

## UNIT - IV Random Process

### Probabilistic Signals.

Random Variables

Sample Space

$$SS \rightarrow R$$

time

$$(X, t) \rightarrow \text{Random Process}$$

### RANDOM VARIABLE

Rule that assigns a real number to every outcome of a random experiment.

### RANDOM PROCESS

A rule that assigns a time function to every outcome of a random experiment.

Putting it collectively, a random process is a collection of random variable that are functions of real variables in time  $t$  and Sample Space  $S$ .  $\{X(s, t)\}, t \in T$ .

NOTE :-

1. If  $s$  and  $t$  are fixed then  $\{X(s, t)\}$  is a number
2. If  $t$  is fixed then the process  $\{X(s, t)\}$  is Random Variable
3. If  $s$  is fixed then the process  $\{X(s, t)\}$  is a single time function
4. CX

### CLASSIFICATION OF Random Process.

Let  $t \in T, s \in S$ .

1. If both  $T$  &  $S$  are discrete then RP is called discrete Random Sequence.  
ex, outcome of the  $n^{\text{th}}$  toss of a fair dice

2. T is discrete but  $x$  is continuous, then RP is called Continuous Random Sequence.

ex, temp at the end of  $n^{\text{th}}$  hour of a day.

3. T is continuous and  $x$  is discrete, then RP is called discrete Random Process.

ex, The no. of telephone calls received in a day.

4. Both T & S is continuous, then RP is called Continuous Random process.

ex, Max temp in a place in the interval  $(0, T)$

## Stationarity PROCESS

Probability distribution or Average do not depend on T then the RP is called

Stationary Process.

A RP that is not stationary is called evolutionary process.

## 1<sup>st</sup> ORDER STATIONARY FUNC:

If  $f(x_i, t_i) = f(x_i, t_i + h)$ , where  $h$  is a positive number  $h > 0$  for all  $t \in T$ .

then the process is called 1<sup>st</sup> order stationary func

this implies the process does not change with respect to shift in time origin hence if this condition holds. The process becomes independent of time  $E[x(t)]^2 = \mu = \text{constant}$

## 2<sup>nd</sup> ORDER STATIONARY PROCESS.

$$f(x_1, x_2, t_1, t_2) = f(x_1, x_2, t_1 + h, t_2 + h)$$

this implies the process is invariant under  
translation of time.  $T = t_1 - t_2$

## N<sup>th</sup> ORDER STATIONARY PROCESS (Strong sense stationary)

$$f(x_1, x_2, \dots, x_n, t_1, t_2, \dots, t_n) = f(x_1, x_2, \dots, x_n, t_1 + h, t_2 + h, \dots, t_n + h).$$

## AUTOCORRELATION.

$$R_{xx}(t) \text{ or } R_x(t_1, t_2) = E[x(t_1)x(t_2)]$$

$x(t_1), x(t_2)$  are two members of  $\{x(t)\}$

## WIDE-SENSE OR WEAK SENSE STATIONARY PROCESS.

A random process with finite 1<sup>st</sup> & 2<sup>nd</sup> order moments is called WSS process if

1.  $E[x(t)]$  is a constant

2. Auto correlation is a func of  $T \Rightarrow E[x(t_1)x(t_2)] = f(T)$

## STATIONARY PROCESS.

1. Mean - Const

2. Variance - Const

## Joint WSS

1.  $E[x(t)]$  must be WSS.

2.  $E[y(t)]$  must be WSS.

3. Cross Correlation  $R_{xy}(t_1, t_2) = E[x(t_1)y(t_2)] = f(T)$

1. If  $\{X(t)\}$  is a WSS process with autocorrelation function  $R_x(z) = Ae^{-\alpha|z|}$ , determine the 2nd order moment of the RV  $X(8) - X(5)$ .

$E[X]$  = first order moment

$E[X^2]$  = second order moment

$$\begin{aligned}
 E[(X(8) - X(5))^2] &= E[X^2(8) + X^2(5) - 2X(8)X(5)] \\
 &= E[X^2(8)] + E[X^2(5)] - 2E[X(8)X(5)] \\
 &= R_x(8, 8) + R_x(5, 5) - 2R_x(8, 5) \\
 &= Ae^{-\alpha|8-8|} + Ae^{-\alpha|5-5|} + (-2Ae^{-\alpha|8-5|}) \\
 &= Ae^{-\alpha(0)} + Ae^{-\alpha(0)} + (-2Ae^{-\alpha 3}) \\
 &= 2A - 2Ae^{-\alpha 3} \\
 &= 2A(1 - e^{-\alpha 3})
 \end{aligned}$$

2. Show that the process  $x(t) = A \cos \lambda t + B \sin \lambda t$  where  $A \in B$  are RV is a WSS if

$$\text{i)} E(A) = E(B) = 0$$

$$\text{ii)} E[A^2] = E[B^2]$$

$$\text{iii)} E(AB) = 0$$

WSS.

