

**ME 254 Computational Fluid Dynamics**  
**Homework 4**

Due on 03/07/19 at 11:59 pm (through Catcourses)

Maximum points: 160

1. Consider the first order wave equation

Jose A. Millan Higuera  
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$$u_t + u_x = 0 \quad (1)$$

The initial conditions are given by

$$u(x, 0) = \sin(2\pi x) \quad 0 \leq x \leq 1 \quad (2)$$

$$u(x, 0) = 0 \quad 1 < x \leq 5 \quad (3)$$

Assume periodic boundary conditions. To implement this in a finite difference formulation using  $M$  grid points, you could force

$$u_1^{n+1} = u_M^{n+1} \quad (4)$$

Remember that the boundary condition at grid point  $M$  for the wave equation is given by

$$u_M^{n+1} = u_{M-1}^n \quad (5)$$

- (a) **(60 points)** Write a code to solve the above problem numerically using the first-order Upwind, second-order Upwind, Lax-Wendroff and Rusanov schemes. Make sure that your code can take in the value of  $\nu$  and  $\Delta x$  to determine a suitable timestep.
- (b) **(30 points)** Plot the exact solution and the numerical solutions (from all schemes on the same plot) obtained using  $\Delta x = 0.1$  for  $\nu = 1$  and  $\nu = 0.75$  at  $t = 1, t = 2, t = 3$ .
- (c) **(15 points)** Define the  $L_\infty$ ,  $L^1$ ,  $L^2$  norms of the numerical solution as follows

$$L_\infty = \max(|u_i - u_{\text{exact},i}|) \quad (6)$$

$$L^1 = \frac{1}{M} \sum_{i=1}^M |u_i - u_{\text{exact},i}| \quad (7)$$

$$L^2 = \sqrt{\frac{\sum_{i=1}^M |u_i - u_{\text{exact},i}|^2}{M}} \quad (8)$$

where  $i$  is the grid point index. Compute the  $L_\infty$ ,  $L^1$ ,  $L^2$  norms of the numerical solution for  $\Delta x = 0.1$ ,  $\Delta x = 0.05$ ,  $\Delta x = 10^{-2}$  at  $t = 3$  and tabulate (for all schemes considered above). Use  $\nu = 0.75$  for this part.

- (d) **(5 points)** Determine the order of each of the schemes based on your table above (and not based on prior information provided in class).

2. Now modify the initial condition to a square wave

$$u(x, 0) = 1 \quad 0 \leq x \leq 1 \quad (9)$$

$$u(x, 0) = 0 \quad 1 < x \leq 5 \quad (10)$$

- (a) **(30 points)** Plot the exact solution and the numerical solutions (from all schemes on the same plot) obtained using  $\Delta x = 0.1$  for  $\nu = 1$  and  $\nu = 0.75$  at  $t = 1, t = 2, t = 3$ .

(b) **(15 points)** Define the  $L_\infty$ ,  $L^1$ ,  $L^2$  norms of the numerical solution as follows

$$L_\infty = \max(|u_i - u_{\text{exact},i}|) \quad (11)$$

$$L^1 = \frac{1}{M} \sum_{i=1}^M |u_i - u_{\text{exact},i}| \quad (12)$$

$$L^2 = \sqrt{\frac{\sum_{i=1}^M |u_i - u_{\text{exact},i}|^2}{M}} \quad (13)$$

where  $i$  is the grid point index. Compute the  $L_\infty$ ,  $L^1$ ,  $L^2$  norms of the numerical solution for  $\Delta x = 0.1$ ,  $\Delta x = 0.05$ ,  $\Delta x = 10^{-2}$  at  $t = 3$  and tabulate (for all schemes considered above). Use  $\nu = 0.75$  for this part.

(c) **(5 points)** Determine the order of each of the schemes based on your table above (and not based on their names or prior information provided in class).

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% The following code is for the wave equation
% using 1st order upwind scheme

function wave_methods(dx,Y,time,n)

dt = Y*dx;

% rows in the matrix
t = 0:dt:time;
% columns in the matrix
L = 0:dx:5;

%initial condition in wavelength
IC1 = sin(2*pi*(0:dx:1));
%secondary initial condition in wavelength
IC2 = 0*((1+dx):dx:5);

u1 = zeros(length(t),length(L));
u1(size(u1,1),:) = [IC1,IC2];

