

Deep Learning for Audio

Lecture 3

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Outline

1. RNN-Transducer (RNN-T)
2. Language models for ASR
3. Byte-pair encoding (BPE)
4. State-of-the-art ASR

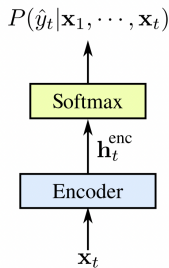
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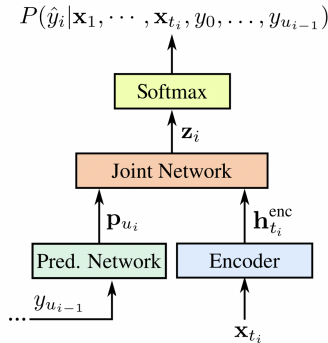
CTC and Attention models: recap

	CTC	Listen, Attend and Spell: LAS	?
Summary	Maximize probability of all possible CTC-paths leading to target.	Encoder-decoder architecture with attention.	???
Online	+	-	+
Context dependent	-	+	+
Multiple outputs for each input	-	-	+

RNN-T: idea



(a.) CTC



(b.) RNN-Transducer

- ▶ Predictor is autoregressive: takes as input the previous outputs.
- ▶ Joiner – feedforward network, combines the encoder vector \mathbf{h}_t and predictor vector \mathbf{p}_u

He et al. *Streaming End-to-end Speech Recognition for Mobile Devices* / 2019, Google, Inc.

RNN-T: model

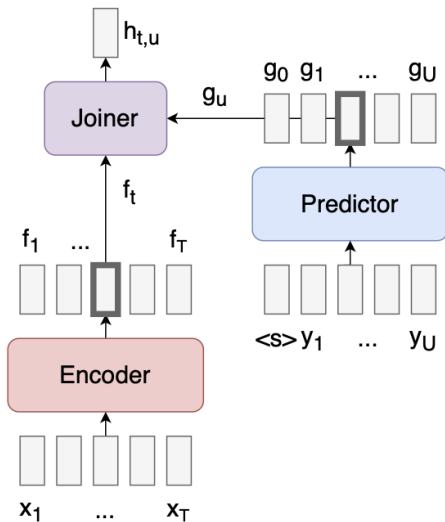


Figure: RNN-T architecture

RNN-T: model

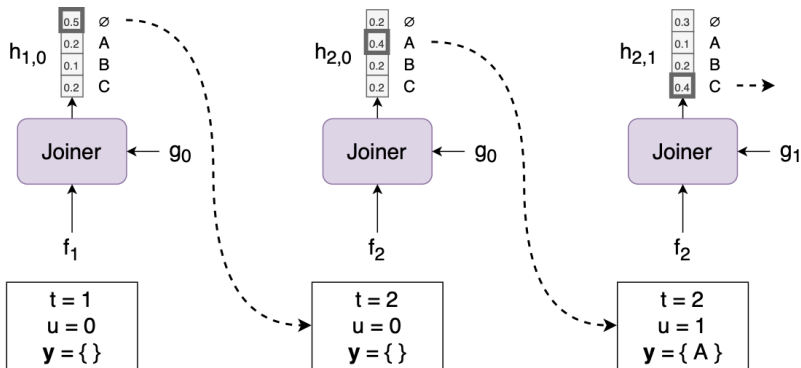


Figure: Steps example of RNN-T inference: t – audio-encoder timestamp, u – Predictor (char network) step

RNN-T: training

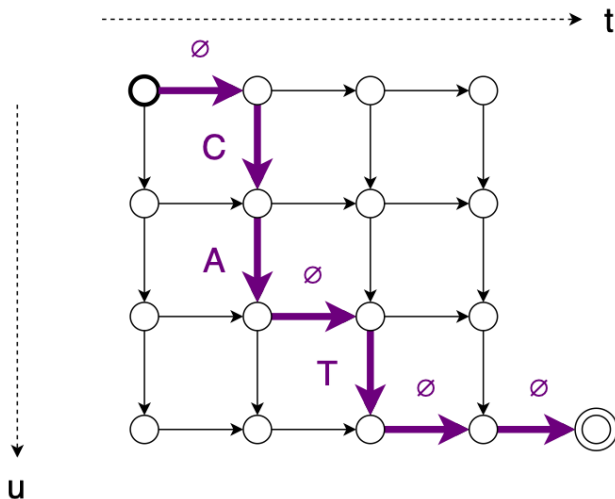


Figure: Alignment $\{\emptyset, C, A, \emptyset, T, \emptyset, \emptyset\}$ for input sequence of length $T = 4$ and an output sequence "CAT" of length $U = 3$

