

k-Nearest Neighbor (kNN) exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the [assignments page](https://compsci682-fa19.github.io/assignments2019/assignment1) (<https://compsci682-fa19.github.io/assignments2019/assignment1>) on the course website.

The kNN classifier consists of two stages:

- During training, the classifier takes the training data and simply remembers it
- During testing, kNN classifies every test image by comparing to all training images and transferring the labels of the k most similar training examples
- The value of k is cross-validated

In this exercise you will implement these steps and understand the basic Image Classification pipeline, cross-validation, and gain proficiency in writing efficient, vectorized code.

In [1]:

```
# Run some setup code for this notebook.
from __future__ import print_function

import random
import numpy as np
from cs682.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

# This is a bit of magic to make matplotlib figures appear inline in the notebook
# rather than in a new window.
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# Some more magic so that the notebook will reload external python modules;
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

In [2]:

```
# Load the raw CIFAR-10 data.
cifar10_dir = 'cs682/datasets/cifar-10-batches-py'

# Cleaning up variables to prevent loading data multiple times (which may cause
memory issue)
try:
    del X_train, y_train
    del X_test, y_test
    print('Clear previously loaded data.')
except:
    pass

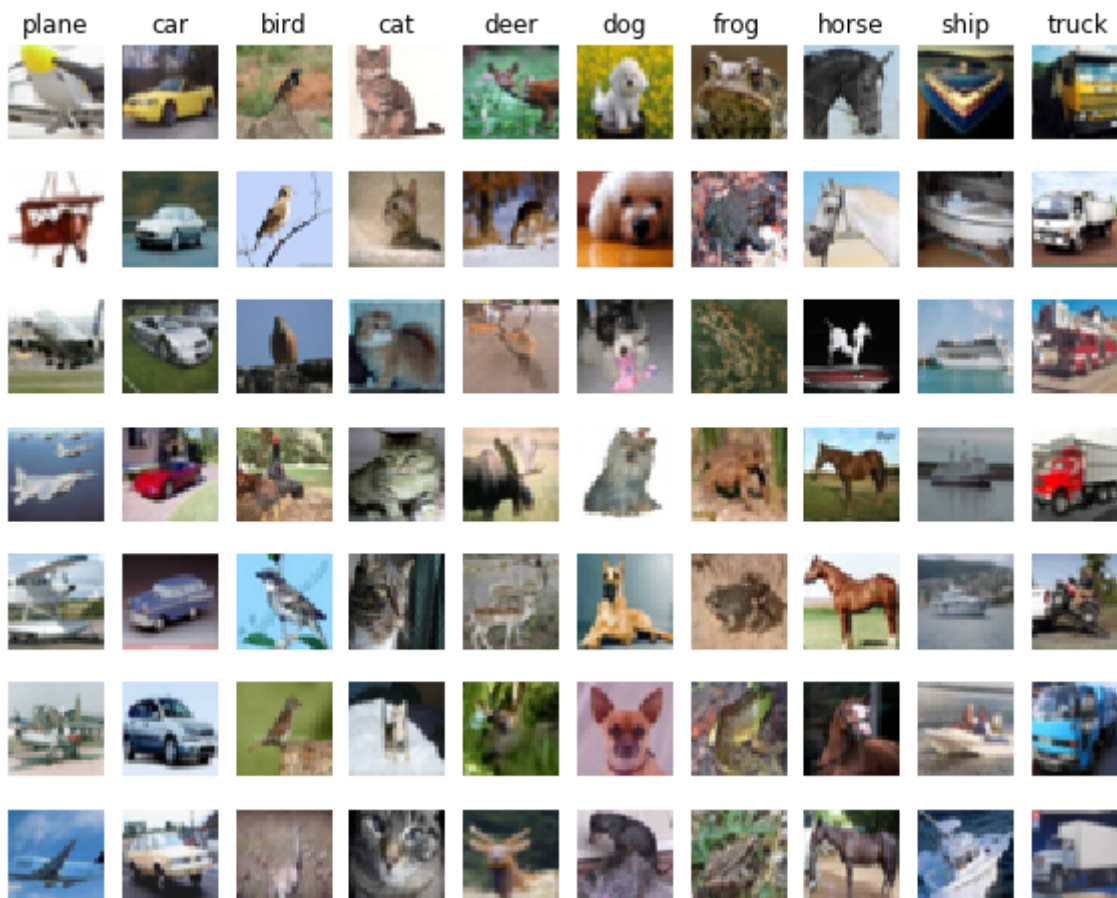
X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

# As a sanity check, we print out the size of the training and test data.
print('Training data shape: ', X_train.shape)
print('Training labels shape: ', y_train.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

```
Training data shape: (50000, 32, 32, 3)
Training labels shape: (50000,)
Test data shape: (10000, 32, 32, 3)
Test labels shape: (10000,)
```

In [3]:

```
# Visualize some examples from the dataset.
# We show a few examples of training images from each class.
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship',
            'truck']
num_classes = len(classes)
samples_per_class = 7
for y, cls in enumerate(classes):
    idxs = np.flatnonzero(y_train == y)
    idxs = np.random.choice(idxs, samples_per_class, replace=False)
    for i, idx in enumerate(idxs):
        plt_idx = i * num_classes + y + 1
        plt.subplot(samples_per_class, num_classes, plt_idx)
        plt.imshow(X_train[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls)
plt.show()
```



In [4]:

```
# Subsample the data for more efficient code execution in this exercise
num_training = 5000
mask = list(range(num_training))
X_train = X_train[mask]
y_train = y_train[mask]

num_test = 500
mask = list(range(num_test))
X_test = X_test[mask]
y_test = y_test[mask]
```

In [5]:

```
# Reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))
print(X_train.shape, X_test.shape)

(5000, 3072) (500, 3072)
```

In [6]:

```
from cs682.classifiers import KNearestNeighbor

# Create a kNN classifier instance.
# Remember that training a kNN classifier is a noop:
# the Classifier simply remembers the data and does no further processing
classifier = KNearestNeighbor()
classifier.train(X_train, y_train)
```

We would now like to classify the test data with the kNN classifier. Recall that we can break down this process into two steps:

1. First we must compute the distances between all test examples and all train examples.
2. Given these distances, for each test example we find the k nearest examples and have them vote for the label

Lets begin with computing the distance matrix between all training and test examples. For example, if there are **Ntr** training examples and **Nte** test examples, this stage should result in a **Nte x Ntr** matrix where each element (i,j) is the distance between the i-th test and j-th train example.

First, open `cs682/classifiers/k_nearest_neighbor.py` and implement the function `compute_distances_two_loops` that uses a (very inefficient) double loop over all pairs of (test, train) examples and computes the distance matrix one element at a time.

In [7]:

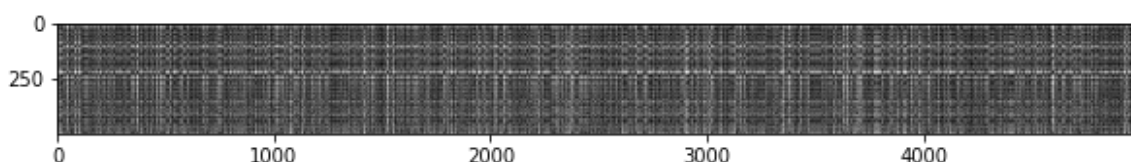
```
# Open cs682/classifiers/k_nearest_neighbor.py and implement
# compute_distances_two_loops.

# Test your implementation:
dists = classifier.compute_distances_two_loops(X_test)
print(dists.shape)

(500, 5000)
```

In [8]:

```
# We can visualize the distance matrix: each row is a single test example and
# its distances to training examples
plt.imshow(dists, interpolation='none')
plt.show()
```



Inline Question #1: Notice the structured patterns in the distance matrix, where some rows or columns are visible brighter. (Note that with the default color scheme black indicates low distances while white indicates high distances.)

- What in the data is the cause behind the distinctly bright rows?
- What causes the columns?

Your Answer: Each value in the distance matrix represents the euclidean distance (L2) between the pixel values of an image from the test set and that of from the training set. Here, the rows represent a test set and the columns represent the training set.

1. Distinctly bright rows represent images from the test set that have noticeably different intensity values from all the images in the training set
2. Distinctly bright columns represent images from the training set that have noticeably different intensity values from all the images in the test set

In [9]:

```
# Now implement the function predict_labels and run the code below:
# We use k = 1 (which is Nearest Neighbor).
y_test_pred = classifier.predict_labels(dists, k=1)

# Compute and print the fraction of correctly predicted examples
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

Got 137 / 500 correct => accuracy: 0.274000

You should expect to see approximately 27% accuracy. Now lets try out a larger k, say k = 5 :

In [10]:

```
y_test_pred = classifier.predict_labels(dists, k=5)
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

Got 145 / 500 correct => accuracy: 0.290000

You should expect to see a slightly better performance than with k = 1 .

Inline Question 2 We can also other distance metrics such as L1 distance. The performance of a Nearest Neighbor classifier that uses L1 distance will not change if (Select all that apply.):

1. The data is preprocessed by subtracting the mean.
2. The data is preprocessed by subtracting the mean and dividing by the standard deviation.
3. The coordinate axes for the data are rotated.
4. None of the above. (Mean and standard deviation in (1) and (2) are vectors and can be different across dimensions) *Your Answer:* 1, 2

Your explanation:

1. Let the original distance be $|x - y|$. After subtraction the mean of the dimension, $|(x - m) - (y - m)| = |x - m - y + m| = |x - y|$, the distance remains the same
2. Preprocessing the data by subtracting the mean and dividing by the standard deviation, normalizes the data with mean = 0 and std = 1. This does not change the performance of the k-NN classifier
3. The relative distances do not hold with L1 after the data are rotated.

In [11]:

```
# Now lets speed up distance matrix computation by using partial vectorization
# with one loop. Implement the function compute_distances_one_loop and run the
# code below:
dists_one = classifier.compute_distances_one_loop(X_test)

# To ensure that our vectorized implementation is correct, we make sure that it
# agrees with the naive implementation. There are many ways to decide whether
# two matrices are similar; one of the simplest is the Frobenius norm. In case
# you haven't seen it before, the Frobenius norm of two matrices is the square
# root of the squared sum of differences of all elements; in other words, reshap
e
# the matrices into vectors and compute the Euclidean distance between them.
difference = np.linalg.norm(dists - dists_one, ord='fro')
print('Difference was: %f' % (difference, ))
if difference < 0.001:
    print('Good! The distance matrices are the same')
else:
    print('Uh-oh! The distance matrices are different')
```

Difference was: 0.000000

Good! The distance matrices are the same

In [12]:

```
# Now implement the fully vectorized version inside compute_distances_no_loops
# and run the code
dists_two = classifier.compute_distances_no_loops(X_test)

# check that the distance matrix agrees with the one we computed before:
difference = np.linalg.norm(dists - dists_two, ord='fro')
print('Difference was: %f' % (difference, ))
if difference < 0.001:
    print('Good! The distance matrices are the same')
else:
    print('Uh-oh! The distance matrices are different')
```

Difference was: 0.000000

Good! The distance matrices are the same

In [14]:

```
# Let's compare how fast the implementations are
def time_function(f, *args):
    """
    Call a function f with args and return the time (in seconds) that it took to
    execute.
    """
    import time
    tic = time.time()
    f(*args)
    toc = time.time()
    return toc - tic

two_loop_time = time_function(classifier.compute_distances_two_loops, X_test)
print('Two loop version took %f seconds' % two_loop_time)

one_loop_time = time_function(classifier.compute_distances_one_loop, X_test)
print('One loop version took %f seconds' % one_loop_time)

no_loop_time = time_function(classifier.compute_distances_no_loops, X_test)
print('No loop version took %f seconds' % no_loop_time)

# you should see significantly faster performance with the fully vectorized impl
mentation
```

Two loop version took 33.365682 seconds

One loop version took 31.677212 seconds

No loop version took 9.560447 seconds

Cross-validation

We have implemented the k-Nearest Neighbor classifier but we set the value $k = 5$ arbitrarily. We will now determine the best value of this hyperparameter with cross-validation.

