

Advanced Python

FOSSEE

August 18, 2016

Outline

- 1 Interactive Plotting
- 2 Embellishing Plots
- 3 Saving to Scripts
- 4 Saving Plots
- 5 Multiple Plots
- 6 Plotting Data
- 7 Other kinds of Plots
- 8 Arrays
- 9 Accessing pieces of arrays
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- 12 Solving Equations
- 13 ODEs
- 14 Using Python modules
- 15 Other packages

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First Plot

- Start IPython with `-pylab`

```
$ ipython -pylab
```

```
In[]: p = linspace(-pi,pi,100)
```

```
In[]: plot(p, cos(p))
```

linspace

- `p` has a hundred points in the range $-\pi$ to π

```
In[]: print p[0], p[-1], len(p)
```

- Look at the doc-string of `linspace` for more details

```
In[]: linspace?
```

- `plot` simply plots the two arguments with default properties

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Plot color and thickness

```
In[]: clf()
```

```
In[]: plot(p, sin(p), 'r')
```

- Gives a sine curve in Red.

```
In[]: plot(p, cos(p), linewidth=2)
```

- Sets line thickness to 2

```
In[]: clf()
```

```
In[]: plot(p, sin(p), '.')
```

- Produces a plot with only points

```
In[]: plot?
```

title

```
In[]: x = linspace(-2, 4, 50)
```

```
In[]: plot(x, -x*x + 4*x - 5, 'r',  
          linewidth=2)
```

```
In[]: title("Parabolic function  $-x^2+4x-5$ ")
```

- We can set title using \LaTeX

```
In[]: title("Parabolic function  $-x^2+4x-5$ ")
```


Axes labels

```
In[]: xlabel("x")
```

```
In[]: ylabel("f(x)")
```

- We could, if required use \LaTeX

Annotate

```
In[]: annotate("local maxima", xy=(2, -1))
```

- First argument is the annotation text
- The argument to `xy` is a tuple that gives the location of the text.

Limits of Plot area

```
In[]: xlim()
```

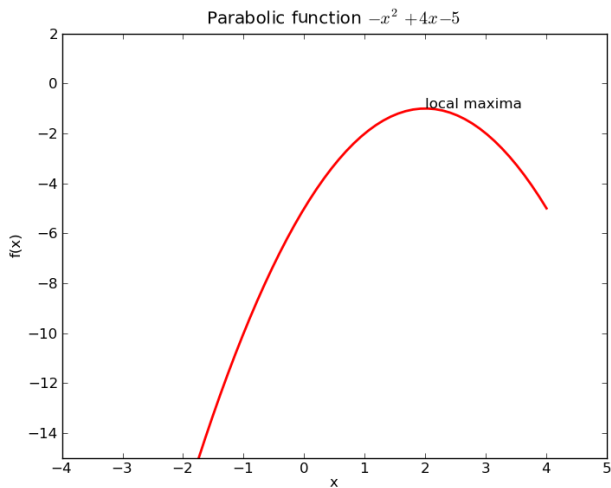
```
In[]: ylim()
```

- With no arguments, `xlim` & `ylim` get the current limits
- New limits are set, when arguments are passed to them

```
In[]: xlim(-4, 5)
```

```
In[]: ylim(-15, 2)
```

Plot



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Command history

- To see the history of commands, we typed

```
In[]: %hist
```

- All commands, valid or invalid, appear in the history
- `%hist` is a magic command, available only in IPython

```
In[]: %hist 5  
# last 5 commands
```

```
In[]: %hist 5 10  
# commands between 5 and 10
```

Saving to a script

- We wish to save commands for reproducing the parabola
- Look at the history and identify the commands that will reproduce the parabolic function along with all embellishment
- `%save` magic command to save the commands to a file

```
In[]: %save plot_script.py 1 3-6 8
```

- File name must have a `.py` extension

Running the script

```
In[]: %run -i plot_script.py
```

- There were no errors in the plot, but we don't see it!
- Running the script means, we are not in interactive mode
- We need to explicitly ask for the image to be shown

```
In[]: show()
```

- `-i` asks the interpreter to check for names, unavailable in the script, in the interpreter
- `sin`, `plot`, etc. are taken from the interpreter

