# CS-E4830 Kernel Methods in Machine Learning Assignment 2

Kunal Ghosh, 546247

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$$K_{Aj}^{C} = K_{C}(x_{i}, x_{j}) = \langle \Phi_{C}(x_{i}), \Phi_{C}(x_{j}) \rangle$$

$$\Phi_{C}(x) = \Phi(x) - \frac{1}{N} \sum_{i=1}^{N} \Phi(x_{i})$$

$$\therefore = \langle \Phi_{C}(x_{i}) \Phi_{C}(x_{j}) \rangle = \left[ \Phi(x_{i}) - \frac{1}{N} \sum_{j=1}^{N} \Phi(x_{j}) \right]^{T} \left[ \Phi(x_{j}) - \frac{1}{N} \sum_{j=1}^{N} \Phi(x_{j}) \right] - \left[ \Phi(x_{i}) - \frac{1}{N} \sum_{j=1}^{N} \Phi(x_{j}) \right] - \left[ \Phi(x_{i}) \Phi(x_{j}) - \frac{1}{N} \sum_{j=1}^{N} \Phi(x_{j}) \right] - \left[ \Phi(x_{i}) \Phi(x_{j}) - \frac{1}{N} \sum_{j=1}^{N} \Phi(x_{j}) + \frac{1}{N} \sum_{j=1}^{N} \Phi(x_{j}) \right] + \frac{1}{N} \left[ \sum_{j=1}^{N} \Phi(x_{j}) + \frac{1}{N} \sum_{j=1}^{N} \Phi(x_{j}) \right] = 2$$

$$= K_{ij} - \frac{1}{N} \sum_{p=1}^{N} \Phi^{T}(x_{p}) \cdot \Phi(x_{d}) \cdot - \frac{1}{N} \sum_{q=1}^{N} \Phi^{T}(x_{i}) \cdot \Phi(x_{q}) \cdot + \frac{1}{N^{2}} \sum_{p=1}^{N} \sum_{q=1}^{N} \Phi^{T}(x_{p}) \cdot \Phi(x_{q}) \cdot - \frac{3}{N} \sum_{p=1}^{N} \sum_{q=1}^{N} \sum_{q=1}^{N} K_{pq} - \frac{1}{N^{2}} \sum_{p=1}^{N} \sum_{q=1}^{N} K_{pq} - \frac{4}{N^{2}} \cdot \frac{1}{N^{2}} \cdot \frac{$$

Here, in Eq3.  $\frac{1}{N} \sum_{i} \Phi(x_{p}) \cdot \Phi(x_{j})$ , for each value of p.  $\Phi(x_{p})$  is a vector, of which, we find a dot product with  $\Phi(x_{j})$ , if we have only  $1.1.x_{p}$ ? Then we have  $\Phi(x_{p}) \cdot \Phi(x_{j}) = K_{pq}$ , but we have  $P \in \mathcal{F}_{1}, ..., N_{p}$  which we are averaging over that's why we have  $\frac{1}{N} \sum_{p=1}^{N} K_{pq}$ .

## 1 (b)

b.  $K_c(x_i, t_j) = \langle \Phi_c(x_i) , \Phi_c(t_j) \rangle$  We need to continuthe data with the braining dataset.

$$= \left( \Phi_{\bullet}(x_i) - \frac{1}{N} \sum_{j=1}^{N} \Phi(x_j) \right)^{T} \left( \Phi_{\bullet}(t_j) - \frac{1}{N} \sum_{q=1}^{N} \Phi(t_i \times q) \right)$$

$$= \left[ \varphi_{\Delta}(x_1) - \frac{1}{1} \sum_{j=1}^{N} \varphi_{\Delta}(x_j) \right] \left[ \varphi(\xi_1) - \frac{1}{1} \sum_{j=1}^{N} \varphi(x_j) \right]$$

