# CHAPTER 0. PRELIMINARY

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## 1 Norm

**Definition 1.1** (Norm)**.** A real-valued function $\|\cdot\|$ defined on linear space $\mathbb{E}$ is called norm, if it satisfies:

1. (being positive definite) $\forall x \in \mathbb{E}$, we have $\|x\| \geq 0$, and $\|x\| = 0$ if and only if $x = 0$.
2. (being absolutely homogeneous) $\forall x \in \mathbb{E}, \alpha \in \mathbb{R}$, we have $\|\alpha x\| = |\alpha| \cdot \|x\|$.
3. (the triangle inequality) $\forall x, y \in \mathbb{E}$, we have $\|x + y\| \leq \|x\| + \|y\|$.

### 1.1 Vector Norm

We consider vector norm defined on vector space $\mathbb{E} = \mathbb{R}^n$.

**Definition 1.2** ($\ell_p$-norm)**.** The $\ell_p$-norm ($p \geq 1$) is defined as:

$$\|x\|_p = (|x_1|^p + |x_2|^p + \cdots + |x_n|^p)^{1/p},$$

for all $x = (x_1, x_2, \cdots, x_n)^\top \in \mathbb{R}^n$.

Specifically, we have the following commonly used definition of $\ell_1$-norm and $\ell_2$-norm for vector $x = (x_1, x_2, \cdots, x_n)^\top \in \mathbb{R}^n$. When $p = 1$, the $\ell_1$-norm is given by:

$$\|x\|_1 = |x_1| + |x_2| + \cdots + |x_n|.$$

When $p = 2$, the $\ell_2$-norm is the same as the Euclidean norm:

$$\|x\|_2 = \sqrt{x_1^2 + x_2^2 + \cdots + x_n^2}.$$

We have the following useful Cauchy's inequality for $\ell_2$ norm:

**Proposition 1.3** (Cauchy's inequality)**.** $\forall x, y \in \mathbb{R}^n$, we have

$$|\langle x, y\rangle| \leq \|x\|_2 \cdot \|y\|_2,$$

where $\langle x, y\rangle = x^\top y$ denotes the inner product of $x$ and $y$, and the equality holds if and only if $x$ and $y$ are linearly correlated (i.e., $\exists\, \alpha, \beta \in \mathbb{R}$, s.t. $\alpha^2 + \beta^2 > 0$ and $\alpha x + \beta y = 0$).

**Definition 1.4** ($\ell_\infty$-norm)**.** The $\ell_\infty$-norm is defined as:

$$\|x\|_\infty = \max\{|x_1|, |x_2|, \cdots, |x_n|\},$$

for all $x = (x_1, x_2, \cdots, x_n)^\top \in \mathbb{R}^n$.

**Definition 1.5** (Norm induced by a positive definite matrix $A$)**.** Given a positive definite matrix $A \in \mathbb{R}^{n\times n}$, we define:

$$\|x\|_A = \sqrt{x^\top A x},$$

for all $x = (x_1, x_2, \cdots, x_n)^\top \in \mathbb{R}^n$.

## 1.2 Matrix norm

We consider matrix norms defined on matrix space $\mathbb{E} = \mathbb{R}^{m\times n}$.

**Definition 1.6** (Frobenius norm / F-norm)**.** The Frobenius norm (or F-norm) of matrix $A \in \mathbb{R}^{m\times n}$ is defined as:

$$\|A\|_F = \sqrt{\mathrm{tr}(A^\top A)} = \sqrt{\sum_{i=1}^{m}\sum_{j=1}^{n} A_{i,j}^2},$$

where $A_{i,j}$ represents the $(i, j)$-th element of matrix $A$.

The Frobenius norm has similar properties as the $\ell_2$-norm. For example, we have the following Cauchy's inequality for the Frobenius norm.

**Proposition 1.7** (Cauchy's inequality)**.** $\forall A, B \in \mathbb{R}^{m\times n}$, we have

$$|\langle A, B\rangle| \le \|A\|_F \cdot \|B\|_F,$$

where $\langle A, B\rangle = \mathrm{tr}(A^\top B) = \mathrm{tr}(AB^\top)$ denotes the Frobenius inner product of $A$ and $B$, and the equality holds if and only if $A$ and $B$ are linearly correlated.