1. Mean  $E[x(t)]$  is const

$$2. R_{xx}(t_1, t_2) = E[x(t_1) \cdot x(t_2)] = f(\tau)$$

$$x(t) = A \cos \lambda t + B \sin \lambda t$$

$$E[x(t)] = E[A \cos \lambda t + B \sin \lambda t]$$

$$= E[A \cos \lambda t] + E[B \sin \lambda t]$$

$$= \cos \lambda t E(A) + \sin \lambda t E(B)$$

$$= \cos \lambda t(0) + \sin \lambda t(0)$$

$$E[x(t)] = 0. \text{ is a constant}$$

Hence i) is proved.

$$x(t_1) = A \cos \lambda t_1 + B \sin \lambda t_1$$

$$x(t_2) = A \cos \lambda t_2 + B \sin \lambda t_2$$

$$R_{xx}(t_1, t_2) = E[x(t_1) x(t_2)]$$

$$= E[(A \cos \lambda t_1 + B \sin \lambda t_1) (A \cos \lambda t_2 + B \sin \lambda t_2)]$$

$$= E[A^2 \cos \lambda t_1 \cos \lambda t_2 + AB \cos \lambda t_1 \sin \lambda t_2 + AB \cos \lambda t_2 \sin \lambda t_2 + B^2 \sin \lambda t_2]$$

$$= E[A^2 \cos \lambda t_1 \cos \lambda t_2] + E[AB \cos \lambda t_1 \sin \lambda t_2] +$$

$$E[AB \cos \lambda t_2 \sin \lambda t_2] + E[B^2 \sin \lambda t_2]$$

$$= \cos \lambda t_1 \cos \lambda t_2 E[A^2] + E[B^2] \sin \lambda t_1 \sin \lambda t_2 \\ + E[AB] \cos \lambda t_1 \sin \lambda t_2 + E[AB] \cos \lambda t_2 \sin \lambda t_1$$

ii)  $E(A^2) = E(B^2) = k$ . iii)  $E(AB) = 0$ .

$$= k [\cos \lambda t_1 \cos \lambda t_2 + \sin \lambda t_1 \sin \lambda t_2] + 0$$

$$= k [\cos(\lambda t_1 - \lambda t_2)] \cdot \frac{\cos A \cos B + \sin A \sin B}{\cos(A-B)}$$

$$= k [\cos \lambda(t_1 - t_2)]$$

$R_{xx}(t_1, t_2) = k [\cos \lambda T]$  is a func of T.

3. If  $x(t) = B \cos \omega t + A \sin \omega t$  Show that  $x(t)$  is WSS if A & B are uncorrelated with 0 mean and same variance &  $\omega$  is a const.

To prove  $x(t)$  is a WSS

i) Mean is a Const

ii) Autocorrelation is a func of T.

Uncorrelated  $\Rightarrow E(AB) = 0$ .

Zero mean  $\Rightarrow E(A) = E(B) = 0$

Same Variance  $\Rightarrow \text{Var}(A) = \text{Var}(B)$

$$E[A^2] - [E(A)]^2 = E[B^2] - [E(B)]^2$$

$$E(A^2) = E(B^2)$$

$$E[x(t)] = E[B \cos \omega t] + E[A \sin \omega t]$$

$$= \cos \omega t E[B] + E[A] \sin \omega t$$

$$= \cos \omega t (0) + \sin \omega t (0)$$

$$E[x(t)] = 0$$

$$R_{xx}(t_1, t_2) = E[x(t_1) \cdot x(t_2)]$$

$$x(t_1) = B \cos \omega t_1 + A \sin \omega t_1$$

$$x(t_2) = B \cos \omega t_2 + A \sin \omega t_2$$

$$R_{xx}(t_1, t_2) = E[(B \cos \omega t_1 + A \sin \omega t_1) \cdot (B \cos \omega t_2 + A \sin \omega t_2)]$$

$$= E[B^2 \cos \omega t_1 \cos \omega t_2 + AB \sin \omega t_1 \cos \omega t_2 + AB \sin \omega t_2 \cos \omega t_1 + A^2 \sin \omega t_1 \sin \omega t_2]$$

$$= E[B^2 \cos \omega t_1 \cos \omega t_2] + E[AB \sin \omega t_1 \cos \omega t_2]$$

$$+ E[AB \sin \omega t_2 \cos \omega t_1] + E[A^2 \sin \omega t_1 \sin \omega t_2]$$

$$= \cos \omega t_1 \cos \omega t_2 E(B^2) + E(AB) \sin \omega t_1 \cos \omega t_2$$

$$+ E(AB) \sin \omega t_2 \cos \omega t_1 + E(A^2) \sin \omega t_1 \sin \omega t_2$$

$$= K [\cos \omega t_1 \cos \omega t_2 + \sin \omega t_1 \sin \omega t_2]$$

$$= K [\cos(\omega t_1 - \omega t_2)]$$

$$= K [\cos \omega(t_1 - t_2)]$$

$$\therefore K = E(A^2) = E(B^2)$$

$$R_{xx}(t_1, t_2) = K (\cos \omega \tau)$$

$\therefore$  Auto correlation is a fun of  $\tau$ .