$$= K(x_{i}, t_{j}) - \frac{1}{N} \sum_{q=1}^{N} \phi^{T}(x_{i}) \phi(x_{q}) - \frac{1}{N} \sum_{p=1}^{N} \phi^{T}(x_{p}) \cdot \phi(t_{j}) + \frac{1}{N^{2}} \sum_{p=1}^{N} \sum_{q=1}^{N} \phi^{T}(x_{p}) \cdot \phi(t_{j}) + \frac{1}{N^{2}} \sum_{p=1}^{N} \phi^{T}(x_{p}) \cdot \phi(t_{j}) + \frac{1}{N^{2}} \sum_{p=1}^{N$$

$$= K(x_i, t_j) - \frac{1}{N} \sum_{q=1}^{N} K_{iq} - \frac{1}{N} \sum_{p=1}^{N} K(x_p, t_j) + \frac{1}{N^2} \sum_{q=1}^{N} \sum_{q=1}^{N} K_{pq}.$$
from (train, test) Theorem from from (Train, Train)
Kernel.

(Train, Train) Kernel.

(Train, Train) Kernel.

- (b) Derivation of dual problem.
  - Expressing the primal problem in the saw nical form

min 
$$\frac{1}{2} \|\omega\|^2 + \frac{c}{2} \sum_{i=1}^{m} \xi_{i}^2$$
.

NOTE: here "b" is included as a cohumn of constants in the vector 'x'

let us define a lagrange variable & and derive the Lagrangian due

i.e. 
$$\min_{\omega, \xi} \cdot \frac{1}{2} \|\omega\|^2 + \frac{c}{2} \sum_{i=1}^{m} \xi_{ii}^2 + \sum_{i=1}^{m} \lambda_i (1 - \gamma_i(\omega^T \times i) - \xi_{ii}) \cdot \forall i=1...m$$

$$= L(\omega, \xi_i, \lambda) \quad \text{s.t.} \quad \lambda_i \geqslant 0.$$

· Finding the minimal of the lagrangian by finding the derivative 20.7 the primal variables and setting the derivative to zero.

$$\nabla_{\omega} L(\omega, \xi, \lambda) = \omega - \sum_{i=1}^{m} \lambda_i y_i \times_i = 0$$

$$\dots \omega = \sum_{i=1}^{m} \lambda \forall i \times i - \mathbf{Q}$$

$$\nabla_{\xi_{i}} L(\omega, \xi_{i}, \lambda) = C \xi_{i} - \lambda i = 0$$
 .  $\xi_{i} = \frac{\lambda i}{C} - 3$ 

or  $C = \frac{\lambda i}{\xi_{i}}$ 

Substituting @ and & in 1 in we get.

$$\frac{1}{2} \left\| \sum_{i=1}^{m} \lambda_{i} y_{i} \times i \right\|^{2} + \sum_{i=1}^{m} \frac{\lambda_{i}}{E_{1}} \times \underbrace{\frac{2}{2}}_{i=1}^{2} + \sum_{i=1}^{m} \lambda_{i} \left(1 - y_{i} \left(\sum_{j=1}^{m} \lambda_{j} y_{j} x_{j}\right) X_{i} - y_{i} \left(\sum_{j=1}^{m} \lambda_{j} y_{j} x_{j}\right) X_{i} \right)$$

$$= \frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \lambda_i \lambda_j Y_i Y_j \times_i^T \times_j + \sum_{i=1}^{m} \frac{\lambda_i \mathcal{E}_{ii}}{2} \cdot + \sum_{i=1}^{m} \lambda_i - \sum_{i=1}^{m} \lambda_i \mathcal{E}_{ii}$$

$$- \sum_{i=1}^{m} \sum_{j=1}^{m} \lambda_i \lambda_j Y_i Y_j \times_j^T \times_i$$

$$= \sum_{i=1}^{m} \lambda_{i} - \sum_{i=1}^{m} \frac{\lambda_{i} \mathcal{E}_{i}}{a} - \frac{1}{a} \sum_{i=1}^{m} \frac{\lambda_{i}}{\lambda_{i}} \gamma_{i} \gamma_{j} \mathcal{K}(\mathcal{K}_{i} \mathcal{K}_{j} \mathcal{K}_{j} \langle \times_{i}, \times_{j} \rangle); s.t. \lambda_{i}$$
Can be supposed by a Kernel

$$= \max_{\lambda_{i}} \sum_{i=1}^{m} \lambda_{i} \left(1 - \underbrace{\Xi_{i}}_{2}\right) - \underbrace{\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \lambda_{i} \lambda_{j}}_{j=1} \gamma_{i} \lambda_{j} \gamma_{i} \gamma_{j} \kappa(x_{i}, x_{j}) .$$
 (The dual problem)

2 (a)

a). By definition, the constraint C>O controls the balance between maximizing the margin & amount of slack needed. also 2i>O : from Eq3.

$$\mathcal{E}_{i} = \frac{\lambda i}{c}$$

So, this constraint holds implicitly.

