

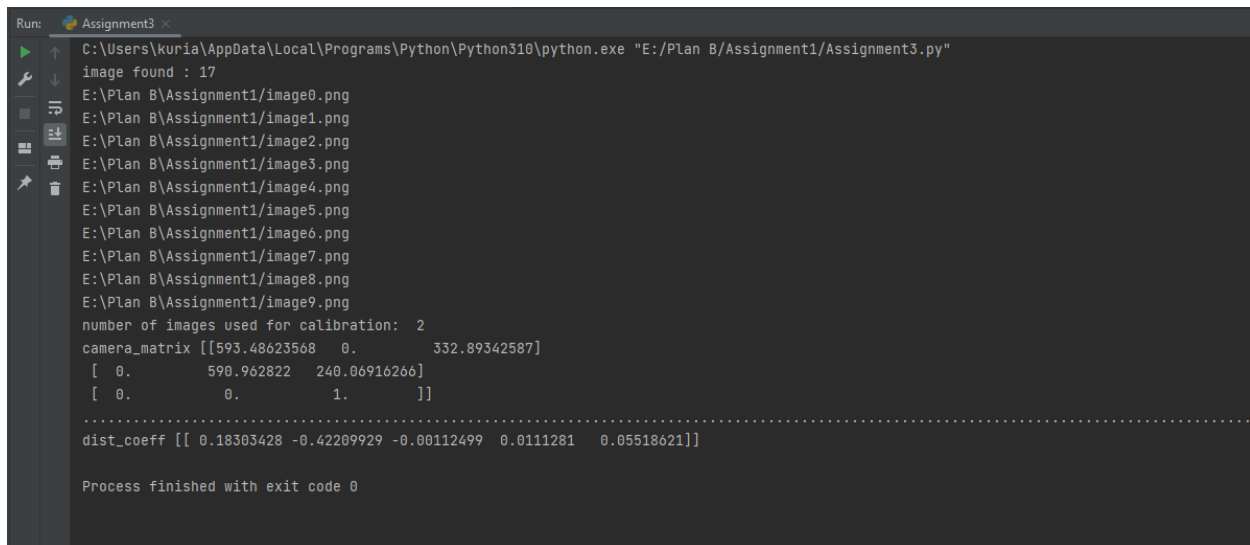
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Assignment 3

9/16/22

For this assignment I am printing out the calibration pattern for the images. For this I consider the image of chess board. In coding, my code does is, it saves more than one photos of pattern board in various angles and saves the parameters to a pickle file and load it from the pickle file and undistort the images from the same camera where the photo is taken. By doing this project I learned how to use open cv with python, by printing out and mount calibration pattern. From the code I learned types of distortion caused by cameras how to find the intrinsic and extrinsic properties of a camera how to undistort images based off these properties

Output of Calibration and save parameters



```
Run: Assignment3
C:\Users\kuria\AppData\Local\Programs\Python\Python310\python.exe "E:/Plan B/Assignment1/Assignment3.py"
image found : 17
E:\Plan B\Assignment1/image0.png
E:\Plan B\Assignment1/image1.png
E:\Plan B\Assignment1/image2.png
E:\Plan B\Assignment1/image3.png
E:\Plan B\Assignment1/image4.png
E:\Plan B\Assignment1/image5.png
E:\Plan B\Assignment1/image6.png
E:\Plan B\Assignment1/image7.png
E:\Plan B\Assignment1/image8.png
E:\Plan B\Assignment1/image9.png
number of images used for calibration: 2
camera_matrix [[593.48623568  0.          332.89342587]
 [ 0.          590.962822  240.06916266]
 [ 0.           0.           1.          ]]
.....
dist_coeff [[ 0.18303428 -0.42209929 -0.00112499  0.0111281  0.05518621]]

Process finished with exit code 0
```

Screenshot