**Definition 1.8** (Spectral norm)**.** The spectral norm of matrix $A \in \mathbb{R}^{m\times n}$ is defined as:

$$\|A\|_2 = \max_{x\in\mathbb{R}^n, \|x\|_2=1} \|Ax\|_2.$$

For a given matrix $A \in \mathbb{R}^{m\times n}$, it can be shown that $\|A\|_2$ equals the largest singular value of $A$, and $\|A\|_2^2$ equals the largest eigenvalue of $A^\top A$ (and $AA^\top$).

By definition, we also have the following inequality:

$$\|Ax\|_2 \le \|A\|_2\|x\|_2,$$

for all $A \in \mathbb{R}^{m\times n}$ and $x \in \mathbb{R}^n$.

**Definition 1.9** (Nuclear norm)**.** The nuclear norm of matrix $A \in \mathbb{R}^{m\times n}$ is defined as:

$$\|A\|_* = \sigma_1 + \sigma_2 + \cdots + \sigma_r,$$

where $r = \mathrm{rank}(A)$ and $\sigma_1 \ge \sigma_2 \ge \cdots \ge \sigma_r$ are non-zero singular values of $A$.

We have the following inequalities for the matrix norms:

$$\begin{aligned}\|AB\|_F &\le \|A\|_2\|B\|_F,\\ |\langle A, B\rangle| &\le \|A\|_2\|B\|_*.\end{aligned}$$

# 2 Gradient

## 2.1 Gradient and Hessian matrix

**Definition 2.1** (Gradient)**.** Suppose $f : \mathbb{R}^n \to \mathbb{R}$ is continuously differentiable, its gradient $\nabla f : \mathbb{R}^n \to \mathbb{R}^n$ is defined at point $x = (x_1, x_2, \cdots, x_n)^\top$ as:

$$\nabla f(x) = \left(\frac{\partial f(x)}{\partial x_1}, \frac{\partial f(x)}{\partial x_2}, \cdots \frac{\partial f(x)}{\partial x_n}\right)^\top.$$

**Definition 2.2** (Hessian matrix)**.** Suppose $f : \mathbb{R}^n \to \mathbb{R}$ is twice continuously differentiable, its Hessian matrix $\nabla^2 f : \mathbb{R}^n \to \mathbb{R}^{n\times n}$ is defined at point $x = (x_1, x_2, \cdots, x_n)^\top$ as:

$$\nabla^2 f(x) = \begin{pmatrix} \frac{\partial^2 f(x)}{\partial x_1^2} & \frac{\partial^2 f(x)}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f(x)}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f(x)}{\partial x_2 \partial x_1} & \frac{\partial^2 f(x)}{\partial x_2^2} & \cdots & \frac{\partial^2 f(x)}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f(x)}{\partial x_n \partial x_1} & \frac{\partial^2 f(x)}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f(x)}{\partial x_n^2} \end{pmatrix}.$$

As an example, we consider gradients and Hessian matrices of two typical functions.

1. (The least squares problem) Let $f(x) := \frac{1}{2}\|Ax - b\|_2^2$, we have $\nabla f(x) = A^\top(Ax - b)$ and $\nabla^2 f(x) = A^\top A$.

2. (The logistic regression problem) Let $f(x) := \frac{1}{M}\sum_{i=1}^M \ln(1 + \exp(-b_i a_i^\top x))$, we have

$$\nabla f(x) = \frac{1}{M}\sum_{i=1}^M \frac{-b_i \exp(-b_i a_i^\top x)}{1 + \exp(-b_i a_i^\top x)} a_i,$$

and

$$[\nabla^2 f(x)]_{j,k} = \frac{1}{M}\sum_{i=1}^M \frac{b_i^2 \exp(-b_i a_i^\top x) a_{i,j} a_{i,k}}{[1 + \exp(-b_i a_i^\top x)]^2}.$$

