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Table of Contents

1	Int	roduction and functional overview	7
2	Ac	ronyms and abbreviations	9
3	Re	lated documentation	10
	3.1	Input documents	10
	3.2	Related standards and norms	
	3.3	Related specification	10
4	Co	nstraints and assumptions	11
	4.1	Limitations	11
	4.2	Applicability to car domains	
5	De	pendencies to other modules	12
6	Re	quirements traceability	13
7	Fu	nctional specification	21
	7.1	Error classification	21
	7.1	.1 Development Errors	21
	7.1	·	
	7.1	.3 Transient Faults	21
	7.1		
	7.1	.5 Extended Production Errors	21
8	AP	I specification	22
	8.1	Imported types	
	8.1	71	
	8.2		
	8.2	- =- ····· 71 ·	
	8.2	· ···	
	8.3		
		8.1 Memlf_Read	
	8.3	=	
	8.3	-	
	8.3 8.3	-	
	8.3	=	
	8.3	=	
	8.3	=	
	8.4	Call-back notifications	
	8.5	Scheduled functions	
	8.6	Expected Interfaces	
		5.1 Mandatory Interfaces	
	8.6	· · · · · · · · · · · · · · · · · · ·	
	8.6	•	
_		G	
9	Se	quence diagrams	აპ



10	Confi	guration specification	34
1	0.1 Co	ontainers and configuration parameters	34
		Memlf	
		MemlfGeneral	
11	Not a	pplicable requirements	36



1 Introduction and functional overview

This specification describes the functionality, API and configuration of the AUTOSAR Basic Software Module "Memory Abstraction Interface" (MemIf). This module allows the NVRAM manager to access several memory abstraction modules (FEE or EA modules) (see Figure 1).

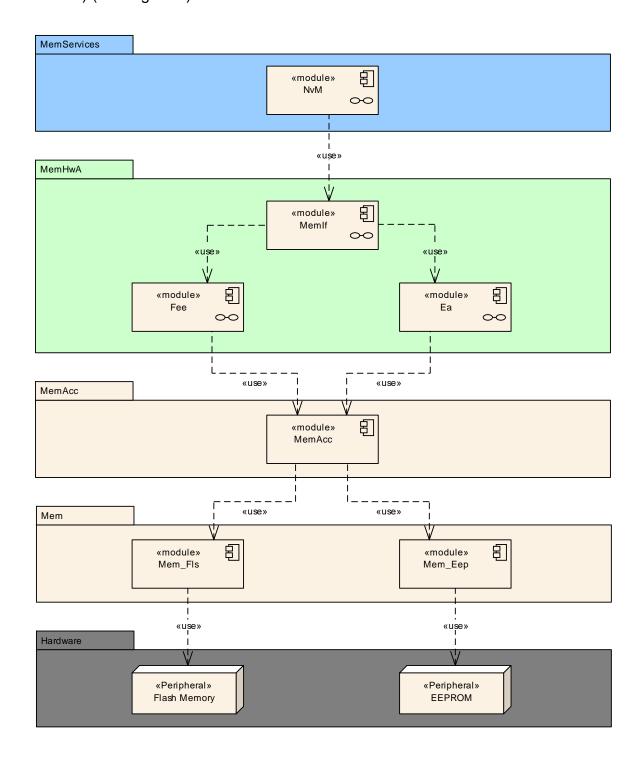
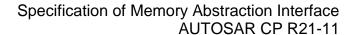


Figure 1: Module overview of memory hardware abstraction layer





The Memory Abstraction Interface (MemIf) shall abstract from the number of underlying FEE or EA modules and provide upper layers with a virtual segmentation on a uniform linear address space.



2 Acronyms and abbreviations

Acronyms and abbreviations which have a local scope and therefore are not contained in the AUTOSAR glossary must appear in a local glossary.

Abbreviation /	Description:
Acronym:	
EA	EEPROM Abstraction
EEPROM	Electrically Erasable and Programmable ROM (Read Only Memory)
FEE	Flash EEPROM Emulation
LSB	Least significant bit / byte (depending on context). Here it's bit.
Mem	AUTOSAR Basic Software Module Memory Driver
MemAcc	AUTOSAR Basic Software Module Memory Access
MemIf	Memory Abstraction Interface
MSB	Most significant bit / byte (depending on context). Here it's bit.
NvM	NVRAM Manager
NVRAM	Non-volatile RAM (Random Access Memory)
Address area	Contiguous memory area in the logical address space. Typically, multiple physical memory sectors are combined to one logical address area.
Fast Mode	E.g. during startup / shutdown the underlying driver may be switched into fast mode in order to allow for fast reading / writing in those phases.
	Note: Whether this is possible depends on the implementation of the driver and the capabilities of the underlying device. Whether it is done depends on the configuration of the NVRAM manager and thus on the needs of a specific project.
Slow Mode	During normal operation the underlying driver may be used in slow mode in order to reduce the resource usage in terms of runtime or blocking time of the underlying device / communication media.
	Note: Whether this is possible depends on the implementation of the driver and the capabilities of the underlying device. Whether it is done depends on the configuration of the NVRAM manager and thus on the needs of a specific project.
Vendor specific library	A vendor specific library is an ICC-2 implementation of the FEE/FLS and EA/EEP modules respectively. It provides the same upper layer interface (API) and functionality as the corresponding ICC-3 implementation.