Given a RV  $Y$  with characteristic func.  
 and a random process RP  $\{x(t)\}$ ,  $x(t) = \cos(\lambda t + Y)$   
 $\Phi(w) = E[e^{iwY}] = E[\cos wY + i \sin wY]$ . Show that  
 $x(t)$  is a WSS if  $\Phi(1) = \Phi(2) = 0$ .

$$\Phi(1) = E[\cos Y + i \sin Y] = 0.$$

$$\Rightarrow E[\cos Y] + i E[\sin Y] = 0 + i 0$$

$$E[\cos Y] = 0 \quad E[\sin Y] = 0. \quad \text{--- (1)}$$

$$\Phi(2) = E[\cos 2Y + i \sin 2Y] = 0.$$

$$E[\cos 2Y] = 0 \quad E[\sin 2Y] = 0. \quad \text{--- (2)}$$

To prove  $x(t)$  is WSS,

1. Mean  $\rightarrow$  Constant.

$$\begin{aligned} E[x(t)] &= E[\cos(\lambda t + Y)] \\ &= E[\cos \lambda t \cos Y - \sin \lambda t \sin Y] \\ &= \cos \lambda t E[\cos Y] - \sin \lambda t E[\sin Y]. \end{aligned}$$

By Condition (1).

$$E[x(t)] \neq 0$$

$$2. \quad x(t_1) = \cos(\lambda t_1 + Y)$$

$$R_{xx}(t_1, t_2) = E[x(t_1)x(t_2)]$$

$$x(t_2) = \cos(\lambda t_2 + Y).$$

$$\cos A \cos B = \frac{1}{2} [\cos(A+B) + \cos(A-B)]$$

$$R_{xx}(t_1, t_2) = E[\cos(\lambda t_1 + Y) \cdot \cos(\lambda t_2 + Y)]$$

$$= E\left[\frac{1}{2} [\cos(\lambda t_1 + Y + \lambda t_2 + Y) + \cos(\lambda t_1 + Y - \lambda t_2 - Y)]\right]$$

$$= \frac{1}{2} E[\cos(\lambda t_1 + \lambda t_2 + 2Y)] + \frac{1}{2} E[\cos(\lambda t_1 - \lambda t_2)]$$

$$= \frac{1}{2} E[\cos(\lambda t_1 + \lambda t_2 + 2Y)] + \frac{1}{2} E[\cos(\lambda t_1 - \lambda t_2)]$$

$$\begin{aligned}
&= \frac{1}{2} E[\cos(\lambda t_1 + \lambda t_2) \cos(2Y) - \sin(\lambda(t_1 + t_2)) \sin(2Y)] \\
&\quad + \frac{1}{2} E[\cos \lambda(t_1 - t_2)] \\
&= \frac{1}{2} \cos \lambda(t_1 + t_2) E[\cos 2Y] - \frac{1}{2} \sin \lambda(t_1 + t_2) E[\sin 2Y] \\
&\quad + \frac{1}{2} E[\cos \lambda(t_1 - t_2)] \\
&= \frac{1}{2} [\cos \lambda(t_1 - t_2)] \quad t_1 - t_2 = T \\
&= \frac{1}{2} (\cos \lambda T) = \text{function of } T.
\end{aligned}$$

$$(1-x)^{-1} = 1 + x + x^2 + x^3 + x^4 + \dots$$

$$(1-x)^{-2} = 1 + 2x + 3x^2 + 4x^3 + \dots$$

$$(1-x)^{-3} = 1 + 3x + 6x^2 + 10x^3 + 15x^4 + \dots$$

$$= \frac{1}{2} [1 \times 2 + 2 \times 3x + 3 \times 4x^2 + 4 \times 5x^3 + \dots]$$

2. The process  $\{X(t)\}$  whose prob. distribution under a certain condition is given by  $P[X(t)=n]^3 = \frac{(at)^{n-1}}{(1+at)^{n+1}}, n=1,2,3$   
 $= \frac{at}{1+at}, n=0$ . Verify if the process  $\{X'(t)\}$  is stationary.

n	0	1	2	3	4	5
$P[X(t)=n]^3$	$\frac{at}{1+at}$	$\frac{1}{(1+at)^2}$	$\frac{at}{(1+at)^3} + \frac{(at)^2}{(1+at)^4}$	$\frac{(at)^3}{(1+at)^5}$		

