

Lecture 23

Last time we analyzed error of Newton and Secant method.

We proved that in Newton's method

$$e_{n+1} \approx C e_n^2 \quad C \text{ constant}$$

while in Secant method

$$e_{n+1} \approx C e_n e_{n-1}$$

We then defined order of convergence

$$\lim_{n \rightarrow \infty} \frac{|e_{n+1}|}{|e_n|^p} = \text{non-zero constant}$$

→ For most fixed pt iteration
order of convergence = 1

→ For Newton's method, order = 2

→ For secant method order = $\frac{1+\sqrt{5}}{2} = 1.618 \dots$

Today we learn iterative methods to solve linear equations.

It is based on fixed pt iteration

We want to solve

$$A\bar{x} = \bar{b}$$

It is equivalent to find zero of

$$f(x) = A\bar{x} - \bar{b}$$

We write it in equivalent form

$$\bar{x} = g(\bar{x})$$

A fixed pt $\bar{\xi}$ of $g(\bar{x})$ will be root of $f(x)$. i.e. $A\bar{\xi} = \bar{b}$.

Iteration initial given $x^{(0)}$

and then we generate the sequence

$$x^{(m+1)} = g(x^{(m)}) \quad m = 0, 1, 2, \dots$$

For convergence we require the following theorem

$S \subseteq \mathbb{R}^n$ is closed if any ^{seq} $\{x_n\}$ $x_n \in S$
 $\Rightarrow \lim_{n \rightarrow \infty} x_n \in S$

Example :- 1) $[0, 1]$ is not closed
2) $[a, b] \times [c, d]$ is closed in \mathbb{R}^2

Theorem :- Suppose $g: S \rightarrow S$, S closed set in \mathbb{R}^n . Suppose further that g is contraction on S , i.e.,

$$\|g(x) - g(y)\| \leq k \|x - y\|$$

for all $x, y \in S$ and $0 \leq k < 1$

Then

1) g has a unique fixed pt ξ in S

2) Fixed pt iteration starting with any $x^{(0)}$ in S converges to ξ . i.e., $\lim_{m \rightarrow \infty} \|\xi - x^{(m)}\| = 0$

for such a seq $x^{(m+1)} = g(x^{(m)})$, $m = 0, 1, 2, \dots$
More explicitly

$$(*) \quad \|\xi - x^{(m)}\| \leq \frac{k}{1-k} \|x^{(m)} - x^{(m-1)}\|$$

$$(**) \quad \|\xi - x^{(m)}\| \leq \frac{k^m}{1-k} \|x^{(1)} - x^{(0)}\|$$

S is closed set, $g: S \rightarrow S$ contractive
 $\Rightarrow g$ has a fixed pt.

non-trivial theorem

derivation of (*) and (**)

$$\begin{aligned}\|\xi - x^{(m)}\| &= \|g(\xi) - g(x^{(m-1)})\| \\ &\leq K \|\xi - x^{(m-1)}\|\end{aligned}$$

by Δ^k rule

$$\begin{aligned}\|\xi - x^{(m-1)}\| &\leq \|\xi - x^{(m)}\| + \|x^{(m)} - x^{(m-1)}\| \\ &\leq K \|\xi - x^{(m-1)}\| + \|x^{(m)} - x^{(m-1)}\| \\ (1-K) \|\xi - x^{(m-1)}\| &\leq \|x^{(m)} - x^{(m-1)}\|\end{aligned}$$

$$\text{So } \|\xi - x^{(m)}\| \leq \frac{K}{1-K} \|x^{(m)} - x^{(m-1)}\|$$

This proves (*)

$$\begin{aligned}\|x^{(m)} - x^{(m-1)}\| &= \|g(x^{(m-1)}) - g(x^{(m-2)})\| \\ &\leq K \|x^{(m-1)} - x^{(m-2)}\|\end{aligned}$$

$$\text{So } \|\xi - x^{(m)}\| \leq \frac{K^2}{1-K} \|x^{(m-1)} - x^{(m-2)}\|$$

$$\leq \frac{K^m}{1-K} \|x^{(1)} - x^{(0)}\|$$

to solve $Ax = b$

All iteration schemes are based on the notion of approximate inverse,

by this we mean any matrix C for which

$$\|I - CA\| < 1$$

in some matrix norm.

Lemma If C is an approximate inverse for the matrix A , i.e., if $\|I - CA\| < 1$ in some matrix norm, then both C and A are invertible

Pf If C OR A is not invertible then

So would the matrix CA .

