

# AE 230

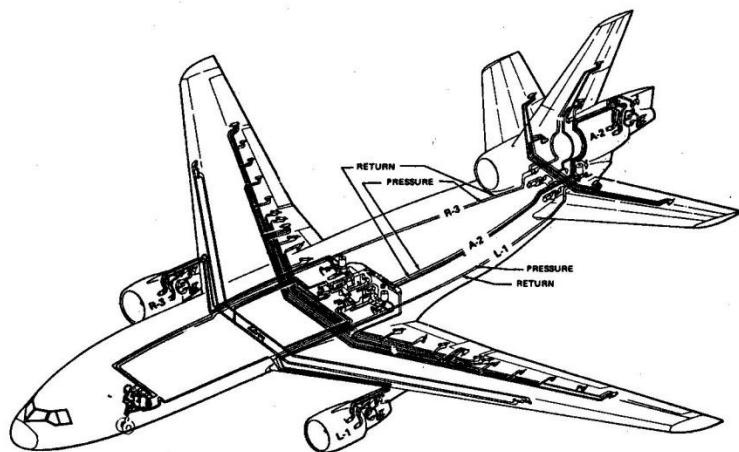
## Fluid Systems

# AE 230

## Fluid Systems

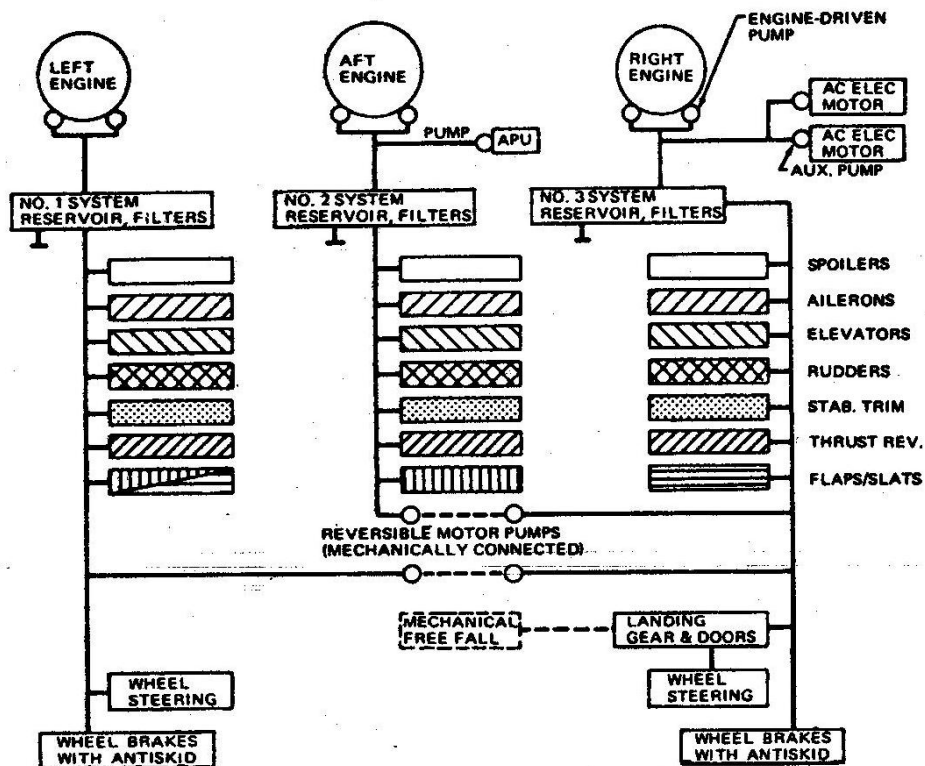
- Water supply in home, city etc.
- Transportation of gas, oil etc in pipe lines
- Flow of chemicals in the industry
- Flow of air in industry
- Flow of oil in aircraft
- Flow of fuel in aircraft
- Flow water in hydraulic power plant

