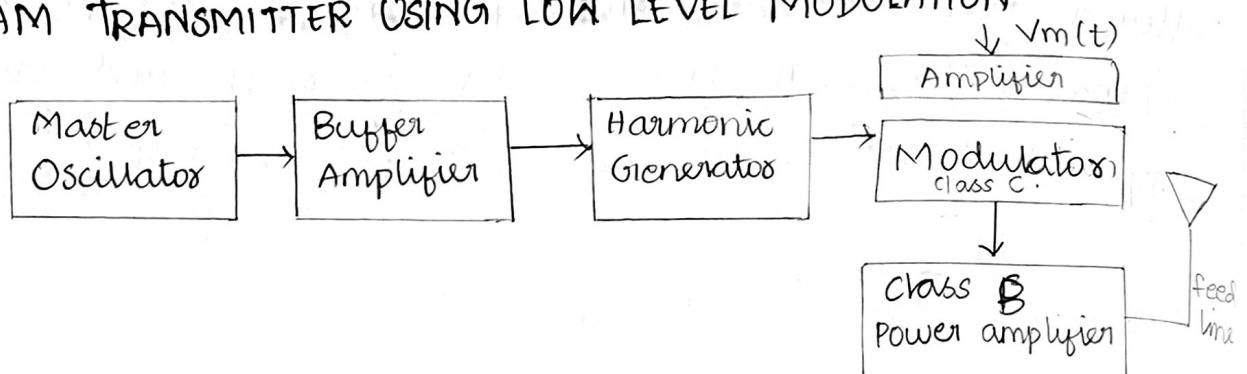


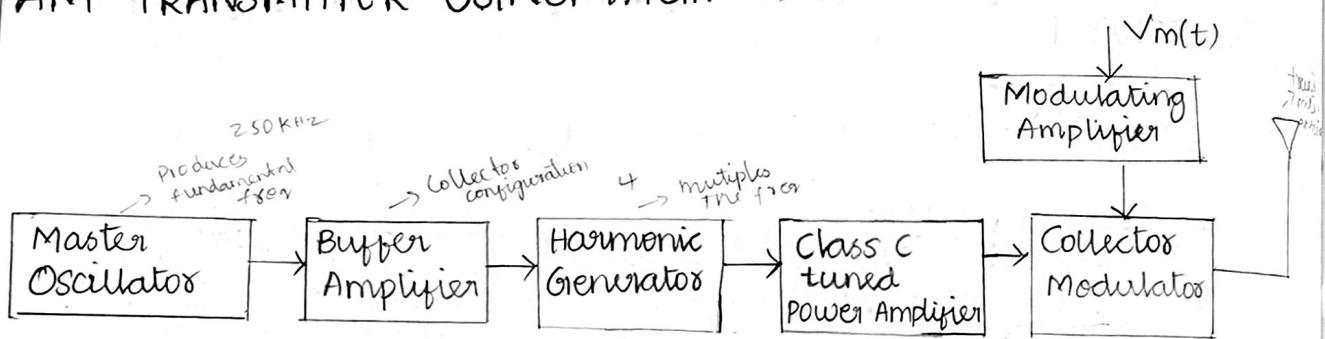
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UNIT 2: TRANSMITTER AND RECEIVER

AM TRANSMITTER USING LOW LEVEL MODULATION



AM TRANSMITTER USING HIGH LEVEL MODULATION



Modulation takes place at low power level and then amplified by a class B power amplifier (low level)

The carrier is first amplified by a ^{class C} amplifier and then modulation is done at high power level. (high level)

MASTER OSCILLATOR.

Generates carrier frequency at fundamental frequency. Frequency is increased to the desired frequency value by Harmonic generator

BUFFER AMPLIFIER

Buffer amplifier is used between master oscillator and Harmonic oscillator and provides high input impedance from the MO.

amplifier to match the antenna power rating

HARMONIC GENERATOR.

Harmonic generator produces frequency through frequency multiplication. The desired frequency is

Chosen through class C tuned power amplifier.

NOTE:

One more stage of class C tuned power amplifier is used at high level modulation used to amplify the C.S.

FEEDER AND THE ANTENNA

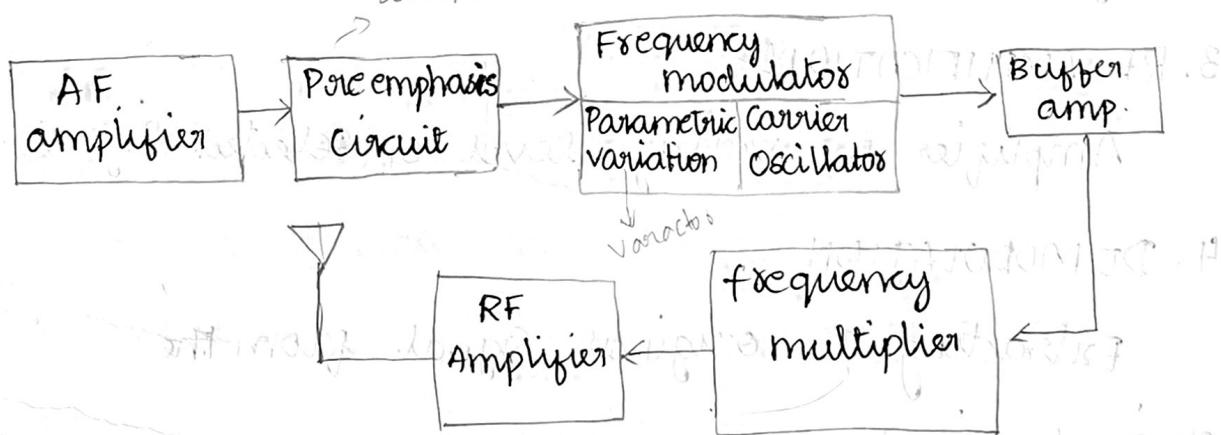
The transmitted power is fed to the antenna for radiation through a properly designed feeder (transmission line).