Thus we can find $\bar{x} \neq 0$ s.t. $CA\bar{x} = 0$

But then

$$\begin{aligned} 0 \neq \|x\| &= \|(I - CA)\bar{x}\| \\ &\leq \|I - CA\| \|\bar{x}\| \\ &< \|x\| \end{aligned}$$

this is a contradiction

Iteration function

Let C be an approximate inverse to A

$$\begin{aligned} g(\bar{x}) &= C\bar{b} + (I - CA)\bar{x} \\ &= \bar{x} + C(\bar{b} - A\bar{x}) \end{aligned}$$

$$\text{If } g(\bar{\xi}) = \bar{\xi}$$

$$\text{then } \bar{\xi} = \bar{\xi} + C(\bar{b} - A\bar{\xi})$$

$$C(\bar{b} - A\bar{\xi}) = 0$$

$$C \text{ invertible. So } A\bar{\xi} = \bar{b}$$

$$\begin{aligned} g(x) - g(y) &= C\bar{b} + (I - CA)x - \left(C\bar{b} + (I - CA)y \right) \\ &= (I - CA)(x - y) \end{aligned}$$

$$\begin{aligned} \text{So } \|g(x) - g(y)\| &= \|(I - CA)(x - y)\| \\ &\leq \|I - CA\| \|x - y\| \end{aligned}$$

So g is contractive with $k = \|I - CA\| < 1$

Therefore the fixed pt iteration
 $S = \mathbb{R}^n$
 $x^{(m+1)} = x^{(m)} + C(b - Ax^{(m)}) \quad m=0,1,2,\dots$

starting from any $x^{(0)}$ will converge to the unique solution ξ

Two most common choices of C

$$A = (a_{ij})$$

$$= \hat{L} + \hat{D} + \hat{U}$$

$$\hat{L} = (l_{ij})$$

$$l_{ij} = \begin{cases} a_{ij} & i > j \\ 0 & i \leq j \end{cases}$$

$$\hat{D} = (d_{ij})$$

$$d_{ij} = \begin{cases} a_{ij} & \text{if } i=j \\ 0 & i \neq j \end{cases}$$

$$\hat{U} = (u_{ij})$$

$$u_{ij} = \begin{cases} 0 & \text{if } i \geq j \\ a_{ij} & \text{if } i < j \end{cases}$$

example

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 4 & 5 \\ 6 & 7 & 8 \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 3 & 0 & 0 \\ 6 & 7 & 0 \end{pmatrix}}_{\hat{L}} + \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 8 \end{pmatrix}}_{\hat{D}} + \underbrace{\begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 5 \\ 0 & 0 & 0 \end{pmatrix}}_{\hat{U}}$$

We assume all diagonal entries of A are non-zero

(if this is not so at the outset, we first rearrange the equation so that this condition is satisfied. This can always be done since A is invertible)

Jacobi iteration

$$C = \hat{D}^{-1}$$

This converges if $\|I - \hat{D}^{-1}A\| < 1$ for some norm.

$$x^{(m+1)} = x^{(m)} + \hat{D}^{-1} (b - Ax^{(m)})$$

$$\boxed{x_i^{(m+1)} = \frac{b_i - \sum_{j \neq i} a_{ij} x_j^{(m)}}{a_{ii}}}$$

$i=1, 2, \dots, n$

Example

$$10x_1 - x_2 = 9$$

$$-x_1 + 10x_2 - 2x_3 = 7$$

$$-2x_2 + 10x_3 = 6$$

$$\begin{cases} x_1 = 0.1x_2 + 0.9 \\ x_2 = 0.1x_1 + 0.2x_3 + 0.7 \\ x_3 = 0.2x_2 + 0.6 \end{cases}$$

Jacobi iteration

initial $x_1^{(0)} = 0$

$$x_2^{(0)} = 0$$

$$x_3^{(0)} = 0$$

iteration
scheme

$$x_1^{(m+1)} = 0.1x_2^{(m)} + 0.9$$

$$x_2^{(m+1)} = 0.1x_1^{(m)} + 0.2x_3^{(m)} + 0.7$$

$$x_3^{(m+1)} = 0.2x_2^{(m)} + 0.6$$

Iteration

m	0	1	2	3	4
$x_1^{(m)}$	0	0.9	0.97	0.991	0.9941
$x_2^{(m)}$	0	0.7	0.91	0.941	0.9555
$x_3^{(m)}$	0	0.6	0.72	0.782	0.7564

m	5	6	7	8	9
$x_1^{(m)}$	0.99555	0.995069	0.995778	0.995115	0.995719
$x_2^{(m)}$	0.95069	0.957775	0.951151	0.957889	0.951174
$x_3^{(m)}$	0.7911	0.758220	0.791555	0.758311	0.791578

converging nicely to exact solⁿ (in 6 sig
digs)

$$x_1 = 0.995789$$

$$x_2 = 0.957895$$

$$x_3 = 0.791579$$

$$A = \hat{L} + \hat{D} + \hat{U}$$

for Jacobi method

$$C = \hat{D}^{-1}$$

For Gauss-Seidel iteration

$$C = (\hat{L} + \hat{D})^{-1}$$

$$x^{(m+1)} = x^{(m)} + (\hat{L} + \hat{D})^{-1} (b - Ax^{(m)})$$

$$(\hat{L} + \hat{D}) x^{(m+1)} = (\hat{L} + \hat{D} - A) x^{(m)} + b$$

$$\hat{D} x^{(m+1)} = -\hat{L} x^{(m+1)} - \hat{U} x^{(m)} + b$$

This gives the formula's

$$x_i^{(m+1)} = \frac{-\sum_{j < i} a_{ij} x_j^{(m+1)} - \sum_{j > i} a_{ij} x_j^{(m)} + b_i}{a_{ii}}$$