Like univariate functions, we have Taylor expansions in the multivariate case:

**Proposition 2.3** (Taylor expansion)**.** Suppose $f : \mathbb{R}^n \to \mathbb{R}$ is continuously differentiable, $\forall x, y \in \mathbb{R}^n$, we have

$$f(x + y) = f(x) + \langle \nabla f(x + \theta_1 y), y \rangle,$$

for some $\theta_1 \in (0, 1)$. If $f$ is further twice continuously differentiable, it holds that

$$\nabla f(x + y) = \nabla f(x) + \int_0^1 \nabla^2 f(x + ty) y \mathrm{d}t,$$

and

$$f(x + y) = f(x) + \langle \nabla f(x), y \rangle + \frac{1}{2} y^\top \nabla^2 f(x + \theta_2 y) y,$$

for some $\theta_2 \in (0, 1)$.

### 2.2 $L$-smoothness

**Definition 2.4** ($L$-smoothness)**.** Function $f : \mathbb{R}^n \to \mathbb{R}$ is said to be $L$-smooth if $\forall x, y \in \mathbb{R}^n$,

$$\|\nabla f(x) - \nabla f(y)\|_2 \leq L\|x - y\|_2,$$

where $L > 0$ is the Lipschitz constant of $\nabla f$.

**Theorem 2.5** ($L$-smooth property)**.** Suppose $f : \mathbb{R}^n \to \mathbb{R}$ is $L$-smooth, it holds for $\forall x, y \in \mathbb{R}^n$ that

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2}\|y - x\|_2^2.$$

*Proof.* Let $g(t) := f(x + t(y - x))$, we have

$$g'(t) = \langle \nabla f(x + t(y - x)), y - x \rangle,$$

thus

$$\begin{aligned}
& f(y) - f(x) - \langle \nabla f(x), y - x \rangle \\
=& g(1) - g(0) - g'(0) \\
=& \int_0^1 (g'(t) - g'(0)) \mathrm{d}t \\
=& \int_0^1 \langle \nabla f(x + t(y - x)) - \nabla f(x), y - x \rangle \mathrm{d}t \\
\leq& \int_0^1 \|\nabla f(x + t(y - x)) - \nabla f(x)\|_2 \cdot \|y - x\|_2 \mathrm{d}t \\
\leq& \int_0^1 Lt\|y - x\|_2^2 \mathrm{d}t \\
=& \frac{L}{2}\|y - x\|_2^2.
\end{aligned}$$

□

# 3 Convexity

## 3.1 Convex set

**Definition 3.1** (Convex set)**.** A set $\mathcal{X} \subseteq \mathbb{R}^n$ is called convex, if for $\forall x, y \in \mathcal{X}$, it holds that

$$\theta x + (1 - \theta) y \in \mathcal{X}, \quad \forall \theta \in [0, 1].$$

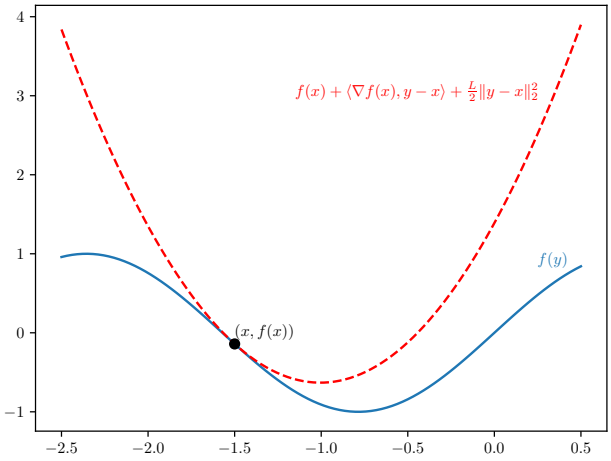


Figure 1: $L$-smooth property

**Theorem 3.2** (Projection onto closed convex sets)**.** Suppose $\mathcal{X} \subseteq \mathbb{R}^n$ is a closed convex set, then for $\forall y \in \mathbb{R}^n$, there exists a unique $x^\star \in \mathcal{X}$ such that $\|x^\star - y\|_2 \leq \|x - y\|_2$ for any $x \in \mathcal{X}$. The point $x^\star$ is called the projection of $y$ onto $\mathcal{X}$, denoted by $\mathcal{P}_{\mathcal{X}}(y)$.