3 Related documentation

3.1 Input documents

- [1] List of Basic Software Modules AUTOSAR_TR_BSWModuleList.pdf
- [2] Layered Software Architecture
 AUTOSAR EXP LayeredSoftwareArchitecture.pdf.pdf
- [3] General Requirements on Basic Software Modules AUTOSAR_SRS_BSWGeneral.pdf
- [4] General Requirements on SPAL AUTOSAR_SRS_SPALGeneral.pdf
- [5] Requirements on Memory Hardware Abstraction Layer AUTOSAR_SRS_MemoryHWAbstractionLayer.doc
- [6] Specification of Default Error Tracer AUTOSAR_SWS_DefaultErrorTracer.pdf
- [7] General Specification of Basic Software Modules AUTOSAR_SWS_BSWGeneral.pdf

3.2 Related standards and norms

- [7] Specification of NVRAM Manager AUTOSAR_SWS_NVRAMManager.doc
- [8] Specification of Flash EEPROM Emulation AUTOSAR_SWS_FlashEEPROMEmulation.pdf
- [9] Specification of EEPROM Abstraction AUTOSAR_SWS_EEPROMAbstraction.pdf

3.3 Related specification



4 Constraints and assumptions

4.1 Limitations

No limitations.

4.2 Applicability to car domains

No restrictions.



5 Dependencies to other modules



6 Requirements traceability

Requirement	Description	Satisfied by
RS_BRF_02272	AUTOSAR shall offer tracing of application software behavior	SWS_MemIf_00042
SRS_BSW_00005	Modules of the µC Abstraction Layer (MCAL) may not have hard coded horizontal interfaces	SWS_MemIf_00999
SRS_BSW_00006	The source code of software modules above the µC Abstraction Layer (MCAL) shall not be processor and compiler dependent.	SWS_MemIf_00999
SRS_BSW_00007	All Basic SW Modules written in C language shall conform to the MISRA C 2012 Standard.	SWS_MemIf_00999
SRS_BSW_00009	All Basic SW Modules shall be documented according to a common standard.	SWS_MemIf_00999
SRS_BSW_00010	The memory consumption of all Basic SW Modules shall be documented for a defined configuration for all supported platforms.	SWS_MemIf_00999
SRS_BSW_00101	The Basic Software Module shall be able to initialize variables and hardware in a separate initialization function	SWS_MemIf_00999
SRS_BSW_00159	All modules of the AUTOSAR Basic Software shall support a tool based configuration	SWS_MemIf_00999
SRS_BSW_00160	Configuration files of AUTOSAR Basic SW module shall be readable for human beings	SWS_MemIf_00999
SRS_BSW_00161	The AUTOSAR Basic Software shall provide a microcontroller abstraction layer which provides a standardized interface to higher software layers	SWS_MemIf_00999
SRS_BSW_00162	The AUTOSAR Basic Software shall provide a hardware abstraction layer	SWS_MemIf_00999
SRS_BSW_00164	The Implementation of interrupt service routines shall be done by the Operating System, complex drivers or modules	SWS_MemIf_00999
SRS_BSW_00168	SW components shall be tested by a function defined in a common API in the Basis-SW	SWS_MemIf_00999



SRS_BSW_00170	The AUTOSAR SW Components shall provide information about their dependency from faults, signal qualities, driver demands	SWS_MemIf_00999
SRS_BSW_00172	The scheduling strategy that is built inside the Basic Software Modules shall be compatible with the strategy used in the system	SWS_MemIf_00999
SRS_BSW_00300	All AUTOSAR Basic Software Modules shall be identified by an unambiguous name	SWS_MemIf_00999
SRS_BSW_00302	All AUTOSAR Basic Software Modules shall only export information needed by other modules	SWS_MemIf_00999
SRS_BSW_00304	All AUTOSAR Basic Software Modules shall use only AUTOSAR data types instead of native C data types	SWS_MemIf_00999
SRS_BSW_00306	AUTOSAR Basic Software Modules shall be compiler and platform independent	SWS_MemIf_00999
SRS_BSW_00307	Global variables naming convention	SWS_MemIf_00999
SRS_BSW_00308	AUTOSAR Basic Software Modules shall not define global data in their header files, but in the C file	SWS_MemIf_00999
SRS_BSW_00309	All AUTOSAR Basic Software Modules shall indicate all global data with read-only purposes by explicitly assigning the const keyword	SWS_MemIf_00999
SRS_BSW_00312	Shared code shall be reentrant	SWS_MemIf_00999
SRS_BSW_00314	All internal driver modules shall separate the interrupt frame definition from the service routine	SWS_MemIf_00999
SRS_BSW_00321	The version numbers of AUTOSAR Basic Software Modules shall be enumerated according specific rules	SWS_MemIf_00999
SRS_BSW_00323	All AUTOSAR Basic Software Modules shall check passed API parameters for validity	SWS_MemIf_00022
SRS_BSW_00325	The runtime of interrupt service routines and functions that are running in interrupt context shall be kept short	SWS_MemIf_00999
SRS_BSW_00327	Error values naming convention	SWS_MemIf_00006