Hence, its not needed to be included

among the constraints in the original optimization problem.

2 (c)

C). In this problem, let  $\alpha$  be the dual variable, the complementary slockness conditions are  $\alpha$  is  $[y_i(\omega^Tx_i)-1+\Sigma_i]=0$  for i=1...m. What is the value (or range) of the margin  $y_i(\omega^Tx_i+b)$  for  $\alpha$  is  $\alpha$ 

and di = 0.

at the optimal condition ( $\omega^*$ ). the complementary stackness condition holds.

i.e. if 
$$\alpha i > 0$$
 then  $y_i [(\omega^* x_i) - 1 + \mathcal{E}_i]_k = 0$ .  

$$y_i (\omega^* x_i) = 1 - \mathcal{E}_i$$

and when 
$$\alpha_i = 0$$
 this Yi (w\*Txi) - 1 + Egi < 0

#### Solution to Question 3

#### Solution to Question 4

We can then encapsulate the kernel\_ridge\_regression method and the get\_prediction\_mse method to a more convenient single method.

### Solution to Question 5 (a)

Applying the kernel\_ridge\_regression code to the UCI forest fire dataset.

```
% -----
% Predicting forest fires.
% -----
load data_all.mat
lambdas = 10 \cdot (-3:7);
sigmas = 10 .^ (-1:4);
% Matrices to save the value of MSE for train and test data.
sigma_len = size(sigmas, 2);
lambda_len = size(lambdas,2);
result_shape = [sigma_len, lambda_len];
mse_test = zeros(result_shape);
mse_train = zeros(result_shape);
mse_cv = zeros(result_shape);
lowest_cv_error = Inf;
best_sigma = 0;
best_lambda = 0;
K = 5; % K fold cross validation
for sigma_idx = 1:sigma_len
  for lambda_idx = 1:lambda_len
       sigma = sigmas(sigma_idx);
       lambda = lambdas(lambda_idx);
       % we keep saving the errors so that later we don't need to recompute them
       [mse_train(sigma_idx, lambda_idx), mse_test(sigma_idx, lambda_idx)] = ...
           kernel_ridge_regression_on_dataset(X_train, y_train, X_test, y_test, sigma,
           → lambda);
       %-----
       % Calculate K-fold cross validation error
       %-----
       mse_cv(sigma_idx, lambda_idx) = get_k_fold_cv_error_new(K, X_train, y_train,

→ sigmas(sigma_idx), lambdas(lambda_idx));
       cv_error = mse_cv(sigma_idx, lambda_idx)
       % check if cross validation error lower than previous lowest
       %-----
       if cv_error < lowest_cv_error</pre>
           lowest_cv_error = cv_error;
           best_sigma = sigmas(sigma_idx);
           best_lambda = lambdas(lambda_idx);
       end
  end
end
	ilde{\mbox{\it %}} -- MSE on the full training dataset using the best parameters
best_sigma_idx = find(sigmas == best_sigma);
best_lambda_idx = find(lambdas == best_lambda);
mse_test_for_best_params = mse_test(best_sigma_idx, best_lambda_idx);
display(mse_test_for_best_params);
% -- Best parameter values from the K-fold cross validation
display(best_sigma);
display(best_lambda);
%% MSE Test 3D plot
```

```
figure();
meshc(log10(lambdas),log10(sigmas),log10(mse_test))
xlabel('Lambda');
ylabel('Sigma');
zlabel('Mean Squared Error');
%% MSE Train 3D plot
hold on;
meshc(log10(lambdas),log10(sigmas),log10(mse_cv))
% meshc(log10(lambdas),log10(sigmas),log10(mse_train))

%title('MSE of Test data (top plane) and Training data (bottom plane), all values in log10

$\rightarrow$ scale.');
```