1. Mean

$$E[X(t)] = \sum np(n)$$

$$\begin{aligned}
&= 0 \cdot \frac{at}{1+at} + 1 \cdot \frac{1}{(1+at)^2} + 2 \cdot \frac{at}{(1+at)^3} + 3 \cdot \frac{(at)^2}{(1+at)^4} \\
&\quad + 4 \cdot \frac{(at)^3}{(1+at)^5} + \dots
\end{aligned}$$

$$\begin{aligned}
&= \frac{1}{(1+at)^2} + \frac{2at}{(1+at)^3} + \frac{3(at)^2}{(1+at)^4} + \frac{4(at)^3}{(1+at)^5} + \dots \\
&= \frac{1}{(1+at)^2} \left[ 1 + \frac{2at}{(1+at)} + \frac{3(at)^2}{(1+at)^2} + 4 \left( \frac{at}{1+at} \right)^3 + \dots \right] \\
&= \frac{1}{(1+at)^2} \left[ 1 - \frac{at}{1+at} \right]^{-2} \\
&= \frac{1}{(1+at)^2} \left[ \frac{1+at-at}{1+at} \right]^{-2} \\
&= \frac{(1+at)^2}{(1+at)^2} = 1.
\end{aligned}$$

2. Variance = const

$$\begin{aligned}
\text{Var}(x) &= E[x^2] - E[x]^2. \quad \begin{aligned} n^2 &= n(n+1-1) \\ &= n(n+1)-n \\ &= 1 \end{aligned} \\
E[x^2(t)] &= \sum n^2 \cdot P(n) \\
&= \sum n(n+1) P(n) - \sum n P(n) \\
&= \left[ 0(1) \cdot \frac{a(t)}{1+at} + (1)(2) \cdot \frac{1}{(1+at)^2} + 2(3) \cdot \frac{at}{(1+at)^3} \right. \\
&\quad \left. + 3(4) \cdot \frac{(at)^2}{(1+at)^4} + \dots \right] - 1 \\
&= \left[ 1 \cdot 2 \frac{1}{(1+at)^2} + 2 \cdot 3 \frac{at}{(1+at)^3} + 3 \cdot 4 \frac{(at)^2}{(1+at)^4} + \dots \right] - 1 \\
&= \frac{2}{(1+at)^2} \left[ 1 + 3 \frac{at}{(1+at)} + 6 \left( \frac{at}{1+at} \right)^2 + \dots \right] - 1 \\
&= \frac{2}{(1+at)^2} \left[ 1 - \frac{at}{1+at} \right]^{-3} - 1 \\
&= \frac{2}{(1+at)^2} \left[ \frac{1+at-at}{1+at} \right]^{-3} - 1 = \frac{2}{(1+at)^{-1}} \\
&= 2(1+at)^{-1} = 2 + 2at - 1 \\
E[x^2(t)] &= 2at + 1
\end{aligned}$$

$$\text{Var}[x(t)] = E[x^2(t)] - E[x(t)]^2 = 2at + 1$$

$$\text{Var}[x(t)] = 2at$$

$\therefore \text{Var}[x(t)]$  is not const.

$\therefore P(x(t))$  is not stationary.

Property of Expectation

$$E[g(x)] = \int_{-\infty}^{\infty} g(x) \cdot f_n(x) dx$$

where  $f_n(x)$  is the marginal density function.

Uniform distribution

$$f(x) = \frac{1}{b-a} ; a < x < b.$$

1. Show that the Random process:  $\{x(t)\} = A \cos(\omega t + \theta)$  WSS  $A, \omega$  are Constant  $\theta$  is uniformly distributed RV in the interval  $(0, 2\pi)$

$$f(\theta) = \frac{1}{2\pi}$$

$$①. E[x(t)] = E[A \cos(\omega t + \theta)].$$

$$= \int_{-\infty}^{\infty} A \cos(\omega t + \theta) \cdot \frac{1}{2\pi} d\theta.$$

$$= \int_0^{2\pi} A \cos(\omega t + \theta) \cdot \frac{1}{2\pi} d\theta.$$

$$= \frac{A}{2\pi} \int_0^{2\pi} \cos(\omega t + \theta) d\theta.$$

$$= \frac{A}{2\pi} \left[ \sin(\omega t + \theta) \right]_0^{2\pi}$$

$$\sin(2\pi + \theta) = \sin \theta$$

$$= \frac{A}{2\pi} \left[ \sin(wt + 2\pi) - \sin(wt + 0) \right]$$

$$= \frac{A}{2\pi} [\sin wt - \sin wt]$$

$$= 0.$$

Mean = 0.