SRS_BSW_00328	All AUTOSAR Basic Software Modules shall avoid the duplication of code	SWS_MemIf_00999
SRS_BSW_00330	It shall be allowed to use macros instead of functions where source code is used and runtime is critical	SWS_MemIf_00999
SRS_BSW_00333	For each callback function it shall be specified if it is called from interrupt context or not	SWS_MemIf_00999
SRS_BSW_00334	All Basic Software Modules shall provide an XML file that contains the meta data	SWS_MemIf_00999
SRS_BSW_00336	Basic SW module shall be able to shutdown	SWS_MemIf_00999
SRS_BSW_00337	Classification of development errors	SWS_MemIf_00006
SRS_BSW_00339	Reporting of production relevant error status	SWS_MemIf_00999
SRS_BSW_00341	Module documentation shall contains all needed informations	SWS_MemIf_00999
SRS_BSW_00342	It shall be possible to create an AUTOSAR ECU out of modules provided as source code and modules provided as object code, even mixed	SWS_MemIf_00999
SRS_BSW_00343	The unit of time for specification and configuration of Basic SW modules shall be preferably in physical time unit	SWS_MemIf_00999
SRS_BSW_00347	A Naming seperation of different instances of BSW drivers shall be in place	SWS_MemIf_00999
SRS_BSW_00348	All AUTOSAR standard types and constants shall be placed and organized in a standard type header file	SWS_MemIf_00999
SRS_BSW_00353	All integer type definitions of target and compiler specific scope shall be placed and organized in a single type header	SWS_MemIf_00999
SRS_BSW_00358	The return type of init() functions implemented by AUTOSAR Basic Software Modules shall be void	SWS_MemIf_00999
SRS_BSW_00359	All AUTOSAR Basic Software Modules callback functions shall avoid return types other than void if possible	SWS_MemIf_00999
SRS_BSW_00360	AUTOSAR Basic Software Modules callback functions are	SWS_MemIf_00999



SRS_BSW_00361 All mappings of not standardized keywords of compiler specific scope shall be placed and organized in a compiler specific type and keyword header SRS_BSW_00369 All AUTOSAR Basic Software Modules shall not return specific development error codes via the API SWS_MemIf_00099 SWS_MemIf_00024	
Modules shall not return specific development error codes via the	
SRS_BSW_00373 The main processing function of each AUTOSAR Basic Software Module shall be named according the defined convention SWS_MemIf_00999	
SRS_BSW_00375 Basic Software Modules shall report wake-up reasons SWS_MemIf_00999	
SRS_BSW_00378 AUTOSAR shall provide a SWS_MemIf_00999 boolean type	
SRS_BSW_00380 Configuration parameters being stored in memory shall be placed into separate c-files	
SRS_BSW_00384 The Basic Software Module specifications shall specify at least in the description which other modules they require	
SRS_BSW_00385 List possible error notifications SWS_MemIf_00048	
SRS_BSW_00386 The BSW shall specify the configuration for detecting an error SWS_MemIf_00006, SWS_MemI	f_00023
SRS_BSW_00392 Parameters shall have a type SWS_MemIf_00037, SWS_MemIf_00064, SWS_MemI	lf_00065
SRS_BSW_00398 The link-time configuration is achieved on object code basis in the stage after compiling and before linking SWS_MemIf_00999	
SRS_BSW_00399 Parameter-sets shall be located in a separate segment and shall be loaded after the code SWS_MemIf_00999	
SRS_BSW_00400 Parameter shall be selected from multiple sets of parameters after code has been loaded and started SWS_MemIf_00999	
SRS_BSW_00401 Documentation of multiple instances of configuration parameters shall be available SWS_MemIf_00999	
SRS_BSW_00404 BSW Modules shall support SWS_MemIf_00999 post-build configuration	
SRS_BSW_00405 BSW Modules shall support SWS_MemIf_00999 multiple configuration sets	
SRS_BSW_00406 A static status variable denoting SWS_MemIf_00999	



h		
	if a BSW module is initialized shall be initialized with value 0 before any APIs of the BSW module is called	
SRS_BSW_00407	Each BSW module shall provide a function to read out the version information of a dedicated module implementation	SWS_MemIf_00045
SRS_BSW_00413	An index-based accessing of the instances of BSW modules shall be done	SWS_MemIf_00999
SRS_BSW_00414	Init functions shall have a pointer to a configuration structure as single parameter	SWS_MemIf_00999
SRS_BSW_00415	Interfaces which are provided exclusively for one module shall be separated into a dedicated header file	SWS_MemIf_00999
SRS_BSW_00416	The sequence of modules to be initialized shall be configurable	SWS_MemIf_00999
SRS_BSW_00417	Software which is not part of the SW-C shall report error events only after the DEM is fully operational.	SWS_MemIf_00999
SRS_BSW_00422	Pre-de-bouncing of error status information is done within the DEM	SWS_MemIf_00999
SRS_BSW_00423	BSW modules with AUTOSAR interfaces shall be describable with the means of the SW-C Template	SWS_MemIf_00999
SRS_BSW_00424	BSW module main processing functions shall not be allowed to enter a wait state	SWS_MemIf_00999
SRS_BSW_00425	The BSW module description template shall provide means to model the defined trigger conditions of schedulable objects	SWS_MemIf_00999
SRS_BSW_00426	BSW Modules shall ensure data consistency of data which is shared between BSW modules	SWS_MemIf_00999
SRS_BSW_00427	ISR functions shall be defined and documented in the BSW module description template	SWS_MemIf_00999
SRS_BSW_00428	A BSW module shall state if its main processing function(s) has to be executed in a specific order or sequence	SWS_MemIf_00999
SRS_BSW_00429	Access to OS is restricted	SWS_MemIf_00999
SRS_BSW_00432	Modules should have separate	SWS_MemIf_00999
Parameter Control of the Control of	<u>-</u>	



