15/09/2020 km

k-Nearest Neighbor (kNN) exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the <u>assignments page</u> (https://compsci682-fa19.github.io/assignments2019/assignment1) on the course website.

The kNN classifier consists of two stages:

- · During training, the classifier takes the training data and simply remembers it
- During testing, kNN classifies every test image by comparing to all training images and transfering the labels of the k most similar training examples
- · The value of k is cross-validated

In this exercise you will implement these steps and understand the basic Image Classification pipeline, cross-validation, and gain proficiency in writing efficient, vectorized code.

In [1]:

```
# Run some setup code for this notebook.
from __future __ import print_function
import random
import numpy as np
from cs682.data utils import load CIFAR10
import matplotlib.pyplot as plt
# This is a bit of magic to make matplotlib figures appear inline in the noteboo
k
# rather than in a new window.
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'
# Some more magic so that the notebook will reload external python modules;
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipytho
%load ext autoreload
%autoreload 2
```

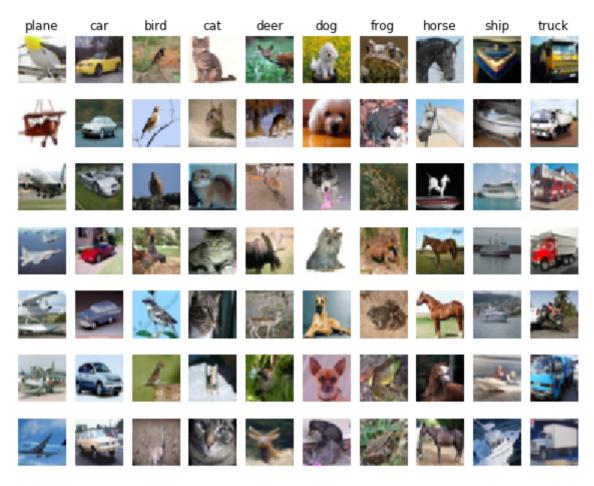
In [2]:

```
# Load the raw CIFAR-10 data.
cifar10_dir = 'cs682/datasets/cifar-10-batches-py'
# Cleaning up variables to prevent loading data multiple times (which may cause
 memory issue)
try:
   del X train, y train
   del X_test, y_test
   print('Clear previously loaded data.')
except:
   pass
X_train, y_train, X_test, y_test = load_CIFAR10(cifar10_dir)
# As a sanity check, we print out the size of the training and test data.
print('Training data shape: ', X_train.shape)
print('Training labels shape: ', y_train.shape)
print('Test data shape: ', X_test.shape)
print('Test labels shape: ', y_test.shape)
```

```
Training data shape: (50000, 32, 32, 3)
Training labels shape: (50000,)
Test data shape: (10000, 32, 32, 3)
Test labels shape: (10000,)
```

In [3]:

```
# Visualize some examples from the dataset.
# We show a few examples of training images from each class.
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship'
, 'truck']
num classes = len(classes)
samples_per_class = 7
for y, cls in enumerate(classes):
    idxs = np.flatnonzero(y_train == y)
    idxs = np.random.choice(idxs, samples per class, replace=False)
    for i, idx in enumerate(idxs):
        plt_idx = i * num_classes + y + 1
        plt.subplot(samples per class, num classes, plt idx)
        plt.imshow(X_train[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls)
plt.show()
```



In [4]:

```
# Subsample the data for more efficient code execution in this exercise
num_training = 5000
mask = list(range(num_training))
X_train = X_train[mask]
y_train = y_train[mask]

num_test = 500
mask = list(range(num_test))
X_test = X_test[mask]
y_test = y_test[mask]
```

In [5]:

```
# Reshape the image data into rows
X_train = np.reshape(X_train, (X_train.shape[0], -1))
X_test = np.reshape(X_test, (X_test.shape[0], -1))
print(X_train.shape, X_test.shape)
```

(5000, 3072) (500, 3072)

In [6]:

```
from cs682.classifiers import KNearestNeighbor

# Create a kNN classifier instance.
# Remember that training a kNN classifier is a noop:
# the Classifier simply remembers the data and does no further processing classifier = KNearestNeighbor()
classifier.train(X_train, y_train)
```

We would now like to classify the test data with the kNN classifier. Recall that we can break down this process into two steps:

- 1. First we must compute the distances between all test examples and all train examples.
- 2. Given these distances, for each test example we find the k nearest examples and have them vote for the label

Lets begin with computing the distance matrix between all training and test examples. For example, if there are **Ntr** training examples and **Nte** test examples, this stage should result in a **Nte x Ntr** matrix where each element (i,j) is the distance between the i-th test and j-th train example.