$$2. R_{xx}(t_1, t_2) = E[x(t_1) \cdot x(t_2)].$$

$$= E[A \cos(wt_1 + \theta) \cdot A \cos(wt_2 + \theta)]$$

$$= \frac{A^2}{2} E[\cos(wt_1 + \theta + wt_2 + \theta) + \cos(wt_1 + \theta - wt_2 - \theta)]$$

$$= \frac{A^2}{2} E[\cos(wt_1 + wt_2 + 2\theta)]$$

$$= \frac{A^2}{2} \int_0^{2\pi} \cos(wt_1 + wt_2 + 2\theta) \frac{d\theta}{2\pi} + \frac{A^2}{2} E[\cos(wt_1 - wt_2)]$$

$$= \frac{A^2}{4\pi} \left[ \int_0^{2\pi} \sin(wt_1 + wt_2 + 2\theta) d\theta \right] + \frac{A^2}{2} \cos(wt_1 - wt_2)$$

$$= \frac{A^2}{8\pi} [ \sin(wt_1 + wt_2) - \sin(wt_1 + wt_2) ] + \frac{A^2}{2} \cos(wt)$$

$$= 0 + \frac{A^2}{2} \cos(wt)$$

$$= \frac{A^2}{2} \cos(wt)$$

$x(t) = 20 \sin(\omega t + \theta)$ . As  $\omega$  are constant,  $\theta$  uniform RV in  $[0, 2\pi]$  is a WSS.

$$f(\theta) = \frac{1}{2\pi}$$

$$\begin{aligned} 1. E[x(t)] &= E[20 \sin(\omega t + \theta)] \\ &= 20 \int_0^{2\pi} \sin(\omega t + \theta) \cdot \frac{1}{2\pi} d\theta \\ &= \frac{20}{2\pi} \left[ -\cos(\omega t + \theta) \right]_0^{2\pi} \\ &= \frac{-10}{\pi} [\cos(\omega t + 2\pi) - \cos(\omega t)] \\ &= -\frac{10}{\pi} [\cos \omega t - \cos \omega t] \\ E[x(t)] &= 0 \quad w = \omega. \end{aligned}$$

$$\text{Mean} \rightarrow 0: \quad \sin A \sin B = \frac{1}{2} [\cos(A-B) - \cos(A+B)]$$

$$\begin{aligned} 2. R_{xx}(t_1, t_2) &= E[x(t_1) \cdot x(t_2)] \\ &= E[20 \sin(\omega t_1 + \theta) \cdot 20 \sin(\omega t_2 + \theta)] \\ &= \frac{400}{2} E[\cos(\omega t_1 + \theta - \omega t_2 - \theta) - \cos(\omega t_1 + \theta + \omega t_2 + \theta)] \\ &= 200 E[\cos(\omega t_1 - \omega t_2) - \cos(\omega t_1 + \omega t_2 + 2\theta)] \\ &= 200 E[\cos(\omega t_1 - \omega t_2)] - \frac{1}{2\pi} \int_0^{2\pi} \cos(\omega(t_1 + t_2) + 2\theta) d\theta \\ &= 200 [\cos(\omega \tau)] - \frac{1}{2\pi} \left[ \frac{\sin \theta}{2} (\omega(t_1 + t_2) + 2\theta) \right]_0^{2\pi} \\ &= 200 [\cos(\omega \tau)] - 0. \end{aligned}$$

## AUTO CORRELATION FUNCTIONS:

Definition

$\{x(t)\}$  either WSS.

$$R_{xx}(\tau) = E[x(t) \cdot x(t+\tau)] \quad \begin{matrix} \tau = t_2 - t \\ = t + \tau - t \end{matrix}$$

1. Autocorrelation is an even function  $\tau$ .

$$R_{xx}(\tau) = R_{xx}(-\tau)$$

$$R_{xx}(\tau) = E[x(t) \cdot x(t+\tau)]$$

$$R_{xx}(\tau) = E[x(t) \cdot x(t+\tau)]$$

$$= E[x(t_1+\tau) \cdot x(t_1)] = R_{xx}(\tau).$$

2. The mean square value of the RP obtained by  $\tau=0$ .

$$R_{xx}(0) = E[x(t) \cdot x(t+\tau)]$$

$$R_{xx}(0) = E[x(t) \cdot x(t)]$$

$$= E[x^2(t)]$$

$E[x^2(t)] \rightarrow$  mean square.

3. If a RP  $\{x(t)\}$  has no periodic components and  $E\{x(t)\}$  is denoted by  $\bar{x}$  then

$$(\bar{x})^2 = \lim_{|\tau| \rightarrow \infty} R_{xx}(\tau)$$

$$\bar{x} = \mu_x = \sqrt{\lim_{\tau \rightarrow \infty} R_{xx}(\tau)}$$

4.  $\{x(t)\}$  is Periodic then its autocorrelation function is also periodic with same period.