	main processing functions for read/receive and write/transmit data path	
SRS_BSW_00433	Main processing functions are only allowed to be called from task bodies provided by the BSW Scheduler	SWS_MemIf_00999
SRS_MemHwAb_14010	The FEE and EA modules shall provide a write service that operates only on complete configured logical blocks	SWS_MemIf_00040
SRS_MemHwAb_14019	The Memory Abstraction Interface shall provide uniform access to the API services of the underlying memory abstraction modules	SWS_MemIf_00017
SRS_MemHwAb_14020	The Memory Abstraction Interface shall allow the selection of an underlying memory abstraction module by using a device index	SWS_MemIf_00011, SWS_MemIf_00018, SWS_MemIf_00035
SRS_MemHwAb_14021	The Memory Abstraction Interface shall allow the pre- compile time configuration of the number of underlying memory abstraction modules	SWS_MemIf_00018, SWS_MemIf_00019, SWS_MemIf_00020, SWS_MemIf_00022
SRS_MemHwAb_14022	The Memory Abstraction Interface shall preserve the functionality of the underlying memory abstraction module	SWS_MemIf_00010, SWS_MemIf_00017, SWS_MemIf_00039, SWS_MemIf_00040, SWS_MemIf_00041, SWS_MemIf_00042, SWS_MemIf_00043, SWS_MemIf_00044, SWS_MemIf_00046
SRS_MemHwAb_14023	The Memory Abstraction Interface shall only check those parameters that are used within the interface itself	SWS_MemIf_00022
SRS_MemHwAb_14028	The FEE and EA modules shall provide a service to invalidate a logical block	SWS_MemIf_00044
SRS_MemHwAb_14029	The FEE and EA modules shall provide a read service that allows reading all or part of a logical block	SWS_MemIf_00039
SRS_MemHwAb_14031	The FEE and EA modules shall provide a service that allows canceling an ongoing asynchronous operation	SWS_MemIf_00041
SRS_MemHwAb_14032	The FEE and EA modules shall provide an erase service that operates only on complete logical blocks containing immediate data	SWS_MemIf_00046



SRS_SPAL_00157	All drivers and handlers of the AUTOSAR Basic Software shall implement notification mechanisms of drivers and handlers	SWS_MemIf_00999
SRS_SPAL_12056	All driver modules shall allow the static configuration of notification mechanism	SWS_MemIf_00999
SRS_SPAL_12057	All driver modules shall implement an interface for initialization	SWS_MemIf_00999
SRS_SPAL_12063	All driver modules shall only support raw value mode	SWS_MemIf_00999
SRS_SPAL_12064	All driver modules shall raise an error if the change of the operation mode leads to degradation of running operations	SWS_MemIf_00999
SRS_SPAL_12067	All driver modules shall set their wake-up conditions depending on the selected operation mode	SWS_MemIf_00999
SRS_SPAL_12068	The modules of the MCAL shall be initialized in a defined sequence	SWS_MemIf_00999
SRS_SPAL_12069	All drivers of the SPAL that wake up from a wake-up interrupt shall report the wake-up reason	SWS_MemIf_00999
SRS_SPAL_12075	All drivers with random streaming capabilities shall use application buffers	SWS_MemIf_00999
SRS_SPAL_12077	All drivers shall provide a non blocking implementation	SWS_MemIf_00999
SRS_SPAL_12078	The drivers shall be coded in a way that is most efficient in terms of memory and runtime resources	SWS_MemIf_00019, SWS_MemIf_00020
SRS_SPAL_12092	The driver's API shall be accessed by its handler or manager	SWS_MemIf_00999
SRS_SPAL_12125	All driver modules shall only initialize the configured resources	SWS_MemIf_00999
SRS_SPAL_12129	The ISRs shall be responsible for resetting the interrupt flags and calling the according notification function	SWS_MemIf_00999
SRS_SPAL_12163	All driver modules shall implement an interface for de-initialization	SWS_MemIf_00999
SRS_SPAL_12263	The implementation of all driver modules shall allow the	SWS_MemIf_00999



	configuration of specific module parameter types at link time	
SRS_SPAL_12265	Configuration data shall be kept constant	SWS_MemIf_00999
SRS_SPAL_12267	Wakeup sources shall be initialized by MCAL drivers and/or the MCU driver	SWS_MemIf_00999
SRS_SPAL_12448	All driver modules shall have a specific behavior after a development error detection	SWS_MemIf_00023
SRS_SPAL_12461	Specific rules regarding initialization of controller registers shall apply to all driver implementations	SWS_MemIf_00999
SRS_SPAL_12462	The register initialization settings shall be published	SWS_MemIf_00999
SRS_SPAL_12463	The register initialization settings shall be combined and forwarded	SWS_MemIf_00999



7 Functional specification

7.1 Error classification

The section 7.2 "Error Handling" of the document "General Specification of Basic Software Modules" describes the error handling of the Basic Software in detail. Above all, it constitutes a classification scheme consisting of five error types which may occur in BSW modules.

Based on this foundation, the following section specifies particular errors arranged in the respective subsections below.