*Proof.* We first prove the existence of point $x^\star$. For a given $y \in \mathbb{R}^n$, let $d := \inf_{x \in \mathcal{X}} \|x - y\|_2$, there exists sequence $\{x_k\}_{k=1}^{\infty} \subseteq \mathcal{X}$ such that $\|x_k - y\|_2^2 \leq d^2 + 1/k$. For any integers $0 < m < n$, by the convexity of $\mathcal{X}$ we have $(x_m + x_n)/2 \in \mathcal{X}$. By the definition of $d$, we have $\|(x_m + x_n)/2 - y\|_2 \geq d$. Consequently,

$$\begin{aligned}
&\langle x_m - y, x_n - y \rangle = 2\|(x_m + x_n)/2 - y\|_2^2 - \frac{\|x_m - y\|_2^2 + \|x_n - y\|_2^2}{2} \geq d^2 - \frac{1}{m}, \\
\Rightarrow &\|x_m - x_n\|_2^2 = \|x_m - y\|_2^2 + \|x_n - y\|_2^2 - 2\langle x_m - y, x_n - y \rangle \leq \frac{4}{m}.
\end{aligned}$$

Thus $\{x_k\}_{k=1}^{\infty}$ is a Cauchy sequence, which implies the existence of point $x^\star \in \mathbb{R}^n$ such that $x^\star = \lim_{k \to \infty} x_k$. By closedness of $\mathcal{X}$ we know $x^\star \in \mathcal{X}$, and by the continuity of $\ell_2$-norm we know $\|x^\star - y\|_2 = d$. Next we show the uniqueness of $x^\star$. Otherwise $\exists\, x_1^\star, x_2^\star \in \mathcal{X} (x_1^\star \neq x_2^\star)$ such that $\|x_1^\star - y\|_2 = \|x_2^\star - y\|_2 = d$, we thus have

$$\|(x_1^\star + x_2^\star)/2 - y\|_2^2 = \frac{1}{2}\|x_1^\star - y\|_2^2 + \frac{1}{2}\|x_2^\star - y\|_2^2 - \frac{1}{4}\|x_1^\star - x_2^\star\|_2^2 < d,$$

a contradiction with the definition of $d$. □

## 3.2 Convex function

**Definition 3.3** (Convex function)**.** Function $f : \mathcal{X} \to \mathbb{R}$ is said to be convex if $\mathcal{X} \subseteq \mathbb{R}^n$ is a convex set and $\forall x, y \in \mathcal{X}$, it holds that

$$f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y), \quad \forall\, \theta \in [0,1].$$

Here we list some common convex functions:

1. vector norm: $f(x) = \|x\|$,
2. quadratic function: $f(x) = \frac{1}{2}x^\top Ax$ where $A$ is positive semi-definite,
3. linear function: $f(x) = \langle a, x\rangle$ for some $a \in \mathbb{R}^n$,
4. combination of convex functions: $f(x) = \alpha_1 f_1(x) + \alpha_2 f_2(x) + \cdots + \alpha_m f_m(x)$ where $f_1, f_2, \cdots, f_m$ are convex and $\alpha_1, \alpha_2, \cdots, \alpha_m$ are non-negative.