RNN-T: training

We need to get $p(\mathbf{y}|\mathbf{x})$ as the sum of the probabilities of all possible alignments between \mathbf{x} and \mathbf{y}

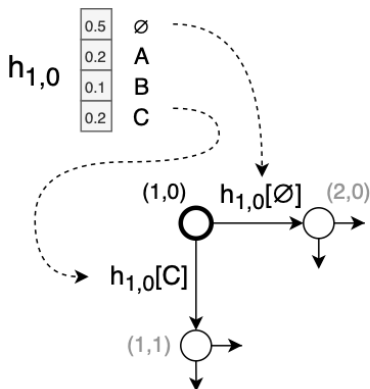


Figure:

$\mathbf{z} = \emptyset, C, A, \emptyset, T, \emptyset, \emptyset$

$$p(\mathbf{z} | \mathbf{x}) = h_{1,0}[\emptyset] \cdot h_{2,0}[C] \cdot h_{2,1}[A] \cdot h_{2,2}[\emptyset] \cdot h_{3,2}[T] \cdot h_{3,3}[\emptyset] \cdot h_{4,3}[\emptyset]$$

Sequence-to-sequence learning with Transducers blog post

RNN-T: training

Objective: minimize the loss function $-\log p(y|x)$

To compute the sum efficiently, compute $\alpha_{t,u}$, for $1 \leq t \leq T$ and $0 \leq u \leq U$

$$\alpha_{t,u} = \alpha_{t-1,u} \cdot h_{t-1,u}[\emptyset] + \alpha_{t,u-1} \cdot h_{t,u-1}[y_{u-1}]$$

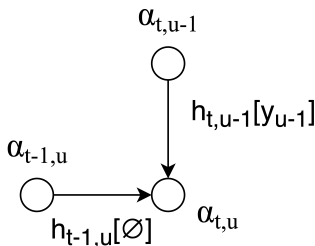


Figure: Computing $\alpha_{t,u}$ to get $p(\mathbf{y} | \mathbf{x}) = \alpha_{T,U} \cdot h_{T,U}[\emptyset]$

Losses in ASR: summary

- ▶ CTC Loss
 - ▶ Pros: output can be computed parallel, very fast, goes well with LMs
 - ▶ Cons: no context dependences; often LMs are big and slow (can't do on devices)
- ▶ CrossEntropyLoss (Autoregressive Encoder-Decoder, LAS)
 - ▶ Pros: High Quality because of autoregression, often has attention (good for seq-to-seq tasks)
 - ▶ Cons: hard inference, hard to do in production (slow), not online
- ▶ RNN-T Loss (Transducer)
 - ▶ Pros: can be online, better quality because of autoregression, often used in devices
 - ▶ Cons: hard inference, hard to build in attention, need a lot of GPUs to train, output are computed not in parallel

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Language models (LM): why need in ASR?

- ▶ Language models recap: a model that estimates the probability of a text.
 - ▶ N-gramms
 - ▶ Neural networks (BERT, GPT-3, ...)
 - ▶ Example:
 $P(\text{let's go two a movie}) = 0.01$
 $P(\text{let's go to a movie}) = 0.6$
- ▶ ASR problem:
 - ▶ Spelling of a word heavily depends on its context
 - ▶ Labeled audio data is difficult to obtain
- ▶ How LM helps:
 - ▶ Improves final WER
 - ▶ Improves performance for small audio datasets
 - ▶ Can be used to adapt model to new domain

LM: how to integrate in ASR?