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savefig

```
In[]: x = linspace(-3*pi, 3*pi, 100)
In[]: plot(x, sin(x))
In[]: savefig('sine.png')
```

- `savefig` takes one argument
- The file-type is decided based on the extension
- `savefig` can save as png, pdf, ps, eps, svg

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Overlaid plots

```
In[]: x = linspace(0, 50, 10)
In[]: plot(x, sin(x))
```

- The curve isn't as smooth as we expected
- We chose too few points in the interval

```
In[]: y = linspace(0, 50, 500)
In[]: plot(y, sin(y))
```

- The plots are overlaid
- It is the default behaviour of `pylab`

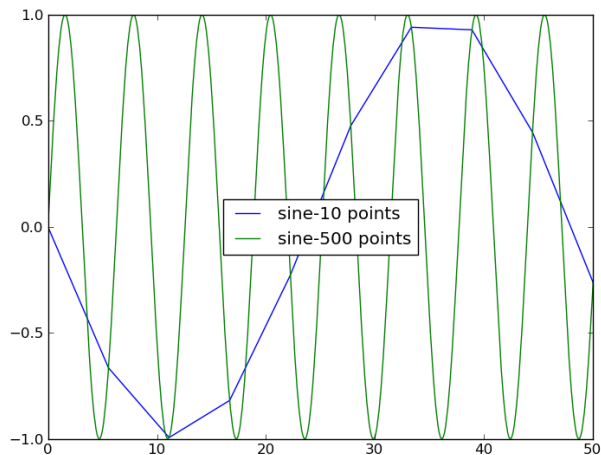
Legend

```
In[]: legend(['sine-10 points',  
             'sine-500 points'])
```

- Placed in the location, `pylab` thinks is 'best'
- `loc` parameter allows to change the location

```
In[]: legend(['sine-10 points',  
             'sine-500 points'],  
             loc='center')
```

Overlaid Plots



Plotting in separate figures

```
In[]: clf()
In[]: x = linspace(0, 50, 500)
In[]: figure(1)
In[]: plot(x, sin(x), 'b')
In[]: figure(2)
In[]: plot(x, cos(x), 'g')
```

- `figure` command allows us to have plots separately
- It is also used to switch context between the plots

```
In[]: savefig('cosine.png')
In[]: figure(1)
In[]: title('sin(y)')
In[]: savefig('sine.png')
In[]: close()
In[]: close()
```

Subplots

```
In[]: subplot(2, 1, 1)
```

- number of rows
- number of columns
- plot number, in serial order, to access or create

```
In[]: subplot(2, 1, 2)
```

```
In[]: x = linspace(0, 50, 500)
```

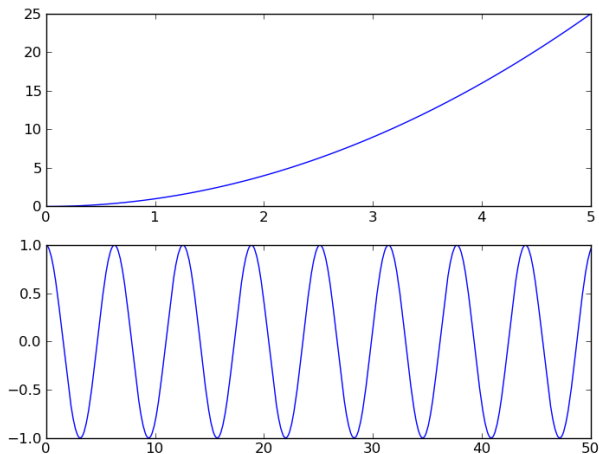
```
In[]: plot(x, cos(x))
```

```
In[]: subplot(2, 1, 1)
```

```
In[]: y = linspace(0, 5, 100)
```

```
In[]: plot(y, y ** 2)
```


Subplots



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Loading data

- `primes.txt` contains a list of primes listed column-wise
- We read the data using `loadtxt`

```
In[]: primes = loadtxt('primes.txt')
```

```
In[]: print primes
```