## HYDRAULIC POWER SYSTEM AND PIPING



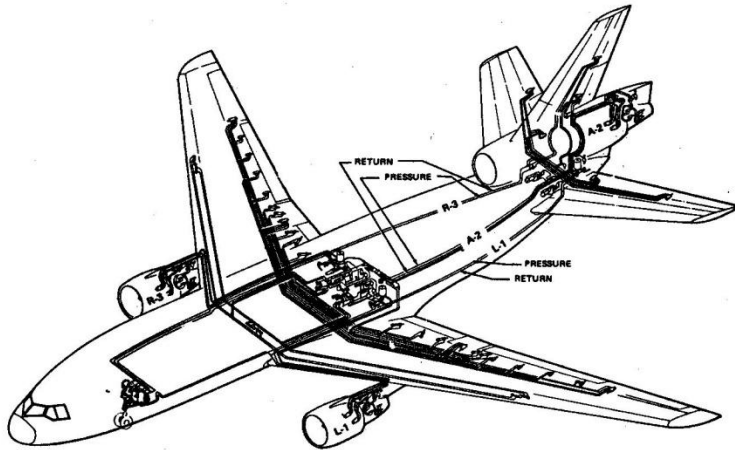
HYDRAULIC SYSTEM

## HYDRAULIC SYSTEM



Aircraft hydraulic system.

## HYDRAULIC POWER SYSTEM AND PIPING



HYDRAULIC SYSTEM

- Pipes carrying liquid
- Valves to control the flow
- Pumps to pressurise the fluid
- Heat exchanger to remove heat
- Tanks to balance the weight

# Fluid systems - hydraulic capacitance

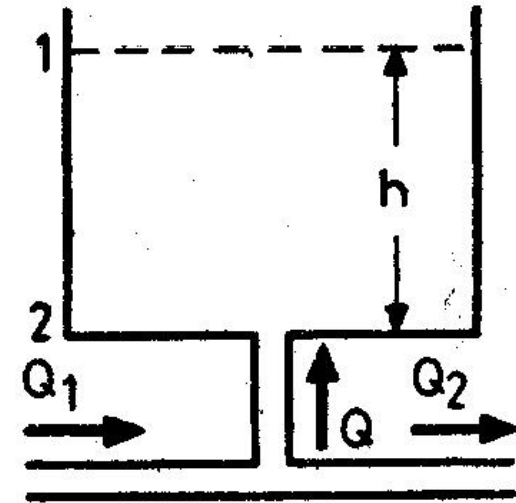
Storage tank of constant area  $A$

$$P_2 - P_1 = P = \rho gh \quad h = \frac{P}{\rho g}$$

$\rho$  = Mass density of the fluid

$h$  = Height of the fluid level in the tank

$A$  = Cross-sectional area of the tank



(a) Storage tank

$$\text{Volume flow rate } Q_1 - Q_2 = Q = A \frac{dh}{dt} = A \frac{d}{dt} \left( \frac{P}{\rho g} \right) = \left( \frac{A}{\rho g} \right) \frac{dP}{dt}$$

$Q$  is equivalent of current and  $P$  is equivalent to voltage

$$Q = \left( \frac{A}{\rho g} \right) \frac{dP}{dt} = C \frac{dP}{dt} \quad C \text{ is equivalent to hydraulic capacitance}$$

# Fluid systems – hydraulic capacitance

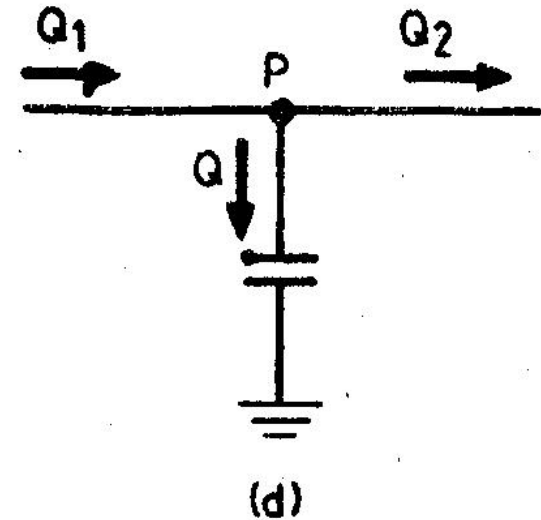
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**Hydraulic capacitance.**