Let  $\{x(t)\}$  be periodic with period  $\tau$ .

$$x(t) = x(t + \tau)$$

$$= x(\tau + n\tau) \quad n = 1, 2, 3, 4, \dots$$

$$R_{xx}(\tau) = E[x(t) \cdot x(t + \tau)]$$

$$= E[x(t) \cdot x(t + n\tau)]$$

$$= R_{xx}(t - n\tau - t)$$

$$= R_{xx}(-n\tau)$$

$$= R_{xx}(n\tau).$$

5. Max Value of  $R_{xx}(\tau)$  is attained at  $\tau = 0$ .

$$|R_{xx}(\tau)| \leq R_{xx}(0)$$

$$\rightarrow E[x^2(t)].$$

Proof, By Cauchy Schwartz inequality,

$$E[xy]^2 \leq E[x^2] \cdot E[y^2].$$

$$Y = x(t + \tau) \quad X = x(t).$$

$$E[x(t) \cdot x(t + \tau)]^2 \leq E[x^2(t)] E[x^2(t + \tau)].$$

$$R_{xx}(\tau)^2 \leq E[x^2(t)] E[x^2(t + \tau)].$$

Since we know that mean & Variance are constant for a stationary process.

$$R_{xx}(\tau)^2 \leq E[x^2(t)] E[x^2(t)].$$

$$R_{xx}(\tau)^2 \leq E[x^2(t)]^2.$$

$$R_{xx}(\tau) \leq E[x^2(t)] = R_{xx}(0).$$

6 Auto correlation of R function cannot have an arbitrary shape.

1. Check whether the following are valid autocorrelated function.

$$1. R_{xx}(\tau) = \frac{25\tau^2}{4+5\tau^2}$$

$$2. R_{xx}(\tau) = \cos(\tau) + \frac{1}{\tau}$$

$$3. R_{xx}(\tau) = \tau^3 + \tau^2$$

$$1. R_{xx}(\tau) = \frac{25\tau^2}{4+5\tau^2}$$

$$R_{xx}(-\tau) = \frac{25(-\tau)^2}{4+5(-\tau)^2} = \frac{25\tau^2}{4+5\tau^2} = R_{xx}(\tau)$$

∴ It is a valid autocorrelation func.

$$2. R_{xx}(\tau) = \cos(\tau) + \frac{1}{\tau}$$

$$R_{xx}(-\tau) = \cos(-\tau) + \frac{1}{(-\tau)}$$

$$= \cos\tau + \frac{1}{\tau} = R_{xx}(\tau)$$

∴ It is valid.

$$3. R_{xx}(\tau) = \tau^3 + \tau^2$$

$$R_{xx}(-\tau) = -\tau^3 + \tau^2$$

$$= -\tau^3 + \tau^2 \neq R_{xx}(\tau)$$

2. A stationary process has an R<sub>xx</sub>(τ) =  $\frac{25\tau^2 + 36}{6.25\tau^2 + 4}$   
 find the mean & variance of the process.

$$\text{mean, } \mu_x = \sqrt{\lim_{|\tau| \rightarrow \infty} R_{xx}(\tau)}$$

$$\begin{aligned}\mu_x^2 &= \lim_{|\tau| \rightarrow \infty} \tau^2 \left[ \frac{25 + \frac{36}{\tau^2}}{6.25 + \frac{4}{\tau^2}} \right] \\ &= \lim_{|\tau| \rightarrow \infty} \frac{\tau^2 \left[ 25 + \frac{36}{\tau^2} \right]}{6.25 + \frac{4}{\tau^2}} \\ &= \frac{25}{6.25} = 4.\end{aligned}$$

$$E[x^2(\tau)] = .$$

$$\mu_x = 2.$$

$$\text{Var}(x) = E[x^2(\tau)] - E[x(\tau)]^2$$

$$\begin{aligned}&= R_{xx}(0) - (2)^2 \\ &= 9 - 4 \\ &= 5.\end{aligned}$$

$$R_{xx}(0) = \frac{36}{4} = 9$$

3. Find the mean & variance of the stationary process, whose R<sub>xx</sub>(τ) = 18 +  $\frac{2}{6+\tau^2}$

$$\mu_x = \sqrt{\lim_{|\tau| \rightarrow \infty} R_{xx}(\tau)}$$

$$\mu_x^2 = \lim_{|\tau| \rightarrow \infty} 18 + \frac{2}{6+\tau^2}$$

$$\mu_x^2 = 18$$

$$\mu_x = \sqrt{18} = 3\sqrt{2}$$

$$\sqrt{2 \times 2} = 3\sqrt{2}.$$

$$\begin{aligned}\text{Var}(x) &= E[x^2(t)] - E[x(t)]^2 \\ &= R_{xx}(0) - (18) \\ &= \left(18 + \frac{2}{6}\right) - 18 \\ &= \frac{1}{3}.\end{aligned}$$

3. Autocorrelation func of stationary process

$$R_{xx}(\tau) = 9 + 2 e^{-|\tau|} \text{ find mean of the random variable } Y = \int_0^2 x(t) \cdot dt \text{ & Var}[x(t)].$$

$$E[Y] = E\left[\int_0^2 x(t) \cdot dt\right].$$

Expectation & Integral can be interchangable

$$= \int_0^2 E[x(t)] \cdot dt.$$

$$\begin{aligned}E[x(t)] &= \mu_x = \sqrt{\lim_{T \rightarrow \infty} R_{xx}(\tau)} \\ &= \sqrt{9} = 3 \quad E[Y] = \int_0^2 3 \cdot dt = [3t]_0^2 = 6\end{aligned}$$

$$\begin{aligned}\text{Var}[x(t)] &= E[x^2(t)] - E[x(t)]^2 \\ &= R_{xx}(0) - 9 \\ &= 11 - 9 = 2.\end{aligned}$$