- `primes` is a sequence of floats

Reading two column data

- `pendulum.txt` has two columns of data
- Length of pendulum in the first column
- Corresponding time period in second column
- `loadtxt` requires both columns to be of same length

```
In[]: pend = loadtxt('pendulum.txt')
```

```
In[]: print pend
```

- `pend` is not a simple sequence like `primes`

Unpacking with `loadtxt`

```
In[]: L, T = loadtxt('pendulum.txt',  
                    unpack=True)
```

```
In[]: print L
```

```
In[]: print T
```

- We wish to plot L vs. T^2
- `square` function gives us the squares
- (We could instead iterate over T and calculate)

```
In[]: Tsq = square(T)
```

```
In[]: plot(L, Tsq, '.')
```

errorbar

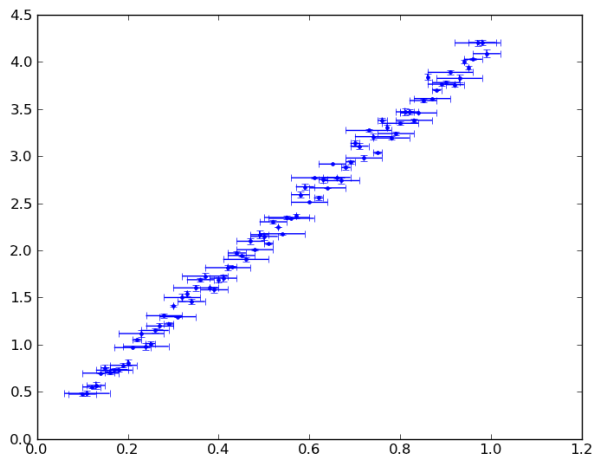
- Experimental data always has errors
- `pendulum_error.txt` contains errors in L and T
- Read the values and make an error bar plot

```
In[]: L, T, L_err, T_err = \
      loadtxt('pendulum_error.txt',
             unpack=True)
```

```
In[]: Tsq = square(T)
```

```
In[]: errorbar(L, Tsq , xerr=L_err,
              yerr=T_err, fmt='b.')
```

Errorbar



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Scatter Plot

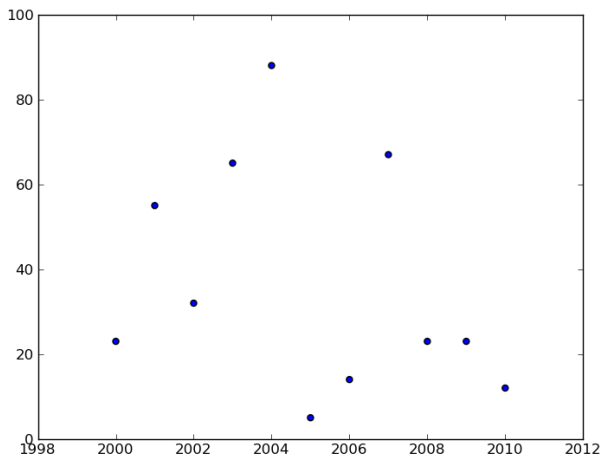
- The data is displayed as a collection of points
- Value of one variable determines position along x-axis
- Value of other variable determines position along y-axis
- Let's plot the data of profits of a company

```
In[]: year, profit = loadtxt(  
                                     'company-a-data.txt',  
                                     dtype=type(int()))
```

```
In[]: scatter(year, profit)
```

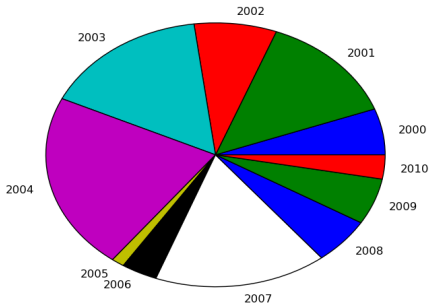
- `dtype=int`; default is float

Scatter Plot



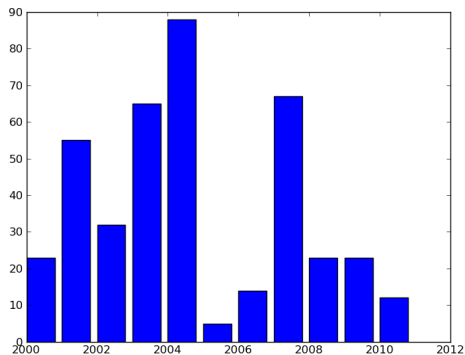
Pie Chart

```
In[]: pie(profit, labels=year)
```



