Deep Learning Audio

Lecture 4

Pavel Severilov

Moscow Institute of Physics and Technology

2022

Outline

1. RNN-Transducer (RNN-T)

2. Language models for ASR

3. Byte-pair encoding (BPE)

ASR: SOTA models

- RNN-T (2018, Google)
- ► MoChA (2018, Google) (Tricks to make LAS online)
- wav2vec (2019, Facebook AI Research) (use WAV not spectrograms)
- ▶ Jasper (2019, Nvidia) (Encoder CNN ; Loss: CTC)
- QuartzNet (2019, Nvidia) (Encoder TDS CNN; Loss CTC)
- ContextNet (2020, Google) (Encoders CNN and LSTM; Loss – RNN-T)
- Whisper (2022, OpenAi) (Encoder Transformer; Loss multitask)

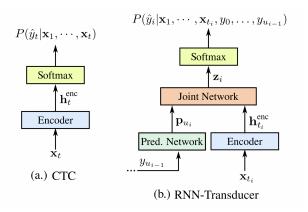
Outline

- 1. RNN-Transducer (RNN-T)
- 2. Language models for ASR
- 3. Byte-pair encoding (BPE)

CTC and Attention models: recap

	стс	Listen, Attend and Spell: LAS	?
Summary	Maximize probability of all possible CTC-paths leading to target.	Encoder-decoder architecture with attention.	???
Online	+	-	+
Context dependent	-	+	+
Multiple outputs for each input	-	-	+

RNN-T: idea



- Predictor is autoregressive: takes as input the previous outputs.
- ▶ Joiner feedforward network, combines the encoder vector h_t and predictor vector p_u

He et al. Streaming End-to-end Speech Recognition for Mobile Devices / 2019, Google, Inc.

RNN-T: model

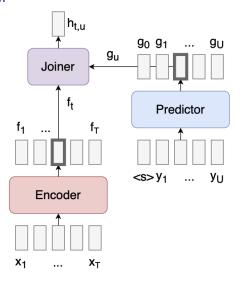


Figure: RNN-T architecture

RNN-T: model

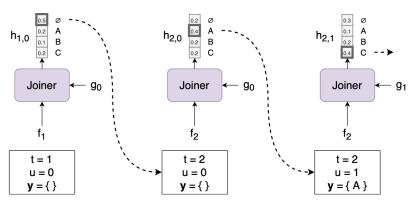


Figure: Steps example of RNN-T inference: t – audio-encoder timestamp, u – Predictor (char network) step

RNN-T: training

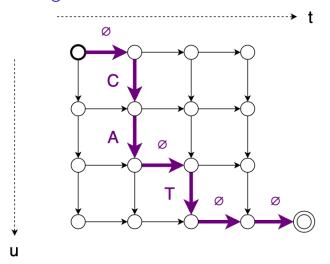


Figure: Alignment $\{\emptyset, C, A, \emptyset, T, \emptyset, \emptyset\}$ for input sequence of length T=4 and an output sequence "CAT" of length U=3

RNN-T: training

We need to get p(y|x) as the sum of the probabilities of all possible alignments between x and y

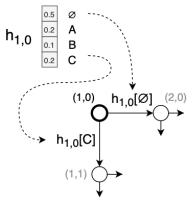


Figure:

$$\mathbf{z} = \varnothing, C, A, \varnothing, T, \varnothing, \varnothing$$
$$p(\mathbf{z} \mid \mathbf{x}) = h_{1.0}[\varnothing] \cdot h_{2.0}[C] \cdot h_{2.1}[A] \cdot h_{2.2}[\varnothing] \cdot h_{3.2}[T] \cdot h_{3.3}[\varnothing] \cdot h_{4.3}[\varnothing]$$

RNN-T: training

To compute the sum efficiently, compute $\alpha_{t,u}$, for $1 \le t \le T$ and 0 < u < U

$$\alpha_{t,u} = \alpha_{t-1,u} \cdot h_{t-1,u}[\varnothing] + \alpha_{t,u-1} \cdot h_{t,u-1}[y_{u-1}]$$

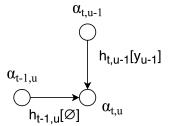


Figure: Computing $\alpha_{t,u}$ to get $p(\mathbf{y} \mid \mathbf{x}) = \alpha_{T,U} \cdot h_{T,U}[\varnothing]$

Outline

- RNN-Transducer (RNN-T)
- 2. Language models for ASR
- 3. Byte-pair encoding (BPE)

Language models (LM): why need in ASR?