FM TRANSMITTERS (DIRECT METHOD)

$$\Phi_{FM}(t) = V_c \cos [w_c t + k_f V_m(t)]$$

$k_f = \frac{\Delta w}{V_m} = \frac{\Delta f}{V_m}$

artificial boosting of amp of high freq components

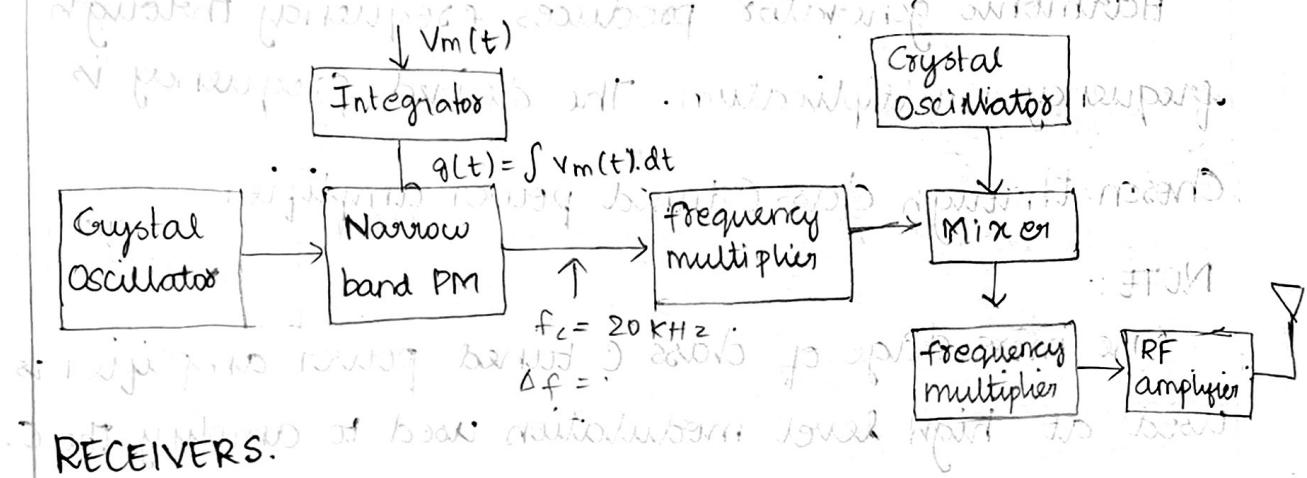


Show that a square law circuit provides harmonics of the FM signal and also the frequency deviation.

$$\begin{aligned}\Phi_{FM}^2(t) &= V_c^2 \cos^2 [w_c t + k_f V_m(t)] \\ &= \frac{V_c^2}{2} \left[1 + \cos [2w_c t + 2k_f V_m(t)] \right]\end{aligned}$$

Received Signal \rightarrow Noisy Version of The Transmitted Signal.

FM TRANSMITTER



RECEIVERS:

Functions of Receiver.

1. INTERCEPTION

Interception is the process of accepting electromagnetic signals.

1. Interception

2. Selection \rightarrow tuned circuit

3. RF amplification

4. Demodulation

(Detection) \rightarrow AF_o

5. Reproduction

2. SELECTION.

Selecting the particular desired RF carrier frequency using tuned circuit.

3. RF AMPLIFICATION

Amplifies the voltage level of selected signal.

4. DEMODULATION

Extracting the original signal from the received signal.

5. REPRODUCTION

Conversion of audio signal into message signal.

CHARACTERISTICS OF RECEIVERS.

1. Selectivity
2. Sensitivity
3. Fidelity

SELECTIVITY

Ability of the receiver to select desired frequency.

For better selectivity, proper tuned circuit with sharpened response, low Q factor, wide bandwidth.

SENSITIVITY.