In [15]:

```

num_folds = 5
k_choices = [1, 3, 5, 8, 10, 12, 15, 20, 50, 100]

X_train_folds = []
y_train_folds = []
#####
# TODO:
# Split up the training data into folds. After splitting, X_train_folds and
# y_train_folds should each be lists of length num_folds, where
# y_train_folds[i] is the label vector for the points in X_train_folds[i].
# Hint: Look up the numpy array_split function.
#####
X_train_folds = np.array_split(X_train, num_folds, axis=0)
y_train_folds = np.array_split(y_train, num_folds)
#####
#                                     END OF YOUR CODE
#####

# A dictionary holding the accuracies for different values of k that we find
# when running cross-validation. After running cross-validation,
# k_to_accuracies[k] should be a list of length num_folds giving the different
# accuracy values that we found when using that value of k.
k_to_accuracies = {}

#####
# TODO:
# Perform k-fold cross validation to find the best value of k. For each
# possible value of k, run the k-nearest-neighbor algorithm num_folds times,
# where in each case you use all but one of the folds as training data and the
# last fold as a validation set. Store the accuracies for all fold and all
# values of k in the k_to_accuracies dictionary.
#####

for i in range(num_folds):
    # Populate the cross validation subsets
    X_train_subset = np.vstack(tuple(X_train_folds[:i] + X_train_folds[i+1:]))
    y_train_subset = np.concatenate(tuple(y_train_folds[:i] + y_train_folds[i+1
:]))

    # kNN classifier instance.
    classifier = KNearestNeighbor()
    classifier.train(X_train_subset, y_train_subset)
    dists_cv = classifier.compute_distances_no_loops(X_train_folds[i])

    for k in k_choices:

        y_test_pred_cv = classifier.predict_labels(dists_cv, k)
        num_correct_cv = np.sum(y_test_pred_cv == y_train_folds[i])
        accuracy = float(num_correct_cv) / np.shape(X_train_folds)[0]

        if k not in k_to_accuracies:
            k_to_accuracies[k] = []
        k_to_accuracies[k].append(accuracy)
#####
#                                     END OF YOUR CODE
#####

# Print out the computed accuracies

```

```
for k in sorted(k_to_accuracies):  
    for accuracy in k_to_accuracies[k]:  
        print('k = %d, accuracy = %f' % (k, accuracy))
```

```
k = 1, accuracy = 52.600000  
k = 1, accuracy = 51.400000  
k = 1, accuracy = 52.800000  
k = 1, accuracy = 55.600000  
k = 1, accuracy = 53.200000  
k = 3, accuracy = 51.400000  
k = 3, accuracy = 52.600000  
k = 3, accuracy = 54.600000  
k = 3, accuracy = 56.400000  
k = 3, accuracy = 54.000000  
k = 5, accuracy = 53.000000  
k = 5, accuracy = 55.000000  
k = 5, accuracy = 59.000000  
k = 5, accuracy = 59.600000  
k = 5, accuracy = 56.800000  
k = 8, accuracy = 54.400000  
k = 8, accuracy = 59.000000  
k = 8, accuracy = 56.800000  
k = 8, accuracy = 59.600000  
k = 8, accuracy = 58.000000  
k = 10, accuracy = 54.400000  
k = 10, accuracy = 60.600000  
k = 10, accuracy = 57.800000  
k = 10, accuracy = 58.400000  
k = 10, accuracy = 57.000000  
k = 12, accuracy = 54.200000  
k = 12, accuracy = 61.000000  
k = 12, accuracy = 57.000000  
k = 12, accuracy = 57.800000  
k = 12, accuracy = 56.200000  
k = 15, accuracy = 52.000000  
k = 15, accuracy = 60.400000  
k = 15, accuracy = 58.400000  
k = 15, accuracy = 58.400000  
k = 15, accuracy = 57.000000  
k = 20, accuracy = 53.600000  
k = 20, accuracy = 58.600000  
k = 20, accuracy = 58.200000  
k = 20, accuracy = 57.400000  
k = 20, accuracy = 57.200000  
k = 50, accuracy = 54.600000  
k = 50, accuracy = 58.200000  
k = 50, accuracy = 54.800000  
k = 50, accuracy = 53.400000  
k = 50, accuracy = 54.600000  
k = 100, accuracy = 52.200000  
k = 100, accuracy = 54.400000  
k = 100, accuracy = 53.400000  
k = 100, accuracy = 52.000000  
k = 100, accuracy = 53.400000
```

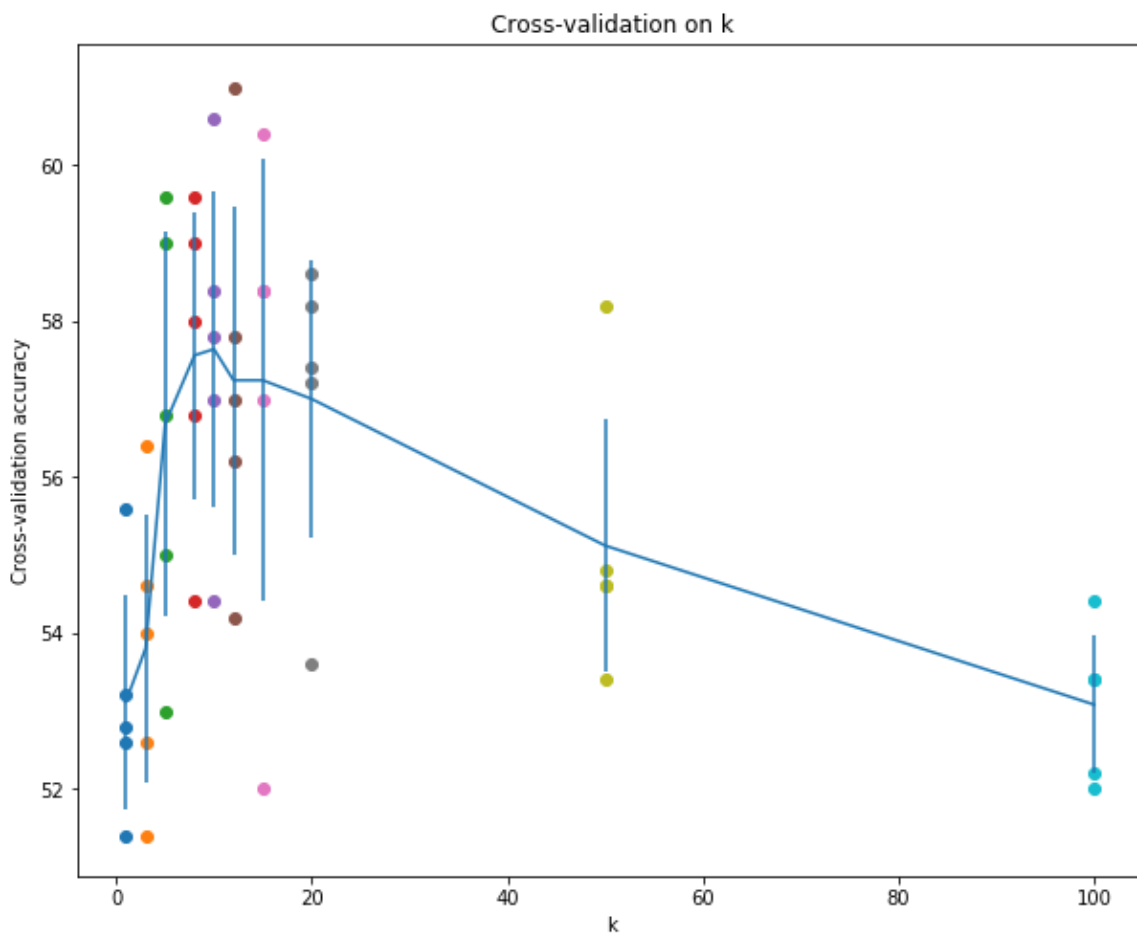
In [16]:

```

# plot the raw observations
for k in k_choices:
    accuracies = k_to_accuracies[k]
    plt.scatter([k] * len(accuracies), accuracies)

# plot the trend line with error bars that correspond to standard deviation
accuracies_mean = np.array([np.mean(v) for k,v in sorted(k_to_accuracies.items
())])
accuracies_std = np.array([np.std(v) for k,v in sorted(k_to_accuracies.items
())])
plt.errorbar(k_choices, accuracies_mean, yerr=accuracies_std)
plt.title('Cross-validation on k')
plt.xlabel('k')
plt.ylabel('Cross-validation accuracy')
plt.show()

```



In [17]:

```
# Based on the cross-validation results above, choose the best value for k,
# retrain the classifier using all the training data, and test it on the test
# data. You should be able to get above 28% accuracy on the test data.
best_k = 7

classifier = KNearestNeighbor()
classifier.train(X_train, y_train)
y_test_pred = classifier.predict(X_test, k=best_k)

# Compute and display the accuracy
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

Got 146 / 500 correct => accuracy: 0.292000

Inline Question 3 Which of the following statements about k -Nearest Neighbor (k -NN) are true in a classification setting, and for all k ? Select all that apply.

1. The training error of a 1-NN will always be better than or equal to that of 5-NN.
2. The test error of a 1-NN will always be better than that of a 5-NN.
3. The decision boundary of the k -NN classifier is linear.
4. The time needed to classify a test example with the k -NN classifier grows with the size of the training set.
5. None of the above.

Your Answer: 1, 4

Your explanation:

1. The training error of a 1-NN will always be 0 since the nearest neighbor of each example will be itself.
2. The test error of a 1-NN will differ in comparison to that of a 5-NN. The errors will vary based on the data. However, in most cases, a 5-NN will be more a generalized classifier since the label is an average of the 5 nearest neighbor rather than just 1.
3. The decision boundary of a k -NN classifier is non-linear. This is so because the distance functions (L1, L2, etc) used to find the k nearest neighbors are not linear, so it usually won't lead to a linear decision boundary.
4. When we classify a test example, we compute the distance between the test example and each example in the training set to find the k nearest neighbors. Therefore, with more examples in the training set, we have to compute more distances.

Multiclass Support Vector Machine exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the [assignments page](https://compsci682-fa19.github.io/assignments2019/assignment1/) (<https://compsci682-fa19.github.io/assignments2019/assignment1/>) on the course website.

In this exercise you will:

- implement a fully-vectorized **loss function** for the SVM
- implement the fully-vectorized expression for its **analytic gradient**
- **check your implementation** using numerical gradient
- use a validation set to **tune the learning rate and regularization strength**
- **optimize** the loss function with **SGD**
- **visualize** the final learned weights

In [1]:

```
# Run some setup code for this notebook.
from __future__ import print_function
import random
import numpy as np
from cs682.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

# This is a bit of magic to make matplotlib figures appear inline in the
# notebook rather than in a new window.
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# Some more magic so that the notebook will reload external python modules;
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

CIFAR-10 Data Loading and Preprocessing

In [2]:

```
# Load the raw CIFAR-10 data.
cifar10_dir = 'cs682/datasets/cifar-10-batches-py'

# Cleaning up variables to prevent loading data multiple times (which may cause
memory issue)
try:
    del X_train, y_train
    del X_test, y_test
    print('Clear previously loaded data.')
except:
    pass

X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

# As a sanity check, we print out the size of the training and test data.
print('Training data shape: ', X_train.shape)
print('Training labels shape: ', y_train.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

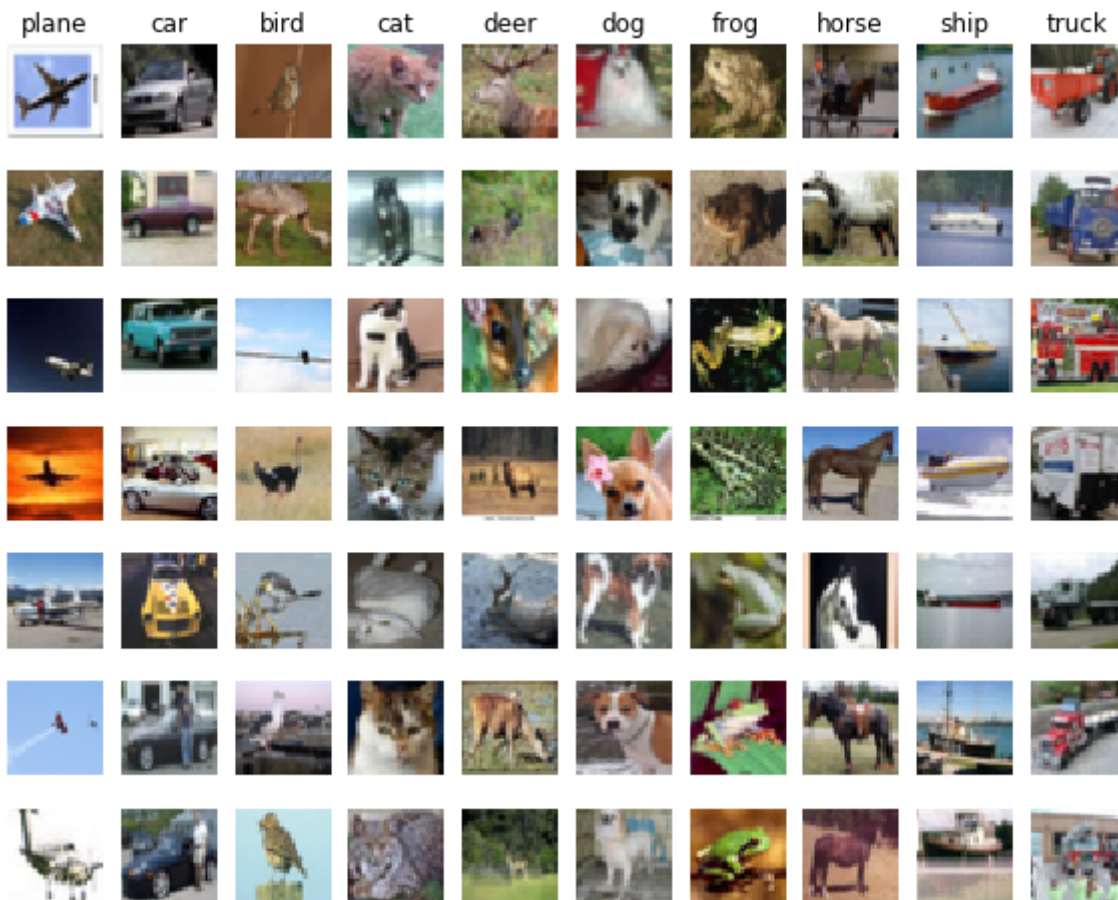
```
Training data shape: (50000, 32, 32, 3)
Training labels shape: (50000,)
Test data shape: (10000, 32, 32, 3)
Test labels shape: (10000,)
```

In [3]:

```

# Visualize some examples from the dataset.
# We show a few examples of training images from each class.
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
num_classes = len(classes)
samples_per_class = 7
for y, cls in enumerate(classes):
    idxs = np.flatnonzero(y_train == y)
    idxs = np.random.choice(idxs, samples_per_class, replace=False)
    for i, idx in enumerate(idxs):
        plt_idx = i * num_classes + y + 1
        plt.subplot(samples_per_class, num_classes, plt_idx)
        plt.imshow(X_train[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls)
plt.show()

```



In [4]:

```
# Split the data into train, val, and test sets. In addition we will
# create a small development set as a subset of the training data;
# we can use this for development so our code runs faster.
num_training = 49000
num_validation = 1000
num_test = 1000
num_dev = 500

# Our validation set will be num_validation points from the original
# training set.
mask = range(num_training, num_training + num_validation)
X_val = X_train[mask]
y_val = y_train[mask]

# Our training set will be the first num_train points from the original
# training set.
mask = range(num_training)
X_train = X_train[mask]
y_train = y_train[mask]

# We will also make a development set, which is a small subset of
# the training set.
mask = np.random.choice(num_training, num_dev, replace=False)
X_dev = X_train[mask]
y_dev = y_train[mask]

# We use the first num_test points of the original test set as our
# test set.
mask = range(num_test)
X_test = X_test[mask]
y_test = y_test[mask]

print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

```
Train data shape: (49000, 32, 32, 3)
Train labels shape: (49000,)
Validation data shape: (1000, 32, 32, 3)
Validation labels shape: (1000,)
Test data shape: (1000, 32, 32, 3)
Test labels shape: (1000,)
```


In [5]:

```
# Preprocessing: reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_val = np.reshape(X_val, (X_val.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))
X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))

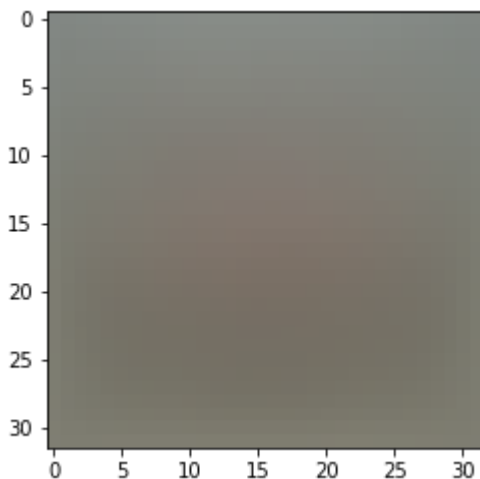
# As a sanity check, print out the shapes of the data
print('Training data shape: ', X_train.shape)
print('Validation data shape: ', X_val.shape)
print('Test data shape: ', X_test.shape)
print('dev data shape: ', X_dev.shape)
```

```
Training data shape: (49000, 3072)
Validation data shape: (1000, 3072)
Test data shape: (1000, 3072)
dev data shape: (500, 3072)
```

In [6]:

```
# Preprocessing: subtract the mean image
# first: compute the image mean based on the training data
mean_image = np.mean(X_train, axis=0)
print(mean_image[:10]) # print a few of the elements
plt.figure(figsize=(4,4))
plt.imshow(mean_image.reshape((32,32,3)).astype('uint8')) # visualize the mean i
mage
plt.show()
```

```
[130.64189796 135.98173469 132.47391837 130.05569388 135.34804082
 131.75402041 130.96055102 136.14328571 132.47636735 131.48467347]
```



In [7]:

```
# second: subtract the mean image from train and test data
X_train -= mean_image
X_val -= mean_image
X_test -= mean_image
X_dev -= mean_image
```

In [8]:

```
# third: append the bias dimension of ones (i.e. bias trick) so that our SVM
# only has to worry about optimizing a single weight matrix W.
X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])

print(X_train.shape, X_val.shape, X_test.shape, X_dev.shape)
```

```
(49000, 3073) (1000, 3073) (1000, 3073) (500, 3073)
```

SVM Classifier

Your code for this section will all be written inside **cs682/classifiers/linear_svm.py**.

As you can see, we have prefilled the function `svm_loss_naive` which uses for loops to evaluate the multiclass SVM loss function.

In [9]:

```
# Evaluate the naive implementation of the loss we provided for you:
from cs682.classifiers.linear_svm import svm_loss_naive
import time

# generate a random SVM weight matrix of small numbers
W = np.random.randn(3073, 10) * 0.0001

loss, grad = svm_loss_naive(W, X_dev, y_dev, 0.000005)
print('loss: %f' % (loss, ))
```

```
loss: 9.073862
```

The `grad` returned from the function above is right now all zero. Derive and implement the gradient for the SVM cost function and implement it inline inside the function `svm_loss_naive`. You will find it helpful to interleave your new code inside the existing function.

To check that you have correctly implemented the gradient correctly, you can numerically estimate the gradient of the loss function and compare the numeric estimate to the gradient that you computed. We have provided code that does this for you:

In [10]:

```
# Once you've implemented the gradient, recompute it with the code below
# and gradient check it with the function we provided for you

# Compute the loss and its gradient at W.
loss, grad = svm_loss_naive(W, X_dev, y_dev, 0.0)

# Numerically compute the gradient along several randomly chosen dimensions, and
# compare them with your analytically computed gradient. The numbers should match
# almost exactly along all dimensions.
from cs682.gradient_check import grad_check_sparse
f = lambda w: svm_loss_naive(w, X_dev, y_dev, 0.0)[0]
grad_numerical = grad_check_sparse(f, W, grad)

# do the gradient check once again with regularization turned on
# you didn't forget the regularization gradient did you?
loss, grad = svm_loss_naive(W, X_dev, y_dev, 5e1)
f = lambda w: svm_loss_naive(w, X_dev, y_dev, 5e1)[0]
grad_numerical = grad_check_sparse(f, W, grad)
```

```
numerical: -39.192483 analytic: -39.192483, relative error: 1.590054e-12
numerical: 12.895098 analytic: 12.895098, relative error: 6.604636e-12
numerical: 5.285776 analytic: 5.285776, relative error: 7.956810e-12
numerical: 8.696481 analytic: 8.696481, relative error: 2.618756e-11
numerical: -53.227029 analytic: -53.227029, relative error: 6.662561e-12
numerical: 8.125639 analytic: 8.125639, relative error: 3.089710e-11
numerical: -23.448604 analytic: -23.448604, relative error: 2.045038e-11
numerical: -41.439736 analytic: -41.439736, relative error: 6.176223e-12
numerical: -2.221601 analytic: -2.221601, relative error: 1.029301e-10
numerical: 7.310186 analytic: 7.310186, relative error: 1.873195e-11
numerical: -15.506266 analytic: -15.506266, relative error: 1.185279e-11
numerical: 19.253898 analytic: 19.253898, relative error: 2.121943e-11
numerical: -8.468002 analytic: -8.468002, relative error: 3.950757e-11
numerical: -7.125721 analytic: -7.125721, relative error: 3.506616e-11
numerical: -16.655677 analytic: -16.655677, relative error: 3.178435e-12
numerical: -38.494505 analytic: -38.494505, relative error: 4.966018e-12
numerical: -16.762696 analytic: -16.762696, relative error: 1.858972e-11
numerical: -12.635094 analytic: -12.628071, relative error: 2.779750e-04
numerical: 14.922341 analytic: 14.922341, relative error: 3.761780e-11
numerical: 19.333585 analytic: 19.333585, relative error: 1.033091e-12
```

Inline Question 1:

It is possible that once in a while a dimension in the gradcheck will not match exactly. What could such a discrepancy be caused by? Is it a reason for concern? What is a simple example in one dimension where a gradient check could fail? How would change the margin affect of the frequency of this happening? *Hint: the SVM loss function is not strictly speaking differentiable*

Your Answer: Yes, it is possible that the dimension in the gradcheck will not match exactly. This can occur when parts of the function are discontinuous ie. not differentiable. The SVM function: $\max(0, x + c)$, where x refers to the difference between the scores for the incorrect classes and correct class and c is a constant, is discontinuous. For example, let's consider a simple function: $f(y) = \max(0, y)$. The analytical gradient at $y = -1e-5$ is 0. However, the numerical gradient will be positive and non zero if h is greater $-1e-5$ since $f(y+h)$ is 1.

In [11]:

```
# Next implement the function svm_loss_vectorized; for now only compute the loss;
# we will implement the gradient in a moment.
tic = time.time()
loss_naive, grad_naive = svm_loss_naive(W, X_dev, y_dev, 0.000005)
toc = time.time()
print('Naive loss: %e computed in %fs' % (loss_naive, toc - tic))

from cs682.classifiers.linear_svm import svm_loss_vectorized
tic = time.time()
loss_vectorized, _ = svm_loss_vectorized(W, X_dev, y_dev, 0.000005)
toc = time.time()
print('Vectorized loss: %e computed in %fs' % (loss_vectorized, toc - tic))

# The losses should match but your vectorized implementation should be much faster.
print('difference: %f' % (loss_naive - loss_vectorized))
```

```
Naive loss: 9.073862e+00 computed in 0.155197s
Vectorized loss: 9.073862e+00 computed in 0.010908s
difference: -0.000000
```

In [12]:

```
# Complete the implementation of svm_loss_vectorized, and compute the gradient
# of the loss function in a vectorized way.

# The naive implementation and the vectorized implementation should match, but
# the vectorized version should still be much faster.
tic = time.time()
_, grad_naive = svm_loss_naive(W, X_dev, y_dev, 0.000005)
toc = time.time()
print('Naive loss and gradient: computed in %fs' % (toc - tic))

tic = time.time()
_, grad_vectorized = svm_loss_vectorized(W, X_dev, y_dev, 0.000005)
toc = time.time()
print('Vectorized loss and gradient: computed in %fs' % (toc - tic))

# The loss is a single number, so it is easy to compare the values computed
# by the two implementations. The gradient on the other hand is a matrix, so
# we use the Frobenius norm to compare them.
difference = np.linalg.norm(grad_naive - grad_vectorized, ord='fro')
print('difference: %f' % difference)
```

```
Naive loss and gradient: computed in 0.111164s
Vectorized loss and gradient: computed in 0.005182s
difference: 0.000000
```

Stochastic Gradient Descent

We now have vectorized and efficient expressions for the loss, the gradient and our gradient matches the numerical gradient. We are therefore ready to do SGD to minimize the loss.

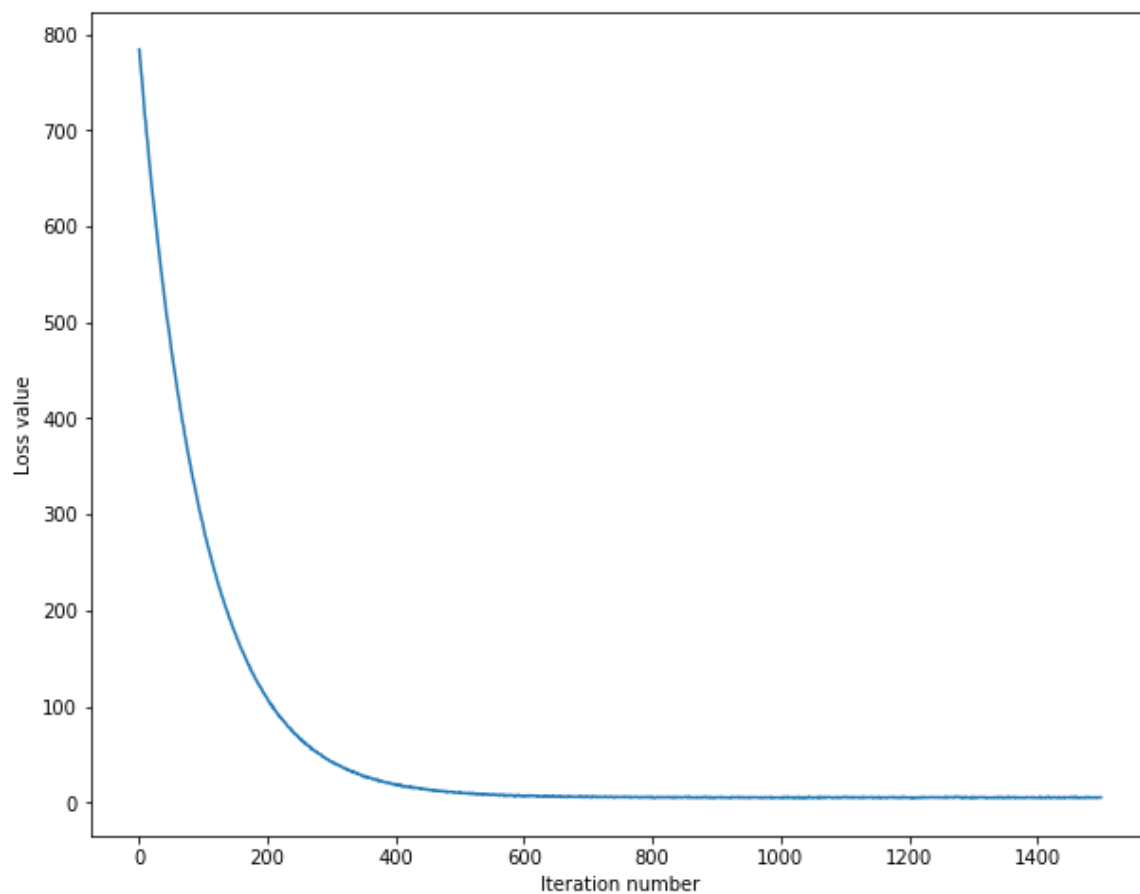
In [13]:

```
# In the file linear_classifier.py, implement SGD in the function  
# LinearClassifier.train() and then run it with the code below.  
from cs682.classifiers import LinearSVM  
svm = LinearSVM()  
tic = time.time()  
loss_hist = svm.train(X_train, y_train, learning_rate=1e-7, reg=2.5e4,  
                      num_iters=1500, verbose=True)  
toc = time.time()  
print('That took %fs' % (toc - tic))
```

```
iteration 0 / 1500: loss 784.044080  
iteration 100 / 1500: loss 286.692431  
iteration 200 / 1500: loss 107.319111  
iteration 300 / 1500: loss 42.370495  
iteration 400 / 1500: loss 18.522366  
iteration 500 / 1500: loss 10.454446  
iteration 600 / 1500: loss 7.203443  
iteration 700 / 1500: loss 5.827619  
iteration 800 / 1500: loss 5.253334  
iteration 900 / 1500: loss 5.114946  
iteration 1000 / 1500: loss 4.757744  
iteration 1100 / 1500: loss 5.528209  
iteration 1200 / 1500: loss 5.244670  
iteration 1300 / 1500: loss 5.446721  
iteration 1400 / 1500: loss 5.101956  
That took 15.071801s
```