First, open cs682/classifiers/k_nearest_neighbor.py and implement the function compute_distances_two_loops that uses a (very inefficient) double loop over all pairs of (test, train) examples and computes the distance matrix one element at a time.

In [7]:

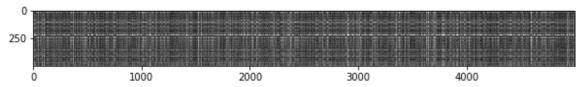
```
# Open cs682/classifiers/k_nearest_neighbor.py and implement
# compute_distances_two_loops.

# Test your implementation:
dists = classifier.compute_distances_two_loops(X_test)
print(dists.shape)
```

(500, 5000)

In [8]:

```
# We can visualize the distance matrix: each row is a single test example and
# its distances to training examples
plt.imshow(dists, interpolation='none')
plt.show()
```



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Inline Question #1: Notice the structured patterns in the distance matrix, where some rows or columns are visible brighter. (Note that with the default color scheme black indicates low distances while white indicates high distances.)

- What in the data is the cause behind the distinctly bright rows?
- · What causes the columns?

Your Answer: Each value in the distance matrix represents the euclidean distance (L2) between the pixel values of an image from the test set and that of from the training set. Here, the rows represent a test set and the columns represent the training set.

- 1. Distinctly bright rows represent images from the test set that have noticeably different intensity values from all the images in the training set
- 2. Distinctly bright columns represent images from the training set that have noticeably different intensity values from all the images in the test set

In [9]:

```
# Now implement the function predict_labels and run the code below:
# We use k = 1 (which is Nearest Neighbor).
y_test_pred = classifier.predict_labels(dists, k=1)

# Compute and print the fraction of correctly predicted examples
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

```
Got 137 / 500 correct => accuracy: 0.274000
```

You should expect to see approximately 27% accuracy. Now lets try out a larger k, say k = 5:

In [10]:

```
y_test_pred = classifier.predict_labels(dists, k=5)
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

```
Got 145 / 500 correct => accuracy: 0.290000
```

You should expect to see a slightly better performance than with k = 1.

Inline Question 2 We can also other distance metrics such as L1 distance. The performance of a Nearest Neighbor classifier that uses L1 distance will not change if (Select all that apply.):

- 1. The data is preprocessed by subtracting the mean.
- 2. The data is preprocessed by subtracting the mean and dividing by the standard deviation.
- 3. The coordinate axes for the data are rotated.
- 4. None of the above. (Mean and standard deviation in (1) and (2) are vectors and can be different across dimensions) *Your Answer*: 1, 2

Your explanation:

- 1. Let the original distance be |x y|. After subtraction the mean of the dimension, |(x m) (y m)| = |x m y + m| = |x y|, the distance remains the same
- 2. Preprocessing the data by subtracting the mean and dividing by the standard deviation, normalizes the data with mean = 0 and std = 1. This does not change the performance of the k-NN classifier
- 3. The relative distances do not hold with L1 after the data are rotated.

In [11]:

```
# Now lets speed up distance matrix computation by using partial vectorization
# with one loop. Implement the function compute_distances_one_loop and run the
# code below:
dists_one = classifier.compute_distances_one_loop(X_test)

# To ensure that our vectorized implementation is correct, we make sure that it
# agrees with the naive implementation. There are many ways to decide whether
# two matrices are similar; one of the simplest is the Frobenius norm. In case
# you haven't seen it before, the Frobenius norm of two matrices is the square
# root of the squared sum of differences of all elements; in other words, reshap
e
# the matrices into vectors and compute the Euclidean distance between them.
difference = np.linalg.norm(dists - dists_one, ord='fro')
print('Difference was: %f' % (difference, ))
if difference < 0.001:
    print('Good! The distance matrices are the same')
else:
    print('Uh-oh! The distance matrices are different')</pre>
```

Difference was: 0.000000
Good! The distance matrices are the same

In [12]:

```
# Now implement the fully vectorized version inside compute_distances_no_loops
# and run the code
dists_two = classifier.compute_distances_no_loops(X_test)

# check that the distance matrix agrees with the one we computed before:
difference = np.linalg.norm(dists - dists_two, ord='fro')
print('Difference was: %f' % (difference, ))
if difference < 0.001:
    print('Good! The distance matrices are the same')
else:
    print('Uh-oh! The distance matrices are different')</pre>
```

