

Lecture 15

Last time we studied numerical methods to solve system of linear equations

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$
$$\vdots$$
$$\vdots$$

$$a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n$$

$$A = (a_{ij}) \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \quad b = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$Ax = b$$

We have a two step procedure to solve this

1) (Gauss Elimination, GE)

We convert $Ax = b$ into equivalent system

$Ux = \tilde{b}$, where U is upper-triangular.

$U = (u_{ij})$ then $u_{ij} = 0$ for $i < j$

(2) We solve $Ux = \tilde{b}$ by back substitution

G E equivalent system
To convert $Ax = b$ into $Ux = \tilde{b}$

We do the following

- 1) We interchange rows
- 2) We subtract one row with a multiply of another row

Operations required to do G E

$O\left(\frac{n^3}{3}\right)$ multiplication / division

$O\left(\frac{n^3}{3}\right)$ addition / subtractions

operation required for back substit

$O\left(\frac{n^2}{2}\right)$ multiplication / division

$O\left(\frac{n^2}{2}\right)$ addition / subtraction

Today we learn

LU factorization

steps used to solve a system $Ax=b$ can be used to factor the matrix A . The factorization is particularly useful when it has the form $A=LU$ where L is lower triangular and U is upper triangular.

Although not all matrices have this type of representation, many do that occur in the study of numerical techniques.

Application :- We would want to solve $Ax=b$ for many different values of b .

If we do GE each time

then we would need $O(n^3/3)$ operation
each time we solve $Ax=b$

On the other hand once $A=LU$

Then we can solve $Ax=b$

as follows

Set $y = Ux$

we solve $LUx = b$

$$Ly = b$$

L is triangular. So determining y requires
 $O(n^2)$ operation

Then solving $Ux = y$
requires only $O(n^2)$ operation

Thus the number of operation needed to solve the system $Ax=b$ is reduced from $O(n^3/3)$ to $O(2n^2)$ when $n \geq 100$ this reduces number of computations by more than 99%.

Construction of LU factorization

Suppose $Ax=b$ can be solved without row interchanges

$$Ax=b$$

$$A = A^{(1)} = (a_{ij}^{(1)})$$

First step in GE process consists of performing for each $j=2,3,\dots,n$

the operations $R_i - m_{ji} R_1$ where $m_{ji} = \frac{a_{ji}^{(1)}}{a_{11}^{(1)}}$

equivalently one can multiply the original matrix A on the left by the matrix

$$M^{(1)} = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ -m_{21} & 1 & 0 & & 0 \\ -m_{31} & 0 & 1 & & 0 \\ \vdots & & & \ddots & \\ -m_{n1} & 0 & 0 & \dots & 1 \end{bmatrix}$$

Set $A = A^{(1)} \quad b = b^{(1)}$

$$A^{(1)} x = b^{(1)}$$

$$M^{(1)} A^{(1)} x = M^{(1)} b^{(1)}$$

Set $A^{(2)} = M^{(1)} A^{(1)}$

$$b^{(2)} = M^{(1)} b^{(1)}$$

so we have system

$$A^{(2)} x = b^{(2)}$$

$A^{(2)}$ has $a_{i1}^{(2)} = 0$ for $i \geq 2$.

In a similar manner we construct $M^{(2)}$, the identity matrix with entries below the diagonal in the second column replaced by the negatives of the multipliers

$$m_{j,2} = \frac{a_{j2}^{(2)}}{a_{22}^{(2)}}$$

$A^{(3)} = M^{(2)} A^{(2)}$ has zeros below the diagonal in first 2 column

$$b^{(3)} = M^{(2)} b^{(2)}$$

So we have $A^{(3)} x = b^{(3)}$

In general with $A^{(k)} x = b^{(k)}$ already formed, multiply both sides by

$$M^{(k)} = \begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & \ddots & & \\ & & & 1 & \\ 0 & & & -m_{k+1,k} & \\ & & & \vdots & \\ & & & & 0 \\ & & & & & 1 \end{bmatrix} \quad \begin{matrix} (k) \\ \vdots \\ (k) \end{matrix}$$

$$A^{(k+1)} = M^{(k)} A^{(k)} = M^{(k)} M^{(k-1)} \dots M^{(1)} A$$

$$b^{(k+1)} = M^{(k)} b^{(k)} = M^{(k)} M^{(k-1)} \dots M^{(1)} b$$

So we have $A^{(k+1)} x = b^{(k+1)}$

The process ends with $A^{(n)} x = b^{(n)}$

where

$$A^{(n)} = \begin{pmatrix} a_{11}^{(1)} & a_{12}^{(1)} & \dots & a_{1n}^{(1)} \\ 0 & a_{22}^{(2)} & \dots & a_{2n}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn}^{(n)} \end{pmatrix}$$

is upper triangular

$$\text{Set } U = A^{(n)}$$

$$\text{Therefore } U = \underline{M^{(n-1)} M^{(n-2)} \dots M^{(1)}} A$$

$$\begin{aligned} \text{Set } L &= \left[M^{(n-1)} M^{(n-2)} \dots M^{(1)} \right]^{-1} \\ &= M^{(1)-1} M^{(2)-1} \dots M^{(n-1)-1} \end{aligned}$$

$$M^{(1)} = \begin{bmatrix} 1 & & & \\ -m_{21} & 1 & & \\ -m_{31} & & 1 & \\ & & & 1 \\ -m_{n1} & & & & 1 \end{bmatrix}$$

$$M^{(1)-1} = \begin{bmatrix} 1 & & & \\ m_{21} & 1 & & \\ m_{31} & & 1 & \\ & & & 1 \\ m_{n1} & & & & 1 \end{bmatrix}$$

And so on.