Bar Chart

```
In[]: bar(year, profit)
```



Log-log plot

- Plot a log-log chart of $y = 5x^3$ for x from 1 to 20

```
In[]: x = linspace(1,20,100)
```

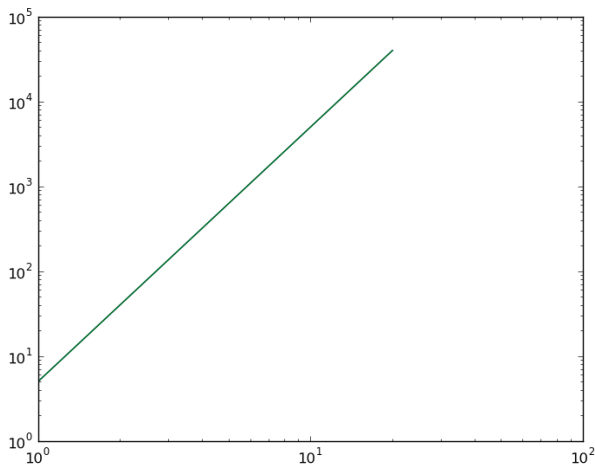
```
In[]: y = 5*x**3
```

```
In[]: loglog(x, y)
```

```
In[]: plot(x, y)
```

- Look at <http://matplotlib.sourceforge.net/contents.html> for more!

Log-log plot Plot



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Arrays: Introduction

- Similar to lists, but homogeneous
- Much faster than arrays

```
In[]: a1 = array([1, 2, 3, 4])
```

```
In[]: a1 # 1-D
```

```
In[]: a2 = array([[1, 2, 3, 4], [5, 6, 7, 8]])
```

```
In[]: a2 # 2-D
```


arange and shape

```
In[]: ar1 = arange(1, 5)
```

```
In[]: ar2 = arange(1, 9)
```

```
In[]: print ar2
```

```
In[]: ar2.shape = 2, 4
```

```
In[]: print ar2
```

- linspace and loadtxt also returned arrays

```
In[]: ar1.shape
```

```
In[]: ar2.shape
```

Special methods

```
In[]: identity(3)
```

- array of shape (3, 3) with diagonals as 1s, rest 0s

```
In[]: zeros((4, 5))
```

- array of shape (4, 5) with all 0s

```
In[]: a = zeros_like([1.5, 1, 2, 3])
```

```
In[]: print a, a.dtype
```

- An array with all 0s, with similar shape and dtype as argument
- Homogeneity makes the dtype of a to be float
- ones, ones_like, empty, empty_like

Operations on arrays

```
In[]: a1
```

```
In[]: a1 * 2
```

```
In[]: a1
```

- The array is not changed; New array is returned

```
In[]: a1 + 3
```

```
In[]: a1 - 7
```

```
In[]: a1 / 2.0
```

Operations on arrays ...

- Like lists, we can assign the new array, the old name

```
In[]: a1 = a1 + 2
```

```
In[]: a1
```

- Beware of Augmented assignment!

```
In[]: a, b = arange(1, 5), arange(1, 5)
```

```
In[]: print a, a.dtype, b, b.dtype
```

```
In[]: a = a/2.0
```

```
In[]: b /= 2.0
```

```
In[]: print a, a.dtype, b, b.dtype
```

- Operations on two arrays; element-wise

```
In[]: a1 + a1
```

```
In[]: a1 * a2
```

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Accessing & changing elements

```
In[]: A = array([12, 23, 34, 45, 56])
```

```
In[]: C = array([[11, 12, 13, 14, 15],  
                [21, 22, 23, 24, 25],  
                [31, 32, 33, 34, 35],  
                [41, 42, 43, 44, 45],  
                [51, 52, 53, 54, 55]])
```

```
In[]: A[2]
```

```
In[]: C[2, 3]
```