**Theorem 3.4** (Convex property)**.** Suppose $f : \mathcal{X} \to \mathbb{R}$ is differentiable, then $f$ is convex if and only if

$$f(y) \geq f(x) + \langle \nabla f(x), y - x\rangle, \quad \forall\, x, y \in \mathcal{X}. \tag{1}$$

Similarly, $f$ is convex if and only if

$$\langle \nabla f(y) - \nabla f(x), y - x\rangle \geq 0, \quad \forall\, x, y \in \mathcal{X}. \tag{2}$$

*Proof.* Step 1: we prove that (1) holds if $f$ is convex. By definition we have for any $\theta \in [0,1]$ that $f(\theta y + (1-\theta)x) \leq \theta f(y) + (1-\theta)f(x)$. Thus,

$$\begin{aligned} f(y) - f(x) &= \lim_{\theta \to 0+0} \frac{\theta f(y) + (1-\theta)f(x) - f(x)}{\theta} \\ &\geq \lim_{\theta \to 0+0} \frac{f(\theta y + (1-\theta)x) - f(x)}{\theta} \\ &= \lim_{\theta \to 0+0} \frac{f(x + \theta(y-x)) - f(x)}{\theta} \\ &= \langle \nabla f(x), y - x\rangle. \end{aligned}$$

Step 2: we prove that $f$ is convex if (1) holds. By (1) we have for $\forall x, y \in \mathcal{X}$ and $\theta \in [0,1]$ that

$$\begin{aligned} &\theta f(x) + (1-\theta)f(y) - f(\theta x + (1-\theta)f(y)) \\ =&\theta(f(x) - f(\theta x + (1-\theta)y)) + (1-\theta)(f(y) - f(\theta x + (1-\theta)y)) \\ \geq&\theta\langle \nabla f(\theta x + (1-\theta)y), (1-\theta)(x-y)\rangle + (1-\theta)\langle \nabla f(\theta x + (1-\theta)y), \theta(y-x)\rangle \\ =&0. \end{aligned}$$

Step 3: we prove that (1) implies (2). By (1) we have

$$\begin{aligned} f(y)+f(x) \geq & (f(x)+\langle \nabla f(x), y-x\rangle)+(f(y)+\langle \nabla f(y), x-y\rangle) \\ = & f(x)+f(y)-\langle \nabla f(y)-\nabla f(x), y-x\rangle, \end{aligned}$$

which is equivalent to (2).
Step 4: we prove that (2) implies (1). This follows from

$$\begin{aligned} f(y)-f(x) &= \int_0^1 \langle \nabla f(x+t(y-x)), y-x\rangle \mathrm{d}t \\ &= \int_0^1 \left( \langle \nabla f(x), y-x\rangle + \frac{1}{t}\langle \nabla f(x+t(y-x))-\nabla f(x), t(y-x)\rangle \right) \mathrm{d}t \\ &\geq \int_0^1 \langle \nabla f(x), y-x\rangle \mathrm{d}t \\ &= \langle \nabla f(x), y-x\rangle. \end{aligned}$$

□

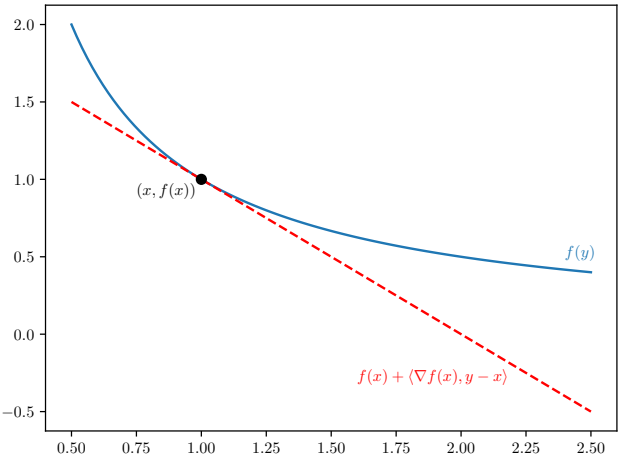


Figure 2: convex property

The following Jensen's inequality is an important property of convex functions.

**Proposition 3.5** (Jensen's inequality)**.** Let $f : \mathcal{X} \to \mathbb{R}$ be convex, then for any $x_1, x_2, \cdots, x_m \in \mathcal{X}$ and non-negative $\theta_1, \theta_2, \cdots, \theta_m$ satisfying $\theta_1+\theta_2+\cdots+\theta_m = 1$, it holds that

$$f(\theta_1 x_1+\theta_2 x_2+\cdots+\theta_m x_m) \leq \theta_1 f(x_1)+\theta_2 f(x_2)+\cdots+\theta_m f(x_m).$$

**Definition 3.6** ($\mu$-strongly convex function)**.** Function $f : \mathcal{X} \to \mathbb{R}$ is said to be $\mu$-strongly convex if

$$g(x) := f(x) - \frac{\mu}{2}\|x\|_2^2$$

is a convex function.