7.1.1 Development Errors

[SWS_MemIf_00006][

Type of error	Related error code	Error value
API service called with wrong device index parameter	MEMIF_E_PARAM_DEVICE	0x01
API service called with NULL pointer argument	MEMIF_E_PARAM_POINTER	0x02

[(SRS_BSW_00337, SRS_BSW_00386, SRS_BSW_00327)

7.1.2 Runtime Errors

There are no runtime errors.

7.1.3 Transient Faults

There are no transient faults.

7.1.4 Production Errors

There are no production errors.

7.1.5 Extended Production Errors

There are no extended production errors.



8 API specification

8.1 Imported types

8.1.1 Standard types

In this chapter, all types included from the following modules are listed:

[SWS_MemIf_00037][

Module	Header File	Imported Type
	MemAcc.h	MemAcc_AddressArealdType (draft)
	MemAcc.h	MemAcc_AddressType (draft)
MemAcc	MemAcc.h	MemAcc_DataType (draft)
	MemAcc.h	MemAcc_JobResultType (draft)
	MemAcc.h	MemAcc_LengthType (draft)
Std	Std_Types.h	Std_ReturnType
	Std_Types.h	Std_VersionInfoType

(SRS_BSW_00392)

8.2 Type definitions

[SWS_MemIf_00010] [The types specified in this chapter shall not be changed or extended for a specific memory abstraction module or hardware platform.] (SRS_MemHwAb_14022)

[SWS_MemIf_00011] [The data type for the memory device index shall be uint8. The lowest value to be used for this device index shall be 0. The allowed range of indices thus shall be 0..MEMIF NUMBER OF DEVICES-1.] (SRS_MemHwAb_14020)

8.2.1 Memlf_StatusType

[SWS Memlf 00064][

Name	MemIf_StatusType		
Kind	Enumeration		
Dongo	MEMIF_UNINIT		The underlying abstraction module or device driver has not been initialized (yet).
Range	MEMIF_IDLE		The underlying abstraction module or device driver is currently idle.



	MEMIF_BUSY		The underlying abstraction module or device driver is currently busy.
	MEMIF_BUSY_ INTERNAL		The underlying abstraction module is busy with internal management operations. The underlying device driver can be busy or idle.
Description	Denotes the current status of the underlying abstraction module and device drive.		
Available via	Memlf.h		

J(SRS_BSW_00392)

8.2.2 Memlf_JobResultType

[SWS_MemIf_00065]{OBSOLETE} [

[OVVO_Mem	SVV3_INIEITIII_UUUU3]{\OBSOLETE}				
Name	MemIf_JobResultType (obsolete)				
Kind	Enumeration				
	MEMIF_JOB_OK		The job has been finished successfully.		
	MEMIF_JOB_FAILED		The job has not been finished successfully.		
	MEMIF_JOB_PENDING		The job has not yet been finished.		
Range	MEMIF_JOB_ CANCELED		The job has been canceled.		
	MEMIF_BLOCK_ INCONSISTENT		The requested block is inconsistent, it may contain corrupted data. 2. Block is NOT found.		
	MEMIF_BLOCK_ INVALID		The requested block has been marked as invalid, the requested operation can not be performed.		
Description	Denotes the result of the last job. Tags: atp.Status=obsolete				
Available via	Memlf.h				

(SRS_BSW_00392)

8.3 Function definitions

[SWS_MemIf_00017] [The API specified in this chapter shall be mapped to the API of the underlying memory abstraction modules. For functional behavior refer to the specification of those modules respectively to that of the underlying memory drivers.] (SRS_MemHwAb_14019, SRS_MemHwAb_14022)

[SWS_MemIf_00018] [The parameter <code>DeviceIndex</code> shall be used for selection of memory abstraction modules (and thus memory devices). If only one memory abstraction module is configured, the parameter <code>DeviceIndex</code> shall be ignored.] (SRS_MemHwAb_14020, SRS_MemHwAb_14021)



[SWS_MemIf_00019] [If only one memory abstraction module is configured, the Memory Abstraction Interface shall be implemented as a set of macros mapping the Memory Abstraction Interface API to the API of the corresponding memory abstraction module.] (SRS_SPAL_12078, SRS_MemHwAb_14021)

Example:

```
#define MemIf_Write(DeviceIndex, BlockNumber, DataPtr) \
    Fee Write(BlockNumber, DataPtr)
```

[SWS_MemIf_00020] [If more than one memory abstraction module is configured, the Memory Abstraction Interface shall use efficient mechanisms to map the API calls to the appropriate memory abstraction module.] (SRS_SPAL_12078, SRS MemHwAb 14021)

Note: One solution is to use tables of pointers to functions where the parameter <code>DeviceIndex</code> is used as array index.

Example:

Note: The service IDs given in this interface specification are related to the service IDs of the underlying memory abstraction module(s). For that reason, they may not start with 0.