In [14]:

```
# A useful debugging strategy is to plot the loss as a function of  
# iteration number:  
plt.plot(loss_hist)  
plt.xlabel('Iteration number')  
plt.ylabel('Loss value')  
plt.show()
```



In [15]:

```
# Write the LinearSVM.predict function and evaluate the performance on both the  
# training and validation set  
y_train_pred = svm.predict(X_train)  
print('training accuracy: %f' % (np.mean(y_train == y_train_pred), ))  
y_val_pred = svm.predict(X_val)  
print('validation accuracy: %f' % (np.mean(y_val == y_val_pred), ))
```

```
training accuracy: 0.367082  
validation accuracy: 0.381000
```


In [16]:

```
# Use the validation set to tune hyperparameters (regularization strength and
# learning rate). You should experiment with different ranges for the learning
# rates and regularization strengths; if you are careful you should be able to
# get a classification accuracy of about 0.4 on the validation set.
learning_rates = [1e-7, 5e-7]
regularization_strengths = [1.5e4, 2e4, 2.5e4, 3.5e4]

# results is dictionary mapping tuples of the form
# (learning_rate, regularization_strength) to tuples of the form
# (training_accuracy, validation_accuracy). The accuracy is simply the fraction
# of data points that are correctly classified.
results = {}
best_val = -1 # The highest validation accuracy that we have seen so far.
best_svm = None # The LinearSVM object that achieved the highest validation rat
e.

#####
# TODO:
# Write code that chooses the best hyperparameters by tuning on the validation #
# set. For each combination of hyperparameters, train a linear SVM on the #
# training set, compute its accuracy on the training and validation sets, and #
# store these numbers in the results dictionary. In addition, store the best #
# validation accuracy in best_val and the LinearSVM object that achieves this #
# accuracy in best_svm.
#
# Hint: You should use a small value for num_iters as you develop your #
# validation code so that the SVMs don't take much time to train; once you are #
# confident that your validation code works, you should rerun the validation #
# code with a larger value for num_iters.
#####
for lr in learning_rates:
    for reg in regularization_strengths:
        # new instance of SVM
        svm = LinearSVM()
        loss_hist = svm.train(X_train, y_train, learning_rate=lr, reg=reg,
                               num_iters=2000, verbose=False)
        # evaluate the performance on the training set
        y_train_pred = svm.predict(X_train)
        train_accuracy = np.mean(y_train == y_train_pred)
        # evaluate the performance on the validation set
        y_val_pred = svm.predict(X_val)
        val_accuracy = np.mean(y_val == y_val_pred)
        # store the results
        results[(lr, reg)] = (train_accuracy, val_accuracy)
        if (val_accuracy > best_val):
            best_val = val_accuracy
            best_svm = svm
#####
#
# END OF YOUR CODE
#
#####

# Print out results.
for lr, reg in sorted(results):
    train_accuracy, val_accuracy = results[(lr, reg)]
    print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
        lr, reg, train_accuracy, val_accuracy))

print('best validation accuracy achieved during cross-validation: %f' % best_val
)
```

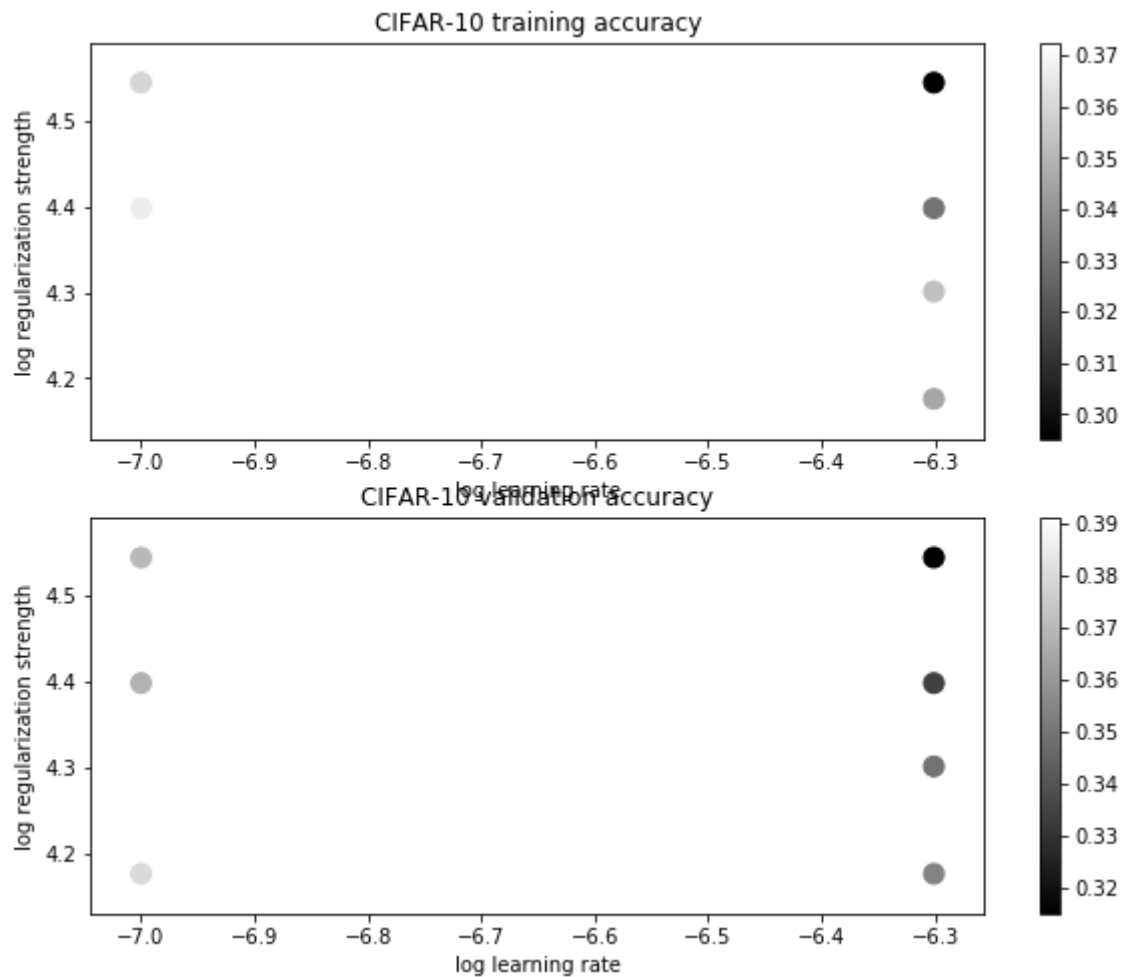
```
lr 1.000000e-07 reg 1.500000e+04 train accuracy: 0.372347 val accuracy: 0.380000
lr 1.000000e-07 reg 2.000000e+04 train accuracy: 0.372224 val accuracy: 0.391000
lr 1.000000e-07 reg 2.500000e+04 train accuracy: 0.366735 val accuracy: 0.368000
lr 1.000000e-07 reg 3.500000e+04 train accuracy: 0.359857 val accuracy: 0.370000
lr 5.000000e-07 reg 1.500000e+04 train accuracy: 0.345306 val accuracy: 0.354000
lr 5.000000e-07 reg 2.000000e+04 train accuracy: 0.353184 val accuracy: 0.349000
lr 5.000000e-07 reg 2.500000e+04 train accuracy: 0.330122 val accuracy: 0.334000
lr 5.000000e-07 reg 3.500000e+04 train accuracy: 0.295286 val accuracy: 0.315000
best validation accuracy achieved during cross-validation: 0.391000
```

In [17]:

```
# Visualize the cross-validation results
import math
x_scatter = [math.log10(x[0]) for x in results]
y_scatter = [math.log10(x[1]) for x in results]

# plot training accuracy
marker_size = 100
colors = [results[x][0] for x in results]
plt.subplot(2, 1, 1)
plt.scatter(x_scatter, y_scatter, marker_size, c=colors)
plt.colorbar()
plt.xlabel('log learning rate')
plt.ylabel('log regularization strength')
plt.title('CIFAR-10 training accuracy')

# plot validation accuracy
colors = [results[x][1] for x in results] # default size of markers is 20
plt.subplot(2, 1, 2)
plt.scatter(x_scatter, y_scatter, marker_size, c=colors)
plt.colorbar()
plt.xlabel('log learning rate')
plt.ylabel('log regularization strength')
plt.title('CIFAR-10 validation accuracy')
plt.show()
```



In [18]:

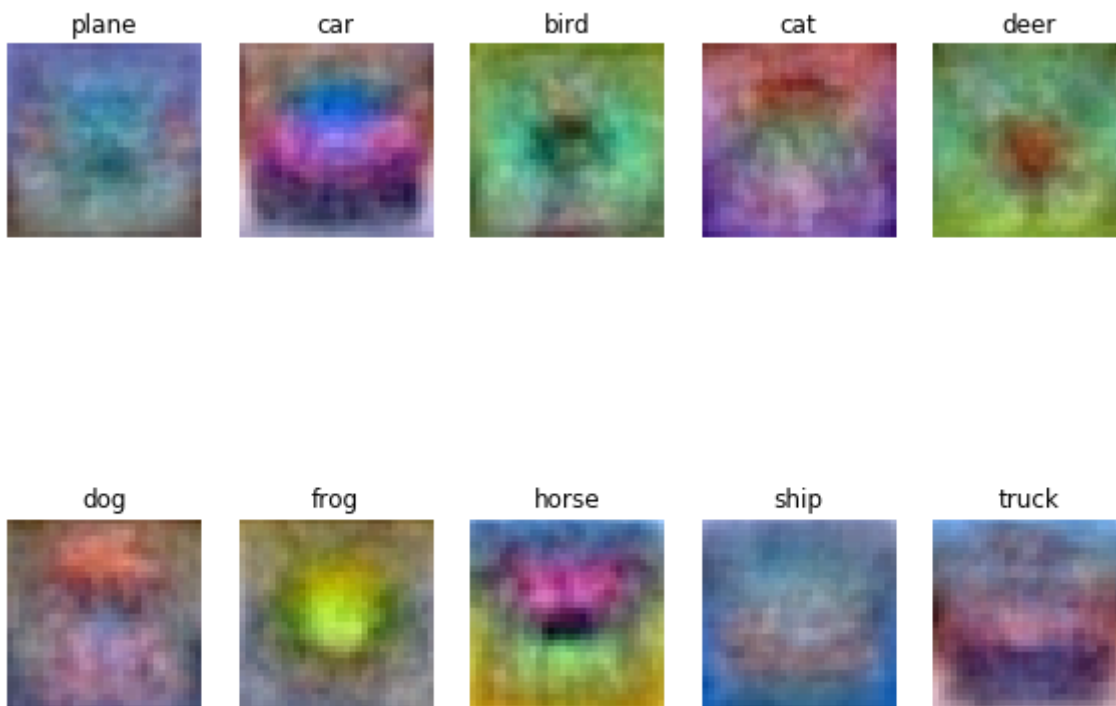
```
# Evaluate the best svm on test set
y_test_pred = best_svm.predict(X_test)
test_accuracy = np.mean(y_test == y_test_pred)
print('linear SVM on raw pixels final test set accuracy: %f' % test_accuracy)
```

linear SVM on raw pixels final test set accuracy: 0.363000

In [19]:

```
# Visualize the learned weights for each class.
# Depending on your choice of learning rate and regularization strength, these may
# or may not be nice to look at.
w = best_svm.W[:-1,:] # strip out the bias
w = w.reshape(32, 32, 3, 10)
w_min, w_max = np.min(w), np.max(w)
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
for i in range(10):
    plt.subplot(2, 5, i + 1)

    # Rescale the weights to be between 0 and 255
    wimg = 255.0 * (w[:, :, :, i].squeeze() - w_min) / (w_max - w_min)
    plt.imshow(wimg.astype('uint8'))
    plt.axis('off')
    plt.title(classes[i])
```



Inline question 2:

Describe what your visualized SVM weights look like, and offer a brief explanation for why they look the way that they do.

Your answer: Since the SVM weights are learnt from the training data, the visualizations look like an average image from the training set for each label. For example, the visualization for a deer has a green background and a cluster of brown pixels in the center. This is possibly because the examples in the training data had deer in forests or with trees in the background. The visualization for a horse has two heads. This is so because the examples in the training set had a set of pictures from different angles.

Softmax exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the [assignments page](https://compsci682-fa19.github.io/assignments2019/assignment1/) (<https://compsci682-fa19.github.io/assignments2019/assignment1/>) on the course website.