One can prove that

$$L = \begin{pmatrix} 1 & & & & \\ m_{21} & 1 & & & \\ m_{31} & m_{32} & & & \\ \vdots & & & & \\ m_{n1} & m_{n2} & - & - & - & 1 \end{pmatrix}$$

Example

$$x_1 + x_2 + 0x_3 + 3x_4 = 4$$

$$2x_1 + x_2 - x_3 + x_4 = 1$$

$$3x_1 - x_2 - x_3 + 2x_4 = -3$$

$$-x_1 + 2x_2 + 3x_3 - x_4 = 4$$

Step 1 $R_2 - 2R_1, R_3 - 3R_1, R_4 + R_1$

giving $A^{(2)} = \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & -4 & -1 & -7 \\ 0 & 3 & 3 & 2 \end{pmatrix}$

$$L = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 3 & & 1 & 0 \\ -1 & & & 1 \end{pmatrix}$$

Step 2

$$R_3 - 4R_2$$

$$R_4 + 3R_2$$

$$A^{(3)} = \begin{pmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & 0 & 3 & 13 \\ 0 & 0 & 0 & -13 \end{pmatrix} = U$$

$$L = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 3 & 4 & 1 & 0 \\ -1 & -3 & \underline{\underline{0}} & 1 \end{pmatrix}$$

note

solve

$$Ax = b = \begin{pmatrix} 8 \\ 7 \\ 14 \\ -7 \end{pmatrix}$$

$$\text{Set } y = Ux$$

$$Ly = b$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 3 & 4 & 1 & 0 \\ -1 & -3 & 0 & 1 \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} 8 \\ 7 \\ 14 \\ -7 \end{pmatrix}$$

$$y_1 = 8$$

$$2y_1 + y_2 = 7$$

$$y_2 = 7 - 16 = -9$$

$$3y_1 + 4y_2 + y_3 = 14 \quad \text{so } y_3 = 26$$

$$-y_1 - 3y_2 + y_4 = -7 \quad \text{so } y_4 = -26$$

We then solve $Ux = y$

$$\begin{bmatrix} 1 & 1 & 0 & 3 \\ 0 & -1 & -1 & -5 \\ 0 & 0 & 3 & 13 \\ 0 & 0 & 0 & -13 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{pmatrix} 8 \\ -9 \\ 26 \\ -26 \end{pmatrix}$$

We use "back substitution"

$$-13x_4 = -26$$

$$\text{so } x_4 = 2$$

$$3x_3 + 13x_4 = 26 \Rightarrow x_3 = 0$$

$$-x_2 - x_3 - 5x_4 = -9 \Rightarrow x_2 = -1$$

$$x_1 + x_2 + 3x_4 = 8 \Rightarrow x_1 = 3$$

Two classes of matrices for which Gauss elimination can be performed effectively without row interchanges

- (1) strictly diagonally dominant matrices
- (2) positive definite matrices

Recall

An $n \times n$ matrix $A = (a_{ij})$ is said to be strictly diagonally dominant if

$$|a_{ii}| > \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}|$$

for each $i = 1, 2, \dots, n$

Example

$$A = \begin{bmatrix} 7 & 2 & 0 \\ 3 & 5 & -1 \\ 0 & 5 & -6 \end{bmatrix}$$

A is strictly diagonally dominant

Note $A^t = \begin{bmatrix} 7 & 3 & 0 \\ 2 & 5 & 5 \\ 0 & -1 & -6 \end{bmatrix}$

A^t is not strictly diagonally dominant

Theorem A strictly diagonally dominant matrix A is non-singular.

Proof We prove by contradiction

Suppose A is singular.

So there exists $x \neq 0$ such that

$$Ax = 0$$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

Let k be index for which

$$0 < |x_k| = \max_{1 \leq j \leq n} |x_j|$$

since $\sum_{j=1}^n a_{ij} x_j = 0$ for each $i=1, \dots, n$

we have when $i=k$

$$\sum_{j=1}^n a_{kj} x_j = 0$$

$$\text{So } a_{kk} x_k = - \sum_{\substack{j=1 \\ j \neq k}}^n a_{kj} x_j$$

$$\text{So } |a_{kk}| |x_k| \leq \sum_{\substack{j=1 \\ j \neq k}}^n |a_{kj}| |x_j|$$

$$\text{or } |a_{kk}| \leq \sum_{\substack{j=1 \\ j \neq k}}^n |a_{kj}| \frac{|x_j|}{|x_k|} \leq \sum_{\substack{j=1 \\ j \neq k}}^n |a_{kj}|$$

This inequality contradicts the strict diagonal dominance of A

Positive definite matrices

A matrix A is positive definite

if 1) it is symmetric, i.e. $A^t = A$

2) $x^t A x > 0$ for every
n-dim vector $x \neq 0$

Remark A positive definite
matrix is non-singular

$$\text{for } Ax = 0$$

$$\Rightarrow x^t A x = 0$$

$$\Rightarrow x = 0$$