- Indexing starts from 0
- Assign new values, to change elements

```
In[]: A[2] = -34
```

```
In[]: C[2, 3] = -34
```

Accessing rows

- Indexing works just like with lists

```
In[]: C[2]
```

```
In[]: C[4]
```

```
In[]: C[-1]
```

- Change the last row into all zeros

```
In[]: C[-1] = [0, 0, 0, 0, 0]
```

OR

```
In[]: C[-1] = 0
```

Accessing columns

```
In[]: C[:, 2]
```

```
In[]: C[:, 4]
```

```
In[]: C[:, -1]
```

- The first parameter is replaced by a `:` to specify we require all elements of that dimension

```
In[]: C[:, -1] = 0
```


Slicing

```
In[]: I = imread('squares.png')  
In[]: imshow(I)
```

- The image is just an array

```
In[]: print I, I.shape
```

- 1 Get the top left quadrant of the image
- 2 Obtain the square in the center of the image

Slicing ...

- Slicing works just like with lists

```
In[]: C[0:3, 2]
```

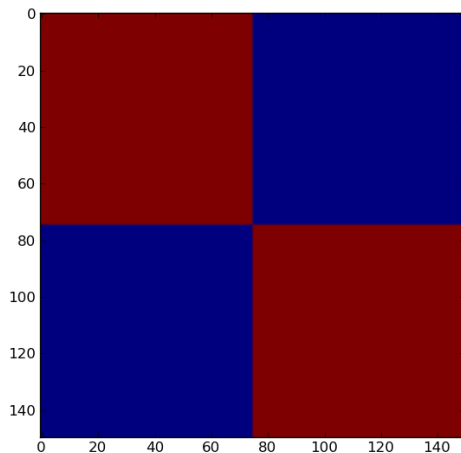
```
In[]: C[2, 0:3]
```

```
In[]: C[2, :3]
```

```
In[]: imshow(I[:150, :150])
```

```
In[]: imshow(I[75:225, 75:225])
```

Image after slicing



Striding

- Compress the image to a fourth, by dropping alternate rows and columns
- We shall use striding
- The idea is similar to striding in lists

```
In[]: C[0:5:2, 0:5:2]
```

```
In[]: C[:, :2]
```

```
In[]: C[1::2, ::2]
```

- Now, the image can be shrunk by

```
In[]: imshow(I[:, :2])
```

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Matrix Operations using `arrays`

We can perform various matrix operations on `arrays`
A few are listed below.

Operation	How?	Example
Transpose	<code>.T</code>	<code>A.T</code>
Product	<code>dot</code>	<code>dot(A, B)</code>
Inverse	<code>inv</code>	<code>inv(A)</code>
Determinant	<code>det</code>	<code>det(A)</code>
Sum of all elements	<code>sum</code>	<code>sum(A)</code>
Eigenvalues	<code>eigvals</code>	<code>eigvals(A)</code>
Eigenvalues & Eigenvectors	<code>eig</code>	<code>eig(A)</code>
Norms	<code>norm</code>	<code>norm(A)</code>
SVD	<code>svd</code>	<code>svd(A)</code>

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Least Square Fit

```
In[]: L, t = loadtxt("pendulum.txt",  
                    unpack=True)
```

```
In[]: L
```

```
In[]: t
```

```
In[]: tsq = t * t
```

```
In[]: plot(L, tsq, 'bo')
```

```
In[]: plot(L, tsq, 'r')
```

- Both the plots, aren't what we expect – linear plot
- Enter Least square fit!