This exercise is analogous to the SVM exercise. You will:

- implement a fully-vectorized **loss function** for the Softmax classifier
- implement the fully-vectorized expression for its **analytic gradient**
- **check your implementation** with numerical gradient
- use a validation set to **tune the learning rate and regularization strength**
- **optimize** the loss function with **SGD**
- **visualize** the final learned weights

In [1]:

```
from __future__ import print_function
import random
import numpy as np
from cs682.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading external modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

In [2]:

```

def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000, num_dev=500):
    """
    Load the CIFAR-10 dataset from disk and perform preprocessing to prepare
    it for the linear classifier. These are the same steps as we used for the
    SVM, but condensed to a single function.
    """
    # Load the raw CIFAR-10 data
    cifar10_dir = 'cs682/datasets/cifar-10-batches-py'

    X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

    # subsample the data
    mask = list(range(num_training, num_training + num_validation))
    X_val = X_train[mask]
    y_val = y_train[mask]
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]
    mask = np.random.choice(num_training, num_dev, replace=False)
    X_dev = X_train[mask]
    y_dev = y_train[mask]

    # Preprocessing: reshape the image data into rows
    X_train = np.reshape(X_train, (X_train.shape[0], -1))
    X_val = np.reshape(X_val, (X_val.shape[0], -1))
    X_test = np.reshape(X_test, (X_test.shape[0], -1))
    X_dev = np.reshape(X_dev, (X_dev.shape[0], -1))

    # Normalize the data: subtract the mean image
    mean_image = np.mean(X_train, axis = 0)
    X_train -= mean_image
    X_val -= mean_image
    X_test -= mean_image
    X_dev -= mean_image

    # add bias dimension and transform into columns
    X_train = np.hstack([X_train, np.ones((X_train.shape[0], 1))])
    X_val = np.hstack([X_val, np.ones((X_val.shape[0], 1))])
    X_test = np.hstack([X_test, np.ones((X_test.shape[0], 1))])
    X_dev = np.hstack([X_dev, np.ones((X_dev.shape[0], 1))])

    return X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev

# Cleaning up variables to prevent loading data multiple times (which may cause
# memory issue)
try:
    del X_train, y_train
    del X_test, y_test
    print('Clear previously loaded data.')
except:
    pass

# Invoke the above function to get our data.
X_train, y_train, X_val, y_val, X_test, y_test, X_dev, y_dev = get_CIFAR10_data

```

```
(
print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
print('dev data shape: ', X_dev.shape)
print('dev labels shape: ', y_dev.shape)
```

```
Train data shape: (49000, 3073)
Train labels shape: (49000,)
Validation data shape: (1000, 3073)
Validation labels shape: (1000,)
Test data shape: (1000, 3073)
Test labels shape: (1000,)
dev data shape: (500, 3073)
dev labels shape: (500,)
```

Softmax Classifier

Your code for this section will all be written inside **cs682/classifiers/softmax.py**.

In [3]:

```
# First implement the naive softmax loss function with nested loops.
# Open the file cs682/classifiers/softmax.py and implement the
# softmax_loss_naive function.

from cs682.classifiers.softmax import softmax_loss_naive
import time

# Generate a random softmax weight matrix and use it to compute the loss.
W = np.random.randn(3073, 10) * 0.0001
loss, grad = softmax_loss_naive(W, X_dev, y_dev, 0.0)

# As a rough sanity check, our loss should be something close to -log(0.1).
print('loss: %f' % loss)
print('sanity check: %f' % (-np.log(0.1)))
```

```
loss: 2.337618
sanity check: 2.302585
```

Inline Question 1:

Why do we expect our loss to be close to $-\log(0.1)$? Explain briefly.**

Your answer: Here, the weight matrix is a random set weights. Since we're using the CIFAR-10 dataset, there are 10 classes. Without any learning, on random, the probability of a correct classification is 0.1 and the softmax loss is the negative log of the probability of the correct class ie. $-\log(0.1)$

In [4]:

```
# Complete the implementation of softmax_loss_naive and implement a (naive)
# version of the gradient that uses nested loops.
loss, grad = softmax_loss_naive(W, X_dev, y_dev, 0.0)

# As we did for the SVM, use numeric gradient checking as a debugging tool.
# The numeric gradient should be close to the analytic gradient.
from cs682.gradient_check import grad_check_sparse
f = lambda w: softmax_loss_naive(w, X_dev, y_dev, 0.0)[0]
grad_numerical = grad_check_sparse(f, W, grad, 10)

# similar to SVM case, do another gradient check with regularization
loss, grad = softmax_loss_naive(W, X_dev, y_dev, 5e1)
f = lambda w: softmax_loss_naive(w, X_dev, y_dev, 5e1)[0]
grad_numerical = grad_check_sparse(f, W, grad, 10)
```

```
numerical: -0.702325 analytic: -0.702325, relative error: 8.434424e-
08
numerical: 3.212848 analytic: 3.212847, relative error: 5.669634e-09
numerical: 1.485497 analytic: 1.485497, relative error: 3.899620e-08
numerical: -0.058346 analytic: -0.058346, relative error: 2.205874e-
07
numerical: 0.229335 analytic: 0.229335, relative error: 3.806034e-07
numerical: 3.503413 analytic: 3.503413, relative error: 3.943833e-09
numerical: -1.735472 analytic: -1.735472, relative error: 2.420797e-
08
numerical: -3.558007 analytic: -3.558007, relative error: 2.351884e-
08
numerical: 1.499690 analytic: 1.499690, relative error: 3.377313e-08
numerical: 0.982472 analytic: 0.982471, relative error: 6.262293e-08
numerical: -0.315025 analytic: -0.315025, relative error: 1.025980e-
07
numerical: 3.793594 analytic: 3.793594, relative error: 2.105647e-08
numerical: 2.206939 analytic: 2.206938, relative error: 2.439230e-08
numerical: 2.070291 analytic: 2.070291, relative error: 4.208052e-08
numerical: -1.980808 analytic: -1.980808, relative error: 1.392543e-
08
numerical: 0.736043 analytic: 0.736043, relative error: 1.321836e-08
numerical: 2.634442 analytic: 2.634442, relative error: 1.652637e-08
numerical: 2.535977 analytic: 2.535977, relative error: 1.157886e-08
numerical: 1.540301 analytic: 1.540301, relative error: 4.495272e-08
numerical: 2.846523 analytic: 2.846523, relative error: 2.604984e-09
```

In [5]:

```
# Now that we have a naive implementation of the softmax loss function and its g
radiant,
# implement a vectorized version in softmax_loss_vectorized.
# The two versions should compute the same results, but the vectorized version s
hould be
# much faster.
tic = time.time()
loss_naive, grad_naive = softmax_loss_naive(W, X_dev, y_dev, 0.000005)
toc = time.time()
print('naive loss: %e computed in %fs' % (loss_naive, toc - tic))

from cs682.classifiers.softmax import softmax_loss_vectorized
tic = time.time()
loss_vectorized, grad_vectorized = softmax_loss_vectorized(W, X_dev, y_dev, 0.00
0005)
toc = time.time()
print('vectorized loss: %e computed in %fs' % (loss_vectorized, toc - tic))

# As we did for the SVM, we use the Frobenius norm to compare the two versions
# of the gradient.
grad_difference = np.linalg.norm(grad_naive - grad_vectorized, ord='fro')
print('Loss difference: %f' % np.abs(loss_naive - loss_vectorized))
print('Gradient difference: %f' % grad_difference)
```

```
naive loss: 2.337618e+00 computed in 0.124062s
vectorized loss: 2.337618e+00 computed in 0.005528s
Loss difference: 0.000000
Gradient difference: 0.000000
```

In [6]:

```
# Use the validation set to tune hyperparameters (regularization strength and
# learning rate). You should experiment with different ranges for the learning
# rates and regularization strengths; if you are careful you should be able to
# get a classification accuracy of over 0.35 on the validation set.
from cs682.classifiers import Softmax
results = {}
best_val = -1
best_softmax = None
learning_rates = [1e-5, 1e-6]
regularization_strengths = [1e3, 1.5e3, 2e3]

#####
# TODO:
# Use the validation set to set the learning rate and regularization strength. #
# This should be identical to the validation that you did for the SVM; save #
# the best trained softmax classifier in best_softmax.
#####
for lr in learning_rates:
    for reg in regularization_strengths:
        # new instance of SoftMax
        sm = Softmax()
        loss_hist = sm.train(X_train, y_train, learning_rate=lr, reg=reg,
                             num_iters=1000, verbose=False)
        # evaluate the performance on the training set
        y_train_pred = sm.predict(X_train)
        train_accuracy = np.mean(y_train == y_train_pred)
        # evaluate the performance on the validation set
        y_val_pred = sm.predict(X_val)
        val_accuracy = np.mean(y_val == y_val_pred)
        # store the results
        results[(lr, reg)] = (train_accuracy, val_accuracy)
        if (val_accuracy > best_val):
            best_val = val_accuracy
            best_softmax = sm
#####
#                                     END OF YOUR CODE
#####

# Print out results.
for lr, reg in sorted(results):
    train_accuracy, val_accuracy = results[(lr, reg)]
    print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
        lr, reg, train_accuracy, val_accuracy))

print('best validation accuracy achieved during cross-validation: %f' % best_val
)
```

```
lr 1.000000e-06 reg 1.000000e+03 train accuracy: 0.394449 val accuracy: 0.397000
lr 1.000000e-06 reg 1.500000e+03 train accuracy: 0.395714 val accuracy: 0.384000
lr 1.000000e-06 reg 2.000000e+03 train accuracy: 0.391959 val accuracy: 0.402000
lr 1.000000e-05 reg 1.000000e+03 train accuracy: 0.224571 val accuracy: 0.238000
lr 1.000000e-05 reg 1.500000e+03 train accuracy: 0.255796 val accuracy: 0.241000
lr 1.000000e-05 reg 2.000000e+03 train accuracy: 0.228469 val accuracy: 0.234000
best validation accuracy achieved during cross-validation: 0.402000
```

In [7]:

```
# evaluate on test set
# Evaluate the best softmax on test set
y_test_pred = best_softmax.predict(X_test)
test_accuracy = np.mean(y_test == y_test_pred)
print('softmax on raw pixels final test set accuracy: %f' % (test_accuracy, ))
```

```
softmax on raw pixels final test set accuracy: 0.381000
```

Inline Question - True or False

It's possible to add a new datapoint to a training set that would leave the SVM loss unchanged, but this is not the case with the Softmax classifier loss.

Your answer: True

Your explanation: The SVM loss is a sum of non-negative margins between the score of an incorrect class and that of a correct class (and a constant). On the other hand, the Softmax classifier loss is the negative log of the probability of the correct class. If I add a new datapoint to the training set where the margin between the score of the new datapoint and that of the correct class is negative, it doesn't add to the loss and leaves the SVM loss unchanged. However, the Softmax classifier loss considers the distribution of probabilities of all datapoints and so, alters the loss.

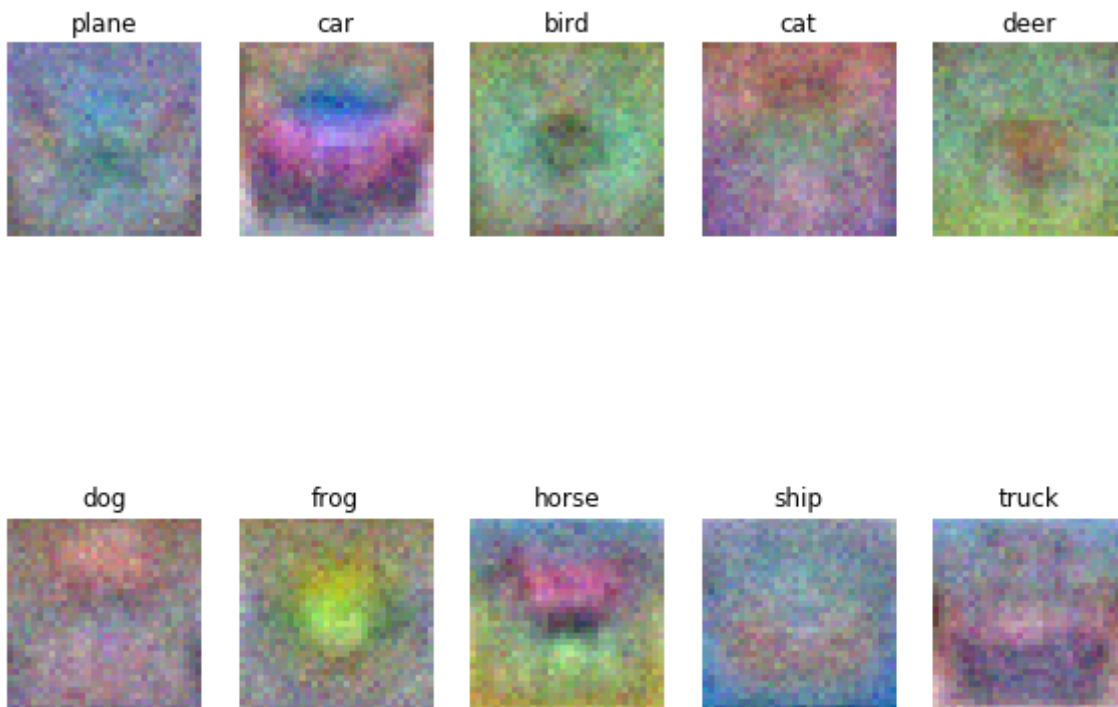
In [8]:

```
# Visualize the learned weights for each class
w = best_softmax.W[:-1,:] # strip out the bias
w = w.reshape(32, 32, 3, 10)

w_min, w_max = np.min(w), np.max(w)

classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship',
           'truck']
for i in range(10):
    plt.subplot(2, 5, i + 1)

    # Rescale the weights to be between 0 and 255
    wimg = 255.0 * (w[:, :, :, i].squeeze() - w_min) / (w_max - w_min)
    plt.imshow(wimg.astype('uint8'))
    plt.axis('off')
    plt.title(classes[i])
```



Implementing a Neural Network

In this exercise we will develop a neural network with fully-connected layers to perform classification, and test it out on the CIFAR-10 dataset.

In [1]:

```
# A bit of setup

from __future__ import print_function
import numpy as np
import matplotlib.pyplot as plt

from cs682.classifiers.neural_net import TwoLayerNet

%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading external modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2

def rel_error(x, y):
    """ returns relative error """
    return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

We will use the class `TwoLayerNet` in the file `cs682/classifiers/neural_net.py` to represent instances of our network. The network parameters are stored in the instance variable `self.params` where keys are string parameter names and values are numpy arrays. Below, we initialize toy data and a toy model that we will use to develop your implementation.