Ability of the receiver to ~~sense~~ detect the smallest change in the received signal

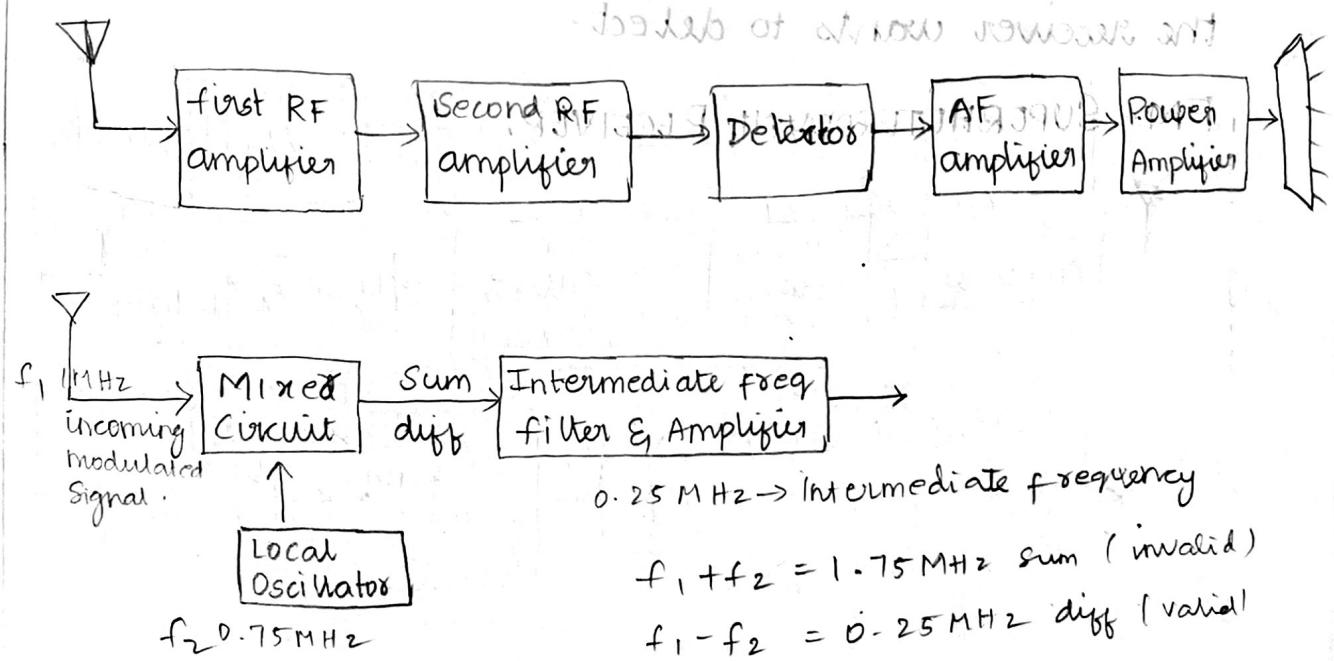
FIDELITY

Ability of the receiver to produce exact replica of message signal at the detector output.

TYPES OF RECEIVER.

Tuned Radio Frequency (TRF)

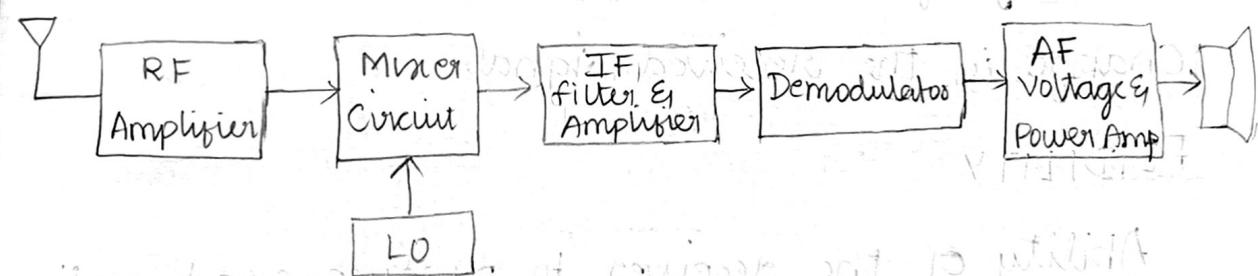
Principle used : Superheterodyne



Superheterodyne principle works based on mixer's circuit, the local oscillator in the above circuit is act as variable oscillator filter frequency filter and tuning is performed by varying the tuned circuit within the receiver.

- The intermediate frequency value for AM radio is 455 kHz.
- For FM broadcast receiver the IF is 10.7 MHz.
- For Satellite and terrestrial, microwave communication the IF is 70 MHz.

