



Course > Week 5... > Proble... > Proble...

Problem Set 5

Problems 1-4 correspond to "Unconstrained optimization I"

Problem 1

1/1 point (graded)

Let F be a function from \mathbb{R}^d to \mathbb{R} . Which of the following is the most accurate description of the derivative ∇F ?

- It is a real number.
- It is a d-dimensional vector.
- \bigcirc For any point $u \in \mathbb{R}^d$, the derivative at that point, $\nabla F(u)$, is a real number.
- ullet For any point $u \in \mathbb{R}^d$, the derivative at that point, $\nabla F(u)$, is a d-dimensional vector.



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1 Answers are displayed within the problem

Problem 2

6/6 points (graded)

Consider the following loss function on vectors $w \in \mathbb{R}^3$:

$$L(w) = w_1^2 - 2w_1w_2 + w_2^2 + 2w_3^2 + 3.$$

a) Compute $\nabla L(w)$. Match each of its coordinates to the following list:

Option 1: $4w_3$

Option 2: $2w_1 - 2w_2$

Option 3: $-2w_1 + 2w_2$

What is dL/dw_1 ? (Just answer 1,2,or 3)



 $dL/dw_2 =$



 $dL/dw_3 =$



b) What is the minimum value of $L\left(w\right)$?



c) Is there is a unique solution w at which this minimum is realized?



d) Suppose we use gradient descent to minimize this function, and that the current estimate is w = (1, 2, 3). If the step size is $\eta = 0.5$, what is the next estimate?

- w = (1, 1, 0)
- w = (-1, 0, 1)
- w = (2, 1, -3)
- $\omega = (0, -1, -1.5)$



Explanation

The derivative of L(w) is $\nabla L(w) = (2w_1 - 2w_2, -2w_1 + 2w_2, 4w_3)$.

To minimize $L\left(w\right)$, we set the derivative to zero and get $w_{1}=w_{2}$ and $w_{3}=0$. Thus there isn't a single minimizer, but rather infinitely many of them. The minimum value of $L\left(w\right)$, obtained at any of these points, is 3.

For the final part, let the current point be w' = (1, 2, 3). The gradient at this point is $\nabla L(w') = (-2, 2, 12)$. Thus the gradient step updates w' to $w' - \eta \nabla L(w') = (1, 2, 3) - 0.5(-2, 2, 12) = (2, 1, -3)$.

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Problem 3

1/1 point (graded)

We are given a set of data points $x^{(1)}, \ldots, x^{(n)} \in \mathbb{R}^d$, and we want to find a single point $z \in \mathbb{R}^d$ that minimizes the loss function

$$L(z) = \sum_{i=1}^{n} \|x^{(i)} - z\|^{2}.$$

Use calculus to determine z, in terms of the $x^{(i)}$. (Hint: It might help to just start by looking at one particular coordinate.) Then select which of the following correctly describes the solution.

- \bigcirc The sum of the $x^{(i)}$ vectors
- \bigcirc The average of the $x^{(i)}$ vectors
- \bigcirc The average of the $x^{(i)}$ vectors, times a constant c
 eq 1
- \bigcirc Zero, regardless of what the $\chi^{(i)}$ vectors are



Notice that

$$L(z) = \sum_{i=1}^{n} \|x^{(i)} - z\|^{2} = \sum_{i=1}^{n} \sum_{j=1}^{d} (x_{j}^{(i)} - z_{j})^{2}.$$

Take the derivative with respect to a single coordinate z_i :

$$\frac{dL}{dz_i} = -2 \sum_{i=1}^{n} (x_j^{(i)} - z_j).$$

Stacking these together into a single d-dimensional vector, we get

$$\nabla L(z) = -2 \sum_{i=1}^{n} (x^{(i)} - z).$$

Setting this to zero then yields the solution

$$z = \frac{1}{n} \sum_{i=1}^{n} x^{(i)}$$
.

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Problem 4

2/2 points (graded)

Given a set of data points $x^{(1)}, \dots, x^{(n)} \in \mathbb{R}^d$, we want to find the vector $w \in \mathbb{R}^d$ that minimizes this loss function:

$$L(w) = \sum_{i=1}^{n} (w \cdot x^{(i)}) + \frac{1}{2}c \|w\|^{2}.$$

Here c > 0 is some constant.

a) Let s denote the sum of the data points, that is, $s = \sum_{i=1}^{n} x^{(i)}$. Express $\nabla L(w)$ in terms of s, c, and w.