$i = 1, 2, \dots, n$

This converges if for some matrix norm

$$\|I - CA\| < 1$$

$$\begin{aligned} I - CA &= I - (\hat{L} + \hat{D})^{-1} (\hat{L} + \hat{D} + \hat{U}) \\ &= (\hat{L} + \hat{D})^{-1} \hat{U} \end{aligned}$$

i.e. if $\|C\hat{U}\| < 1$ then Gauss-Seidel method converges

Example (Same example as before)

$$\begin{aligned} 10x_1 - x_2 &= 9 \\ -x_1 + 10x_2 - 2x_3 &= 7 \\ -2x_2 + 10x_3 &= 6 \end{aligned}$$

$$x_1 = 0.1x_2 + 0.9$$

$$x_2 = 0.1x_1 + 0.2x_3 + 0.7$$

$$x_3 = 0.2x_2 + 0.6$$

Iteration scheme

$$x_1^{(m+1)} = 0.1 x_2^{(m)} + 0.9$$

$$x_2^{(m+1)} = 0.1 \underline{x_1^{(m+1)}} + 0.2 x_3^{(m)} + 0.7$$

$$x_3^{(m+1)} = 0.2 \underline{x_2^{(m+1)}} + 0.6$$

(note the diff from Jacobi-method)

(in Gauss-Seidel while computing $x_i^{(m+1)}$ we can use $x_j^{(m+1)}$ for $j=0, 1, \dots, i-1$)

initial approx. = $(\bar{0}, \bar{0}, \bar{0})$

n	0	1	2	3	4
$x_1^{(n)}$	0	0.9	0.979	0.99495	0.995748
$x_2^{(n)}$	0	0.79	0.9495	0.957475	0.957879
$x_3^{(n)}$	0	0.758	0.7899	0.791495	0.791575

	5	6
$x_1^{(n)}$	0.995787	0.995789
$x_2^{(n)}$	0.957894	0.957895
$x_3^{(n)}$	0.791579	0.791579

Gauss-Seidel iteration is usually faster than Jacobi iteration (not always but!)

It is also easier to compute since in Jacobi iteration two iterates must be kept in memory while in Gauss Seidel only one vector is required to be kept in memory.

Gauss-Seidel iteration can be shown to be convergent if the coefficient matrix A is strictly row diagonally-dominant. It also converges if A is true-definite i.e. if A is symmetric and for all non-zero vectors y , $y^T A y > 0$.

Proposition

Suppose A is strictly row-diagonally dominant. Then the Jacobi-iteration converges.

Proof $A = (a_{ij})$ is strictly row diagonally dominant

$$\text{So } |a_{ii}| > \sum_{j \neq i} |a_{ij}| \quad i=1, 2, \dots, n$$

$\hat{D} = \text{diag}(a_{11}, a_{22}, \dots, a_{nn})$ be the diagonal of A

$$\|x\|_{\infty} = \max_i |x_i|$$

$$\|B\|_{\infty} = \max_{1 \leq i \leq n} \sum_{1 \leq j \leq n} |b_{ij}|$$

$$\|I - \hat{D}^{-1}A\|_{\infty} = \max_i \left\{ 1 - \sum_{j=1}^n \frac{|a_{ij}|}{|a_{ii}|} \right\}$$

$$= \max_i \left\{ \sum_{\substack{j=1 \\ j \neq i}}^n \frac{|a_{ij}|}{|a_{ii}|} \right\}$$

$$< 1$$

Thus \hat{D}^{-1} is an approximate inverse to A .

Therefore the Jacobi-Method converges

Remark

Recall that C is an approximate inverse to A if in some matrix norm

$$\|I - CA\| < 1.$$

Note that in some other matrix norm it is possible that

$$\|I - CA\|' > 1$$

Example

$$B = \begin{bmatrix} 0.9 & 0.9 \\ 0 & 0 \end{bmatrix}$$

$$\|B\|_{\infty} = 1.8 > 1$$

$$\|B\|_1 = 0.9 < 1$$

This makes it important to find ways of telling whether $\|B\| < 1$ in some matrix norm (without having to try out all possible matrix norms)

defⁿ

$\rho(B)$ = spectral radius of B

$$= \max \{ |\lambda| \mid \lambda \text{ is an eigenvalue of } B \}$$

Theorem There exists, for any $\epsilon > 0$, a vector norm for which the associated matrix norm of B satisfies

$$\|B\| \leq \rho(B) + \epsilon$$

Corollary C is an approximate inverse for A iff $\rho(I - CA) < 1$

Remark Iterative methods are usually applied to large linear systems with sparse coefficient matrix.