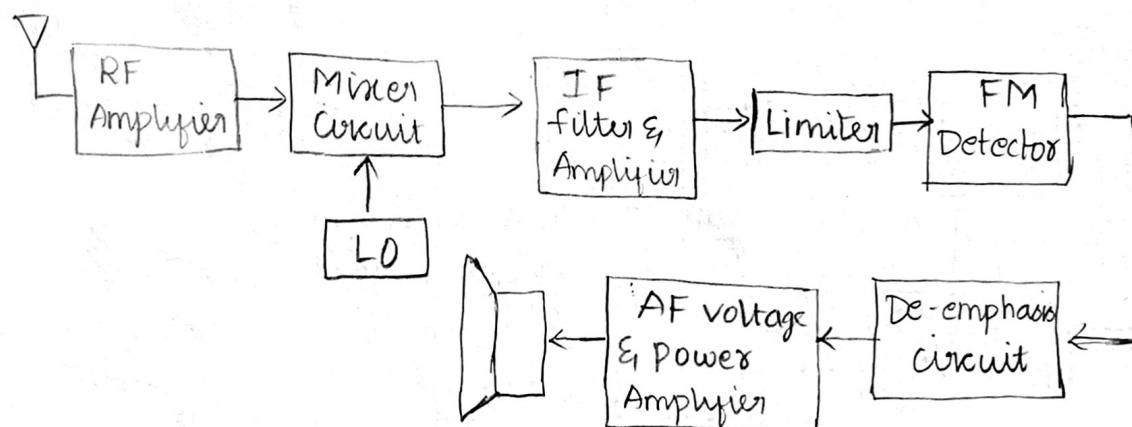
AM - SUPERHETRODYNE RECEIVER.



RF amplifier and tuning is added to select the right frequency and reject the image frequencies.

Demodulators are added according to what signal the receiver wants to detect.

FM- SUPERHETRODYNE RECEIVER.

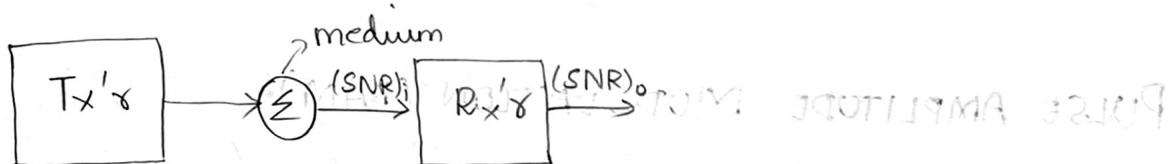


$$\gamma \rightarrow \text{figure of merit} = \frac{(SNR)_o}{(SNR)_i} \quad \text{AWGN - Additive White Gaussian Noise}$$

LIMITER

FM detector needs a constant amplitude FM signal at its input so an IF amplifier output voltage is further amplified to a pre-determined value to remove amplitude fluctuation due to noise.

NOISE

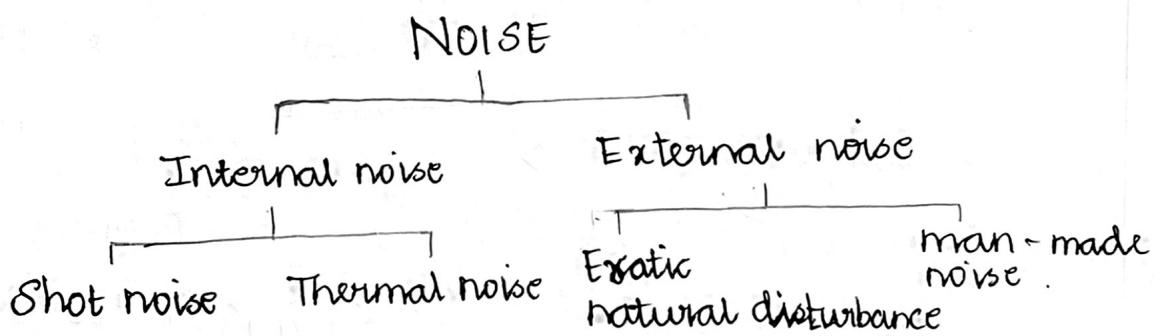


Noise will always appear in Signal's amplitude Variation

$$(SNR)_i = \frac{\text{Signal Power}}{\text{Noise Power}}$$

SNR - Signal to Noise Ratio

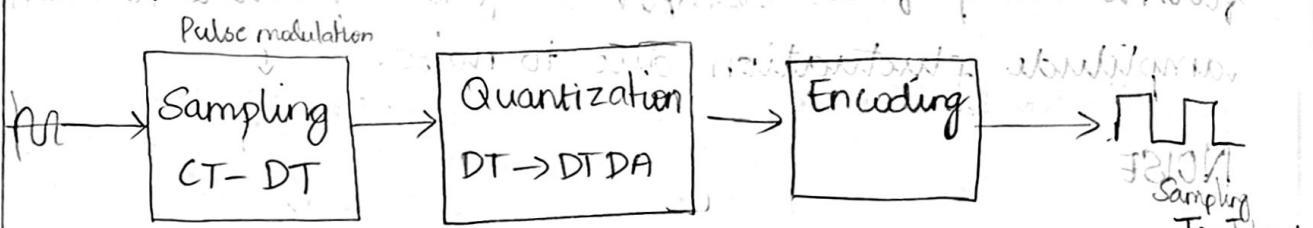
$$\gamma (\text{figure of merit}) = \frac{(SNR)_o}{(SNR)_i}$$