- $\bigcirc \nabla L(w) = s + w$
- $\nabla L(w) = s + cw$
- $\bigcirc \nabla L(w) = cw$
- $\bigcirc \nabla L(w) = s/c + w$



Answer

Correct: The derivative is $\nabla L(w) = \sum_{i} x^{(i)} + cw = s + cw$

b) What value of w minimizes $L\left(w\right)$? Give the answer in terms of s and c.

- $omega w = -\frac{s}{c}$
- $\bigcirc w = cs$
- $\bigcirc w = \frac{s}{4c}$
- $\bigcirc w = -\frac{s}{2c}$



Answer

Correct: This results from setting $\nabla L(w) = 0$.

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Problems 5-7 correspond to "Convexity I"

Problem 5

7/7 points (graded)

For each of the following functions of one variable, say whether it is convex, concave, both, or neither.

a)
$$f(x) = x^2$$

Answer

Correct: f''(x) = 2

b)
$$f(x) = -x^2$$

♦ ✓ Answer: concave concave

Answer

Correct: f''(x) = -2

c)
$$f(x) = x^2 - 2x + 1$$

♦ ✓ Answer: convex convex

Answer

Correct: f''(x) = 2

$$d) f(x) = x$$

♦ ✓ Answer: both both

Answer

Correct: f''(x) = 0

e)
$$f(x) = x^3$$

neither **\Delta \rightarrow Answer:** neither

Answer

Correct: f''(x) = 6x, which is sometimes positive, sometimes negative.

$$f) f(x) = x^4$$

convex Answer: convex **Answer**

Correct: $f''(x) = 12x^2$

g)
$$f(x) = \ln x$$

Answer

Correct: $f''(x) = -1/x^2$

? Hint (1 of 2): First rule: a twice-differentiable function is convex if its second derivative is always ≥ 0 .

Next Hint

Hint (2 of 2): Second rule: a function f is concave if and only if -f is convex.

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Problem 6

1/1 point (graded)

Consider the function $f: \mathbb{R}^3 \to \mathbb{R}$ given by

$$f(x_1, x_2, x_3) = x_1^2 + x_2^2 - x_3^2 - 4x_1x_2 + 6x_2x_3.$$

Compute and select the matrix of second derivatives (the Hessian) H(x).

$$\begin{pmatrix}
1 & -2 & 0 \\
-2 & 1 & 3 \\
0 & 3 & -1
\end{pmatrix}$$

$$\begin{pmatrix}
2 & -4 & 0 \\
-4 & 2 & 6 \\
0 & 6 & 0
\end{pmatrix}$$

$$\begin{pmatrix}
1 & -4 & 0 \\
0 & 2 & 6 \\
0 & 0 & -2
\end{pmatrix}$$



? Hint (1 of 1): Helpful first step: $\nabla f(x) = (2x_1 - 4x_2, 2x_2 - 4x_1 + 6x_3, -2x_3 + 6x_2)$

Next Hint

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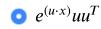
Problem 7

1/1 point (graded)

For some fixed vector $u \in \mathbb{R}^d$, define the function $F : \mathbb{R}^d \to \mathbb{R}$ by

$$F\left(x\right) =e^{u\cdot x}.$$

Which of the following is the Hessian H(x)?



 $\bigcirc e^{(u \cdot x)}I$ (here I is the $d \times d$ identity matrix)

 $\bigcirc e^{(u\cdot x)}\|u\|^2$

 $\bigcirc e^{(u\cdot x)}(u\cdot x)^2$



First derivative:

$$\frac{dF}{dx_j} = e^{u \cdot x} u_j$$

Second derivative:

$$\frac{d^2F}{dx_k\,dx_j}=e^{u\cdot x}u_ju_k$$

Putting together the full $d \times d$ matrix, we get $e^{u \cdot x} u u^T$.

? Hint (1 of 1): Helpful first step: $\nabla F(x) = e^{u \cdot x} u$

Next Hint

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Problems 8-11 correspond to "Positive semidefinite matrices"

Problem 8

1/1 point (graded)

Is the matrix $M = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ positive semidefinite?

- \bigcirc Yes, because every entry in the matrix is ≥ 0
- \bigcirc No, because not every entry is > 0
- \bigcirc Yes, because $u^T M u \ge 0$ for all vectors u
- On No, because there is a vector u for which $u^T M u < 0$



The quadratic function represented by this matrix is $u^T M u = 2u_1 u_2$. This is negative whenever u_1u_2 is negative, for instance with u=(1,-1).