4. If  $\{x(t)\}$  is a process with mean  $\mu(t) = 3$   
 and autocorrelation is  $R_{xx}(t, t+\tau) = 9 + 4e^{-0.2|\tau|}$   
 determine mean, Var, Covar of  $Z = X(5)$  &  $W = X(8)$

$$\text{Mean of } Z : E[Z] = E[X(5)] = \mu(5) = 3,$$

$$\text{Var}(Z) = E[Z^2(t)] - E[Z(t)]^2$$

$$\begin{aligned} E[Z^2(t)] &= E[X^2(5)] = E[X(5) \cdot X(5)] \\ &= 9 + 4e^{-0.2(0)} \\ &= 13 \end{aligned}$$

$$\text{Var}(Z) = 13 - 3^2 = 13 - 9 = 4.$$

$$E[W(t)] = E[X(8)] = \mu(8) = 3.$$

$$\text{Var}(W) = E[W^2(t)] - E[W(t)]^2 \quad \rightarrow t=0.$$

$$E[W^2(t)] = E[W(t) \cdot W(t)] = E[X(8) \cdot X(8)] = 9 + 4 = 13.$$

$$\text{Covar}(X, Y) = E[XY] - E[X]E[Y].$$

$$\begin{aligned} \text{Covar of } (ZW) &= E[ZW] - E[Z]E[W] \\ &\quad \rightarrow \tau = 3 \rightarrow \text{sub in } R_{xx} \\ &= E[X(8) \cdot X(5)] - 3(3) \\ &= (9 + 4e^{-0.2(3)}) - 9 \\ &= 4e^{-0.6} \end{aligned}$$

$$R_{xx}(\tau) = E[x(t) \cdot x(t+\tau)]$$

$$\{x(t)\} \cdot \{y(t)\}$$

Cross Correlation.

$$R_{xy}(t, t+\tau) = E[x(t) \cdot y(t+\tau)]$$

Properties

$$1. R_{xy}(\tau) = R_{yx}(-\tau).$$

Proof, By definition

$$R_{xy}(\tau) = E[x(\tau) \cdot y(t+\tau)].$$

$$R_{xy}(-\tau) = E[y(t) \cdot x(t-\tau)]. \quad \begin{matrix} t - \tau = t_1 \\ t = t_1 + \tau. \end{matrix}$$

$$= E[y(t_1 + \tau) \cdot x(t_1)]$$

$$= E[x(t_1) \cdot y(t_1 + \tau)]$$

$$= R_{xy}(\tau)$$

Cross Correlation is not an even function.

$$2. |R_{xy}(\tau)| \leq \sqrt{R_{xx}(0) \cdot R_{yy}(0)}$$

$R_{xx}(0) \rightarrow$  mean sq value of  $x$

Proof

$$R_{xx}(0) = E[x^2(t)] \quad R_{yy}(0) = E[y^2(t)].$$

for any real no.  $k$ .

$$E[(x(t) + ky(t+\tau))^2] \geq 0.$$

$$E[x^2(t) + k^2y^2(t+\tau) + 2kx(t)y(t+\tau)] \geq 0$$

$$= E[x^2(t)] + k^2 E[y^2(t+\tau)] + 2kE[x(t) \cdot y(t+\tau)] \geq 0.$$

$$2^2 E[x(t) \cdot y(t+\tau)] - E[y^2(t+\tau)] E[x^2(t)] \leq 0.$$

$$(R_{xy}(\tau))^2 \leq R_{xx}(0) R_{yy}(0) \leq 0.$$

$$(R_{xy}(\tau))^2 \leq R_{xx}(0) R_{yy}(0).$$

$$|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0) R_{yy}(0)}$$

$$3. |R_{xy}(\tau)| \leq \frac{1}{2} [R_{xx}(0) + R_{yy}(0)].$$

$$R_{xx}(0) = E[x^2(t)] > 0 \quad R_{yy}(0) = E[y^2(t)] > 0.$$

$$GM \leq AM$$

$$\sqrt{R_{xx}(0) R_{yy}(0)} \leq \frac{R_{xx}(0) + R_{yy}(0)}{2} \quad (1) \quad GM \leq AM$$

$$|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0) R_{yy}(0)} \quad (2)$$

$$|R_{xy}(\tau)| \leq \frac{R_{xx}(0) + R_{yy}(0)}{2}$$

4. If  $\{x(t)\}$  &  $\{y(t)\}$  are orthogonal

$$R_{xy}(\tau) = 0$$

5. If  $\{x(t)\}$  &  $\{y(t)\}$  are independent then

$$R_{xy}(\tau) = \mu_x \cdot \mu_y.$$

$$R_{xy}(\tau) = E[x(t) y(t+\tau)]$$

$$E[xy] = E[x] \cdot E[y]$$

$$= E[x(t)] \cdot E[y(t)]$$

$$= \mu_x \cdot \mu_y.$$

i. Two random processes  $x(t)$  &  $y(t)$  are given by

$$x(t) = A \cos(\omega t + \theta)$$

$y(t) = A \sin(\omega t + \theta)$ . Where  $A$  &  $\omega$  are constant and  $\theta$  is uniformly distributed in  $(0, 2\pi)$ .