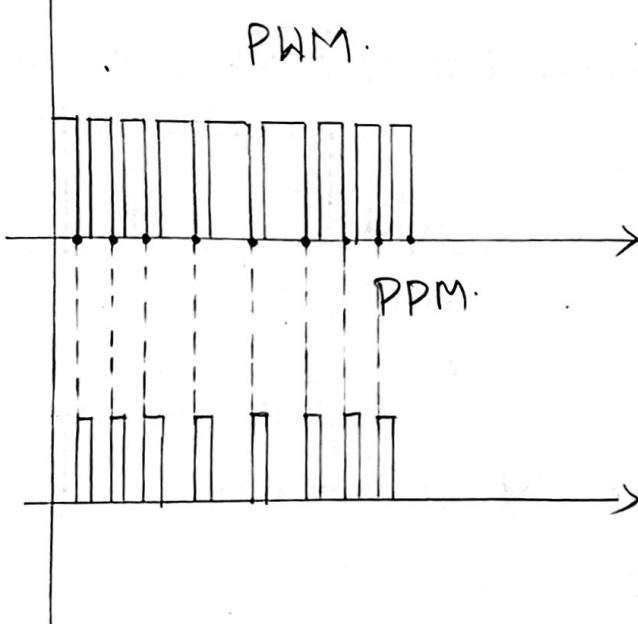
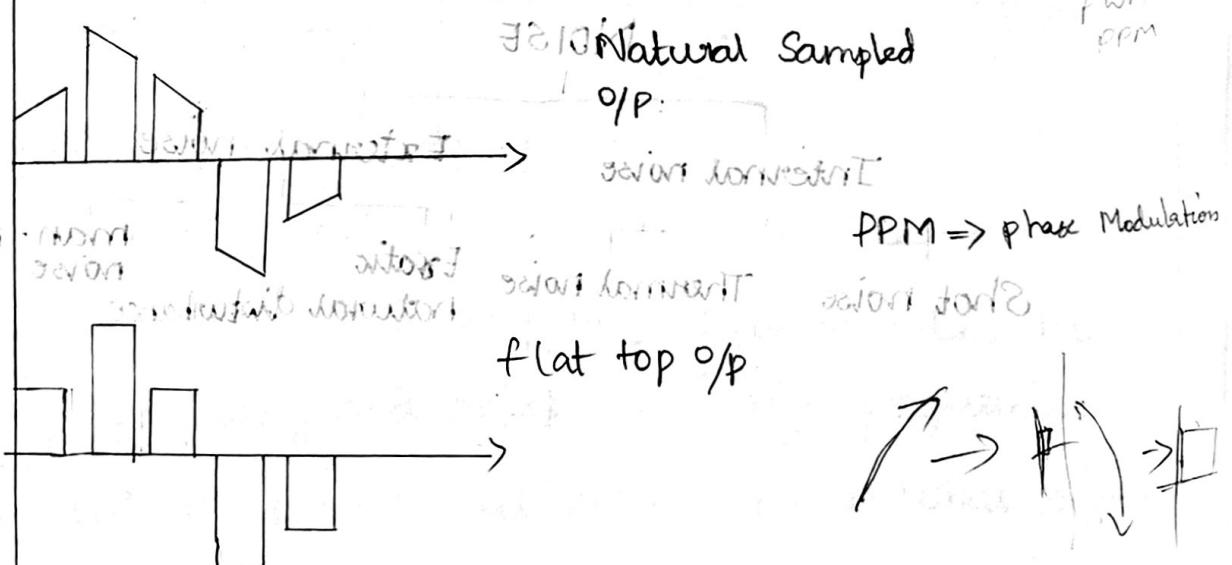
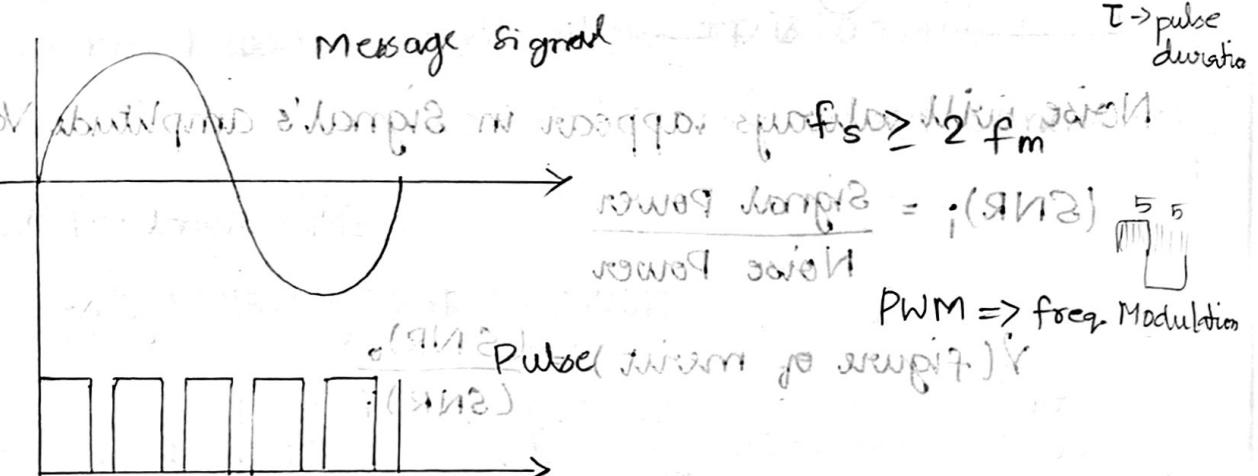
UNIT - 3 PULSE MODULATION SYSTEM M7