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# Fluid systems - hydraulic capacitance

## Accumulator

$$A_p P = K x_p$$

$A_p$  = **Cross sectional area of the plate**

$x_p$  = **displacement of the plate**

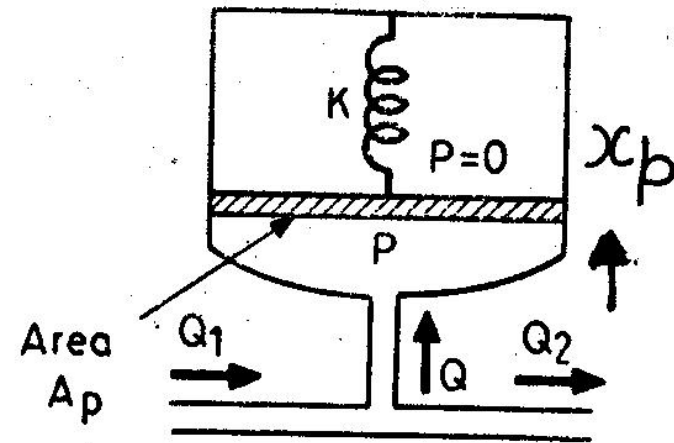
$K$  = **Coefficient of the stiffness of the spring**

$$A_p P = K \int_{-\infty}^t \frac{Q}{A_p} dt$$

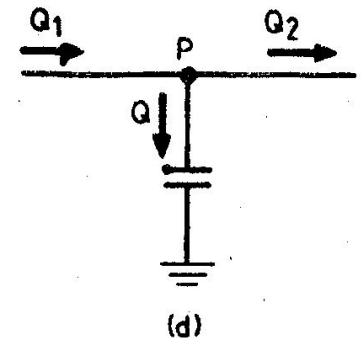
Differentiating above equation

$$A_p \frac{dP}{dt} = K \frac{Q}{A_p}$$

$$Q_1 - Q_2 = Q = \frac{A_p^2}{K} \frac{dP}{dt}$$



(b) Accumulator



(d)

Hydraulic capacitance.