Find the Cross Correlation.

$$x(t) = A \cos(\omega t + \theta)$$

$$y(t) = A \sin(\omega t + \theta)$$

$$R_{xy}(t, t+\tau) = E[x(t) \cdot y(t+\tau)] \quad f(\theta) = \frac{1}{2\pi}$$

$$= E[A \cos(\omega t + \theta) \cdot A \sin(\omega t + \omega\tau + \theta)]$$

$$= A^2 \int_0^{2\pi} \cos(\omega t + \theta) \sin(\omega t + \omega\tau + \theta) \frac{1}{2\pi} d\theta$$

$$= \frac{A^2}{2\pi} \int_0^{2\pi} \frac{1}{2} \int_0^{2\pi} [\sin(\omega t + \theta + \omega\tau + \theta) + \sin(\omega t - \omega\tau - \theta)] d\theta d\theta$$

$$= \frac{A^2}{2\pi} \left[ \int_0^{2\pi} \sin(2\omega t + 2\theta + \omega\tau) d\theta + \int_0^{2\pi} \sin(\omega\tau) d\theta \right]$$

$$= \frac{A^2}{2\pi} \left[ \frac{\cos(2\omega t + 2\theta + \omega\tau)}{2} \Big|_0^{2\pi} + \sin(\omega\tau) \Big|_0^{2\pi} \right]$$

$$= \frac{A^2}{2\pi} \sin \omega t (2\pi - 0)$$

$$= \frac{A^2}{2} \sin \omega t$$

Open QV belong to Some  
existing Books  
location

2. Find the cross correlation function of  $z(t) = A(t) - B(t)$   
 $w(t) = A(t) + B(t)$ . When  $A(t)$  &  $B(t)$  are  
 statistically independent Random Variable with  
 zero mean and auto. correlation  $q$ .

$$R_{AA}(\tau) = e^{-|\tau|}, \quad -\infty < \tau < \infty$$

$$R_{BB}(\tau) = 3e^{-|\tau|}, \quad -\infty < \tau < \infty$$

$$R_{WZ}(t, t+\tau) = E[w(t) \cdot z(t+\tau)].$$

$$= E[(A(t) + B(t)) \cdot (A(t+\tau) - B(t+\tau))]$$

$$= E[A(t) \cdot A(t+\tau)] - E[B(t) \cdot B(t+\tau)] +$$

$$E[B(t) \cdot A(t+\tau)] - E[A(t) \cdot B(t+\tau)]$$

$A$  &  $B$  are independent.

$$E[AB] = E(A)E(B)$$

$$E(A) = 0 \quad E(B) = 0 \quad E[A(t) \cdot A(t+\tau)] = R_{AA}(\tau)$$

$$E[AB] = 0$$

$$= R_{AA}(\tau) - R_{BB}(\tau)$$

$$= e^{-|\tau|} - 3e^{-|\tau|}$$

$$R_{WZ} = -2e^{-|\tau|}$$

3.

Are independent with zero mean  $\bar{x}(t) \bar{y}(t)$

Find the auto-correlation of

$$z(t) = a + b x(t) + c y(t)$$

$$R_{zz}(\tau) = E[z(t) \cdot z(t+\tau)]$$

$$= E[(a + b x(t) + c y(t)) \cdot (a + b x(t+\tau) + c y(t+\tau))]$$

$$= E[a^2] + E[a b x(t+\tau)] + E[a c y(t+\tau)] + E[a b x(t)]$$

$$+ E[b^2 x(t) \cdot x(t+\tau)] + E[b c x(t) \cdot y(t+\tau)] +$$

$$E[a c y(t)] + E[b c y(t) x(t+\tau)] + E[c^2 y(t) y(t+\tau)]$$

$$= a^2 + a b E[x(t+\tau)] + 0 + 0 + 0 + E[b^2 x(t) \cdot x(t+\tau)]$$

$$+ E[c^2 y(t) y(t+\tau)]$$

$$R_{zz}(\tau) = a^2 + b R_{xx}(\tau) + c^2 R_{yy}(\tau)$$

JOINT WSS.

$$\{x(t)\} \quad \{y(t)\}.$$

1.  $\{x(t)\}$  is WSS.

2.  $\{y(t)\}$  is WSS.

$$3. R_{xy}(t_1, t_2) = f_n(\tau).$$

WSS

1. Mean  $\rightarrow$  Const

$$2. R_{xx}(t_1, t_2) = f_n(z)$$