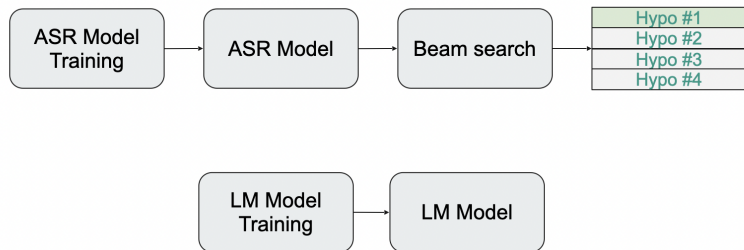


Figure: ASR pipeline VS Language models pipeline

LM: final hypothesis rescoring

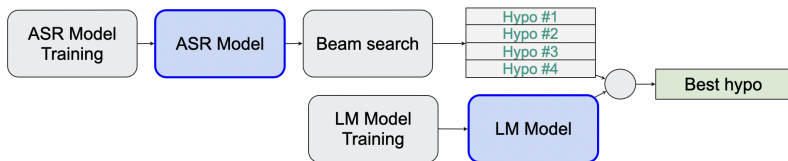


Figure: Final hypothesis rescoring: rescore beam-search output with LM probs

$$\mathbf{y}^* = \arg \max_{\mathbf{y}} \log p(\mathbf{y} \mid \mathbf{x}) + \lambda \log p_{LM}(\mathbf{y}) + \beta \cdot \text{len}(\mathbf{y})$$

$\text{len}(\mathbf{y})$ – function of word length, anti-penalty for long words

LM: shallow fusion

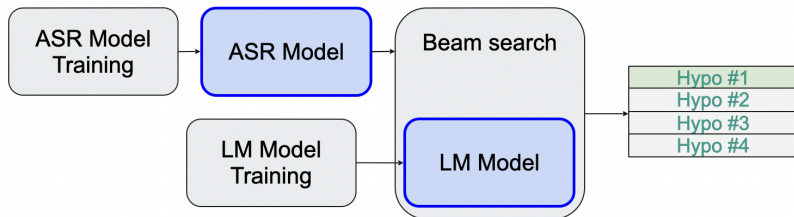


Figure: Shallow fusion: use LM rescoring after each beam search step

Practice:

- ▶ requires much more LM runs
- ▶ use light LM for shallow fusion
- ▶ use heavy LM for second-pass rescoring

LM: Deep fusion

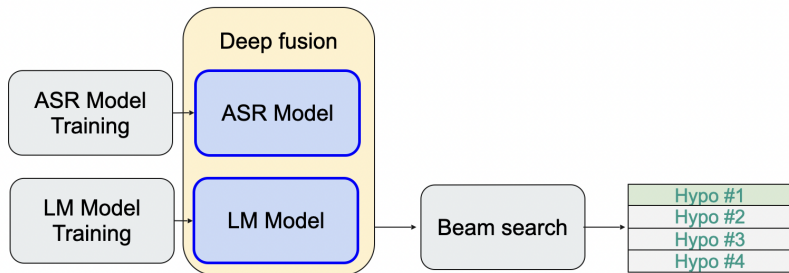


Figure: Deep fusion: integrates the external LM into the encoder-decoder model (ASR) by fusing together the hidden states of the external LM and the decoder

LM: Cold fusion

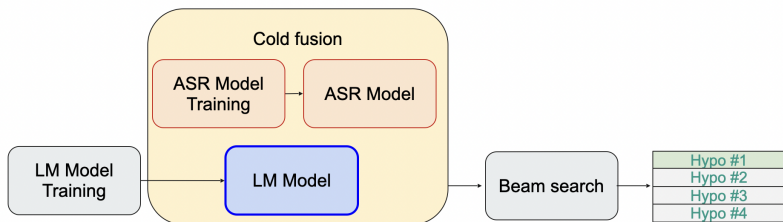


Figure: Cold fusion: train like in Deep fusion, but jointly with ASR model

LM in ASR: comparison of approaches

Model	SWB	CH	Full
LAS	17.1	27.9	22.6
Shallow Fusion	15.6	26.6	21.1
Deep Fusion	16.3	27.2	21.7
Cold Fusion	16.3	27.3	21.8

Table: Word error rates (%) on Eval2000 for the LAS baseline model and fusion approaches. SWB=Switchboard, CH=CallHome, Full=Eval2000.

