
CONVERGENCE OF ZO-GD WITH SPHERE SMOOTHING

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1 Algorithm

Consider the following optimization problem

$$\min_{x \in \mathbb{R}^d} f(x) \tag{1}$$

in which we cannot access the gradient information of $f(x)$. The zeroth-order gradient descent algorithm iterates as follows:

$$g_k = \frac{d}{\tau}(f(x_k + \tau u_k) - f(x_k))u_k, \quad u_k \sim \mathcal{U}(\mathbb{S}^{d-1}(0, 1)), \tag{2a}$$

$$x_{k+1} = x_k - \gamma g_k. \tag{2b}$$

Since u_k is a random variable for any $k = 0, 1, \dots$, variables g_k and x_k are also random during the entire iteration process.

2 Sphere smoothing properties

Lemma 2.1. If $f(x)$ is L -smooth, it holds for any $x_k \in \mathbb{R}^d$ that

$$\|\nabla f(x_k) - \mathbb{E}_u[g_k]\| \leq L\tau \tag{3}$$

Lemma 2.2. If $f(x)$ is L -smooth, it holds for any $x_k \in \mathbb{R}^d$ that

$$\mathbb{E}_u \|g(x_k)\|^2 \leq 2d \|\nabla f(x_k)\|^2 + \frac{\tau^2 L^2 d^2}{2} \quad (4)$$

3 Convergence analysis

3.1 Non-convex analysis

Theorem 3.1. Assume $f(x)$ is L -smooth and $d \geq 8$. If $\gamma = 1/(4dL)$, ZO-GD with sphere smoothing converges as follows:

$$\frac{1}{K+1} \sum_{k=0}^K \mathbb{E} \|\nabla f(x_k)\|^2 \leq \frac{16dL(f(x_0) - f(x^*))}{K+1} + \frac{dL^2\tau^2}{2}. \quad (5)$$

Proof. Since $f(x)$ is L -smooth, we have

$$\begin{aligned} f(x_{k+1}) &\leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} \|x_{k+1} - x_k\|^2 \\ &= f(x_k) - \gamma \langle \nabla f(x_k), g_k \rangle + \frac{L\gamma^2}{2} \|g_k\|^2 \end{aligned} \quad (6)$$

We introduce the filtration $\mathcal{F}_k = \{x_k, u_{k-1}, x_{k-1}, \dots, u_0, x_0\}$ to facilitate the analysis. By taking conditional expectations over both sides of inequality (6), we have

$$\begin{aligned} \mathbb{E}_u[f(x_{k+1})|\mathcal{F}_k] &\leq f(x_k) - \gamma \langle \nabla f(x_k), \mathbb{E}_u[g_k] \rangle + \frac{L\gamma^2}{2} \mathbb{E}_u \|g_k\|^2 \\ &= f(x_k) - \frac{\gamma}{2} \|\nabla f(x_k)\|^2 - \frac{\gamma}{2} \|\mathbb{E}_u[g_k]\|^2 + \frac{\gamma}{2} \|\mathbb{E}_u[g_k] - \nabla f(x_k)\|^2 + \frac{L\gamma^2}{2} \mathbb{E}_u \|g_k\|^2 \\ &\leq f(x_k) - \frac{\gamma}{2} \|\nabla f(x_k)\|^2 + \frac{\gamma L^2 \tau^2}{2} + dL\gamma^2 \|\nabla f(x_k)\|^2 + \frac{\tau^2 L^3 d^2 \gamma^2}{4} \\ &= f(x_k) - \gamma \left(\frac{1}{2} - dL\gamma \right) \|\nabla f(x_k)\|^2 + \frac{\gamma L^2 \tau^2}{2} \left(1 + \frac{\gamma d^2 L}{2} \right). \end{aligned} \quad (7)$$