[SWS_MemIf_00022] [If more than one memory abstraction module is configured and development error detection is enabled for this module, the functions of the Memory Abstraction Interface API shall check the parameter <code>DeviceIndex</code> for being an existing device or the broadcast identifier within the module's services. J (SRS_BSW_00323, SRS_MemHwAb_14021, SRS_MemHwAb_14023)

[SWS_MemIf_00023] [The functions of the Memory Abstraction Interface API shall report detected errors attributed to an illegal parameter <code>DeviceIndex</code> to the Default Error Tracer (DET) with the error code <code>MEMIF_E_PARAM_DEVICE</code> and the called service shall not be executed. | (SRS_BSW_00386, SRS_SPAL_12448)

[SWS_MemIf_00024] [If a called function of the Memory Abstraction Interface API has detected an error attributed to an illegal parameter <code>DeviceIndex</code> and has a return value, it shall be set as follows:

MemIf_GetStatus: MEMIF_UNINIT
MemIf_GetJobResult: MEMIF_JOB FAILED

All other functions: E NOT OK. (SRS_BSW_00369)

8.3.1 Memlf_Read

[SWS_Memlf_00039][

Service Name	MemIf_Read	
Syntax	<pre>Std_ReturnType MemIf_Read (uint16 DeviceIndex,</pre>	

	uint16 BlockNumber, uint16 BlockOffset, uint8* DataBufferPtr, uint16 Length)				
Service ID [hex]	0x02				
Sync/Async	Synchrono	us			
Reentrancy	Non Reent	rant			
	Device Index				
Parameters (in)	Block Number				
(111)	Block Offset				
	Length				
Parameters (inout)	None				
Parameters (out)	Data BufferPtr				
Return value	Std Return- Type In case development error detection is enabled for the Memory Abstraction Interface and a development error is detected according to SWS_MemIf_00022 the function shall return E_NOT_OK else it shall return the value of the called function of the underlying module.				
Description	Invokes the "Read" function of the underlying memory abstraction module selected by the parameter DeviceIndex.				
Available via	Memlf.h				

 $\label{eq:continuous} \begin{tabular}{ll} $ \c SRS_MemHwAb_14029, SRS_MemHwAb_14022) \\ $ \c SRS_MemHwAb_14029, SRS_MemHwAb_14022) \\ \c SRS_MemHwAb_14029, SRS_MemHwAb_14022) \\ \c SRS_MemHwAb_14029, SRS_MemHwAb_14022) \\ \c SRS_MemHwAb_14029, SRS_MemHwAb_14022) \\ \c SRS_MemHwAb_140220 \\ \c SRS_MemHwAb_14020 \\ \c SRS_MemHwAb_14020 \\ \c SRS_MemHwAb_14020 \\ \c SRS_MemHwAb_14020 \\ \c SRS_MemH$

[SWS_MemIf_00040][

Service Name	MemIf_Write	
Syntax	<pre>Std_ReturnType MemIf_Write (uint16 DeviceIndex, uint16 BlockNumber, const uint8* DataBufferPtr)</pre>	
Service ID [hex]	0x03	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	



	Device Index				
Parameters (in)	Block Number				
	Data BufferPtr				
Parameters (inout)	None				
Parameters (out)	None				
Return value	Std Return- Type In case development error detection is enabled for the Memory Abstraction Interface and a development error is detected according to SWS_MemIf_00022 the function shall return E_NOT_OK else it shall return the value of the called function of the underlying module.				
Description	Invokes the "Write" function of the underlying memory abstraction module selected by the parameter DeviceIndex.				
Available via	MemIf.h				

J(SRS_MemHwAb_14010, SRS_MemHwAb_14022) **8.3.3 MemIf_Cancel**

[SWS_MemIf_00041][

Service Name	Memlf_Cancel		
Syntax	<pre>void MemIf_Cancel (uint16 DeviceIndex)</pre>		
Service ID [hex]	0x04		
Sync/Async	Synchronous		
Reentrancy	Non Reentrant		
Parameters (in)	DeviceIndex		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	ion Invokes the "Cancel" function of the underlying memory abstraction module selected by the parameter DeviceIndex.		
Available via	Memlf.h		



J(SRS_MemHwAb_14031, SRS_MemHwAb_14022) **8.3.4 MemIf GetStatus**

[SWS Memlf 00042][

Service Name	MemIf_GetStatus		
Syntax	<pre>MemIf_StatusType MemIf_GetStatus (uint16 DeviceIndex)</pre>		
Service ID [hex]	0x05		
Sync/Async	Synchronous		
Reentrancy	Non Reentrant		
Parameters (in)	DeviceIndex		
Parameters (inout)	None		
Parameters (out)	None		
Return value	MemIf_StatusType		
Description	Invokes the "GetStatus" function of the underlying memory abstraction module selected by the parameter DeviceIndex.		
Available via	Memlf.h		

I(RS_BRF_02272, SRS_MemHwAb_14022)

[SWS_MemIf_00035] [If the function MemIf_GetStatus is called with the device index denoting a broadcast to all configured devices (MEMIF_BROADCAST_ID), the Memory Abstraction Interface module shall call the "GetStatus" functions of all underlying devices in turn. It shall return the value

- MEMIF IDLE if all underlying devices have returned this state
- MEMIF_UNINIT if at least one device returned this state, all other returned states shall be ignored
- MEMIF_BUSY if at least one configured device returned this state and no other device returned MEMIF UNINIT
- MEMIF_BUSY_INTERNAL if at least one configured device returned this state and no other device returned MEMIF_BUSY or MEMIF_UNINIT J (SRS_MemHwAb_14020)

Note: The special "broadcast" device ID in the call to MemIf_GetStatus is used to query whether all devices are idle in order to shut down the ECU.