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BPE: motivation & idea

- ▶ Motivation: a lot of characters have different pronunciation in different contexts
- ▶ Idea: let's use n-gramms as tokens in addition
- ▶ Advantages:
 - ▶ Less decoder steps → faster training and inference
 - ▶ Better generalization → better WER

BPE: algorithm

1. Each character – token
2. Most popular n-gram: add new token
3. Replace n-gram with a new token
4. Restrict maximum length of tokens
5. New vocabulary = all characters + new tokens

Iteration	Sequence	Vocabulary
0	a b a b c a b c	{a, b, c}
1	ab ab c ab c	{a, b, c, ab}
2	ab abc abc	{a, b, c, ab, abc}
3	ababc abc	{a, b, c, ab, abc, ababc}
4	ababcabc	{a, b, c, ab, abc, ababc, ababcabc}

Table: BPE: example for sequence {ababcabc}

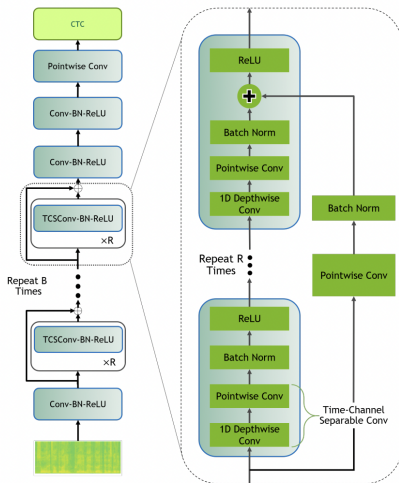
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ASR: SOTA models

- ▶ RNN-T (2018, Google)
- ▶ MoChA (2018, Google) (Tricks to make LAS online)
- ▶ wav2vec (2019, Facebook AI Research) (SSL, use WAV not spectrograms)
- ▶ Jasper (2019, Nvidia) (Encoder: CNN ; Loss: CTC)
- ▶ QuartzNet (2019, Nvidia) (Encoder: TDS CNN ; Loss – CTC)
- ▶ ContextNet (2020, Google) (Encoders: CNN and LSTM ; Loss – RNN-T)
- ▶ wav2vec2 (2020, Facebook AI Research)
- ▶ Conformer (2020, Google) (Encoder: Convolutions + Transformers,)
- ▶ Whisper (2022, OpenAi) (Encoder: Transformer; Loss - multitask)

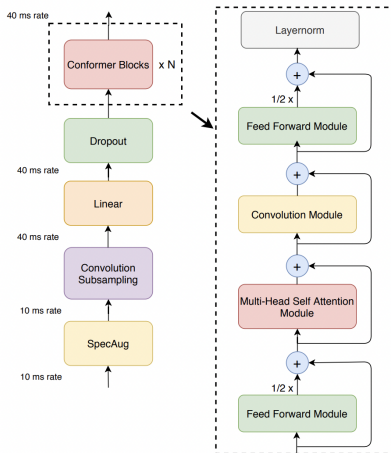
QuartzNet



- ▶ Multiple blocks with residual connections (no transformers)
- ▶ Block: 1D time-channel separable convolutional layers + batch normalization + ReLU
- ▶ Loss: CTC (can be RNN-T)
- ▶ very fast: 2500 SPS on V100 (\approx 45mins in a second)

Kriman, Samuel et al. "QuartzNet: Deep Automatic Speech Recognition with 1D Time-Channel Separable Convolutions", 2020 ICASSP

Conformer



- Combines convolution and transformers blocks
- Loss: CTC, Transducer
- 1900 SPS on V100 (\approx 30mins in a second)

Whisper

- ▶ ASR system trained on 680,000 hours of multilingual and multitask data collected from the web
- ▶ Shows that large and diverse dataset leads to improved robustness to accents, background noise and technical language
- ▶ Can translate text into English
- ▶ 99 languages in train

Whisper: training data

Multitask training data (680k hours)

English transcription



"Ask not what your country can do for ..."



Ask not what your country can do for ...

Any-to-English speech translation



"El rápido zorro marrón salta sobre ..."



The quick brown fox jumps over ...

Non-English transcription



"언덕 위에 올라 내려다보면 너무나 넓고 넓은 ..."



언덕 위에 올라 내려다보면 너무나 넓고 넓은 ...