Sampling \rightarrow PAM, in threshold detector

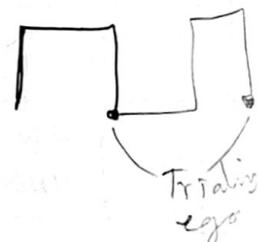
CONVERTING ANALOG TO DIGITAL



PULSE AMPLITUDE MODULATION (PAM)



for every trailing edge of PWM o/p draw a PPM pulse noted for PPM o/p



no of bits "Quantization resolution"

$N \rightarrow$ no of bits used to represent each discrete amplitude.

PULSE CODE MODULATION SYSTEMS (A/D Converter)

→ disadvantage (redundant bits)



$$f_s \geq 2f_m$$

$$L = 2^N$$

$N \rightarrow$ no of bits used to represent each discrete amplitude level.

Sampling

(Sampling) of continuous signal at regular intervals. The sampled output is a discrete time continuous amplitude signal.

$$f_s \geq 2f_m$$

Quantization

Round off the sample amplitude to the closest amplitude levels.

$$L = 2^N \quad (N \rightarrow \text{no of bits})$$

(\Rightarrow) The difference between the original amplitude and the quantized amplitude is known as quantization error.

RESOLUTION

Degree of re present in A/D converter with respect to the power consumption & no of bits used.

$$\left(\frac{A}{2} - \frac{A}{4} \right) \frac{1}{48} = \left[\frac{A}{2} + \frac{A}{4} \right] \frac{1}{48} = \Delta$$

$L \rightarrow$ no of quantization levels.

$$\frac{A}{2} = \left[\frac{A}{8} \right] \frac{1}{48} + \left[\frac{A}{8} + \frac{A}{8} \right] \frac{1}{48}$$

~~X~~ SNR for PCM system. (Signal to Noise Ratio)

$$\text{SNR} = \frac{\text{Signal Power}}{\text{Noise power}}$$

$$\text{Signal Power} = \left(\frac{V_{\max}}{\sqrt{2}} \right)^2 = \frac{V_{\max}^2}{2} \quad R=1$$

QUANTIZATION NOISE POWER (σ_N^2)

$$\text{Quantization noise power}, \sigma_N^2 = E[e^2] - (E[e])^2$$

$e \rightarrow$ quantization error.

e follows uniform distribution, $f(e) = \frac{1}{b-a}$

$$f(e) = \frac{1}{\Delta} \quad -\frac{\Delta}{2} \leq e \leq \frac{\Delta}{2} \quad \Delta \rightarrow \text{step size}$$

$$f(e) = \frac{1}{\Delta} = \frac{1}{\Delta}$$

$$E(e) = \int_{-\Delta/2}^{\Delta/2} e \cdot \frac{1}{\Delta} \cdot de \quad \text{about } E(x) = \int_a^b x f(x) \cdot dx$$

$$= \frac{1}{\Delta} \left[\frac{e^2}{2} \right]_{-\Delta/2}^{\Delta/2} = \frac{1}{2\Delta} \left[\left(\frac{\Delta}{2}\right)^2 - \left(-\frac{\Delta}{2}\right)^2 \right]$$

$$= \frac{1}{2\Delta} (0) = 0 \quad \text{mitteilung ev. rausch}$$

$$E(e^2) = \int_{-\Delta/2}^{\Delta/2} e^2 \cdot \frac{1}{\Delta} \cdot de \quad \text{mitteilung}$$

$$= \frac{1}{\Delta} \left[\frac{e^3}{3} \right]_{-\Delta/2}^{\Delta/2} = \frac{1}{3\Delta} \left[\left(\frac{\Delta}{2}\right)^3 - \left(-\frac{\Delta}{2}\right)^3 \right]$$

$$= \frac{1}{3\Delta} \left[\frac{\Delta^3}{8} + \frac{\Delta^3}{8} \right] = \frac{1}{3\Delta} \left[\frac{2\Delta^3}{8} \right] = \frac{\Delta^2}{12}$$

$$q_N = E(e^2) - [E(e)]^2$$

$$= \frac{\Delta^2}{12} - 0$$

$\therefore q_N = \frac{\Delta^2}{12}$

$$q_N = \frac{\Delta^2}{12}$$

$\therefore T$ without solving matrix

$$\Delta \rightarrow \text{step size. } L = \frac{2T}{n} = T$$

$$\Delta = \frac{2V_{\max}}{L}$$

$$\frac{2T}{n} = \frac{1}{T} \leq \frac{2V_{\max}}{L}$$

$$= \frac{2V_{\max}}{2^n}$$

$$SNR = \frac{\frac{V_{\max}^2}{2}}{\frac{\Delta^2}{12}} = \frac{V_{\max}^2}{2} \times \frac{12}{\Delta^2}$$

$$= \frac{6V_{\max}^2}{\Delta^2} = \frac{6V_{\max}^2}{\left(\frac{2V_{\max}}{2^n}\right)^2}$$