Matrix Formulation

- We need to fit a line through points for the equation $T^2 = m \cdot L + c$
- In matrix form, the equation can be represented as $T_{sq} = A \cdot p$,

where T_{sq} is $\begin{bmatrix} T_1^2 \\ T_2^2 \\ \vdots \\ T_N^2 \end{bmatrix}$, A is $\begin{bmatrix} L_1 & 1 \\ L_2 & 1 \\ \vdots & \vdots \\ L_N & 1 \end{bmatrix}$ and p is $\begin{bmatrix} m \\ c \end{bmatrix}$

- We need to find p to plot the line

Least Square Fit Line

```
In[]: A = array((L, ones_like(L)))
```

```
In[]: A.T
```

```
In[]: A
```

- We now have A and tsq

```
In[]: result = lstsq(A, tsq)
```

- Result has a lot of values along with m and c , that we need

```
In[]: m, c = result[0]
```

```
In[]: print m, c
```

Least Square Fit Line

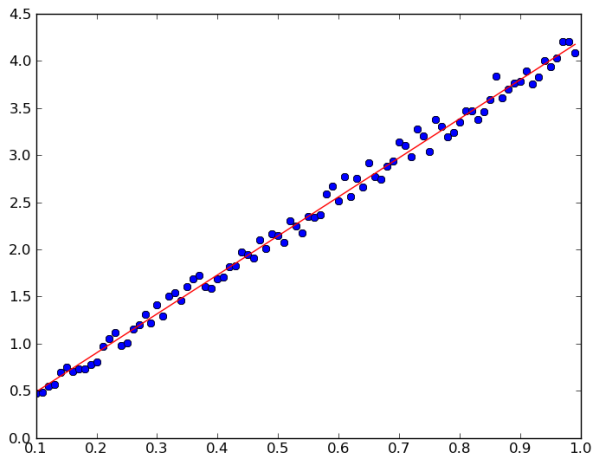
- Now that we have m and c , we use them to generate line and plot

```
In[]: tsq_fit = m * L + c
```

```
In[]: plot(L, tsq, 'bo')
```

```
In[]: plot(L, tsq_fit, 'r')
```

Least Square Fit Line



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Solution of linear equations

Consider,

$$\begin{aligned}3x + 2y - z &= 1 \\2x - 2y + 4z &= -2 \\-x + \frac{1}{2}y - z &= 0\end{aligned}$$

Solution:

$$\begin{aligned}x &= 1 \\y &= -2 \\z &= -2\end{aligned}$$

Solving using Matrices

Let us now look at how to solve this using `matrices`

```
In []: A = array([[3, 2, -1],  
                  [2, -2, 4],  
                  [-1, 0.5, -1]])  
  
In []: b = array([1, -2, 0])  
In []: x = solve(A, b)
```

Solution:

```
In []: x
```

```
Out[]: array([ 1., -2., -2.])
```


Let's check!

```
In []: Ax = dot(A, x)
```

```
In []: Ax
```

```
Out[]: array([ 1.00000000e+00, -2.00000000e+00,  
              -1.11022302e-16])
```

The last term in the matrix is actually 0!

We can use `allclose()` to check.

```
In []: allclose(Ax, b)
```

```
Out[]: True
```

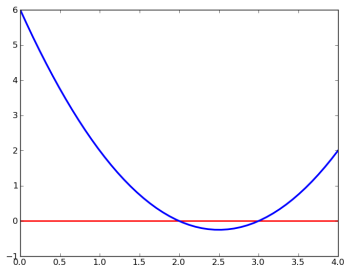
roots of polynomials

- `roots` function can find roots of polynomials
- To calculate the roots of $x^2 - 5x + 6$

```
In []: coeffs = [1, -5, 6]
```

```
In []: roots(coeffs)
```

```
Out[]: array([3., 2.])
```



SciPy: fsolve

```
In []: from scipy.optimize import fsolve
```

- Finds the roots of a system of non-linear equations
- Input arguments - Function and initial estimate
- Returns the solution

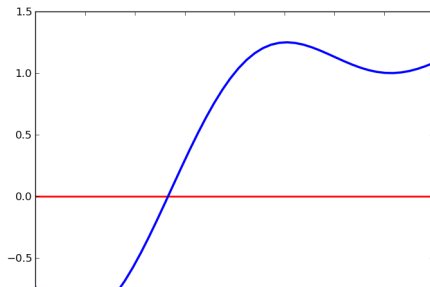
fsolve ...

