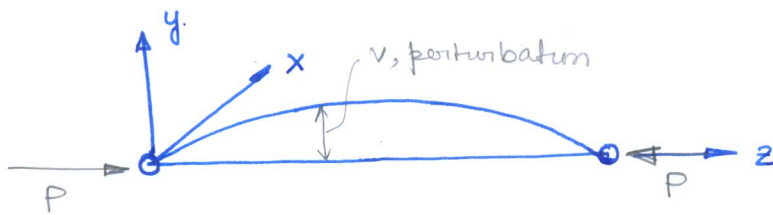


Euler theory of buckling



pinned - pinned
support condn.

Moment balance equation:

$$EI \frac{d^2 v}{dz^2} = -Pv \Rightarrow EI \frac{d^2 v}{dz^2} + Pv = 0$$

$$\Rightarrow \frac{d^2 v}{dz^2} + \mu^2 v = 0 \quad \text{where } \mu^2 = \frac{P}{EI}$$

$$v(z) = A \cos \mu z + B \sin \mu z$$

Boundary Conditions

$$@ z=0, v=0 \quad A=0$$

$$@ z=l, v=0 \quad B \sin \mu l = 0$$

$$\Rightarrow \mu l = n\pi \Rightarrow \frac{P}{EI} = \frac{n^2 \pi^2}{l^2}$$

$$\Rightarrow \boxed{P_{cr} = \frac{n^2 \pi^2 EI}{l^2}}$$

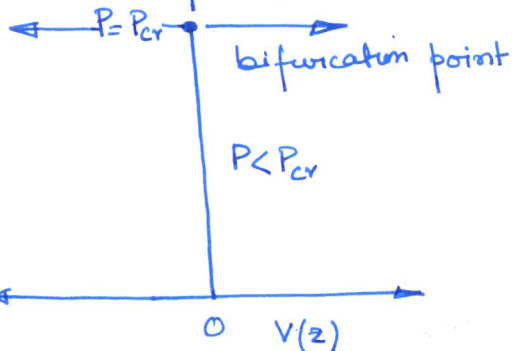
$$P_{cr} = \frac{\pi^2 EI}{l^2} \quad (\text{first buckling mode})$$

$$v(z) = A_1 \sin \frac{\pi z}{l}$$



$$P_{cr} = \frac{4\pi^2 EI}{l^2} \quad (\text{second buckling mode})$$

$$v(z) = A_2 \sin \frac{2\pi z}{l}$$



$$P_{cr} = \frac{\pi^2 E}{(l/r)^2} \quad r \text{ is the radius of gyration.}$$

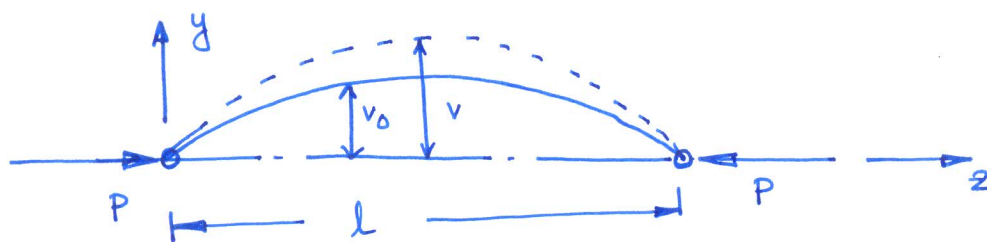
For other support condns:

$$P_{cr} = \frac{4\pi^2 EI}{l^2} \quad (\text{fixed-fixed support})$$

$$P_{cr} = \frac{\pi^2 EI}{4l^2} \quad (\text{fixed-free support})$$

Effect of initial imperfection

(2)



Moment balance equation:

$$EI \frac{d^2 v}{dz^2} - EI \frac{d^2 v_0}{dz^2} = -Pv$$

Assuming

$$v_0(z) = \sum_{n=1}^{\infty} A_n \sin \frac{n\pi z}{l}$$

————— (2)

$$\Rightarrow EI \frac{d^2 v}{dz^2} + Pv = EI \frac{d^2 v_0}{dz^2}$$

$$\Rightarrow \frac{d^2 v}{dz^2} + \mu^2 v = \frac{d^2 v_0}{dz^2} \quad \text{where } \mu^2 = \frac{P}{EI}$$

Substituting (2) in (1), we get, (1)

$$\frac{d^2 v}{dz^2} + \mu^2 v = - \sum \frac{A_n \pi^2 \lambda^2}{l^2} \sin \frac{n\pi z}{l}$$

$$\Rightarrow v(z) = A \cos \mu z + B \sin \mu z + \sum \frac{\pi^2 A_n}{n^2 - \alpha^2} \sin \frac{n\pi z}{l} \quad \alpha^2 = \frac{\mu^2 l^2}{\pi^2} = \frac{Pl^2}{\pi^2 EI}$$

Imposing boundary conditions, @ $z=0, v=0$ and @ $z=l, v=0$ $= \frac{P}{P_{cr}}$

$$A = 0 \text{ and } B = 0$$

$$\Rightarrow v(z) = \sum \frac{\pi^2 A_n}{n^2 - \alpha^2} \sin \frac{n\pi z}{l} \quad \text{as } P \rightarrow P_{cr}, \alpha \rightarrow 1$$

\therefore The first term in the series corresponding to $n=1$ will dominate.