$$C = \frac{A_p^2}{K}$$

# Fluid systems - hydraulic inertance

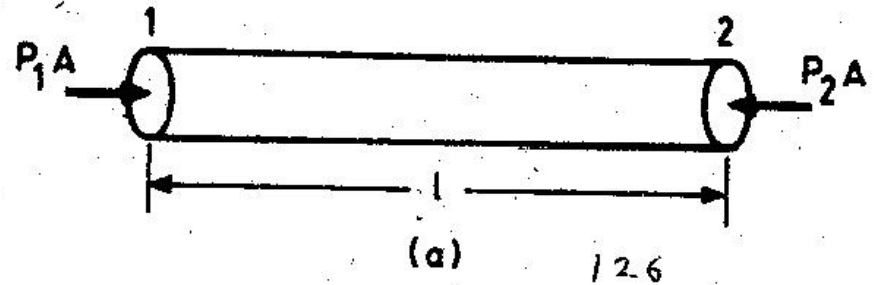
Related to inertia of the fluid

$$P_1 A - P_2 A = \rho A l \frac{dv}{dt}$$

$A$  = Cross-sectional area of the pipe

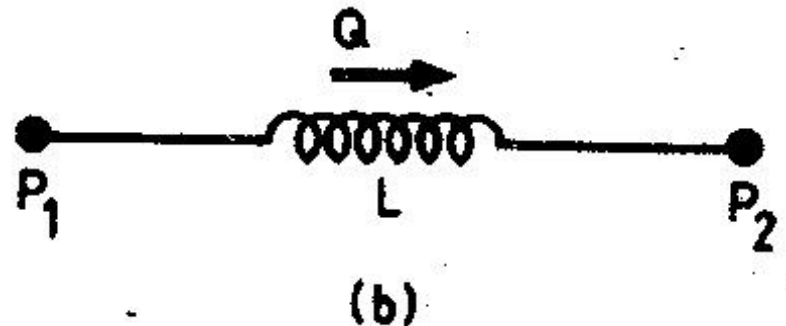
$l$  = length of the pipe

$v = Q / A$  = average fluid velocity in pipe



$$P_1 - P_2 = \frac{\rho l}{A} \frac{dQ}{dt}$$

$$L = \frac{\rho l}{A}$$





# Fluid systems - hydraulic resistance

Related to resistance of the fluid

$$P_1 - P_2 = P = \frac{128l\mu}{\pi D^4} Q \text{ (for laminar flow)}$$

$$P_1 - P_2 = P = \frac{8K_t l \rho}{\pi^2 D^5} Q^2 = K_T Q^2 \text{ (for turbulent flow)}$$

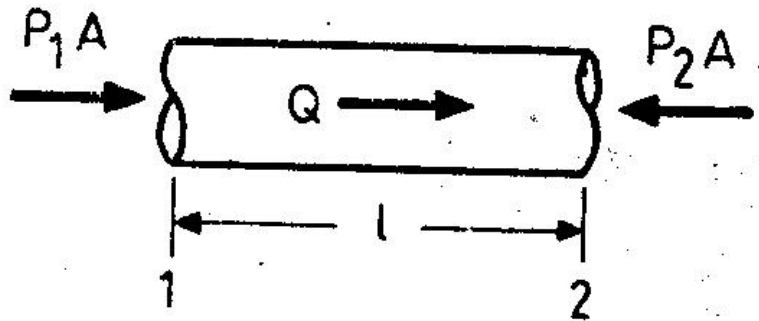
$D$  = Diameter of the pipe

$l$  = length of the pipe

$\mu$  = viscosity of the fluid

$K_t$  = Constant to be determined experimentally

$P = Q R$  analogous to  $e = iR$



# Fluid systems - hydraulic resistance

$$P_1 - P_2 = P = \frac{8K_t l \rho}{\pi^2 D^5} Q^2 = K_T Q^2 \text{ (for turbulent flow)}$$