In [2]:

```
# Create a small net and some toy data to check your implementations.  
# Note that we set the random seed for repeatable experiments.  
  
input_size = 4  
hidden_size = 10  
num_classes = 3  
num_inputs = 5  
  
def init_toy_model():  
    np.random.seed(0)  
    return TwoLayerNet(input_size, hidden_size, num_classes, std=1e-1)  
  
def init_toy_data():  
    np.random.seed(1)  
    X = 10 * np.random.randn(num_inputs, input_size)  
    y = np.array([0, 1, 2, 2, 1])  
    return X, y  
  
net = init_toy_model()  
X, y = init_toy_data()
```

Forward pass: compute scores

Open the file `cs682/classifiers/neural_net.py` and look at the method `TwoLayerNet.loss`. This function is very similar to the loss functions you have written for the SVM and Softmax exercises: It takes the data and weights and computes the class scores, the loss, and the gradients on the parameters.

Implement the first part of the forward pass which uses the weights and biases to compute the scores for all inputs.

In [3]:

```
scores = net.loss(X)
print('Your scores:')
print(scores)
print()
print('correct scores:')
correct_scores = np.asarray([
    [-0.81233741, -1.27654624, -0.70335995],
    [-0.17129677, -1.18803311, -0.47310444],
    [-0.51590475, -1.01354314, -0.8504215 ],
    [-0.15419291, -0.48629638, -0.52901952],
    [-0.00618733, -0.12435261, -0.15226949]])
print(correct_scores)
print()

# The difference should be very small. We get < 1e-7
print('Difference between your scores and correct scores:')
print(np.sum(np.abs(scores - correct_scores)))
```

Your scores:

```
[[-0.81233741 -1.27654624 -0.70335995]
 [-0.17129677 -1.18803311 -0.47310444]
 [-0.51590475 -1.01354314 -0.8504215 ]
 [-0.15419291 -0.48629638 -0.52901952]
 [-0.00618733 -0.12435261 -0.15226949]]
```

correct scores:

```
[[-0.81233741 -1.27654624 -0.70335995]
 [-0.17129677 -1.18803311 -0.47310444]
 [-0.51590475 -1.01354314 -0.8504215 ]
 [-0.15419291 -0.48629638 -0.52901952]
 [-0.00618733 -0.12435261 -0.15226949]]
```

Difference between your scores and correct scores:

```
3.6802720745909845e-08
```

Forward pass: compute loss

In the same function, implement the second part that computes the data and regularization loss.

In [4]:

```
loss, _ = net.loss(X, y, reg=0.05)
correct_loss = 1.30378789133

# should be very small, we get < 1e-12
print('Difference between your loss and correct loss:')
print(np.sum(np.abs(loss - correct_loss)))
```

Difference between your loss and correct loss:

```
1.7985612998927536e-13
```


Backward pass

Implement the rest of the function. This will compute the gradient of the loss with respect to the variables w_1 , b_1 , w_2 , and b_2 . Now that you (hopefully!) have a correctly implemented forward pass, you can debug your backward pass using a numeric gradient check:

In [5]:

```
from cs682.gradient_check import eval_numerical_gradient

# Use numeric gradient checking to check your implementation of the backward pass.
# If your implementation is correct, the difference between the numeric and
# analytic gradients should be less than 1e-8 for each of W1, W2, b1, and b2.

loss, grads = net.loss(X, y, reg=0.05)

# these should all be less than 1e-8 or so
for param_name in grads:
    f = lambda W: net.loss(X, y, reg=0.05)[0]
    param_grad_num = eval_numerical_gradient(f, net.params[param_name], verbose=False)
    print('%s max relative error: %e' % (param_name, rel_error(param_grad_num, grads[param_name])))
```

```
W2 max relative error: 3.440708e-09
b2 max relative error: 4.447625e-11
W1 max relative error: 3.561318e-09
b1 max relative error: 2.738421e-09
```

Train the network

To train the network we will use stochastic gradient descent (SGD), similar to the SVM and Softmax classifiers. Look at the function `TwoLayerNet.train` and fill in the missing sections to implement the training procedure. This should be very similar to the training procedure you used for the SVM and Softmax classifiers. You will also have to implement `TwoLayerNet.predict`, as the training process periodically performs prediction to keep track of accuracy over time while the network trains.

Once you have implemented the method, run the code below to train a two-layer network on toy data. You should achieve a training loss less than 0.2.

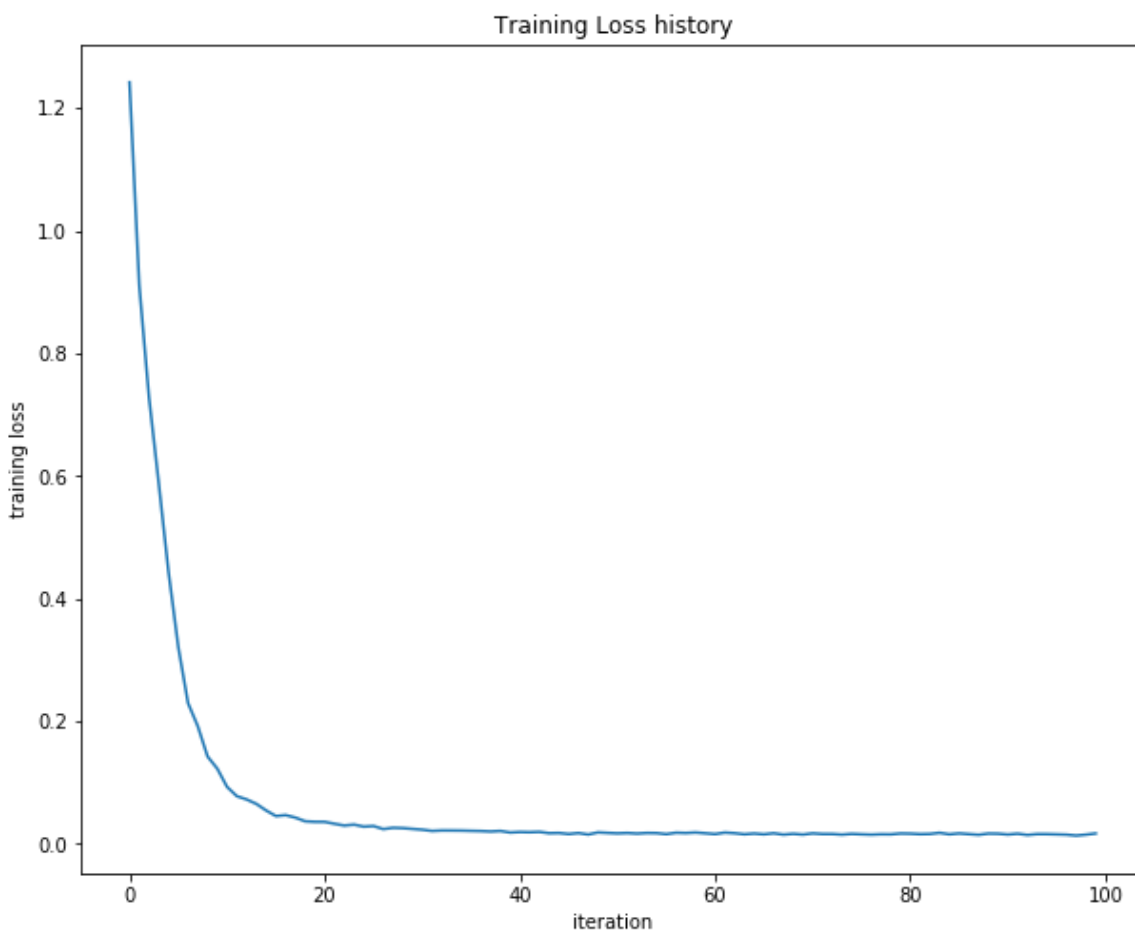
In [6]:

```
net = init_toy_model()
stats = net.train(X, y, X, y,
                  learning_rate=1e-1, reg=5e-6,
                  num_iters=100, verbose=False)

print('Final training loss: ', stats['loss_history'][-1])

# plot the loss history
plt.plot(stats['loss_history'])
plt.xlabel('iteration')
plt.ylabel('training loss')
plt.title('Training Loss history')
plt.show()
```

Final training loss: 0.017149607938732093



Load the data

Now that you have implemented a two-layer network that passes gradient checks and works on toy data, it's time to load up our favorite CIFAR-10 data so we can use it to train a classifier on a real dataset.

In [7]:

```

from cs682.data_utils import load_CIFAR10

def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000):
    """
    Load the CIFAR-10 dataset from disk and perform preprocessing to prepare
    it for the two-layer neural net classifier. These are the same steps as
    we used for the SVM, but condensed to a single function.
    """
    # Load the raw CIFAR-10 data
    cifar10_dir = 'cs682/datasets/cifar-10-batches-py'

    X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

    # Subsample the data
    mask = list(range(num_training, num_training + num_validation))
    X_val = X_train[mask]
    y_val = y_train[mask]
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]

    # Normalize the data: subtract the mean image
    mean_image = np.mean(X_train, axis=0)
    X_train -= mean_image
    X_val -= mean_image
    X_test -= mean_image

    # Reshape data to rows
    X_train = X_train.reshape(num_training, -1)
    X_val = X_val.reshape(num_validation, -1)
    X_test = X_test.reshape(num_test, -1)

    return X_train, y_train, X_val, y_val, X_test, y_test

# Cleaning up variables to prevent loading data multiple times (which may cause
# memory issue)
try:
    del X_train, y_train
    del X_test, y_test
    print('Clear previously loaded data.')
except:
    pass

# Invoke the above function to get our data.
X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()
print('Train data shape: ', X_train.shape)
print('Train labels shape: ', y_train.shape)
print('Validation data shape: ', X_val.shape)
print('Validation labels shape: ', y_val.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)

```

```
Train data shape: (49000, 3072)
Train labels shape: (49000,)
Validation data shape: (1000, 3072)
Validation labels shape: (1000,)
Test data shape: (1000, 3072)
Test labels shape: (1000,)
```

Train a network

To train our network we will use SGD. In addition, we will adjust the learning rate with an exponential learning rate schedule as optimization proceeds; after each epoch, we will reduce the learning rate by multiplying it by a decay rate.

In [8]:

```
input_size = 32 * 32 * 3
hidden_size = 50
num_classes = 10
net = TwoLayerNet(input_size, hidden_size, num_classes)

# Train the network
stats = net.train(X_train, y_train, X_val, y_val,
                  num_iters=1000, batch_size=200,
                  learning_rate=1e-4, learning_rate_decay=0.95,
                  reg=0.25, verbose=True)

# Predict on the validation set
val_acc = (net.predict(X_val) == y_val).mean()
print('Validation accuracy: ', val_acc)
```

```
iteration 0 / 1000: loss 2.302954
iteration 100 / 1000: loss 2.302550
iteration 200 / 1000: loss 2.297648
iteration 300 / 1000: loss 2.259602
iteration 400 / 1000: loss 2.204170
iteration 500 / 1000: loss 2.118565
iteration 600 / 1000: loss 2.051535
iteration 700 / 1000: loss 1.988466
iteration 800 / 1000: loss 2.006591
iteration 900 / 1000: loss 1.951473
Validation accuracy: 0.287
```

Debug the training

With the default parameters we provided above, you should get a validation accuracy of about 0.29 on the validation set. This isn't very good.

