




Particle System



HW1
2024 Computer Animation and
Special Effects



Outline

- Overview
- Environment Setup
- Objective
- Report
- Scoring
- Submission
- Note

Overview (cont.)

- Use arrow keys to move, space bar to stop the sphere
- 1 ~ 4 to pin/unpin the corners



Overview (cont.)

- IDE: Visual studio 2019 / Visual studio 2022
- Graphics API: OpenGL
- Dependencies
 - Eigen
 - glfw
 - glad
 - Dear ImGui

Environment Setup

- Download [Visual Studio 2019 – Community](#) or [Visual Studio 2022 - Community](#)

Visual Studio Community 2019 (version 16.11)

No key required [Info](#) 發行日期: 10/Jan/2023 x64 Multiple Lang... exe

[Download](#)

 **Visual Studio 2022** | 

適用於 Windows 上的 .NET 和 C++ 開發人員的最佳全方位 IDE。全套工具和功能，提升和增強軟體開發的每個階段。

[免費下載](#)

社群
功能強大的 IDE，學生、開放原始碼參與者及個人均可免費使用

Professional
Professional IDE 最適合小型小組

[免費試用](#)

Enterprise
可調整的端對端解決方案，適用於任何規模的小組

[免費試用](#)

預覽
搶先使用尚未在主要版本中推出的最新功能

[深入了解](#) >
[版本資訊](#) >

[版本資訊](#) > [比較版本](#) > [如何離線安裝](#) >

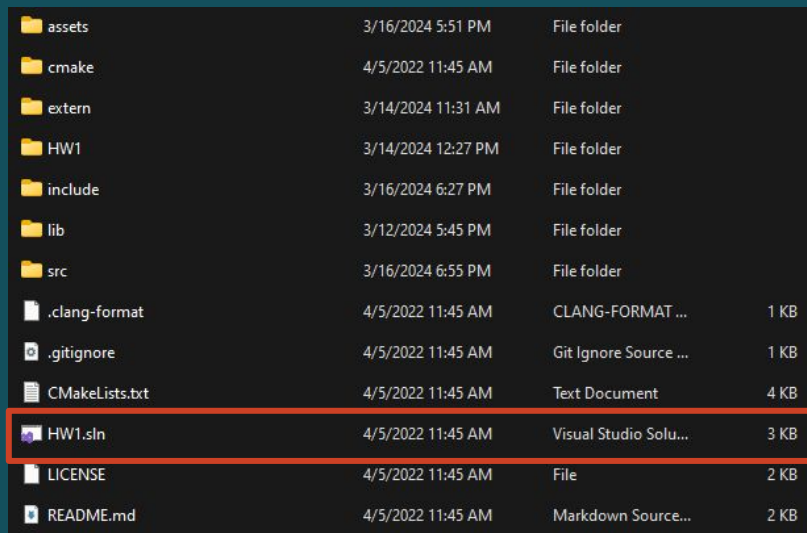
Environment Setup (cont.)

- Launch Visual Studio Installer



Environment Setup (cont.)

- Download HW1.zip and unzip
- Open HW1.sln



assets	3/16/2024 5:51 PM	File folder	
cmake	4/5/2022 11:45 AM	File folder	
extern	3/14/2024 11:31 AM	File folder	
HW1	3/14/2024 12:27 PM	File folder	
include	3/16/2024 6:27 PM	File folder	
lib	3/12/2024 5:45 PM	File folder	
src	3/16/2024 6:55 PM	File folder	
.clang-format	4/5/2022 11:45 AM	CLANG-FORMAT ...	1 KB
.gitignore	4/5/2022 11:45 AM	Git Ignore Source ...	1 KB
CMakeLists.txt	4/5/2022 11:45 AM	Text Document	4 KB
HW1.sln	4/5/2022 11:45 AM	Visual Studio Solu...	3 KB
LICENSE	4/5/2022 11:45 AM	File	2 KB
README.md	4/5/2022 11:45 AM	Markdown Source...	2 KB

Environment Setup (cont.)

- Run the project



- Select config then build (CTRL+SHIFT+B)
- Use F5 to debug or CTRL+F5 to run
 - It will spend a lot of time to debug so release is recommended unless you need debugger

Objective

- src
 - main.cpp
 - cloth.cpp
 - void Cloth::initializeSpring()
 - void Cloth::computeSpringForce()
 - sphere.cpp
 - void Spheres::collide(Cloth* cloth)
 - integrator.cpp
 - void ExplicitEuler::integrate(...)
 - void ImplicitEuler::integrate(...)
 - void MidpointEuler::integrate(...)
 - void RungeKuttaFourth::integrate(...)

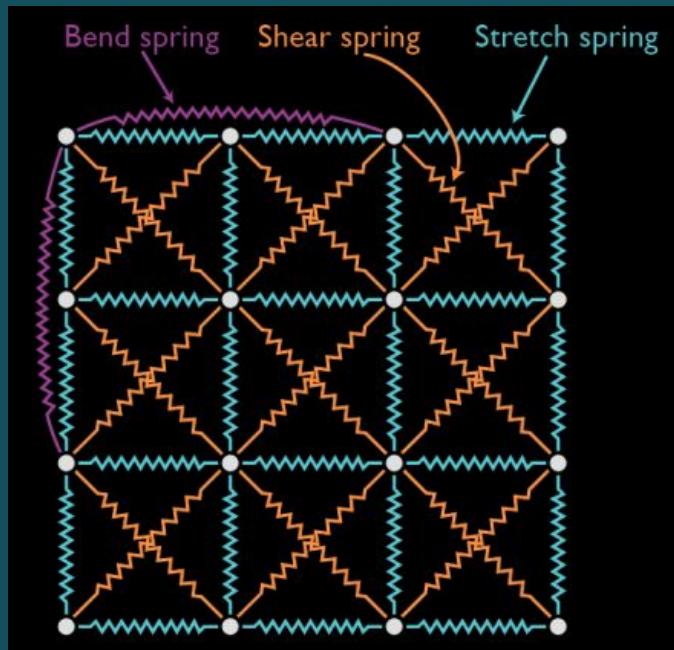
Objective (cont.)