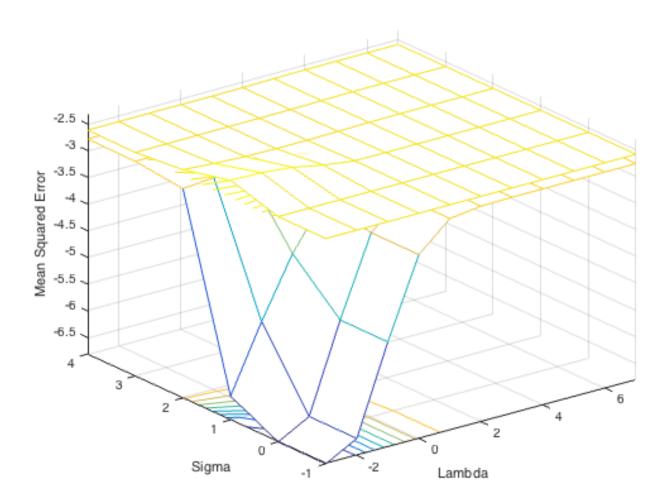


Figure 1: MSE of Test data (top plane) and Training data (bottom plane) all values in log10 scale. In the plot above, for sigma values between  $10^{-1}$  and  $10^2$  and lambda values between  $10^{-3}$  and 1 (all pairs) we notice that the training error (bottom plane) is much lower than the test error (top plane). This would imply that for these values of sigma and lambda the model is overfitting to the training dataset. However, for rest of the values of sigma and lambda the training and test errors don't have a huge gap so we can say that for those parameter values the model generalizes well.

**Observation:** In the above plot, for a small sigma and lambda values, we see that there is overfitting. But for any given (small) sigma, as we increase the regularization (lambda increased) the overfitting reduces and that's as expected. However, for larger sigma values there is no overfitting even for small regularization and so, increasing the regularization doesn't have any effect.

### Solution to Question 5 Part (b)

Parameter combination with lowest cross-validation error. Also reported is the mean-squared-error on the test set using the parameter combination. Note that we have not retrained the model using the best sigma and lambda values since we had already calculated and saved the MSE values. We have just reported the saved MSE values which should remain same after training.

mse\_test\_for\_best\_params =

```
0.0031
best_sigma =
10
best_lambda =
```

#### Code to compute the k-fold cross-validation error

The function below is being invoked in the script defined in Solution to Question 5 part (a)

```
function [ error ] = get_k_fold_cv_error_new(K, X_train, y_train, sigma, lamda)
\mbox{\ensuremath{\it \%}}\ get_k\_fold\_cv\_error\ \mbox{\ensuremath{\it Calculates}}\ the\ \mbox{\ensuremath{\it K}}\ fold\ cross\ validation
num_datapoints = size(X_train,1);
shuffle_idxs = randperm(num_datapoints);
% -- datapoints in each subset
partition_size = floor(num_datapoints / K);
start_idx = 1;
% -- initialize an empty list of mean_squared_errors
mserrors = zeros(1,K);
for k = 1:K-1
    % -- Calculations to get the Train and Validation split
    end_idx = min(start_idx+partition_size-1,length(shuffle_idxs)); % ending index of
     \rightarrow validation set
    validation_set_idxs = (start_idx:end_idx);
    valid_set_X = X_train(validation_set_idxs,:);
    valid_set_Y = y_train(validation_set_idxs,:);
    train_set_idxs = setdiff(shuffle_idxs, validation_set_idxs);
    train_set_X = X_train(train_set_idxs,:);
    train_set_Y = y_train(train_set_idxs,:);
    %----- Actual Training/Testing happens here.
    [, mserrors(1,k)] = ...
        kernel_ridge_regression_on_dataset(train_set_X, train_set_Y, valid_set_X,

    valid_set_Y, sigma, lamda);
    start_idx = end_idx+1; % starting index of next validation set
end
```