Resistance is non-linear; Can be linearized about an operating point

Steady state  $P_0 = K_T Q_0^2$

Retaining only the first order terms  
in Taylor series expansion

$$P = P_0 + \frac{dP}{dQ}_{(P_0-Q_0)} (Q - Q_0)$$

$$P - P_0 = 2K_T Q_0 (Q - Q_0)$$

$$\tilde{P} = \tilde{Q} R \quad R = 2K_T Q_0$$

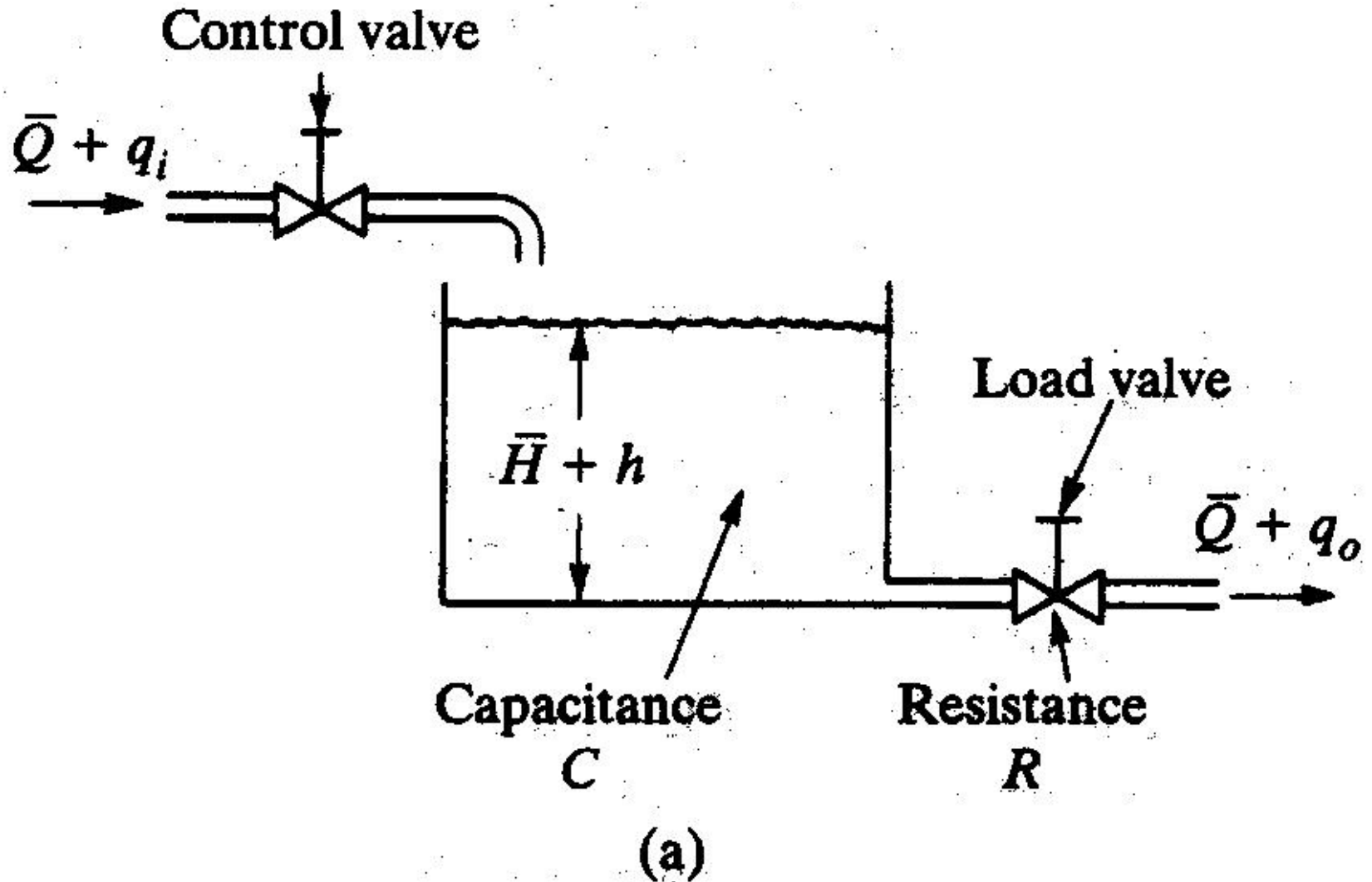
# Fluid systems – Capacitance, inertance resistance

Capacitance : Capacitance of a tank is defined as the change in quantity of stored liquid necessary to cause a unit change in potential or head.

Inertance: Change in potential required to make a unit change in flow rate, velocity or current.