% This is the 1st order upwind scheme
for w = length(t)-1:-1:1

    for i=2:1:length(L)
        u1(w,i) = (Y)*(-u1(w+1,i)+u1(w+1,i-1))+u1(w+1,i);
    end

    u1(w,length(L)) = u1(w+1,length(L)-1);
    u1(w,1) = u1(w+1,length(L)-1);

end

%
-----  

% The following code is for the wave equation
% using lax-wendroff method

u2 = zeros(length(t),length(L));
u2(size(u1,1),:) = [IC1,IC2];

for w = length(t)-1:-1:1
    for i=2:1:length(L)-1
        u2(w,i) = u2(w+1,i)-(1/2)*(Y)*(u2(w+1,i+1)-u2(w+1,i-1))...
+...*(1/2)*(Y)^2*(u2(w+1,i+1)-2*u2(w+1,i)+u2(w+1,i-1));
    end

    u2(w,length(L)) = u2(w+1,length(L)-1);
    u2(w,1) = u2(w+1,length(L)-1);
end

```

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```

%
-----  

% The following code is for the wave equation  

% using second order upwind  

% a predictor is used and then the other values are iterated  

% using a 1 step algorithm  

u3 = zeros(length(t),length(L));  

u3(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    u3(w,2) = u3(w+1,2)-(Y)*(u3(w+1,2)-u3(w+1,1));  

    for i=3:1:length(L)  

        u3(w,i) = u3(w+1,i)-(dt/dx)*(u3(w+1,i)-u3(w+1,i-1))+...  

            (1/2)*(dt/dx)*((dt/dx)-1)*(u3(w+1,i)-...  

                2*u3(w+1,i-1)+u3(w+1,i-2));  

    end  

    u3(w,length(L)) = u3(w+1,length(L)-1);  

    u3(w,1) = u3(w+1,length(L)-1);  

end  

%
-----  

% The following code is for the wave equation  

% using Rusanov method  

u4 = zeros(length(t),length(L));  

u4(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    %for the 1st step before n+1  

    for i=1:1:length(L)-1  

        u4_1(1,i) = (1/2)*(u4(w+1,i+1)+u4(w+1,i))-...  

            (1/3)*Y*(u4(w+1,i+1)-u4(w+1,i));  

    end  

    %for the 2nd step before n+1  

    for i=2:1:length(L)-1  

        u4_2(1,i) = u4(w+1,i)-(2/3)*Y*(u4_1(1,i)-u4_1(1,i-1));  

    end  

    for i=3:1:length(L)-2  

        u4(w,i)=u4(w+1,i)-(1/24)*Y*(-2*u4(w+1,i+2)+7*u4(w+1,i+1)-...  

            7*u4(w+1,i-1)+2*u4(w+1,i-2))-...  