If $\gamma \leq 1/(4dL)$, the above inequality becomes

$$\mathbb{E}_u[f(x_{k+1})|\mathcal{F}_k] \leq f(x_k) - \frac{\gamma}{4} \|\nabla f(x_k)\|^2 + \frac{\gamma L^2 \tau^2}{2} \left(1 + \frac{d}{8} \right). \quad (8)$$

Taking expectations over the filtration \mathcal{F}_k , we have

$$\mathbb{E}[f(x_{k+1})] \leq \mathbb{E}[f(x_k)] - \frac{\gamma}{4} \mathbb{E} \|\nabla f(x_k)\|^2 + \frac{\gamma L^2 \tau^2}{2} \left(1 + \frac{d}{8} \right), \quad (9)$$

which implies that

$$\begin{aligned}\mathbb{E}\|\nabla f(x_k)\|^2 &\leq \frac{4}{\gamma} (\mathbb{E}[f(x_k)] - \mathbb{E}[f(x_{k+1})]) + 2L^2\tau^2(1 + \frac{d}{8}) \\ &\leq \frac{4}{\gamma} (\mathbb{E}[f(x_k)] - \mathbb{E}[f(x_{k+1})]) + \frac{dL^2\tau^2}{2}\end{aligned}\quad (10)$$

where the last inequality holds when $d \geq 8$. Taking the average over $k = 0, \dots, K$, we have

$$\frac{1}{K+1} \sum_{k=0}^K \mathbb{E}\|\nabla f(x_k)\|^2 \leq \frac{4(f(x_0) - f(x^*))}{\gamma(K+1)} + \frac{dL^2\tau^2}{2}. \quad (11)$$

Setting $\gamma = 1/(4dL)$, we achieve the final result. \square

Remark. When we use time-varying τ_k in Algorithm 2 such that $\sum_{k=0}^K \tau_k^2 \leq R^2$, ZO-GD will converge to the exact stationary point at rate

$$\frac{1}{K+1} \sum_{k=0}^K \mathbb{E}\|\nabla f(x_k)\|^2 \leq \frac{16dL(f(x_0) - f(x^*))}{K+1} + \frac{dL^2R^2}{2(K+1)}. \quad (12)$$

We leave the proof as the exercise.

3.2 Strongly-convex analysis

Theorem 3.2. Assume $f(x)$ is L -smooth, μ -strongly convex, and $d \geq 8$. If $\gamma = 1/(4dL)$, ZO-GD with sphere smoothing converges as follows:

$$\mathbb{E}[f(x_k)] - f(x^*) \leq (1 - \frac{\mu}{8dL})^k (\mathbb{E}[f(x_0)] - f(x^*)) + \frac{dL^2\tau^2}{4\mu}. \quad (13)$$

Proof. Since $f(x)$ is L -smooth and μ -strongly convex, we have

$$\|\nabla f(x)\|^2 \geq 2\mu(f(x) - f(x^*)). \quad (14)$$

Its proof can be referred to Eq.(14) in our notes for Chapter 5. Substituting the above inequality into (15), we have

$$\mathbb{E}[f(x_{k+1})] \leq \mathbb{E}[f(x_k)] - \frac{\gamma\mu}{2} \mathbb{E}[f(x_k) - f(x^*)] + \frac{\gamma L^2\tau^2}{2}(1 + \frac{d}{8}). \quad (15)$$

Subtracting $f(x^*)$ from both sides of the above inequality, we have

$$\mathbb{E}[f(x_{k+1})] - f(x^*) \leq (1 - \frac{\gamma\mu}{2})(\mathbb{E}[f(x_k)] - f(x^*)) + \frac{\gamma dL^2\tau^2}{8} \quad (16)$$

where we also used the assumption that $d \geq 8$. Keep iterating the above inequality, we have

$$\mathbb{E}[f(x_k)] - f(x^*) \leq (1 - \frac{\gamma\mu}{2})^k (\mathbb{E}[f(x_0)] - f(x^*)) + \frac{dL^2\tau^2}{4\mu}. \quad (17)$$

Setting $\gamma = 1/(4dL)$ achieves the final result. \square