Resistance: Change in level difference (potential) necessary to cause a unit change in flow

# Fluid systems – Fluid tank problem



# Fluid systems – Fluid tank problem

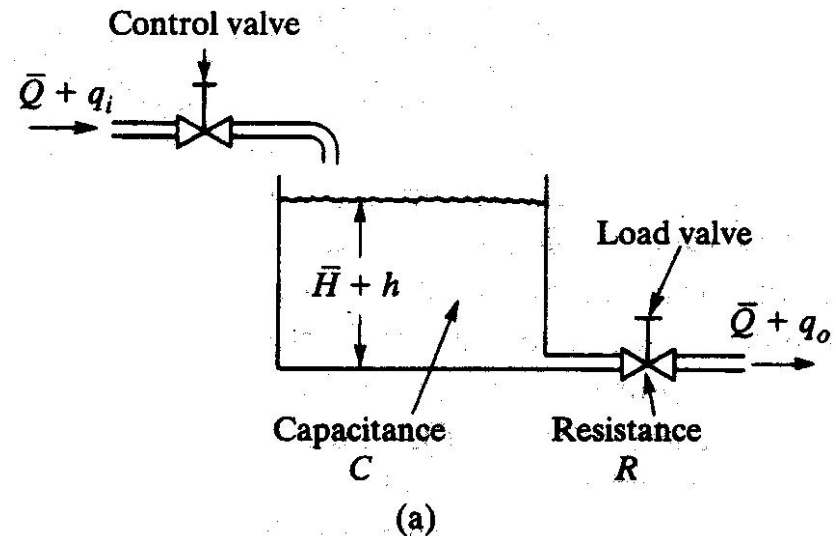
Flow in the valve can be laminar or turbulent