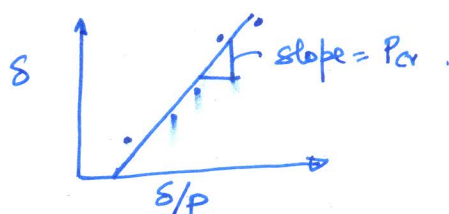
$$\therefore v(z) \approx \frac{A_1}{1 - \alpha^2} \sin \frac{\pi z}{l} \quad \text{as } P \rightarrow P_{cr}$$

$$\text{Deflection at the center of the column } v(z=l/2) = \frac{A_1}{1 - \alpha^2}$$

$$\text{Denoting } \delta = v(z=l/2) - A_1 = \frac{A_1}{1 - P/P_{cr}} - A_1$$

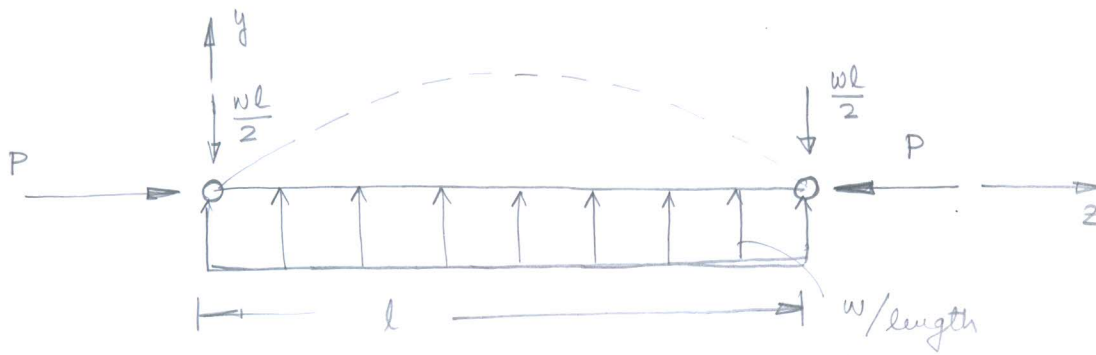
$$\Rightarrow \delta = \frac{\delta P_{cr}}{P} - A_1 \quad \text{————— (3)}$$

Plotting eqn (3) when $P \rightarrow P_{cr}$, we get Southwell plot



(3)

Stability of beams under transverse and axial loads



Moment balance eqn:

$$Pv + \frac{wlz}{2} - \frac{wz^2}{2} = -EI \frac{d^2v}{dz^2}$$

$$\Rightarrow \frac{d^2v}{dz^2} + \mu^2 v = \frac{w}{2EI} (z^2 - lz) \quad \text{where } \mu^2 = \frac{P}{EI}$$

$$v(z) = A \cos \mu z + B \sin \mu z + \frac{w}{2P} \left(z^2 - lz - \frac{2}{\mu^2} \right)$$

Imposing the BCs: @ $z=0, v=0$ and @ $z=l, v=0$, gives

$$A = \frac{w}{\mu^2 P} \quad \text{and} \quad B = \frac{w}{\mu^2 P \sin \mu l} (1 - \cos \mu l)$$

$$v(z) = \frac{w}{\mu^2 P} \left[\cos \mu z + \left(\frac{1 - \cos \mu l}{\sin \mu l} \right) \sin \mu z \right] + \frac{w}{2P} \left(z^2 - lz - \frac{2}{\mu^2} \right)$$

Max^m deflection

occurs at the mid-point
of the beam

$$v_{\max} = \frac{w}{\mu^2 P} \left(\sec \frac{\mu l}{2} - 1 \right) - \frac{wl^2}{8P}$$

$$M_{\max} = \frac{w}{\mu^2} \left(1 - \sec \frac{\mu l}{2} \right)$$

$$= \frac{wl^2}{\pi^2} \frac{P_{cr}}{P} \left(1 - \sec \frac{\pi}{2} \sqrt{\frac{P}{P_{cr}}} \right) \quad P_{cr} = \frac{\pi^2 EI}{l^2}$$