$$= \frac{6V_{\max}^2}{\frac{4V_{\max}^2}{2^{2n}}} = \frac{6V_{\max}^2 \times 2^{2n}}{4V_{\max}^2}$$

$$= \frac{6V_{\max}^2 \times 2^{2n}}{4V_{\max}^2} = \frac{3}{2} \times 2^{2n}$$

$$SNR = \frac{3}{2} \times 2^{2n}$$

$N \rightarrow$ no of bits

$$SNR \text{ in dB} = 10 \log SNR$$

$$= 10 \log \left[\frac{3}{2} \times 2^{2n} \right]$$

$$= 10 \left[\log \left(\frac{3}{2} \right) + \log (2^{2n}) \right]$$

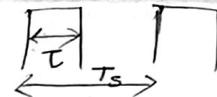
$$= 10 \left[\log (1.5) + 2n \log (2) \right]$$

$$= 10 [0.176 + 2n \times 0.3010]$$

$$SNR \text{ for PCM} = 1.76 + 6N$$

The abv can is the SNR of PCM for sinusoidal i/p

PCM requires more bandwidth



BANDWIDTH OF PCM SYSTEM.

For a N bit binary PCM, if f_s is the Sampling frequency and n time slots are there in one T_s sampling time then pulse width T is

$$T = \frac{T_s}{n} = \frac{1}{n f_s}$$

The channel bandwidth $B_T \geq \frac{1}{2T} = \frac{n f_s}{2}$

Data Rate (R_b) (bits/seconds)

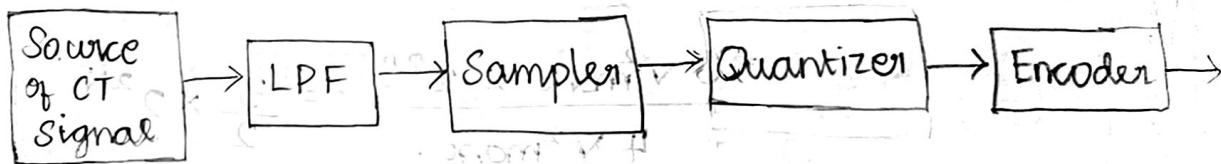
No of bits transmitted per second (BPS)

$$R_b = n f_s$$

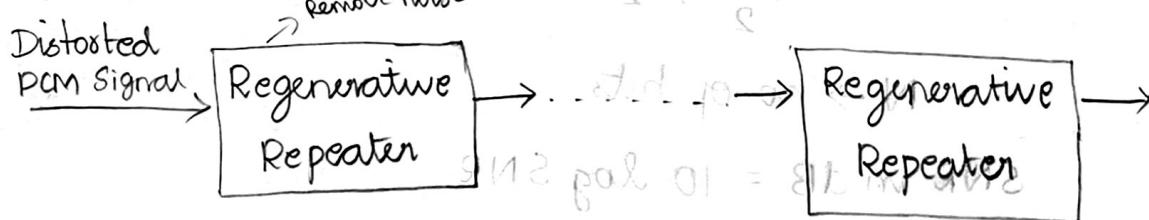
$$B_T \geq \frac{R_b}{2}$$

BLOCK DIAGRAM FOR PCM SYSTEMS.

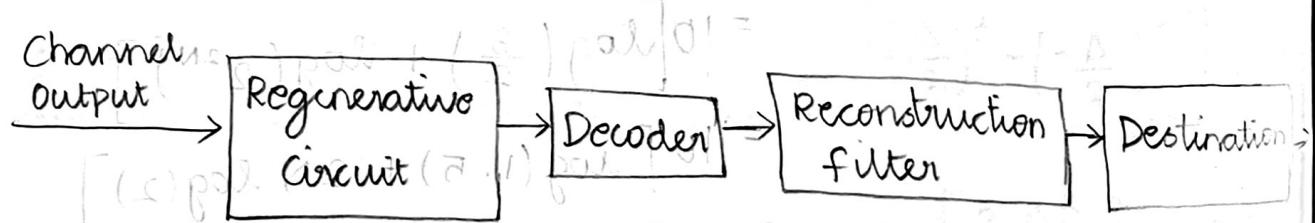
a) TRANSMITTER.



b) TRANSMISSION PATH



c) RECEIVER



at library is not for RNT with m-ary vdp so

Explain the block diagrams of PCM System and Noise in PCM System.

TRANSMITTER.

SOURCE OF CT SIGNAL.

Source of CT signal is a function generator which generates a sinusoidal waveform of desired frequency and amplitude (message signal).

LOW PASS FILTER (LPF)

The message signal which is in the continuous time form, is allowed to pass through a LPF. This LPF has a cut off frequency f_m eliminates the high-frequency components of the message signal and passes only the frequency components that lie below f_m .

SAMPLER (Op of Sampler is PAM)

The output of the LPF is then fed to a sampler which samples the analog signal at regular intervals. The sampling of the signal is done at the sampling frequency f_s . f_s is selected using sampling theorem $f_s \geq 2f_m$. The output of sampler is a discrete time continuous amplitude signal.