For laminar flow  $Q = K_l H$

$Q$  = Steady state flow rate

$K_l$  = Constant

$H$  = Steady state head



For laminar flow resistance

$$R_l = \frac{dH}{dQ} = \frac{1}{K_l} = \frac{H}{Q}$$

# Fluid systems – Fluid tank problem

Flow in the valve can be laminar or turbulent

For turbulent flow  $Q = K_t \sqrt{H}$

$Q$  = Steady state flow rate

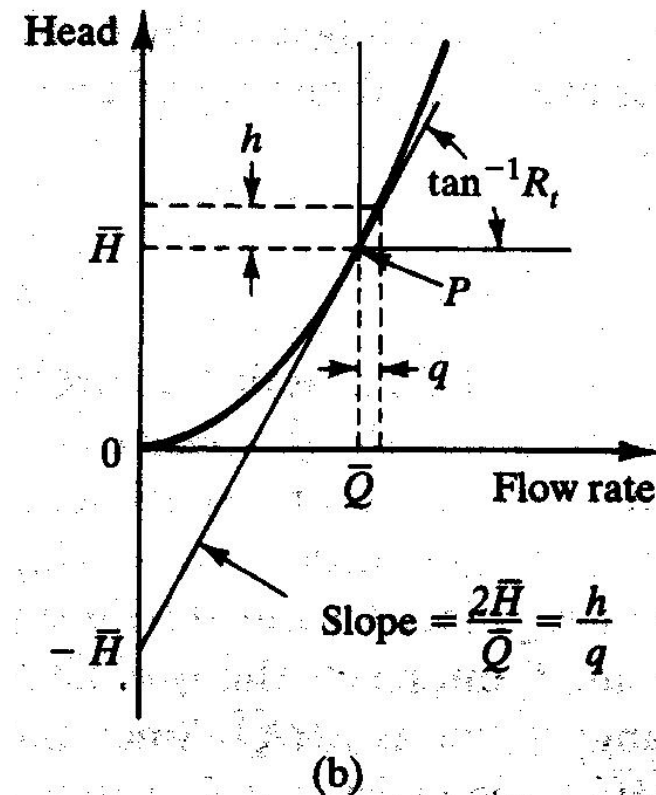
$K_t$  = Constant

$H$  = Steady state head

For turbulent flow resistance  $R_t = \frac{dH}{dQ}$

$$dQ = \frac{K_t}{2\sqrt{H}} dH$$

$$R_t = \frac{2H}{Q}$$



# Fluid systems – Fluid tank problem

$\bar{H}$  = **Steady state head**

$h$  = **Small deviation from Steady state head**

$\bar{Q}$  = **Steady state flow rate**

$q_i$  = **Small deviation of inflow rate from its steady state value**

$q_o$  = **Small deviation of outflow rate from its steady state value**

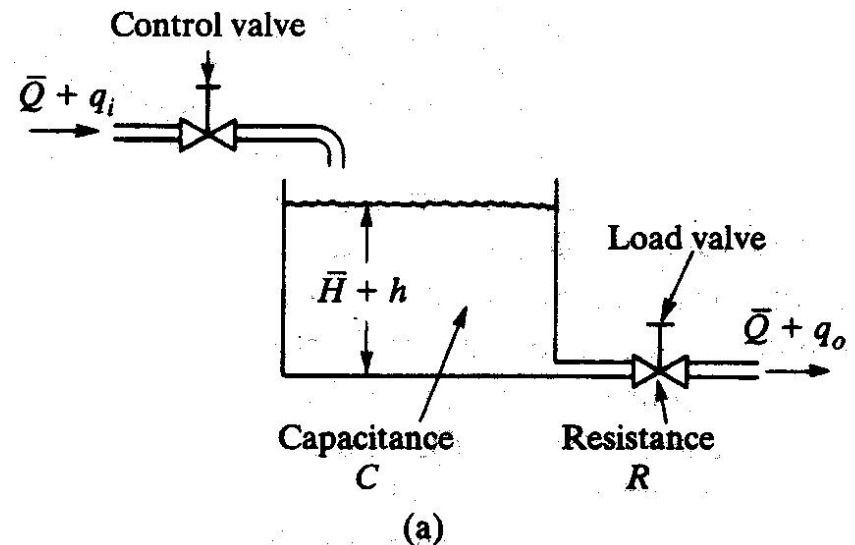
$$Cdh = (q_i - q_o)dt$$

$$R = \frac{dH}{dQ} = \frac{h}{q_o}$$

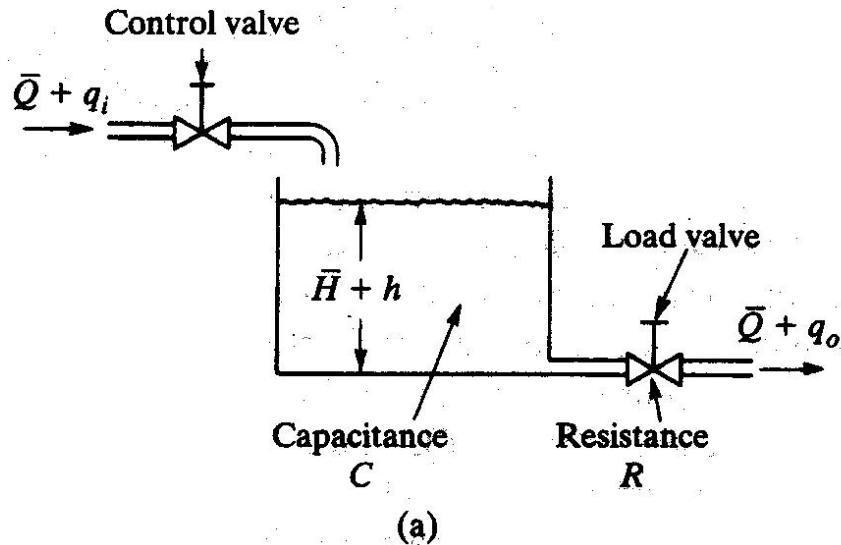
$$C \frac{dh}{dt} = q_i - \frac{h}{R}$$

$$RC \frac{dh}{dt} + h = Rq_i$$

$$RC \frac{dq_o}{dt} + q_o = q_i$$



# Fluid systems – Fluid tank problem



$$RC \frac{dh}{dt} + h = Rq_i$$

$$RC \frac{dq_o}{dt} + q_o = q_i$$

$$RC \frac{de_o}{dt} + e_o = e_i$$

$$\frac{b}{k} \frac{dx_o}{dt} + x_o = x_i$$

