Becs-114.1100 Computational Science – exercise round 5

Kunal Ghosh, 546247

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1 Solution to Question 2

1.1 Solving linear equations using Scaled Pivoting. Weights from corresponding hilbert matrices

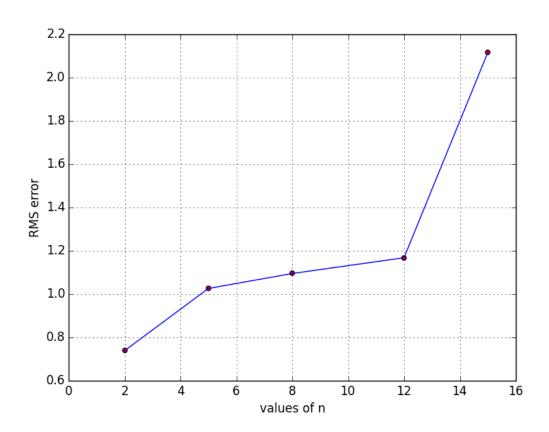


Figure 1: Plot showing that as n increases the RMS error of the solution of a system of linear equations, with the hilbert matrix values as its coefficients, increases. The red dots show the actual error values

The table of n and errors appears on page 4. The corresponding python code can be found at 2

1.2 Solving system of linear equations with coefficients as hilbert(n) for n=3

Solving a system of linear equations with weights as the hilbert matrix. Calculations performed upto 3 descimal places.

A = hilbert (3)
$$\begin{bmatrix} 1 & 0.5 & 0.333 \\ 0.5 & 0.333 & 0.25 \\ 0.333 & 0.25 & 0.2 \end{bmatrix} b = \begin{bmatrix} 1.833 \\ 1.083 \\ 0.783 \end{bmatrix}$$

Theration 1:
$$\frac{|Ai1|}{Si}i = 1,2,3 = \begin{bmatrix} 1/1 \\ 0.5/0.5 \\ 0.333/0.333 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$
 : first highest = 1 = pivot

$$= 0.5/1 = 0.5$$

1.833

$$= 0.333/1 = 0.333$$
.

$$= \begin{bmatrix} 1 & 0.5 & 0.333 \\ 0 & 0.333 - & 0.25 - \\ 0.25 & 0.333 \times 0.5 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0.25 - & 0.2 - \\ 0.85 \times & 0.333 \times \\ 0.333 & 0.333 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0.5 & 0.333 & 0.466 \\ 0 & 0.083 & 0.083 & 0.166 \\ 0 & 0.083 & 0.089 & 0.173 \end{bmatrix}$$

Theration 2:
$$|Ai2|$$
 $i = 2,3 = \begin{bmatrix} 0.083/0.5 \\ 0.083/0.333 \end{bmatrix} = \begin{bmatrix} 0.166 \\ 0.249 \end{bmatrix}$ pivot = 0.249

Muap.
$$(I[2], I[3]) \Rightarrow I = [1, 3, 2]$$

- Find Multiplier for RowZ = A[Row=2, column=2]/A[Pivot, col=2]= 0.083/0.083 = 1.
- . Multiply pivot row by multiplier & subtract from 2.

$$\begin{bmatrix} 1 & 0.5 & 0.333 & 1.833 \\ 0 & -0.006 & -0.007 \\ 0 & 0.083 & 0.089 & 0.173 \end{bmatrix}$$

Back Substitution: reverse order of
$$I = [1, 3, 2]$$
.

$$x_0 = -0.007/-0.006 = 1.167$$

$$\alpha \omega 2$$
; $\alpha_3 = \frac{1}{100}$ $\alpha_2 = \frac{1}{100} \left[\frac{1}{100} \cdot \frac{1}{100} + \frac{1}{100} \cdot \frac{1}{100} \right] = \frac{1}{100} \cdot \frac{1}{100}$

$$\gamma_{0\omega}$$
 3 , $\alpha_{1} = \left[1.833 - (1.167 \times 0.333 + 0.833 \times 0.5)\right]/1 = 1.028$

$$X = \begin{bmatrix} 1.028 \\ 0.833 \\ 1.167 \end{bmatrix}$$

From the thumb rule: if Condition number is 10^k then we may loose upto k digits of accuracy. Over and above the Numerical loss.

