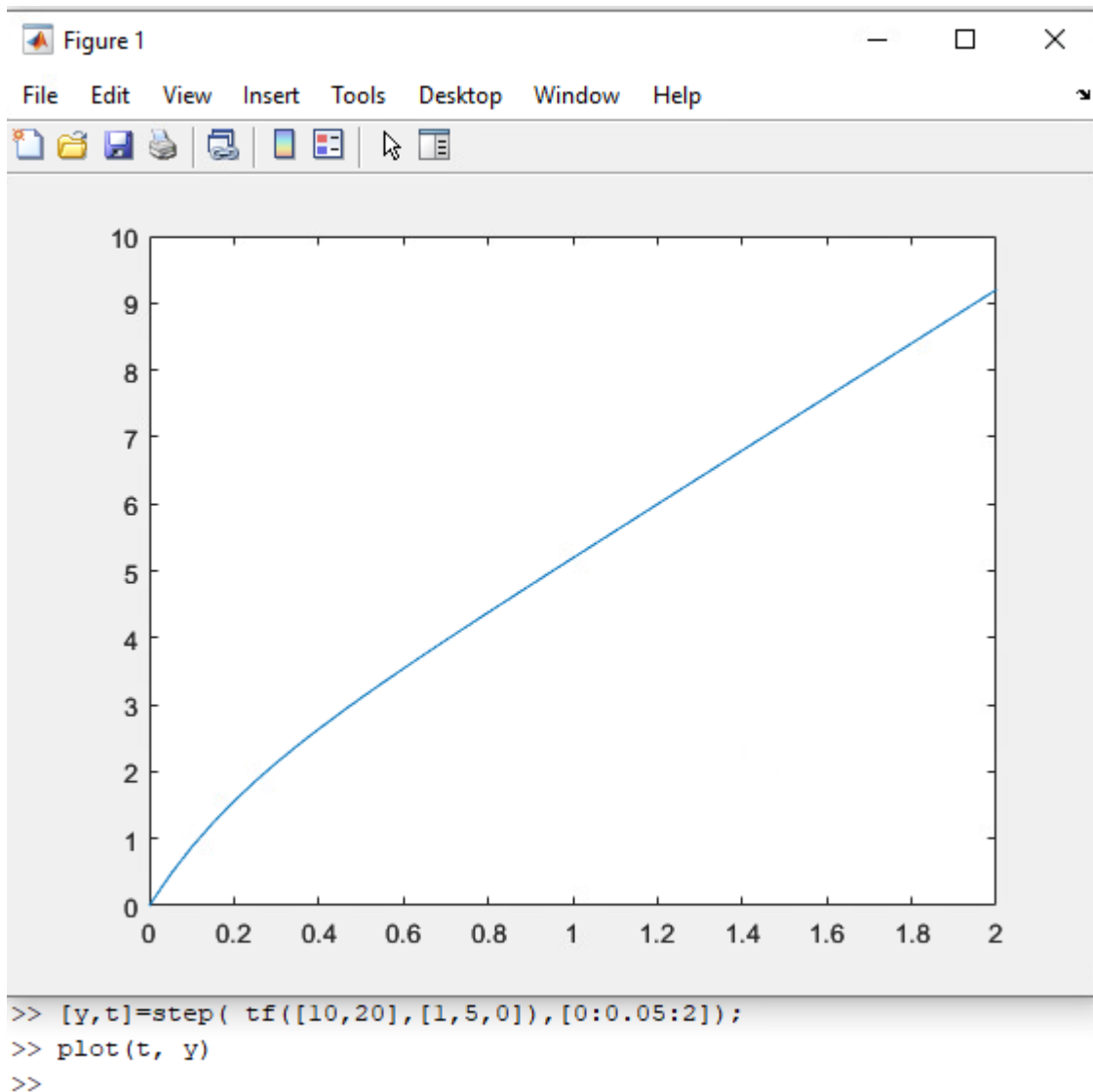
```
>> gd = c2d(g,.05,'zoh')

gd =

    0.46544 (z-0.905)
    -----
   (z-1) (z-0.7788)

Sample time: 0.05 seconds
Discrete-time zero/pole/gain model.
```

(c) Obtain the unit step response of the system with sampled output and analog input.



(d) Obtain the poles of the system in (a), (b), and the output of (c) and comment on the differences between them.

Both (a) and (b) have poles at 1 and 0.7788. (c) has an additional pole at 1 from the unit step.