It can be proved that $f : \mathcal{X} \to \mathbb{R}$ is $\mu$-strongly convex if and only if for $\forall x, y \in \mathcal{X}$ and $\theta \in [0, 1]$, it holds that

$$f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y) - \frac{\mu}{2}\theta(1-\theta)\|x-y\|_2^2.$$

**Theorem 3.7** ($\mu$-strongly convex property)**.** Function $f : \mathcal{X} \to \mathbb{R}$ is $\mu$-strongly convex if and only if

$$f(y) \geq f(x) + \langle \nabla f(x), y - x\rangle + \frac{\mu}{2}\|y-x\|_2^2, \quad \forall\, x, y \in \mathcal{X}, \tag{3}$$

if and only if

$$\langle \nabla f(y) - \nabla f(x), y - x\rangle \geq \mu\|y-x\|_2^2, \quad \forall\, x, y \in \mathcal{X}. \tag{4}$$

*Proof.* Let $g(x) := f(x) - \frac{\mu}{2}\|x\|_2^2$, then $f$ is $\mu$-strongly convex if and only if $g$ is convex. Note that (3) is equivalent to

$$\begin{aligned} &g(y) + \frac{\mu}{2}\|y\|_2^2 \geq g(x) + \frac{\mu}{2}\|x\|_2^2 + \langle \nabla g(x) + \mu x, y - x\rangle + \frac{\mu}{2}\|y-x\|_2^2, \\ \Leftrightarrow &g(y) \geq g(x) + \langle \nabla g(x), y - x\rangle, \end{aligned}$$

and that (4) is equivalent to

$$\begin{aligned} &\langle \nabla g(y) + \mu y - \nabla g(x) - \mu x, y - x\rangle \geq \mu\|y-x\|_2^2 \\ \Leftrightarrow &\langle \nabla g(y) - \nabla g(x), y - x\rangle \geq 0, \end{aligned}$$

it suffices to apply Theorem 3.4. □

**Theorem 3.8** ($\mu$-strongly convex property)**.** Let $f : \mathbb{R}^n \to \mathbb{R}$ be $\mu$-strongly convex, then the following inequalities hold:

$$f(y) \leq f(x) + \langle \nabla f(x), y - x\rangle + \frac{1}{2\mu}\|\nabla f(y) - \nabla f(x)\|_2^2, \quad \forall\, x, y \in \mathbb{R}^n,$$

$$\langle \nabla f(y) - \nabla f(x), y - x\rangle \leq \frac{1}{\mu}\|\nabla f(y) - \nabla f(x)\|_2^2, \quad \forall\, x, y \in \mathbb{R}^n.$$

*Proof.* Fix $x \in \mathbb{R}^n$, and let $\phi(y) := f(y) - f(x) - \langle \nabla f(x), y - x\rangle$, we know $\phi$ is $\mu$-strongly

convex with minimum $\phi(x) = 0$. Thus,

$$\begin{aligned}0 =& \min_v \phi(v) \geq \min_v \left(\phi(y) + \langle \nabla\phi(y), v - y\rangle + \frac{\mu}{2}\|v - y\|_2^2\right)\\ =& \phi(y) - \frac{1}{\mu}\|\nabla\phi(y)\|_2^2 + \frac{\mu}{2}\left\|\frac{1}{\mu}\nabla\phi(y)\right\|_2^2 = \phi(y) - \frac{1}{2\mu}\|\nabla\phi(y)\|_2^2\\ =& f(y) - f(x) - \langle \nabla f(x), y - x\rangle - \frac{1}{2\mu}\|\nabla f(y) - \nabla f(x)\|_2^2,\end{aligned}$$

which is equivalent to

$$f(y) \leq f(x) + \langle \nabla f(x), y - x\rangle + \frac{1}{2\mu}\|\nabla f(y) - \nabla f(x)\|_2^2.$$