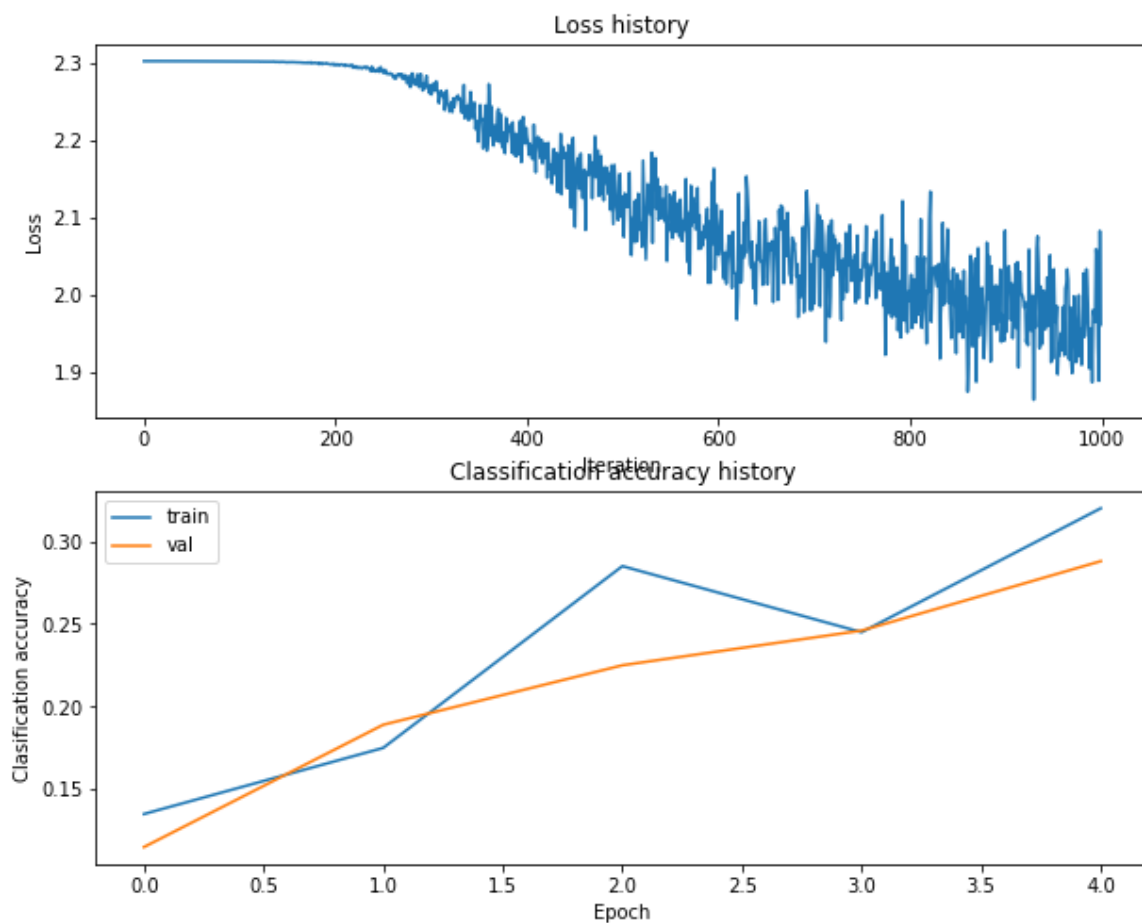
One strategy for getting insight into what's wrong is to plot the loss function and the accuracies on the training and validation sets during optimization.

Another strategy is to visualize the weights that were learned in the first layer of the network. In most neural networks trained on visual data, the first layer weights typically show some visible structure when visualized.

In [9]:

```
# Plot the loss function and train / validation accuracies
plt.subplot(2, 1, 1)
plt.plot(stats['loss_history'])
plt.title('Loss history')
plt.xlabel('Iteration')
plt.ylabel('Loss')

plt.subplot(2, 1, 2)
plt.plot(stats['train_acc_history'], label='train')
plt.plot(stats['val_acc_history'], label='val')
plt.title('Classification accuracy history')
plt.xlabel('Epoch')
plt.ylabel('Classification accuracy')
plt.legend()
plt.show()
```



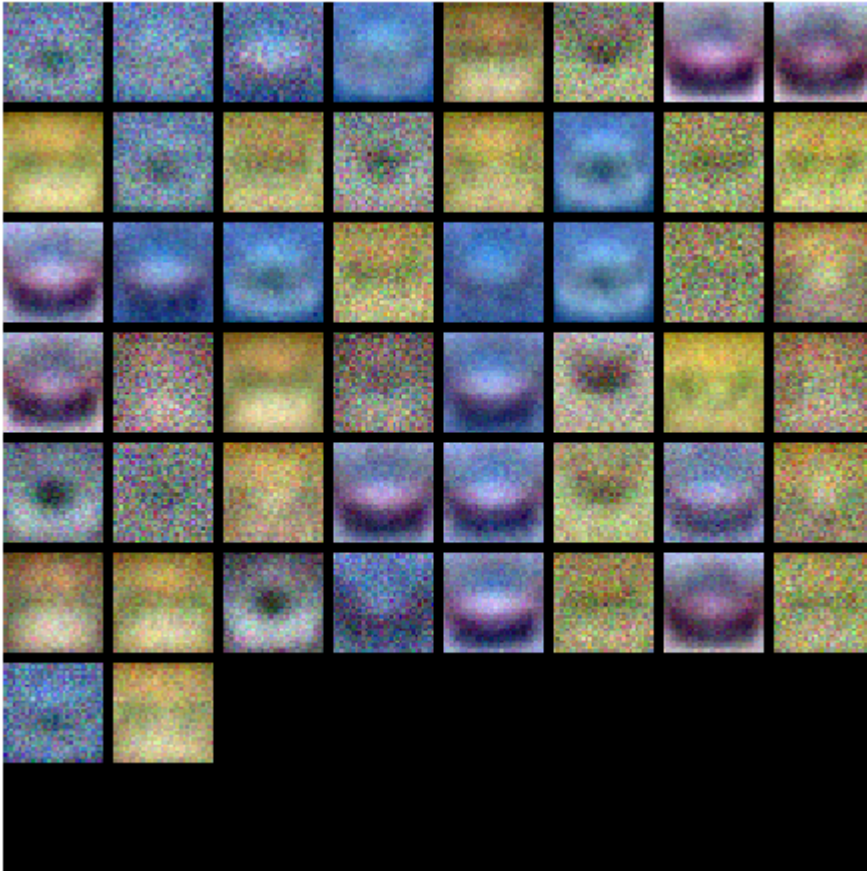
In [10]:

```
from cs682.vis_utils import visualize_grid

# Visualize the weights of the network

def show_net_weights(net):
    W1 = net.params['W1']
    W1 = W1.reshape(32, 32, 3, -1).transpose(3, 0, 1, 2)
    plt.imshow(visualize_grid(W1, padding=3).astype('uint8'))
    plt.gca().axis('off')
    plt.show()

show_net_weights(net)
```



Tune your hyperparameters

What's wrong? Looking at the visualizations above, we see that the loss is decreasing more or less linearly, which seems to suggest that the learning rate may be too low. Moreover, there is no gap between the training and validation accuracy, suggesting that the model we used has low capacity, and that we should increase its size. On the other hand, with a very large model we would expect to see more overfitting, which would manifest itself as a very large gap between the training and validation accuracy.

Tuning. Tuning the hyperparameters and developing intuition for how they affect the final performance is a large part of using Neural Networks, so we want you to get a lot of practice. Below, you should experiment with different values of the various hyperparameters, including hidden layer size, learning rate, number of training epochs, and regularization strength. You might also consider tuning the learning rate decay, but you should be able to get good performance using the default value.

Approximate results. You should be aim to achieve a classification accuracy of greater than 48% on the validation set. Our best network gets over 52% on the validation set.

Experiment: Your goal in this exercise is to get as good of a result on CIFAR-10 as you can, with a fully-connected Neural Network. Feel free to implement your own techniques (e.g. PCA to reduce dimensionality, or adding dropout, or adding features to the solver, etc.).

In [11]:

```

best_net = None # store the best model into this
best_val = -1

learning_rates = [1e-3, 5e-4]
hidden_size = [150, 200]
regularization_strengths = [0.15, 0.25]
#####
#
# TODO: Tune hyperparameters using the validation set. Store your best trained
#
# model in best_net.
#
#
#
# To help debug your network, it may help to use visualizations similar to the
#
# ones we used above; these visualizations will have significant qualitative
#
# differences from the ones we saw above for the poorly tuned network.
#
#
#
# Tweaking hyperparameters by hand can be fun, but you might find it useful to
#
# write code to sweep through possible combinations of hyperparameters
#
# automatically like we did on the previous exercises.
#
#####
#
input_size = 32 * 32 * 3
num_classes = 10

for reg in regularization_strengths:
    for lr in learning_rates:
        for hs in hidden_size:

            net = TwoLayerNet(input_size, hs, num_classes)

            stats = net.train(X_train, y_train, X_val, y_val,
                              num_iters=5000, batch_size=200,
                              learning_rate=lr, learning_rate_decay=0.95,
                              reg=reg, verbose=False)

            # Predict on the training set
            train_acc = (net.predict(X_train) == y_train).mean()

            # Predict on the validation set
            val_acc = (net.predict(X_val) == y_val).mean()

            if val_acc > best_val:
                best_val = val_acc
                best_net = net

            print('lr %e reg %e hid_size %e train accuracy: %f val accuracy: %f'
                  % (
                      lr, reg, hs, train_acc, val_acc))

```



```

print('best validation accuracy achieved during cross-validation: %f' % best_val
)
#####
#
#                               END OF YOUR CODE
#
#####
#

lr 1.000000e-03 reg 1.500000e-01 hid_size 1.500000e+02 train accurac
y: 0.649469 val accuracy: 0.527000
lr 1.000000e-03 reg 1.500000e-01 hid_size 2.000000e+02 train accurac
y: 0.658204 val accuracy: 0.552000
lr 5.000000e-04 reg 1.500000e-01 hid_size 1.500000e+02 train accurac
y: 0.587694 val accuracy: 0.525000
lr 5.000000e-04 reg 1.500000e-01 hid_size 2.000000e+02 train accurac
y: 0.594469 val accuracy: 0.532000
lr 1.000000e-03 reg 2.500000e-01 hid_size 1.500000e+02 train accurac
y: 0.624735 val accuracy: 0.537000
lr 1.000000e-03 reg 2.500000e-01 hid_size 2.000000e+02 train accurac
y: 0.636959 val accuracy: 0.543000
lr 5.000000e-04 reg 2.500000e-01 hid_size 1.500000e+02 train accurac
y: 0.581224 val accuracy: 0.514000
lr 5.000000e-04 reg 2.500000e-01 hid_size 2.000000e+02 train accurac
y: 0.583143 val accuracy: 0.512000
best validation accuracy achieved during cross-validation: 0.552000

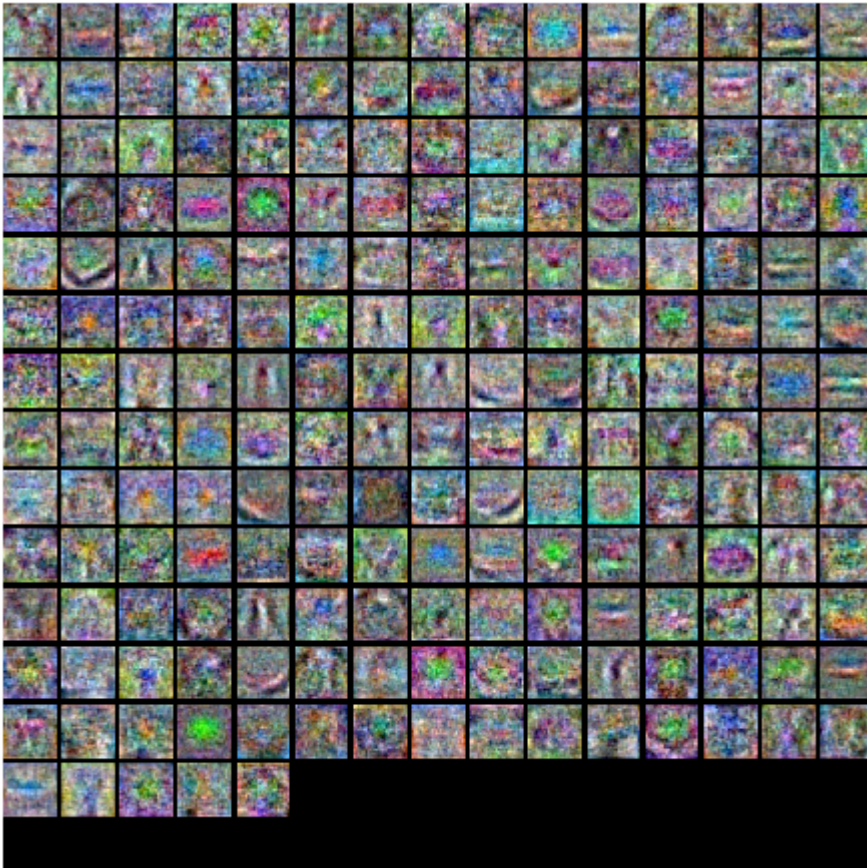
```

In [12]:

```

# visualize the weights of the best network
show_net_weights(best_net)

```



Run on the test set

When you are done experimenting, you should evaluate your final trained network on the test set; you should get above 48%.

In [13]:

```
test_acc = (best_net.predict(X_test) == y_test).mean()  
print('Test accuracy: ', test_acc)
```

Test accuracy: 0.551

Inline Question

Now that you have trained a Neural Network classifier, you may find that your testing accuracy is much lower than the training accuracy. In what ways can we decrease this gap? Select all that apply.

1. Train on a larger dataset.
2. Add more hidden units.
3. Increase the regularization strength.
4. None of the above.

Your answer: 1, 3

Your explanation:

1. Using a larger dataset, gives us an opportunity to extract more insights from the data and generalize better. However, if the additional datapoints are close to the existing examples, we might overfit to the training data.
2. Adding more hidden units to the network will overfit to the training set, ie. it will learn the training data, but it won't be able to generalize to new unseen data.
3. Increasing the regularization strength, incentivizes the classifier to reduce the magnitude of weight matrix and avoids overfitting.

Image features exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the [assignments page](https://compsci682-fa19.github.io/assignments2019/assignment1) (<https://compsci682-fa19.github.io/assignments2019/assignment1>) on the course website.

We have seen that we can achieve reasonable performance on an image classification task by training a linear classifier on the pixels of the input image. In this exercise we will show that we can improve our classification performance by training linear classifiers not on raw pixels but on features that are computed from the raw pixels.

All of your work for this exercise will be done in this notebook.