No speech



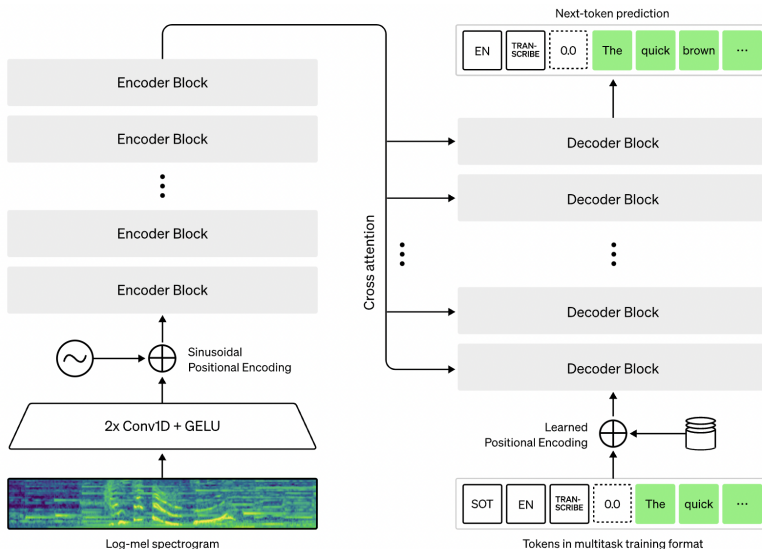
(background music playing)



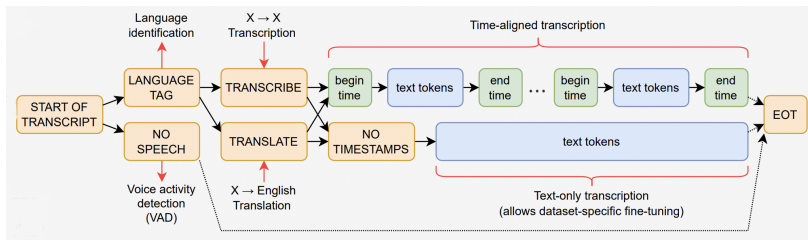
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Figure: 17% Multilingual Speech Recognition (117k hours), 18% Translation (126k hours), 65% English Speech Recognition (438k hours)

Whisper: architecture



Whisper: multitask learning



Whisper: results

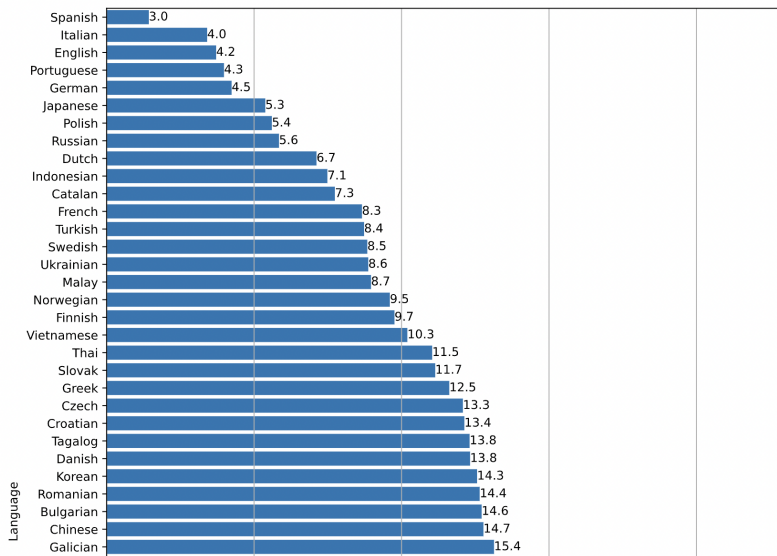


Figure: WER, %, Fleurs dataset

SOTA in production cookbook

- ▶ Use CTC/CrossEntropy/Transducer loss
- ▶ Add LMs or N-grams
- ▶ Models:
 - ▶ Quartznet: very fast, worse quality
 - ▶ Conformer: medium speed, medium quality
 - ▶ wav2vec 2.0: slow, best quality
 - ▶ Whisper: ? most robust ?
 - ▶ Ansambles

SOTA ASR: summary

Model	Average WER	LS Clean	LS Other
Human	-	5.83	12.69
Kaldi	-	8.01	22.49
DeepSpeech2 (CTC)	-	5.15	12.73
LAS	-	3.2	9.8
[PwC] QuartzNet	-	2.69	7.25
[PwC] Conformer large	-	1.9	3.9
[HF] wav2vec2-large	14.47	1.73	3.74
[HF] fastconformer_ ctc_xxlarge	8.34	1.69	3.4
[HF] whisper-large-v2	8.16	2.87	5.16
[HF] fastconformer_ transducer_xlarge	8.06	1.5	2.88

Average WER: on datasets AML, Earnings22, Gigaspeech,
LibriSpeech, SPGISpeech, Tedlium, Voxpopuli, Common Voice
HuggingFace Open ASR Leaderboard