



NAVI MUMBAI

MATLAB

Unit 6-Lecture 20

BTech (CSBS) -Semester VII

30 September 2022, 09:35AM



Control Flow and Operators

- 1) relational and logical operators
- 2) “if ... end” structure
- 3) “for ... end” loop
- 4) “while ... end” loop
- 5) other flow structures
- 6) operator precedence
- 7) saving output to a file



Relational operators

Relational operators compare the elements in two arrays and return logical true or false values to indicate where the relation holds.

<code>==</code>	Determine equality
<code>>=</code>	Determine greater than or equal to
<code>></code>	Determine greater than
<code><=</code>	Determine less than or equal to
<code><</code>	Determine less than
<code>~=</code>	Determine inequality
<code>isequal</code>	Determine array equality
<code>isequaln</code>	Determine array equality, treating NaN values as equal



Relational operators: Examples

Examples: If $x = [1 \ 5 \ 3 \ 7]$ and $y = [0 \ 2 \ 8 \ 7]$, then

$k = x < y$	results in $k = [0 \ 0 \ 1 \ 0]$	because $x_i < y_i$ for $i = 3$,
$k = x \leq y$	results in $k = [0 \ 0 \ 1 \ 1]$	because $x_i \leq y_i$ for $i = 3$ and 4 ,
$k = x > y$	results in $k = [1 \ 1 \ 0 \ 0]$	because $x_i > y_i$ for $i = 1$ and 2 ,
$k = x \geq y$	results in $k = [1 \ 1 \ 0 \ 1]$	because $x_i \geq y_i$ for $i = 1, 2$, and 4 ,
$k = x == y$	results in $k = [0 \ 0 \ 0 \ 1]$	because $x_i = y_i$ for $i = 4$, and
$k = x \neq y$	results in $k = [1 \ 1 \ 1 \ 0]$	because $x_i \neq y_i$ for $i = 1, 2$, and 3 .



Logical operators

<code>&</code>	Find logical AND
<code>~</code>	Find logical NOT
<code> </code>	Find logical OR
<code>xor</code>	Find logical exclusive-OR
<code>all</code>	Determine if all array elements are nonzero or true
<code>any</code>	Determine if any array elements are nonzero
<code>false</code>	Logical 0 (false)
<code>find</code>	Find indices and values of nonzero elements
<code>islogical</code>	Determine if input is logical array
<code>logical</code>	Convert numeric values to logicals
<code>true</code>	Logical 1 (true)



Logical operators: Examples

Examples: For two vectors $x = [0 \ 5 \ 3 \ 7]$ and $y = [0 \ 2 \ 8 \ 7]$,

$m = (x > y) \& (x > 4)$ results in $m = [0 \ 1 \ 0 \ 0]$, because the condition is true only for x_2 ,

$n = x | y$ results in $n = [0 \ 1 \ 1 \ 1]$, because either x_i or y_i is nonzero for $i = [2 \ 3 \ 4]$,

$m = \sim(x | y)$ results in $m = [1 \ 0 \ 0 \ 0]$, which is the logical complement of $x | y$, and

$p = x \text{ xor } y$ results in $p = [0 \ 0 \ 0 \ 0]$, because there is no such index i for which x_i or y_i , but not both, is nonzero.



Logical operators: builtin functions

In addition to these logical operators, there are many useful built-in logical functions, such as:

<code>all</code>	true (= 1) if all elements of a vector are true, <i>Example:</i> <code>all(x<0)</code> returns 1 if each element of x is negative.
<code>any</code>	true (= 1) if any element of a vector is true, <i>Example:</i> <code>any(x)</code> returns 1 if any element of x is nonzero.
<code>exist</code>	true (= 1) if the argument (a variable or a function) exists,
<code>isempty</code>	true (= 1) for an empty matrix,
<code>isinf</code>	true for all infinite elements of a matrix,
<code>isfinite</code>	true for all finite elements of a matrix,
<code>isnan</code> ³	true for all elements of a matrix that are not a number (NaN), and
<code>find</code>	finds indices of nonzero elements of a matrix. <i>Examples:</i> <code>find(x)</code> returns <code>[2 3 4]</code> for $\mathbf{x}=[0\ 2\ 5\ 7]$ and <code>[r,c]=find(A>100)</code> returns the row and column indices i and j of A , in vectors r and c , for which $A_{ij} > 100$.

To complete this list of logical functions, we just mention `isreal`, `issparse`, `isstr`, and `ischar`.