8.3.5 Memlf GetJobResult

[SWS_Memlf_00043][



Service Name	MemIf_GetJobResult		
Syntax	<pre>MemIf_JobResultType MemIf_GetJobResult (uint16 DeviceIndex)</pre>		
Service ID [hex]	0x06		
Sync/Async	Synchronou	us	
Reentrancy	Non Reentrant		
Parameters (in)	Device Index		
Parameters (inout)	None		
Parameters (out)	None		
Return value	Memlf Job- Result- Type In case development error detection is enabled for the Memory Abstraction Interface and a development error is detected according to SWS_Memlf_00022 the function shall return MEMIF_JOB_FAILED else it shall return the value of the called function of the underlying module.		
Description	Invokes the "GetJobResult" function of the underlying memory abstraction module selected by the parameter DeviceIndex.		
Available via	Memlf.h		

[(SRS_MemHwAb_14022)

8.3.6 Memlf_InvalidateBlock

[SWS_MemIf_00044][

Service Name	Memlf_InvalidateBlock		
Syntax	<pre>Std_ReturnType MemIf_InvalidateBlock (uint16 DeviceIndex, uint16 BlockNumber)</pre>		
Service ID [hex]	0x07		
Sync/Async	Synchronous		
Reentrancy	Non Reentrant		
Parameters	Device Index		
(in)	Block Number		
Parameters	None		



(inout)		
Parameters (out)	None	
Return value	Std Return- Type In case development error detection is enabled for the Memory Abstraction Interface and a development error is detected according to SWS_MemIf_00022 the function shall return E_NOT_OK else it shall return the value of the called function of the underlying module.	
Description	Invokes the "InvalidateBlock" function of the underlying memory abstraction module selected by the parameter DeviceIndex.	
Available via	Memlf.h	

J(SRS_MemHwAb_14028, SRS_MemHwAb_14022)

8.3.7 MemIf_GetVersionInfo

[SWS_MemIf_00045][

Service Name	MemIf_GetVersionInfo		
Syntax	<pre>void MemIf_GetVersionInfo (Std_VersionInfoType* VersionInfoPtr)</pre>		
Service ID [hex]	0x08		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	None		
Parameters (inout)	None		
Parameters (out)	VersionInfoPtr Pointer to standard version information structure.		
Return value	None		
Description	Returns version information.		
Available via	Memlf.h		

(SRS_BSW_00407)

8.3.8 Memlf_EraseImmediateBlock

[SWS_Memlf_00046][

Service Name	MemIf_EraseImmediateBlock
Syntax	<pre>Std_ReturnType MemIf_EraseImmediateBlock (uint16 DeviceIndex, uint16 BlockNumber)</pre>



Service ID [hex]	0x09			
Sync/Async	Synchrono	us		
Reentrancy	Non Reent	Non Reentrant		
Parameters	Device Index			
(in)	Block Number			
Parameters (inout)	None			
Parameters (out)	None			
Return value	Std Return- Type In case development error detection is enabled for the Memory Abstraction Interface and a development error is detected according to SWS_MemIf_00022 the function shall return E_NOT_OK else it shall return the value of the called function of the underlying module.			
Description	Invokes the "EraseImmediateBlock" function of the underlying memory abstraction module selected by the parameter DeviceIndex.			
Available via	Memlf.h			

J(SRS_MemHwAb_14032, SRS_MemHwAb_14022)

8.4 Call-back notifications

None, the NVRAM manager shall provide the callback routines for the underlying memory abstraction modules.

8.5 Scheduled functions

None, there are no asynchronous functions in this module.

8.6 Expected Interfaces

8.6.1 Mandatory Interfaces

This chapter defines all interfaces which are required to fulfill the core functionality of the module.

ISWS Memlf 000471[

[
API Function	Header File	Description	
Ea_Erase-	Ea.h	Erases the block BlockNumber.	



Immediate- Block			
Ea_GetStatus	Ea.h	Service to return the Status.	
Ea_Invalidate- Block	Ea.h	Invalidates the block BlockNumber.	
Fee_Erase- Immediate- Block	Fee.h	Service to erase a logical block.	
Fee_Get- Status	Fee.h	Service to return the status.	
Fee Invalidate- Block	Fee.h	Service to invalidate a logical block.	
MemAcc Cancel (draft)	Mem Acc.h	Triggers a cancel operation of the pending job for the address area referenced by the addressAreald. Cancelling affects only jobs in pending state. For any other states, the request will be ignored. Tags: atp.Status=draft	
MemAcc_Get- JobResult (draft)	Mem Acc.h	Returns the consolidated job result of the address area referenced by addressAreald. Tags: atp.Status=draft	
MemAcc Read (draft)	Mem Acc.h	Triggers a read job to copy data from the source address into the referenced destination data buffer. The result of this service can be retrieved using the MemAcc_GetJobResult API. If the read operation was successful, the result of the job is MEMACC_MEM_OK. If the read operation failed, the result of the job is either MEMACC_MEM_FAILED in case of a general error or MEMACC_MEM_ECC_CORRECTED/MEMACC_MEM_ECC_UNCORRECTED in case of a correctable/uncorrectable ECC error. Tags: atp.Status=draft	
MemAcc Write (draft)	Mem Acc.h	Triggers a write job to store the passed data to the provided address area with given address and length. The result of this service can be retrieved using the MemAcc_GetJobResult API. If the write operation was successful, the job result is MEMACC_MEM_OK. If there was an issue writing the data, the result is MEMACC_MEM_FAILED. Tags: atp.Status=draft	

J(SRS_BSW_00384)

8.6.2 Optional Interfaces

This chapter defines all interfaces which are required to fulfill an optional functionality of the module.