Difference was: 0.000000 Good! The distance matrices are the same

In [14]:

```
# Let's compare how fast the implementations are
def time function(f, *args):
    Call a function f with args and return the time (in seconds) that it took to
execute.
    import time
    tic = time.time()
    f(*args)
    toc = time.time()
    return toc - tic
two_loop_time = time_function(classifier.compute_distances_two_loops, X_test)
print('Two loop version took %f seconds' % two loop time)
one loop time = time function(classifier.compute distances one loop, X test)
print('One loop version took %f seconds' % one loop time)
no_loop_time = time_function(classifier.compute_distances_no_loops, X_test)
print('No loop version took %f seconds' % no loop time)
# you should see significantly faster performance with the fully vectorized impl
ementation
```

Two loop version took 33.365682 seconds One loop version took 31.677212 seconds No loop version took 9.560447 seconds

Cross-validation

We have implemented the k-Nearest Neighbor classifier but we set the value k = 5 arbitrarily. We will now determine the best value of this hyperparameter with cross-validation.

In [15]:

```
num folds = 5
k \text{ choices} = [1, 3, 5, 8, 10, 12, 15, 20, 50, 100]
X train folds = []
y train folds = []
# TODO:
# Split up the training data into folds. After splitting, X train folds and
                                                            #
# y train folds should each be lists of length num folds, where
                                                            #
                                                            #
# y train folds[i] is the label vector for the points in X train folds[i].
# Hint: Look up the numpy array split function.
X_train_folds = np.array_split(X_train, num_folds, axis=0)
y train folds = np.array split(y train, num folds)
END OF YOUR CODE
# A dictionary holding the accuracies for different values of k that we find
# when running cross-validation. After running cross-validation,
# k to accuracies[k] should be a list of length num folds giving the different
# accuracy values that we found when using that value of k.
k to accuracies = {}
# TODO:
# Perform k-fold cross validation to find the best value of k. For each
                                                            #
# possible value of k, run the k-nearest-neighbor algorithm num folds times,
# where in each case you use all but one of the folds as training data and the #
# last fold as a validation set. Store the accuracies for all fold and all
# values of k in the k to accuracies dictionary.
for i in range(num_folds):
   # Populate the cross validation subsets
  X train subset = np.vstack(tuple(X train folds[:i] + X train folds[i+1:]))
  y train subset = np.concatenate(tuple(y train folds[:i] + y train folds[i+1
: ] ) )
  # kNN classifier instance.
  classifier = KNearestNeighbor()
  classifier.train(X train subset, y train subset)
  dists cv = classifier.compute distances no loops(X train folds[i])
   for k in k choices:
      y test pred cv = classifier.predict labels(dists cv, k)
      num correct cv = np.sum(y test pred cv == y train folds[i])
      accuracy = float(num correct cv) / np.shape(X train folds)[0]
      if k not in k to accuracies:
         k to accuracies[k] = []
      k to accuracies[k].append(accuracy)
END OF YOUR CODE
# Print out the computed accuracies
```