In [1]:

```
from __future__ import print_function
import random
import numpy as np
from cs682.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading external modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython
%load_ext autoreload
%autoreload 2
```

Load data

Similar to previous exercises, we will load CIFAR-10 data from disk.

In [2]:

```
from cs682.features import color_histogram_hsv, hog_feature

def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000):
    # Load the raw CIFAR-10 data
    cifar10_dir = 'cs682/datasets/cifar-10-batches-py'

    X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)

    # Subsample the data
    mask = list(range(num_training, num_training + num_validation))
    X_val = X_train[mask]
    y_val = y_train[mask]
    mask = list(range(num_training))
    X_train = X_train[mask]
    y_train = y_train[mask]
    mask = list(range(num_test))
    X_test = X_test[mask]
    y_test = y_test[mask]

    return X_train, y_train, X_val, y_val, X_test, y_test

# Cleaning up variables to prevent loading data multiple times (which may cause
memory issue)
try:
    del X_train, y_train
    del X_test, y_test
    print('Clear previously loaded data.')
except:
    pass

X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()
```

Extract Features

For each image we will compute a Histogram of Oriented Gradients (HOG) as well as a color histogram using the hue channel in HSV color space. We form our final feature vector for each image by concatenating the HOG and color histogram feature vectors.

Roughly speaking, HOG should capture the texture of the image while ignoring color information, and the color histogram represents the color of the input image while ignoring texture. As a result, we expect that using both together ought to work better than using either alone. Verifying this assumption would be a good thing to try for your interests.

The `hog_feature` and `color_histogram_hsv` functions both operate on a single image and return a feature vector for that image. The `extract_features` function takes a set of images and a list of feature functions and evaluates each feature function on each image, storing the results in a matrix where each column is the concatenation of all feature vectors for a single image.

In [3]:

```
from cs682.features import *

num_color_bins = 10 # Number of bins in the color histogram
feature_fns = [hog_feature, lambda img: color_histogram_hsv(img, nbins=num_color_
bins)]
X_train_feats = extract_features(X_train, feature_fns, verbose=True)
X_val_feats = extract_features(X_val, feature_fns)
X_test_feats = extract_features(X_test, feature_fns)

# Preprocessing: Subtract the mean feature
mean_feat = np.mean(X_train_feats, axis=0, keepdims=True)
X_train_feats -= mean_feat
X_val_feats -= mean_feat
X_test_feats -= mean_feat

# Preprocessing: Divide by standard deviation. This ensures that each feature
# has roughly the same scale.
std_feat = np.std(X_train_feats, axis=0, keepdims=True)
X_train_feats /= std_feat
X_val_feats /= std_feat
X_test_feats /= std_feat

# Preprocessing: Add a bias dimension
X_train_feats = np.hstack([X_train_feats, np.ones((X_train_feats.shape[0], 1))])
X_val_feats = np.hstack([X_val_feats, np.ones((X_val_feats.shape[0], 1))])
X_test_feats = np.hstack([X_test_feats, np.ones((X_test_feats.shape[0], 1))])
```

```
Done extracting features for 1000 / 49000 images
Done extracting features for 2000 / 49000 images
Done extracting features for 3000 / 49000 images
Done extracting features for 4000 / 49000 images
Done extracting features for 5000 / 49000 images
Done extracting features for 6000 / 49000 images
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Done extracting features for 40000 / 49000 images
Done extracting features for 41000 / 49000 images
Done extracting features for 42000 / 49000 images
Done extracting features for 43000 / 49000 images
Done extracting features for 44000 / 49000 images
Done extracting features for 45000 / 49000 images
Done extracting features for 46000 / 49000 images
Done extracting features for 47000 / 49000 images
Done extracting features for 48000 / 49000 images
```

Train SVM on features

Using the multiclass SVM code developed earlier in the assignment, train SVMs on top of the features extracted above; this should achieve better results than training SVMs directly on top of raw pixels.

In [4]:

```

# Use the validation set to tune the learning rate and regularization strength

from cs682.classifiers.linear_classifier import LinearSVM

learning_rates = [1e-3, 1e-4]
regularization_strengths = [0.01, 0.1]

results = {}
best_val = -1
best_svm = None

#####
# TODO:
# Use the validation set to set the learning rate and regularization strength. #
# This should be identical to the validation that you did for the SVM; save #
# the best trained classifier in best_svm. You might also want to play #
# with different numbers of bins in the color histogram. If you are careful #
# you should be able to get accuracy of near 0.44 on the validation set. #
#####
for lr in learning_rates:
    for reg in regularization_strengths:
        # new instance of SVM
        svm = LinearSVM()
        loss_hist = svm.train(X_train_feats, y_train, learning_rate=lr, reg=reg,
                               num_iters=2000, verbose=False)
        # evaluate the performance on the training set
        y_train_pred = svm.predict(X_train_feats)
        train_accuracy = np.mean(y_train == y_train_pred)
        # evaluate the performance on the validation set
        y_val_pred = svm.predict(X_val_feats)
        val_accuracy = np.mean(y_val == y_val_pred)
        # store the results
        results[(lr, reg)] = (train_accuracy, val_accuracy)
        if (val_accuracy > best_val):
            best_val = val_accuracy
            best_svm = svm
#####
#                                     END OF YOUR CODE                                     #
#####

# Print out results.
for lr, reg in sorted(results):
    train_accuracy, val_accuracy = results[(lr, reg)]
    print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
        lr, reg, train_accuracy, val_accuracy))

print('best validation accuracy achieved during cross-validation: %f' % best_val
)
```

```

lr 1.000000e-04 reg 1.000000e-02 train accuracy: 0.459959 val accuracy: 0.454000
lr 1.000000e-04 reg 1.000000e-01 train accuracy: 0.458592 val accuracy: 0.451000
lr 1.000000e-03 reg 1.000000e-02 train accuracy: 0.504490 val accuracy: 0.497000
lr 1.000000e-03 reg 1.000000e-01 train accuracy: 0.502857 val accuracy: 0.491000
best validation accuracy achieved during cross-validation: 0.497000
```


In [5]:

```
# Evaluate your trained SVM on the test set
y_test_pred = best_svm.predict(X_test_feats)
test_accuracy = np.mean(y_test == y_test_pred)
print(test_accuracy)
```

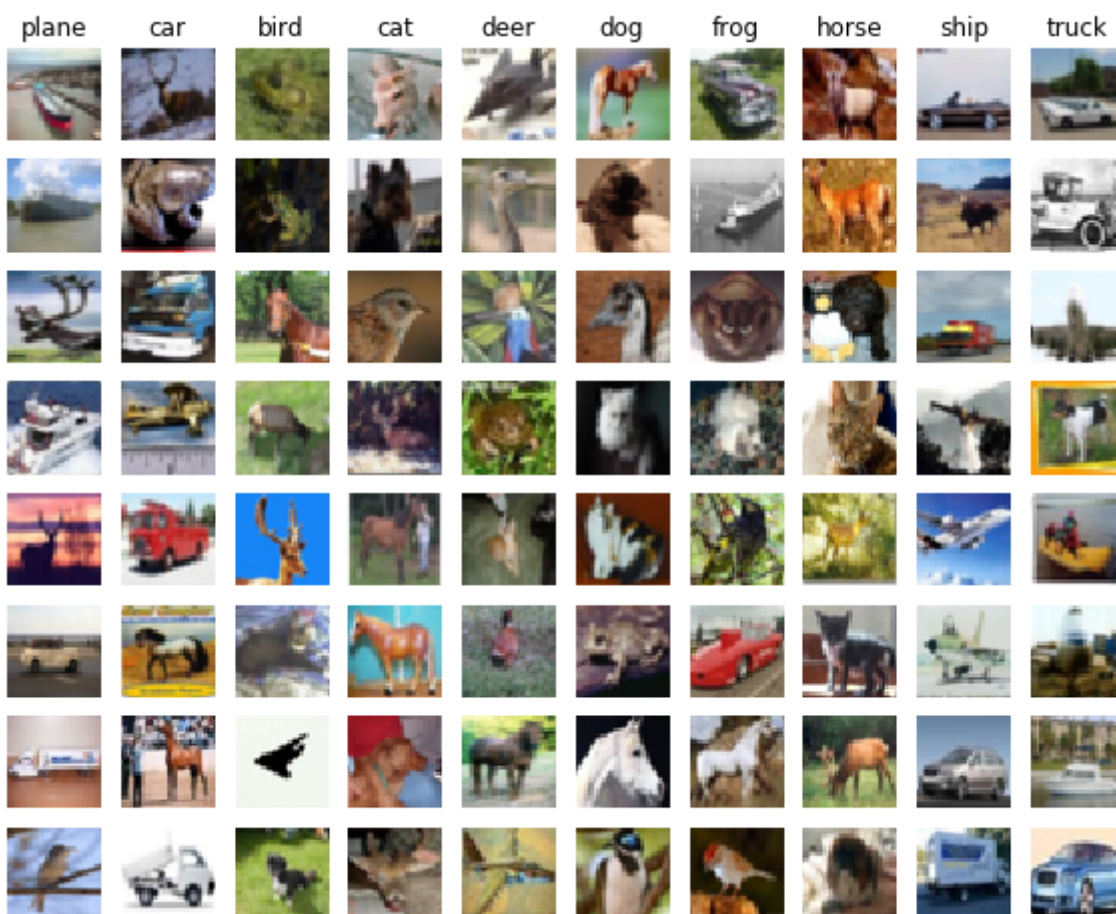
0.488

In [6]:

```
# An important way to gain intuition about how an algorithm works is to
# visualize the mistakes that it makes. In this visualization, we show examples
# of images that are misclassified by our current system. The first column
# shows images that our system labeled as "plane" but whose true label is
# something other than "plane".

examples_per_class = 8
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
for cls, cls_name in enumerate(classes):
    idxs = np.where((y_test != cls) & (y_test_pred == cls))[0]
    idxs = np.random.choice(idxs, examples_per_class, replace=False)
    for i, idx in enumerate(idxs):
        plt.subplot(examples_per_class, len(classes), i * len(classes) + cls + 1)

        plt.imshow(X_test[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls_name)
plt.show()
```



Inline question 1:

Describe the misclassification results that you see. Do they make sense?

There are a lot of misclassifications. Images that represent a horse, squirrels and some birds have been classified as a dog. In some cases, a ship and a boat have been classified as a plane. For the most part, these misclassifications can be attributed to the color features. For instance, the blue waters can be mapped to the blue skies and so boats and ships have been classified as a plane. Additionally, most the examples with animals have trees/grass in the background grouping them together incorrectly.

Neural Network on image features

Earlier in this assignment we saw that training a two-layer neural network on raw pixels achieved better classification performance than linear classifiers on raw pixels. In this notebook we have seen that linear classifiers on image features outperform linear classifiers on raw pixels.

For completeness, we should also try training a neural network on image features. This approach should outperform all previous approaches: you should easily be able to achieve over 55% classification accuracy on the test set; our best model achieves about 60% classification accuracy.

In [7]:

```
# Preprocessing: Remove the bias dimension  
# Make sure to run this cell only ONCE  
print(X_train_feats.shape)  
X_train_feats = X_train_feats[:, :-1]  
X_val_feats = X_val_feats[:, :-1]  
X_test_feats = X_test_feats[:, :-1]  
  
print(X_train_feats.shape)
```

```
(49000, 155)
```

```
(49000, 154)
```

In [9]:

```

from cs682.classifiers.neural_net import TwoLayerNet

input_dim = X_train_feats.shape[1]
num_classes = 10

best_net = None
best_val = -1

learning_rates = [0.5, 0.75]
hidden_dim = [475, 500]
regularization_strengths = [1e-3]
#####
# TODO: Train a two-layer neural network on image features. You may want to #
# cross-validate various parameters as in previous sections. Store your best #
# model in the best_net variable. #
#####
for reg in regularization_strengths:
    for lr in learning_rates:
        for hs in hidden_dim:

            net = TwoLayerNet(input_dim, hs, num_classes)

            stats = net.train(X_train_feats, y_train, X_val_feats, y_val,
                              num_iters=5000, batch_size=200,
                              learning_rate=lr, learning_rate_decay=0.95,
                              reg=reg, verbose=False)

            # Predict on the training set
            train_acc = (net.predict(X_train_feats) == y_train).mean()

            # Predict on the validation set
            val_acc = (net.predict(X_val_feats) == y_val).mean()

            if val_acc > best_val:
                best_val = val_acc
                best_net = net

            print('lr %e reg %e hid_size %e train accuracy: %f val accuracy: %f'
                  % (
                      lr, reg, hs, train_acc, val_acc))

print('best validation accuracy achieved during cross-validation: %f' % best_val)
#####
#                                     END OF YOUR CODE                                     #
#####

```

```

lr 5.000000e-01 reg 1.000000e-03 hid_size 4.750000e+02 train accurac
y: 0.762776 val accuracy: 0.591000
lr 5.000000e-01 reg 1.000000e-03 hid_size 5.000000e+02 train accurac
y: 0.765143 val accuracy: 0.585000
lr 7.500000e-01 reg 1.000000e-03 hid_size 4.750000e+02 train accurac
y: 0.771102 val accuracy: 0.589000
lr 7.500000e-01 reg 1.000000e-03 hid_size 5.000000e+02 train accurac
y: 0.774490 val accuracy: 0.599000
best validation accuracy achieved during cross-validation: 0.599000

```

In [10]:

```
# Run your best neural net classifier on the test set. You should be able  
# to get more than 55% accuracy.
```

```
test_acc = (best_net.predict(X_test_feats) == y_test).mean()  
print(test_acc)
```

0.591