Find the root of $\sin(z) + \cos^2(z)$ nearest to 0

```
In []: def g(z):  
      ....:     return sin(z)+cos(z)*cos(z)
```

```
In []: fsolve(g, 0)
```

```
Out[]: -0.66623943249251527
```



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Solving ODEs using SciPy

- Consider the spread of an epidemic in a population
- $\frac{dy}{dt} = ky(L - y)$ gives the spread of the disease
- L is the total population.
- Use $L = 2.5E5, k = 3E-5, y(0) = 250$
- Define a function as below

```
In []: from scipy.integrate import odeint
In []: def epid(y, t):
....     k = 3.0e-5
....     L = 2.5e5
....     return k*y*(L-y)
....
```

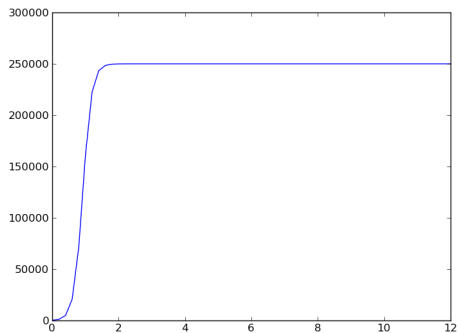
Solving ODEs using SciPy ...

```
In []: t = linspace(0, 12, 61)
```

```
In []: y = odeint(epid, 250, t)
```

```
In []: plot(t, y)
```

Result



ODEs - Simple Pendulum

We shall use the simple ODE of a simple pendulum.

$$\ddot{\theta} = -\frac{g}{L}\sin(\theta)$$

- This equation can be written as a system of two first order ODEs

$$\dot{\theta} = \omega \tag{1}$$

$$\dot{\omega} = -\frac{g}{L}\sin(\theta) \tag{2}$$

At $t = 0$:

$$\theta = \theta_0(10^\circ) \quad \& \quad \omega = 0 \text{ (Initial values)}$$

ODEs - Simple Pendulum ...

- Use `odeint` to do the integration

```
In []: def pend_int(initial, t):  
.....     theta = initial[0]  
.....     omega = initial[1]  
.....     g = 9.81  
.....     L = 0.2  
.....     F=[omega, -(g/L)*sin(theta)]  
.....     return F  
.....
```

ODEs - Simple Pendulum ...

- `t` is the time variable
- `initial` has the initial values

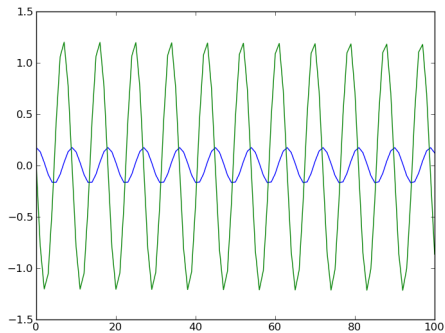
```
In []: t = linspace(0, 20, 101)
```

```
In []: initial = [10*2*pi/360, 0]
```

ODEs - Simple Pendulum ...

```
In []: from scipy.integrate import odeint
In []: pend_sol = odeint(pend_int,
                        initial,t)
```

Result



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hello.py

- Script to print 'hello world' – `hello.py`

```
print "Hello world!"
```

- We have been running scripts from IPython

```
In[]: %run -i hello.py
```

- Now, we run from the shell using python

```
$ python hello.py
```

Simple plot

- Save the following in `sine_plot.py`

```
x = linspace(-2*pi, 2*pi, 100)
plot(x, sin(x))
show()
```

- Now, let us run the script

```
$ python sine_plot.py
```

- What's wrong?

Importing

- `-pylab` is importing a lot of functionality
- Add the following to the top of your file

```
from scipy import *
```

```
$ python sine_plot.py
```

- Now, `plot` is not found
- Add the following as the second line of your script

```
from pylab import *
```

```
$ python sine_plot.py
```

- It works!

Importing ...

- `*` imports everything from `scipy` and `pylab`
- But, It imports lot of unnecessary stuff
- And two modules may contain the same name, causing a conflict
- There are two ways out

```
from scipy import linspace, pi, sin  
from pylab import plot, show
```

- OR change the imports to following and
- Replace `pi` with `scipy.pi`, etc.

```
import scipy  
import pylab
```

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Very useful packages

- <http://ipython.org/>
- <http://sympy.org/>
- <http://pandas.pydata.org/>