[SWS Memlf 00048][

API Function	Header File	Description
Det_ReportError	Det.h	Service to report development errors.



8.6.3 Configurable interfaces

In this chapter all interfaces are listed where the target function could be configured. The target function is usually a call-back function. The names of these kind of interfaces is not fixed because they are configurable.

There are no configurable interfaces for this module.



9 Sequence diagrams

Refer to the specifications of the memory abstraction modules.



10 Configuration specification

10.1 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meaning of the parameters are described in Chapter 7 and Chapter 8.

10.1.1 Memlf

SWS Item	ECUC_Memlf_00025:
Module Name	MemIf
Module Description	Configuration of the MemIf (Memory Abstraction Interface) module.
Post-Build Variant Support	false
Supported Config Variants	VARIANT-PRE-COMPILE

Included Containers		
Container Name	Multiplicity	Scope / Dependency
MemlfGeneral	1	Configuration of the memory abstraction interface (Memif) module.

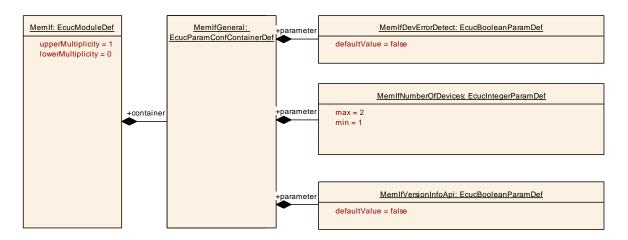


Figure 2: Memlf Configuration Layout

10.1.2 MemlfGeneral

SWS Item	ECUC_Memif_00034:
Container Name	MemlfGeneral
Parent Container	Memlf
Description	Configuration of the memory abstraction interface (Memif) module.
Configuration Parameters	

SWS Item	ECUC_Memlf_00035:		
Name	MemlfDevErrorDetect		
Parent Container	MemlfGeneral		
Description	Switches the development error detection and notification on or off.		
	true: detection and notification is enabled.		



	false: detection and notification is disabled.			
Multiplicity	1			
Type	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_Memlf_00033:			
Name	MemlfNumberOfDevices			
Parent Container	MemlfGeneral			
Description	Concrete number of underlying memory abstraction modules. Calculation Formula: Count number of configured EA and FEE modules.			
Multiplicity	1			
Туре	EcucIntegerParamDef			
Range	12			
Default value				
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Χ	All Variants	
	Link time			
	Post-build time			
Scope / Dependency	scope: local			

SWS Item	ECUC_Memif_00032:				
Name	MemlfVersionInfoApi				
Parent Container	MemlfGeneral				
	Pre-processor switch to enable / disable the API to read out the modules version information. true: Version info API enabled. false: Version info API disabled.				
Multiplicity	1				
Туре	EcucBooleanParamDef				
Default value	false				
Post-Build Variant Value	false				
Value Configuration Class	Pre-compile time	Χ	All Variants		
	Link time				
	Post-build time				
Scope / Dependency	scope: local				

No Included Containers



11 Not applicable requirements

[SWS Memif 00999] [These requirements are not applicable to this specification.] (SRS_BSW_00404, SRS_BSW_00405, SRS_BSW_00159, SRS_BSW_00170, SRS BSW 00380, SRS BSW 00398, SRS BSW 00399, SRS BSW 00400, SRS_BSW_00375, SRS_BSW_00101, SRS_BSW_00416, SRS_BSW_00406, SRS BSW 00168, SRS BSW 00423, SRS BSW 00424, SRS BSW 00425, SRS_BSW_00426, SRS_BSW_00427, SRS_BSW_00428, SRS_BSW_00429, SRS BSW 00432, SRS BSW 00433, SRS BSW 00336, SRS BSW 00339, SRS BSW 00422, SRS BSW 00417, SRS BSW 00161, SRS BSW 00162, SRS BSW 00005, SRS BSW 00415, SRS BSW 00164, SRS BSW 00325, SRS BSW 00342, SRS BSW 00343, SRS BSW 00160, SRS BSW 00007, SRS BSW 00300, SRS BSW 00413, SRS BSW 00347, SRS BSW 00307, SRS_BSW_00373, SRS_BSW_00314, SRS_BSW_00348, SRS_BSW_00353, SRS_BSW_00361, SRS_BSW_00302, SRS_BSW_00328, SRS_BSW_00312, SRS BSW 00006, SRS BSW 00304, SRS BSW 00378, SRS BSW 00306. SRS BSW 00308, SRS BSW 00309, SRS BSW 00358, SRS BSW 00414, SRS_BSW_00359, SRS_BSW_00360, SRS_BSW_00330, SRS_BSW_00009, SRS_BSW_00401, SRS_BSW_00172, SRS_BSW_00010, SRS_BSW_00333, SRS BSW 00321, SRS BSW 00341, SRS BSW 00334, SRS SPAL 12263. SRS_SPAL_12056, SRS_SPAL_12267, SRS_SPAL_12057, SRS_SPAL_12125, SRS SPAL 12163, SRS SPAL 12461, SRS SPAL 12462, SRS SPAL 12463, SRS_SPAL_12068, SRS_SPAL_12069, SRS_SPAL_00157, SRS_SPAL_12063, SRS SPAL 12075. SRS SPAL 12129. SRS SPAL 12064. SRS SPAL 12067. SRS SPAL 12077, SRS SPAL 12092, SRS SPAL 12265)