```
import java.util.*;
class Node {
    String id;
    int heuristicValue;
    List<Edge> edges = new ArrayList♦();
    Node(String id, int heuristicValue) {
        this.id = id;
        this.heuristicValue = heuristicValue;
    }
    void addEdge(Node node, int weight) {
        edges.add(new Edge(node, weight));
    }
    @Override
    public String toString() {
        return id;
}
class Edge {
    Node node;
    int weight;
    Edge(Node node, int weight) {
        this.node = node;
        this.weight = weight;
    }
}
class AStar {
    static class NodeComparator implements Comparator<Node> {
        Map<Node, Integer> gScore;
        NodeComparator(Map<Node, Integer> gScore) {
            this.gScore = gScore;
        }
        @Override
        public int compare(Node node1, Node node2) {
            return (gScore.get(node1) + node1.heuristicValue) - (gScore.get(node2) +
                    node2.heuristicValue);
        }
    }
    static List<Node> aStarAlgo(Node startNode, Node stopNode) {
        Set<Node> openSet = new HashSet<>();
        Set<Node> closedSet = new HashSet<>();
        Map<Node, Integer> gScore = new HashMap♦();
        Map<Node, Node> parents = new HashMap♦();
        gScore.put(startNode, 0);
        parents.put(startNode, startNode);
        openSet.add(startNode);
        while (!openSet.isEmpty()) {
            Node n = Collections.min(openSet, new NodeComparator(gScore));
            if (n = stopNode) {
```

```
List<Node> path = new ArrayList♦();
                while (parents.get(n) \neq n) {
                     path.add(n);
                     n = parents.get(n);
                }
                path.add(startNode);
                Collections.reverse(path);
                System.out.println("Path found: " + path);
                return path;
            }
            openSet.remove(n);
            closedSet.add(n);
            for (Edge edge : n.edges) {
                Node m = edge.node;
                int weight = edge.weight;
                if (!openSet.contains(m) && !closedSet.contains(m)) {
                     openSet.add(m);
                     parents.put(m, n);
                     gScore.put(m, gScore.get(n) + weight);
                } else if (gScore.get(m) > gScore.get(n) + weight) {
                     gScore.put(m, gScore.get(n) + weight);
                     parents.put(m, n);
                     if (closedSet.contains(m)) {
                         closedSet.remove(m);
                         openSet.add(m);
                     }
                }
            }
        }
        System.out.println("Path does not exist!");
        return null;
    }
}
public class Main {
    public static void main(String[] args) {
        Node A = \text{new Node}("A", 11);
        Node B = new Node("B", 6);
        Node C = \text{new Node}("C", 5);
        Node D = \text{new Node}("D", 7);
        Node E = new Node("E", 3);
        Node F = new Node("F", 6);
        Node G = \text{new Node}("G", 5);
        Node H = new Node("H", 3);
        Node I = new Node("I", 1);
        Node J = new Node("J", 0);
        A.addEdge(B, 6);
        A.addEdge(F, 3);
        B.addEdge(A, 6);
        B.addEdge(C, 3);
        B.addEdge(D, 2);
        C.addEdge(B, 3);
        C.addEdge(D, 1);
        C.addEdge(E, 5);
        D.addEdge(B, 2);
```

```
D.addEdge(C, 1);
         D.addEdge(E, 8);
         E.addEdge(C, 5);
         E.addEdge(D, 8);
         E.addEdge(I, 5);
         E.addEdge(J, 5);
         F.addEdge(A, 3);
F.addEdge(G, 1);
F.addEdge(H, 7);
         G.addEdge(F, 1);
         G.addEdge(I, 3);
         H.addEdge(F, 7);
         H.addEdge(I, 2);
         I.addEdge(E, 5);
         I.addEdge(G, 3);
I.addEdge(H, 2);
         I.addEdge(J, 3);
         AStar.aStarAlgo(A, J);
    }
}
Output
```

Path found: [A, F, G, I, J]