QUANTIZER.

The Sampler produces a discrete time continuous amp. signal. The amplitude is still analog. A quantizer rounds off each amplitude to the nearest quantization level. Approximation of amplitude levels introduces some distortion or noise into the signal, this error is known as quantization error.

ENCODER. (min the bandwidth used) hold off align 7

Encoder converts the quantized signal into binary codes. This generates a digitally encoded signal which is a sequence of binary pulses.

No of quantization level, $\Delta = 2^N$

bit pattern $N \rightarrow$ no of bits

TRANSMISSION PATH

REGENERATIVE REPEATER.

A regenerative repeater boosts the signal strength along the transmission path. The medium or channel, through which the signal travels is called transmission path. The medium introduces distortion in the signal during transmission. This distortion is eliminated by the regeneration repeater.

Regenerative repeater detects and regenerates the original signal strength which is free from noise.

RECEIVER.

REGENERATIVE CIRCUIT.

Regenerative circuit at the receiver end is used to compensate the signal loss and reconstruct the signal and also increase its strength.

DECODER.

The decoder circuit decodes the pulse coded waveform to reproduce the original signal. This acts as a demodulator for the encoded output.

RECONSTRUCTION FILTER

After the decoded signal (analog signal) is fed to the reconstruction filter or LPF which retains the original (message) signal by eliminating the higher frequency components.

NOISES IN PCM System

There are two types of noises produced in PCM system.

→ Quantization Noise.

→ Channel Noise.

QUANTIZATION NOISE

Quantization noise is produced in quantizer due to the rounding off of the amplitude. The difference between the original amplitude and the quantized amplitude is known as quantization noise or error.

This can be eliminated by increasing the quantization level (L).

CHANNEL NOISE

The channel introduces distortion in the signal during transmission. This distortion can be eliminated by the regenerative repeater in order to provide a distortionless output (replica of message signal).

$$Q = M + P = M + \frac{1}{2} \sin \omega t$$

$$(M + P) - M + P = P = \frac{1}{2} \sin \omega t$$

$$P = M + P = M + \frac{1}{2} \sin \omega t$$

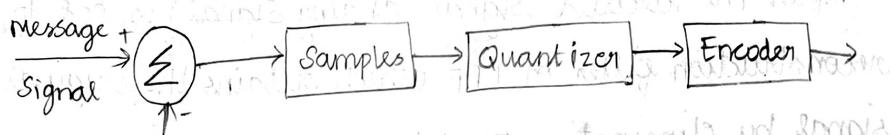
With help of first transmission and 2nd transmission
we can remove noise effects (at point 2) at point 1

With help of 2nd transmission and 3rd transmission
we can remove noise effects (at point 3) at point 2

differential
Quantizer

DIFFERENTIAL PULSE CODE MODULATION (DPCM)

more no of samples in DPCM



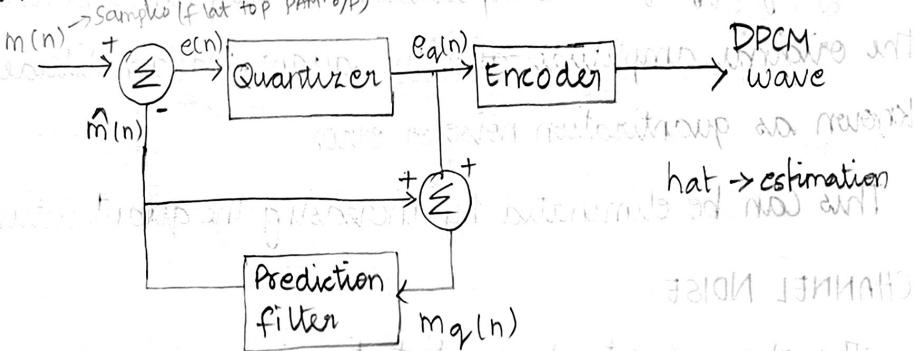
Condition to perform DPCM $\Rightarrow f_s \gg 2f_m$.

DPCM is suitable for voice and video signals.

There is a high correlation between the first and second sample (adjacent) i.e. the signal does not undergo rapid change from one sample to the next. In such cases the difference between the two samples is quantized and encoded.

adjacent signal is quantized and encoded. Prediction filter \rightarrow predicts the next sample value.

DPCM (Transmitter)



$$e(n) = m(n) - \hat{m}(n) \quad \text{--- (1)}$$

$$\hat{m}(n) = m(n) - e(n) \quad \text{--- (1a)}$$

$$e_q(n) = e(n) + q(n) \quad \text{--- (2)}$$

$$M_q(n) = e_q(n) + \hat{m}(n) \quad \text{--- (3)}$$

$$M_q(n) = e(n) + q(n) + m(n) - e(n)$$

$$M_q(n) = q(n) + m(n) \quad \text{--- (4)}$$

from (4) we understand that the quantized sample $M_q(n)$ differs from the quantization

~~error $q(n)$. If the prediction filter works good then
the error $e(n)$ will be negligible.~~

✓
10/29/19/2022