- Language models recap: a model that estimates the probability of a text.
 - N-gramms
 - ► Neural networks (BERT, GPT-3, ...)
 - Example:P(let's go two a movie) = 0.01P(let's go to a movie) = 0.6
- ► ASR problem:
 - Spelling of a word heavily depends on its context
 - Labeled audio data is difficult to obtain
- ► How LM helps:
 - ► Improves final WER
 - Improves performance for small audio datasets
 - Can be used to adapt model to new domain

LM: how to integrate in ASR?

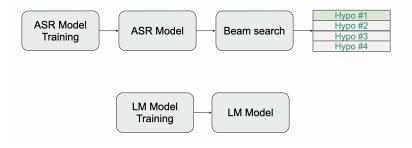


Figure: ASR pipeline VS Language models pipeline

HSE DLA course 14/22

LM: final hypothesis rescoring

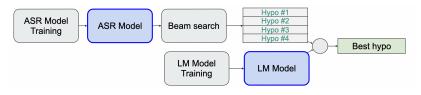


Figure: Final hypothesis rescoring: rescore beam-search output with LM probs

$$\mathbf{y}^* = \underset{\mathbf{y}}{\operatorname{arg\,max}} \log p(\mathbf{y} \mid \mathbf{x}) + \lambda \log p_{LM}(\mathbf{y}) + \beta \cdot \operatorname{len}(\mathbf{y})$$

len(y) – function of word length, anti-penalty for long words

LM: shallow fusion

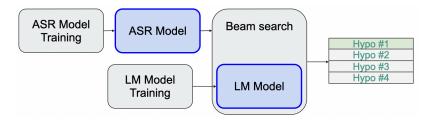


Figure: Shallow fusion: use LM rescoring after each beam search step

Practice:

- requires much more LM runs
- use light LM for shallow fusion
- use heavy LM for second-pass rescoring

LM: Deep fusion

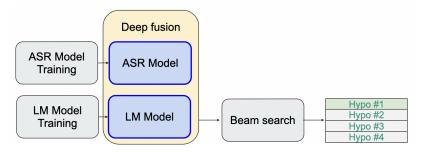


Figure: Deep fusion: integrates the external LM into the encoder-decoder model (ASR) by fusing together the hidden states of the external LM and the decoder

Toshniwal, Shubham et al. "A Comparison of Techniques for Language Model Integration in Encoder-Decoder Speech Recognition." 2018 IEEE

LM: Cold fusion

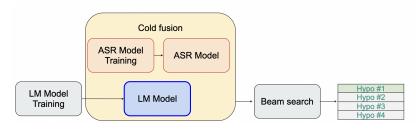


Figure: Cold fusion: train like in Deep fusion, but jointly with ASR model

Toshniwal, Shubham et al. "A Comparison of Techniques for Language Model Integration in Encoder-Decoder Speech Recognition." 2018 IEEE

LM in ASR: comparison of approaches

Model	SWB	CH	Full
LAS	17.1	27.9	22.6
Shallow Fusion	15.6	26.6	21.1
Deep Fusion	16.3	27.2	21.7
Cold Fusion	16.3	27.3	21.8

Table: Word error rates (%) on Eval2000 for the LAS baseline model and fusion approaches. SWB=Switchboard, CH=CallHome, Full=Eval2000.

Outline

- 1. RNN-Transducer (RNN-T)
- 2. Language models for ASR
- 3. Byte-pair encoding (BPE)

BPE: motivation & idea

- Motivation: a lot of characters have different pronunciation in different contexts
- ▶ Idea: let's use n-gramms as tokens in addition
- Advantages:
 - ► Less decoder steps → faster training and inference
 - ▶ Better generalization → better WER

BPE: algorithm

- 1. Each character token
- 2. Most popular n-gram: add new token
- 3. Replace n-gram with a new token
- 4. Restrict maximum length of tokens
- 5. New vocabulary = all characters + new tokens

Iteration	Sequence	Vocabulary
0	ababcabc	{a, b, c}
1	ab ab c ab c	{a, b, c, ab}
2	ab abc abc	$\{a, b, c, ab, abc\}$
3	ababc abc	{a, b, c, ab, abc, ababc}
4	ababcabc	{a, b, c, ab, abc, ababc, ababcabc}

Table: BPE: example for sequence {ababcabc}