Elementary math functions

Trigonometric functions

<code>sin, sind</code>	sine,	<code>sinh</code>	hyperbolic sine,
<code>asin, asind</code>	inverse sine,	<code>asinh</code>	inverse hyperbolic sine,
<code>cos, cosd</code>	cosine,	<code>cosh</code>	hyperbolic cosine,
<code>acos, acosd</code>	inverse cosine,	<code>acosh</code>	inverse hyperbolic cosine,
<code>tan, tand</code>	tangent,	<code>tanh</code>	hyperbolic tangent,
<code>atan, atand</code>	inverse tangent,	<code>atanh</code>	inverse hyperbolic tangent,
<code>atan2</code>	four-quadrant \tan^{-1} ,		
<code>sec, secd</code>	secant,	<code>sech</code>	hyperbolic secant,
<code>asec, asecd</code>	inverse secant,	<code>asech</code>	inverse hyperbolic secant,
<code>csc, cscd</code>	cosecant,	<code>csch</code>	hyperbolic cosecant,
<code>acsc, acscd</code>	inverse cosecant,	<code>acsch</code>	inverse hyperbolic cosecant,
<code>cot, cotd</code>	cotangent,	<code>coth</code>	hyperbolic cotangent,
<code>acot, acotd</code>	inverse cotangent, and	<code>acoth</code>	inverse hyperbolic cotangent.



Elementary math functions

The angles given to these functions as arguments must be in *radians* for `sin`, `cos`, etc., and in *degrees* for `sind`, `cosd`, etc. Thus, `sin(pi/2)` and `sind(90)` produce the same result. All of these functions, except `atan2`, take a single scalar, vector, or matrix as input argument. The function `atan2` takes two input arguments, `atan2(y,x)`, and produces the four-quadrant inverse tangent such that $-\pi \leq \tan^{-1} \frac{y}{x} \leq \pi$. This gives the angle a rectangular to polar conversion.

Examples: If `q=[0 pi/2 pi]`, `x=[1 -1 -1 1]`, and `y=[1 1 -1 -1]`, then

<code>sin(q)</code>	gives <code>[0 1 0]</code> ,
<code>sinh(q)</code>	gives <code>[0 2.3013 11.5487]</code> ,
<code>atan(y./x)</code>	gives <code>[0.7854 -0.7854 0.7854 -0.7854]</code> , and
<code>atan2(y,x)</code>	gives <code>[0.7854 2.3562 -2.3562 -0.7854]</code> .



Exponential Functions

<code>exp</code>	exponential, <i>Example:</i> <code>exp(A)</code> produces a matrix with elements $e^{(A_{ij})}$. So how do you compute e^A ? See the next section.
<code>log</code>	natural logarithm, <i>Example:</i> <code>log(A)</code> produces a matrix with elements $\ln(A_{ij})$.
<code>log10</code>	base 10 logarithm, <i>Example:</i> <code>log10(A)</code> produces a matrix with elements $\log_{10}(A_{ij})$.
<code>sqrt</code>	square root, <i>Example:</i> <code>sqrt(A)</code> produces a matrix with elements $\sqrt{A_{ij}}$. But what about \sqrt{A} ? See the next section.
<code>nthroot</code>	real n th root of real numbers, <i>Example:</i> <code>nthroot(A,3)</code> produces a matrix with elements $\sqrt[3]{A_{ij}}$.



Complex Functions

<code>abs</code>	absolute value, <i>Example:</i> <code>abs(A)</code> produces a matrix of absolute values $ A_{ij} $.
<code>angle</code>	phase angle, <i>Example:</i> <code>angle(A)</code> gives the phase angles of complex A .
<code>complex</code>	constructs complex numbers from given real and imaginary parts, <i>Example:</i> <code>complex(A,B)</code> produces $A + Bi$.
<code>conj</code>	complex conjugate, <i>Example:</i> <code>conj(A)</code> produces a matrix with elements \bar{A}_{ij} .
<code>imag</code>	imaginary part, <i>Example:</i> <code>imag(A)</code> extracts the imaginary part of A .
<code>real</code>	real part, <i>Example:</i> <code>real(A)</code> extracts the real part of A .



Round off Functions

<code>fix</code>	round toward 0, <i>Example:</i> <code>fix([-2.33 2.66]) = [-2 2]</code> .
<code>floor</code>	round toward $-\infty$, <i>Example:</i> <code>floor([-2.33 2.66]) = [-3 2]</code> .
<code>ceil</code>	round toward $+\infty$, <i>Example:</i> <code>ceil([-2.33 2.66]) = [-2 3]</code> .
<code>mod</code>	modulus after division; <code>mod(a,b)</code> is the same as <code>a-floor(a./b)*b</code> , <i>Example:</i> <code>mod(26,5) = 1</code> and <code>mod(-26,5) = 4</code> .
<code>round</code>	round toward the nearest integer, <i>Example:</i> <code>round([-2.33 2.66]) = [-2 3]</code> .
<code>rem</code>	remainder after division, <code>rem(a,b)</code> is the same as <code>a-fix(a./b)*b</code> , <i>Example:</i> If <code>a=[-1.5 7]</code> , <code>b=[2 3]</code> , then <code>rem(a,b) = [-1.5 1]</code> .
<code>sign</code>	signum function, <i>Example:</i> <code>sign([-2.33 2.66]) = [-1 1]</code> .



Matrix Functions

`expm(A)`

finds the exponential of matrix A , e^A ,

`logm(A)`

finds $\log(A)$ such that $A = e^{\log(A)}$, and

`sqrtm(A)`

finds \sqrt{A} .