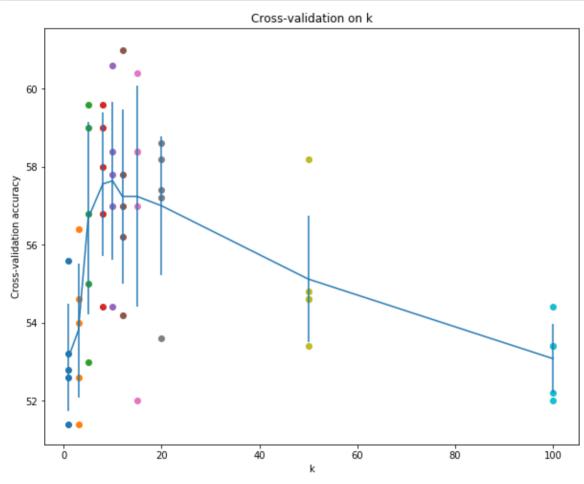
```
for k in sorted(k_to_accuracies):
    for accuracy in k_to_accuracies[k]:
        print('k = %d, accuracy = %f' % (k, accuracy))
```

```
k = 1, accuracy = 52.600000
k = 1, accuracy = 51.400000
k = 1, accuracy = 52.800000
k = 1, accuracy = 55.600000
k = 1, accuracy = 53.200000
k = 3, accuracy = 51.400000
k = 3, accuracy = 52.600000
k = 3, accuracy = 54.600000
k = 3, accuracy = 56.400000
k = 3, accuracy = 54.000000
k = 5, accuracy = 53.000000
k = 5, accuracy = 55.000000
k = 5, accuracy = 59.000000
k = 5, accuracy = 59.600000
k = 5, accuracy = 56.800000
k = 8, accuracy = 54.400000
k = 8, accuracy = 59.000000
k = 8, accuracy = 56.800000
k = 8, accuracy = 59.600000
k = 8, accuracy = 58.000000
k = 10, accuracy = 54.400000
k = 10, accuracy = 60.600000
k = 10, accuracy = 57.800000
k = 10, accuracy = 58.400000
k = 10, accuracy = 57.000000
k = 12, accuracy = 54.200000
k = 12, accuracy = 61.000000
k = 12, accuracy = 57.000000
k = 12, accuracy = 57.800000
k = 12, accuracy = 56.200000
k = 15, accuracy = 52.000000
k = 15, accuracy = 60.400000
k = 15, accuracy = 58.400000
k = 15, accuracy = 58.400000
k = 15, accuracy = 57.000000
k = 20, accuracy = 53.600000
k = 20, accuracy = 58.600000
k = 20, accuracy = 58.200000
k = 20, accuracy = 57.400000
k = 20, accuracy = 57.200000
k = 50, accuracy = 54.600000
k = 50, accuracy = 58.200000
k = 50, accuracy = 54.800000
k = 50, accuracy = 53.400000
k = 50, accuracy = 54.600000
k = 100, accuracy = 52.200000
k = 100, accuracy = 54.400000
k = 100, accuracy = 53.400000
k = 100, accuracy = 52.000000
k = 100, accuracy = 53.400000
```

In [16]:

```
# plot the raw observations
for k in k_choices:
    accuracies = k_to_accuracies[k]
    plt.scatter([k] * len(accuracies), accuracies)

# plot the trend line with error bars that correspond to standard deviation
accuracies_mean = np.array([np.mean(v) for k,v in sorted(k_to_accuracies.items
())])
accuracies_std = np.array([np.std(v) for k,v in sorted(k_to_accuracies.items
())])
plt.errorbar(k_choices, accuracies_mean, yerr=accuracies_std)
plt.title('Cross-validation on k')
plt.xlabel('k')
plt.ylabel('Cross-validation accuracy')
plt.show()
```



In [17]:

```
# Based on the cross-validation results above, choose the best value for k,
# retrain the classifier using all the training data, and test it on the test
# data. You should be able to get above 28% accuracy on the test data.
best_k = 7

classifier = KNearestNeighbor()
classifier.train(X_train, y_train)
y_test_pred = classifier.predict(X_test, k=best_k)

# Compute and display the accuracy
num_correct = np.sum(y_test_pred == y_test)
accuracy = float(num_correct) / num_test
print('Got %d / %d correct => accuracy: %f' % (num_correct, num_test, accuracy))
```

Got 146 / 500 correct => accuracy: 0.292000

Inline Question 3 Which of the following statements about k-Nearest Neighbor (k-NN) are true in a classification setting, and for all k? Select all that apply.

- 1. The training error of a 1-NN will always be better than or equal to that of 5-NN.
- 2. The test error of a 1-NN will always be better than that of a 5-NN.
- 3. The decision boundary of the k-NN classifier is linear.
- 4. The time needed to classify a test example with the k-NN classifier grows with the size of the training set
- 5. None of the above.

Your Answer: 1, 4

Your explanation:

- 1. The training error of a 1-NN will always be 0 since the nearest neighbor of each example will be itself.
- 2. The test error of a 1-NN will differ in comparison to that of a 5-NN. The errors will vary based on the data. However, in most cases, a 5-NN will be more a generalized classifier since the label is an average of the 5 nearest neighbor rather than just 1.
- The decision boundary of a k-NN classifier is non-linear. This is so because the distance functions (L1, L2, etc) used to find the k nearest neighbors are not linear, so it usually won't lead to a linear decision boundary.
- 4. When we classify a test example, we compute the distance between the test example and each example in the training set to find the k nearest neighbors. Therefore, with more examples in the training set, we have to compute more distances.