- `int main()`
 - Change the title to your student ID

```
// TODO: change the title to your student ID
GLFWwindow* window = context.createWindow("HW1 987654321", 1280, 720, GLFW_OPENGL_CORE_PROFILE);
```

Objective (cont.)

- `void Cloth::initializeSpring()`
 - Goal
 - Construct the connection of springs
 - Hint
 - You should initialize three types of spring `struct`, `shear` and `bending`



Objective (cont.)

- Put all springs in `std::vector<Spring> _springs`, which is a member in class Cloth
- Here is a sample code of connecting struct springs in the horizontal direction

```
float structrualLength = (_particles.position(0) - _particles.position(1)).norm();
for (int i = 0; i < particlesPerEdge; ++i) {
    for (int j = 0; j < particlesPerEdge - 1; ++j) {
        int index = i * particlesPerEdge + j;
        _springs.emplace_back(index, index + 1, structrualLength, Spring::Type::STRUCTURAL);
    }
}
```

Objective (cont.)

- `void Cloth::computeSpringForce()`
 - Goal
 - Compute spring and damper forces
 - Hint
 - Review “`particles.pptx`” from p.9 - p.13
 - Trace every spring and apply the force accordingly
 - Set acceleration to apply the force
 - You can use `float Particles::inverseMass(int i)` to get the inverse of mass
 - The parameter `springCoef` and `damperCoef` are defined in `config.h`

Objective (cont.)

- `void Spheres::collide(Cloth* cloth)`
 - Goal
 - Handle collision between spheres and cloth
 - Hint
 - Review “`particles.pptx`” from p.14 - p.19
 - You can use their radius and distance to determine whether they are collided
 - The radius of particles of cloth can be regarded as 0

Objective (cont.)

- To compute the velocity after collision
 - You only need to worry about the component of the velocity that is in the direction of the collision
 - You can assume that the sphere is stationary
 - You can refer to this [website](#) for detailed information

$$v_a = \frac{m_a u_a + m_b u_b + m_b C_R (u_b - u_a)}{m_a + m_b}$$

and

$$v_b = \frac{m_a u_a + m_b u_b + m_a C_R (u_a - u_b)}{m_a + m_b}$$

C_R is the coefficient of restitution

Objective (cont.)

- Integrator

- Update particles' position and velocity
- `void ExplicitEulerIntegrator::integrate(...)`
 - Hint: review “ODE_basics.pptx” from p.15 - p.16
- `void ImplicitEulerIntegrator::integrate(...)`
 - Hint: review “ODE_implicit.pptx” from p.18 - p.19
- `void MidpointEulerIntegrator::integrate(...)`
 - Hint: review “ODE_basics.pptx” from p.18 - p.20 and “pbm.pdf” from B.5 - B.6
- `void RungeKuttaFourthIntegrator::integrate(...)`
 - Hint: review “ODE_basics.pptx” p.21 and “pbm.pdf” from B.5 - B.6

Objective (cont.)

- Bonus – constrained particles (optional)
 - Review “constrainedParticles.pptx”, “clothAnimation.pptx” from p.48 - p.52
 - For example
 - A flag (0 dof along an edge)
 - A curtain (1 dof along an edge)
 - ...
 - Don't break original requirements (if it does, make an toggle for switching between requirement parts and bonus parts)
 - Mention it in your report

Report

- Suggested outline
 - Introduction/Motivation
 - Fundamentals
 - Implementation
 - Result and Discussion
 - The difference between integrators
 - Effect of parameters (springCoef, damperCoef, etc.)
 - Bonus (Optional)
 - Conclusion

Scoring

- Change window title to “HW1 **STUDENT_ID**” (0%)
 - -10% if title is wrong
- Construct the connection of springs - 10%
- Compute internal force - 25%
- Handle Collision - 20%
- Integrator - 25%
 - Explicit Euler - 5%
 - Implicit and Midpoint Euler - 5%
 - Runge-Kutta 4th - 15%
- Report - 20%
- Bonus - up to 15%

Submission

- Please upload `hw1_<your student ID>.zip` and `report_< your student ID>.pdf` respectively
- `hw1_<your student ID>.zip` (root)
 - `src`
 - `include`
- Late policies
 - Penalty of 10 points on each day after deadline
- Cheating policies
 - 0 points for any cheating on assignments
- Deadline
 - Monday, 2024/04/01, 23:59

Note

- Read TODOs in the template and follow TODOs' order

```
// TODO: Connect particles with springs.  
// 1. Compute spring length per type.  
// 2. Iterate the particles. Push spring objects into `_springs` vector  
// Note:  
// 1. The particles index:  
// =====  
// 0 1 2 3 ... particlesPerEdge - 1  
// particlesPerEdge ... ..  
// ... .. particlesPerEdge * particlesPerEdge - 1  
// =====
```

- How to contact TAs?
 - Please ask your questions on new E3 forum or send email to ALL TAs via new E3
 - If you need to ask questions face-to-face, please send an email for appointment