



Transfer Learning Enhanced Deep Reinforcement Learning for Volt-Var Control in Smart Grids

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Challenges & Motivation

- How do high penetration levels of photovoltaic (PV) systems impact the stability and reliability of distribution grids, particularly in terms of voltage regulation and power quality?
- How can AI agent be utilized to develop adaptive control policies that enhance the integration of high PV penetration into distribution grids?
- How can designing effective strategies for managing and integrating high PV penetration reduce the need for costly grid upgrades and investments, providing a cost-effective approach to modernizing the grid?

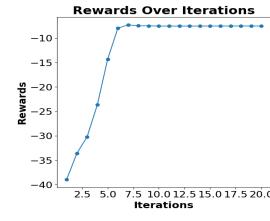
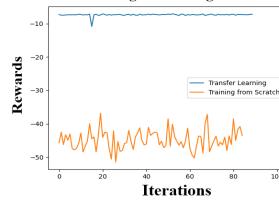
Research Objective:

- Develop a Transfer Learning (TL) with DRL framework to efficiently transfer policy knowledge from one distribution grid to another, enhancing the adaptability and scalability of DRL models.
- Design and implement a policy reuse classifier to determine the suitability of transferring policy knowledge from the IEEE-123 to the IEEE-13 Bus.
- Conduct an impact analysis to evaluate the effectiveness of the TL with DRL technique on the IEEE-13, measuring improvements in training time, computational efficiency, and VVC performance.

Case Study: Transfer Control Policies Knowledge From IEEE-123 to IEEE-13 Bus for VVC

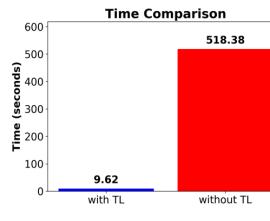
- Transferred the control policies knowledge from IEEE-123 Bus to IEEE-13 Bus test system using policy reuse classifier.
- Performed the effectiveness of the performance using statistical analysis and task adaptation score.

Transfer learning vs Training from scratch



Reward Comparison with and without TL

Total Iterations to adapt in IEEE-13 Bus



Time Comparison for Training

Observations

- The TL techniques for DRL-based VVC environments improved the training time and resources.
- The result shows that control policies are transferred well from the IEEE-123 Bus to the IEEE-13 Bus.

Proposed TL with DRL Framework Methodology for VVC

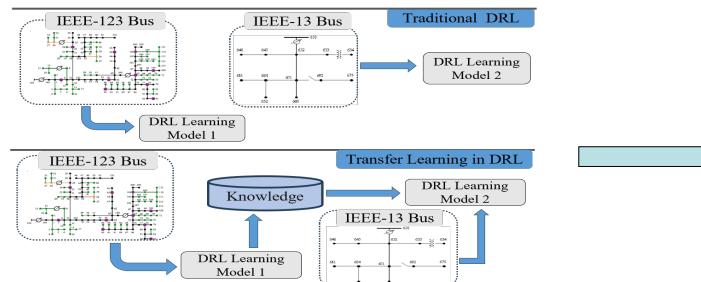


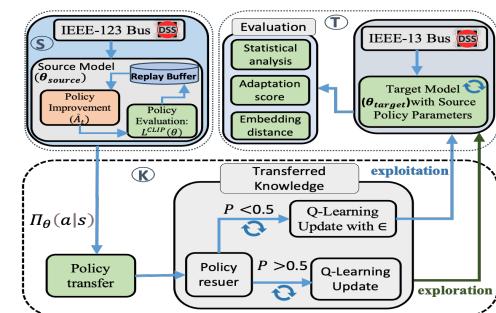
Illustration of Traditional DRL vs TL with DRL

- The reference/source model is trained with the PPO-DRL algorithm for optimal control policies for the IEEE-123 Bus test system.

$$\theta_{\text{source}} = \arg \max_{\theta} \mathbb{E}_{\tau \sim \pi_{\theta}} \left[\sum_{t=0}^T \gamma^t r_t - \beta \text{CLIP}(\theta) \right]$$

- The target model uses the policy reuse classifier, which decides the probability of transferring the control policies from the reference to target environment.

$$\theta_{\text{target}} = \begin{cases} \theta_{\text{source}} & \text{if } P(\text{Reuse}|\text{Observation}) > 0.5 \\ \arg \max_{\theta} \mathbb{E}_{\tau \sim \pi_{\theta}} \left[\sum_{t=0}^T \gamma^t r_t \right] & \text{otherwise} \end{cases}$$



Proposed framework for TL with DRL for VVC

Performance Metric:

Metric	Transfer learning	Training from Scratch
TAS	72.78	-
ED	31.11	-
T-Statistic	102.93	-
P-Value	6.38	-
Mean Reward	-8.310	-27.256
Training_time	9.62 sec	518.38 sec

Conclusion and Future Work

- The proposed TL with DRL framework addresses challenges of high PV penetration in distribution grids.
- Control policy performance improved by 69.51%.
- Training time reduced by 98.14%.
- Successfully transferred knowledge from the IEEE-123 Bus to the IEEE-13 Bus system which demonstrated the adaptability and scalability of the approach.
- Provided a cost-effective solution for modernizing grids with high renewable energy integration.

Future Work:

- Develop more sophisticated control policies for dynamic grid topologies and enhance the TL with DRL framework to handle real-time grid condition changes.
- Improve the robustness and flexibility of control strategies and further reduce computational resources.