Summing the two copies of the above inequality with $x$ and $y$ interchanged, we obtain

$$\langle \nabla f(y) - \nabla f(x), y - x\rangle \leq \frac{1}{\mu}\|\nabla f(y) - \nabla f(x)\|_2^2.$$

□

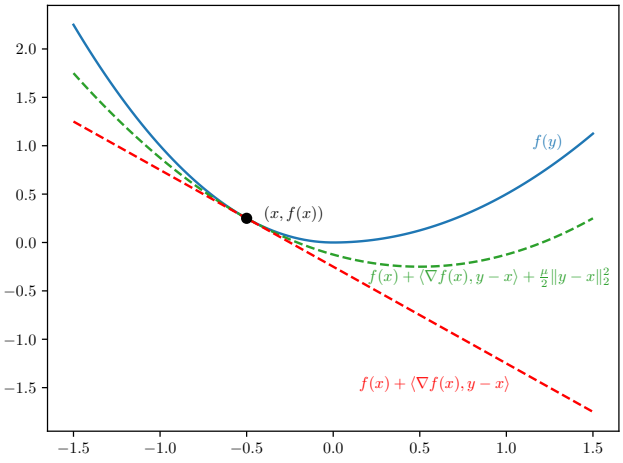


Figure 3: $\mu$-strongly convex property

$L$-smooth convex functions are widely considered in optimization, which have the fundamental properties below.

**Theorem 3.9** ($L$-smooth convex property)**.** Let $f : \mathbb{R}^n \to \mathbb{R}$ be differentiable, then $f$ is convex and $L$-smooth if and only if any one of the following conditions holds:

$$0 \le f(y) - f(x) - \langle \nabla f(x), y - x \rangle \le \frac{L}{2}\|y - x\|_2^2, \quad \forall\, x, y \in \mathbb{R}^n, \tag{5}$$

$$f(y) - f(x) - \langle \nabla f(x), y - x \rangle \ge \frac{1}{2L}\|\nabla f(y) - \nabla f(x)\|_2^2, \quad \forall\, x, y \in \mathbb{R}^n, \tag{6}$$

$$\langle \nabla f(y) - \nabla f(x), y - x \rangle \ge \frac{1}{L}\|\nabla f(y) - \nabla f(x)\|_2^2, \quad \forall\, x, y \in \mathbb{R}^n, \tag{7}$$

$$0 \le \langle \nabla f(y) - \nabla f(x), y - x \rangle \le L\|y - x\|_2^2, \quad \forall\, x, y \in \mathbb{R}^n. \tag{8}$$

*Proof.* Step 1: we show (5) holds when $f$ is $L$-smooth and convex. In fact, (5) is a direct result of Theorem 3.4 and Theorem 2.5.
Step 2: we show (5) implies (6). Fix $x \in \mathbb{R}^n$ and let $\phi(y) := f(y) - f(x) - \langle \nabla f(x), y - x \rangle$. By (5) we know $\phi(x) = 0$ is the minimum of $\phi$. Substituting $y$ by $y - \frac{1}{L}\nabla\phi(y)$ and applying (5), we obtain

$$\begin{aligned}
0 \le& \phi\left(y - \frac{1}{L}\nabla\phi(y)\right) = f\left(y - \frac{1}{L}\nabla\phi(y)\right) - f(x) - \left\langle \nabla f(x), y - \frac{1}{L}\nabla\phi(y) - x \right\rangle \\
\le& f(y) - \left\langle \nabla f(y), \frac{1}{L}\nabla\phi(y) \right\rangle + \frac{L}{2}\left\| \frac{1}{L}\nabla\phi(y) \right\|_2^2 - f(x) - \left\langle \nabla f(x), y - \frac{1}{L}\nabla\phi(y) - x \right\rangle \\
=& f(y) - f(x) - \langle \nabla f(x), y - x \rangle - \frac{1}{2L}\|\nabla f(y) - \nabla f(x)\|_2^2.
\end{aligned}$$