And we can see here that own results are off by 2 digits of precision (A little more than 2 but that can be attributed

To the numerical error.).

Condition

Because of the high; tibert number. The precision we are loosing by Keeping upto 3 decimal places is causing a har large change in the output over and above the numerical error.

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n	RMS Error	Condition Number
2	0.73833521	15.0167409881
5	1.02602254	282901.77002
8	1.09505307	7657562245.89
12	1.16783884	$5.89342127254\mathrm{e}{+15}$
15	2.11656192	$1.74359790918e{+17}$

Table 1: Table showing the values of n and the RMS error after solving the system of linear equations with hilbert(n) as the coefficients.

2 Appendix A

Python source code for 1.1.

```
from __future__ import division
from scipy.linalg import hilbert
import numpy as np
from pprint import pprint
import pylab as pl
def new_solve(A,b):
     new_solve(A,o):
A = np.asarray(A, np.float)
b = np.asarray(b, np.float)
# Create the scale vector max(abs(ri)) of each row ri in A
S = np.zeros(A.shape[0], np.float)
     S = np.max(np.abs(A), axis=1)
# Create the Index vector
     # iterate over as many times as there are rows (r = 0 to rmax)
for idx in range(len(I)):
          r = I[idx]
           # get the values from the idx(th) column
           rows_we_want = I[idx:]
          corresponding_column_values = A[rows_we_want, idx]
# divide the column values by their corresponding scale and get the index of the row with max value
           div_val = np.true_divide(np.abs(corresponding_column_values),S[rows_we_want])
           I_idx = np.argmax(div_val)
          # because the above index is in I, the actual row is
act_idx = I[idx:][I_idx]
max_row = A[act_idx,:]
           # swap current Idx with max_row's idx
# swap the Oth idx and the new max in the sub array of I
I[idx:][0], I[idx:][I_idx] = I[idx:][I_idx], I[idx:][0]
           # iterate over remaining rows and update them
           for rem_rows in I[idx+1:]:
                # Get the appropriate multiple of the pivot row. to make the remaining row's idx column a zero
                w det the appropriate matterne of the proof tow. to make to
multiplier = np.true_divide(A[rem_rows][idx], aax_row[idx])
A[rem_rows,idx:] -= max_row[idx:] * multiplier
b[rem_rows] -= b[act_idx] * multiplier
     return I, A, b
def gauss(I, A, b):
        returns the solutions to x
     x = np.zeros(I.shape)
     # because this is directly used in indexing and # max index of x would be len(x) -1
     len_x = len(x)-1
     # reverse I because we go in reverse I order.
     I = I[::-1]
     for count, row in enumerate(I):
          # get the row which we need to evaluate
weighted_sum_of_already_computed_x = 0
          for i in range(count):
    # if its the first value, we need to evaluate once.
                \mbox{\tt\#} for the second value, we need to evaluate twice and so on.col = len_x-i
           \label{eq:weighted_sum_of_already_computed_x += A[row, col] * x[col] $$ $$ len(x)$-count-1 because indices from 3 to 0 when len(x) = 4 $$
          x[len_x-count] = (b[row] - weighted_sum_of_already_computed_x) / A[row,len_x-count]
     return x
def error(x,x_actual):
     diff = np.abs(x-x actual)
     return np.sqrt(np.divide(np.sum(diff ** 2),x.shape))
if __name__ == '__main__':
    errs = []
     errors = []
n_vals = [2,5,8,12,15]
     for n in n_vals:
          A = hilbert(n)
b = np.sum(A,axis=1)
          I,A,b = new_solve(A,b)
x = gauss(I,A,b)
errors.append(error(x,b))
           print n,errors[-1]
     pl.plot(n_vals, errors,c='b')
     pl.grid()
     pl.scatter(n_vals, errors,c='r',marker="o")
pl.xlabel("values of n")
     pl.ylabel("RMS error of partial pivot and actual solution of hilbert(n)") pl.show()
```