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Problem 9

1/1 point (graded)

Is the matrix $M = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$ positive semidefinite?

- \bigcirc No, because not every entry is ≥ 0
- \bigcirc No, because there is a vector u for which $u^T M u < 0$
- No, because there is a vector u for which $u^T M u = 0$



Explanation

The quadratic function represented by this matrix is $u^{T}Mu = u_1^2 - 2u_1u_2 + u_2^2 = (u_1 - u_2)^2$. This is never negative.

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Problem 10

1/1 point (graded)

For a fixed set of vectors $v^{(1)},\ldots,v^{(n)}\in\mathbb{R}^d$, let M be the n imes n matrix of all pairwise dot products: that is, $M_{ij} = v^{(i)} \cdot v^{(j)}$. Do you see why M is positive semidefinite? Think about it a little bit, and then choose one of the following options (you'll get marked as correct whichever you choose).

		Yes	the	entire	argum	ent is	clear	to	me
٠,	9	103,	CITC	CHUIC	arguin	CITCIS	Cicai	w	1110

\bigcirc	ı	don't get it.	V
	٠	don't get it.	•



Explanation

Let U denote the $n \times d$ matrix whose rows are the $v^{(i)}$. Then $M = UU^T$, and thus M is PSD (any matrix that can be written in this way is PSD).

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Problem 11

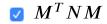
1/1 point (graded)

Suppose M and N are positive semidefinite matrices of the same size. Which of the following matrices are necessarily positive semidefinite? Select all that apply.

$$\sim M + N$$

$$\square M - N$$

$$\sim 2M$$





The first is PSD because the sum of PSD matrices is also PSD. The third and fourth are PSD because any non-negative multiple of a PSD matrix is PSD.

The second option is *not* PSD: consider, for instance, the 1×1 matrices M = 1 and N = 10

For the fourth option, notice that since N is PSD, we can write it in the form $N=UU^T$ for some matrix U. Then,

$$M^T N M = M^T U U^T M = (M^T U) (M^T U)^T = V V^T$$
, where $V = M^T U$. Thus this matrix is also PSD.

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1 Answers are displayed within the problem

Problems 12-13 correspond to "Convexity II"

Problem 12

2/2 points (graded)

For some fixed vector $u \in \mathbb{R}^d$, define

$$F(x) = ||x - u||^2.$$

We wish to determine whether F(x) is a convex function of x.

a) The Hessian matrix H(x) is of the form cI, where I is the $d \times d$ identity matrix and c is some constant. What is c?



b) Is F(x) a convex function?



) No

It depends on the specific vector *u*



Explanation

For the first part, we have

$$F(x) = \sum_{j=1}^{d} (x_j - u_j)^2.$$

$$\frac{dF}{dx_i} = 2\left(x_j - u_j\right)$$

and d^2F/dx_kdx_j is either 2 if j=k or 0 otherwise. Thus the Hessian is 2I, which is PSD, implying that F is convex.

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1 Answers are displayed within the problem

Problem 13

3/3 points (graded)

Let $p = (p_1, p_2, \dots, p_m)$ be a probability distribution over m possible outcomes. The *entropy* of p is a measure of how much randomness there is in the outcome. It is defined as

$$F(p) = -\sum_{i=1}^{m} p_i \ln p_i,$$

where \ln denotes natural logarithm. We wish to ascertain whether F(p) is a convex function of p. As usual, we begin by computing the Hessian.

a) Consider the specific point p = (1/m, 1/m, ..., 1/m). What is the (1, 1) entry of the Hessian at this point? Your answer should be a function of m.

-m

Answer: -m

b) Continuing, what is the (1, 2) entry of the Hessian at this specific point?



c) Is the function F(p) convex, concave, both, or neither?

concave \$		✓ Answer:	concave
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Explanation

First we have

$$\frac{dF}{dp_i} = -\left(1 + \ln p_i\right)$$

Thus, if $j \neq i$, then

$$\frac{d^2F}{dp_jdp_i}=0$$

while

$$\frac{d^2F}{dp_i^2} = -\frac{1}{p_i}.$$

Thus the Hessian is a diagonal matrix with negative entries, meaning the function is concave.

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1 Answers are displayed within the problem

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