Step 3: we show (6) implies (7).

$$\begin{aligned}
\frac{1}{L}\|\nabla f(y) - \nabla f(x)\|_2^2 =& \frac{1}{2L}\|\nabla f(y) - \nabla f(x)\|_2^2 + \frac{1}{2L}\|\nabla f(x) - \nabla f(y)\|_2^2 \\
\le& \left(f(y) - f(x) - \langle \nabla f(x), y - x \rangle\right) + \left(f(x) - f(y) - \langle \nabla f(y), x - y \rangle\right) \\
=& \langle \nabla f(y) - \nabla f(x), y - x \rangle.
\end{aligned}$$

Step 4: we show (7) implies $f$ is $L$-smooth and convex. The convexity can be justified by directly applying Theorem 3.4. By Cauchy's inequality, we have

$$\frac{1}{L}\|\nabla f(y) - \nabla f(x)\|_2^2 \le \langle \nabla f(y) - \nabla f(x), y - x \rangle \le \|\nabla f(y) - \nabla f(x)\|_2 \cdot \|y - x\|_2,$$

which implies

$$\|\nabla f(y) - \nabla f(x)\|_2 \le L\|y - x\|_2.$$

Step 5: we show (5) implies (8). This can be achieved by directly adding two copies of (5) with $x$ and $y$ interchanged.
Step 6: we show (8) implies (5). By Theorem 3.4, it remains to show the second inequality

in (5).

$$\begin{aligned} f(y) - f(x) - \langle \nabla f(x), y - x \rangle &= \int_0^1 \langle \nabla f(x + t(y-x)) - \nabla f(x), y - x \rangle \mathrm{d}t \\ &\leq \int_0^1 \frac{L}{t} \|t(y-x)\|_2^2 \mathrm{d}t \\ &= \frac{L}{2} \|y - x\|_2^2. \end{aligned}$$

□

We also has the following property for $L$-smooth and $\mu$-strongly convex functions. By Theorem 2.5 and Theorem 3.7 we can easily know the fact that $\mu \leq L$.

**Theorem 3.10** ($L$-smooth $\mu$-strongly convex property)**.** Let $f : \mathbb{R}^n \to \mathbb{R}$ be $L$-smooth and $\mu$-strongly convex, then for $\forall\, x, y \in \mathbb{R}^n$, the following inequality holds:

$$\langle \nabla f(y) - \nabla f(x), y - x \rangle \geq \frac{\mu L}{\mu + L} \|y - x\|_2^2 + \frac{1}{\mu + L} \|\nabla f(y) - \nabla f(x)\|_2^2.$$

*Proof.* If $\mu = L$, we have

$$\begin{aligned} &\frac{\mu L}{\mu + L} \|y - x\|_2^2 + \frac{1}{\mu + L} \|\nabla f(y) - \nabla f(x)\|_2^2 \\ =&\frac{\mu}{2} \|y - x\|_2^2 + \frac{1}{2L} \|\nabla f(y) - \nabla f(x)\|_2^2 \\ \leq&\frac{1}{2} \langle \nabla f(y) - \nabla f(x), y - x \rangle + \frac{1}{2} \langle \nabla f(y) - \nabla f(x), y - x \rangle \\ =&\langle \nabla f(y) - \nabla f(x), y - x \rangle. \end{aligned}$$

If $\mu < L$, $g(x) := f(x) - \frac{\mu}{2}\|x\|_2^2$ is $(L - \mu)$-smooth convex function, implying

$$\langle \nabla g(y) - \nabla g(x), y - x \rangle \geq \frac{1}{L - \mu} \|\nabla g(y) - \nabla g(x)\|_2^2,$$

which is equivalent to

$$\langle \nabla f(y) - \nabla f(x), y - x \rangle \geq \frac{\mu L}{\mu + L} \|y - x\|_2^2 + \frac{1}{\mu + L} \|\nabla f(y) - \nabla f(x)\|_2^2.$$

□