            (6/8)*Y*(u4_2(1,i-1)-u4_2(1,i-2))-...  

            ((4*Y^2-Y^4)/24)*(u4(w+1,i+2)-4*u4(w+1,i+1)+6*u4(w+1,i)...  

            -4*u4(w+1,i-1)+u4(w+1,i-2));  

    end  

    u4(w,length(L)-1)=u4(w+1,length(L)-1)-(1/24)*Y*(-2*u4(w+1,2)+7*u4(w+1,length(L))-...)

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7*u4(w+1,length(L)-2)+2*u4(w+1,length(L)-3))-...
(3/8)*Y*(u4_2(1,length(L)-2)-u4_2(1,length(L)-3))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2)-4*u4(w+1,length(L))+6*u4(w
+1,length(L)-1))-...
-4*u4(w+1,length(L)-2)+u4(w+1,length(L)-3));

u4(w,2)=u4(w+1,2)-(1/24)*Y*(-2*u4(w+1,2+2)+7*u4(w+1,2+1)-...
7*u4(w+1,2-1)+2*u4(w+1,length(L)-1))-...
(3/8)*Y*(u4_2(1,2-1)-u4_2(1,length(u4_2)))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2+2)-4*u4(w+1,2+1)+6*u4(w+1,2)...
-4*u4(w+1,2-1)+u4(w+1,length(L)-1));

u4(w,length(L)) = u4(w+1,length(L)-1);
u4(w,1) = u4(w+1,length(L)-1);
end

%
-----%
% The following code is for the wave equation
% using the exact solution
% so u(x) = sin(2*pi*x) from 0,x,1
% u(x) = 0 for 1,x,5
% hence, for the exact solution, u(x,t) = F(x-ct)

u_exact = zeros(length(t),length(L));

for w = length(t):-1:1
    for i=1:1:length(L)
        if ((L(i)-t(w))>=0) && (((L(i)-t(w)))<=1)
            u_exact(w,i) = sin(2*pi*(L(i)-t(w)));
        else
            u_exact(w,i) = 0;
        end
    end
end

figure(n)
plot(L,u_exact(length(t),:),L,u1(1,:),L,u2(1,:),L,u3(1,:),L,u4(1,:));
title(['Wave equation when time: ', num2str(time),'s'])
legend('Exact','1st Order Upwind Scheme','Lax-Wendroff','2nd Order
Upwind',...
'Rusanov (Burstein-Mirin)')

end

Not enough input arguments.

Error in wave_methods (line 6)
dt = Y*dx;

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```
clc
clear all

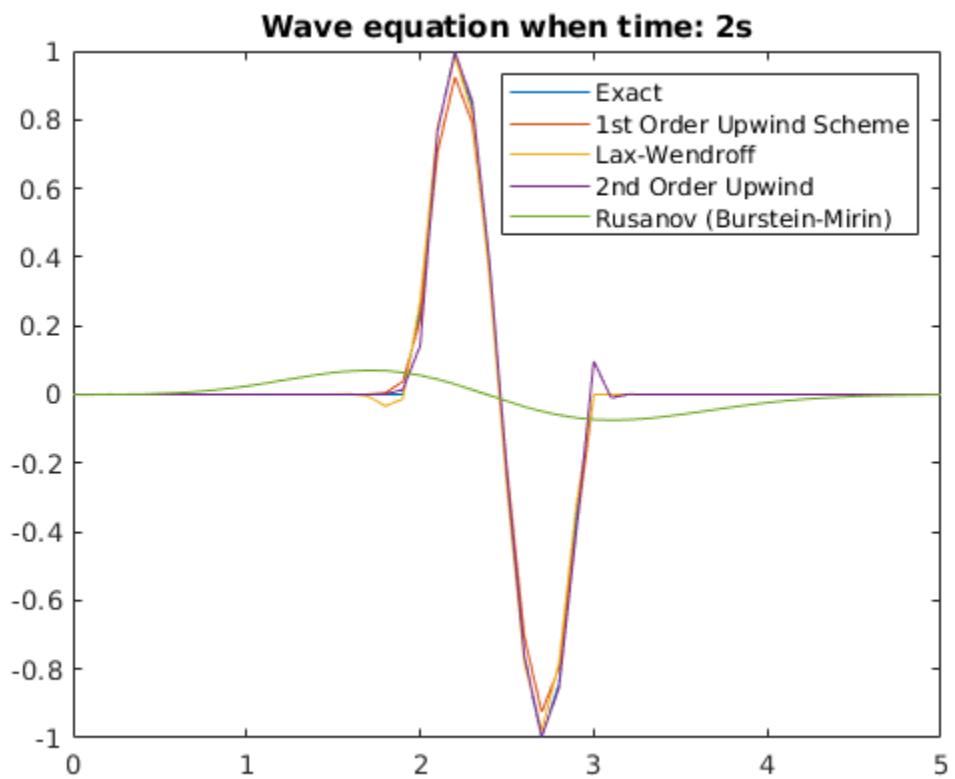
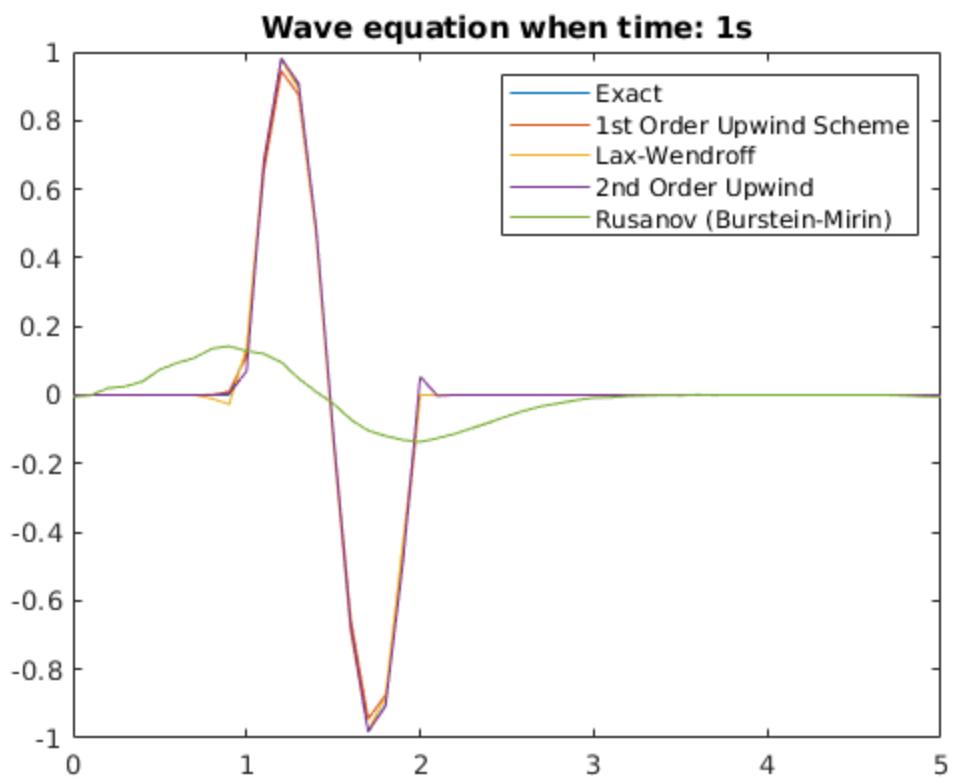
% for Y = 1
% 0.98 was needed in order to be able to distinguish, still 0.98->1
wave_methods(0.1,0.98,1,1);
wave_methods(0.1,0.98,2,2);
wave_methods(0.1,0.98,3,3);

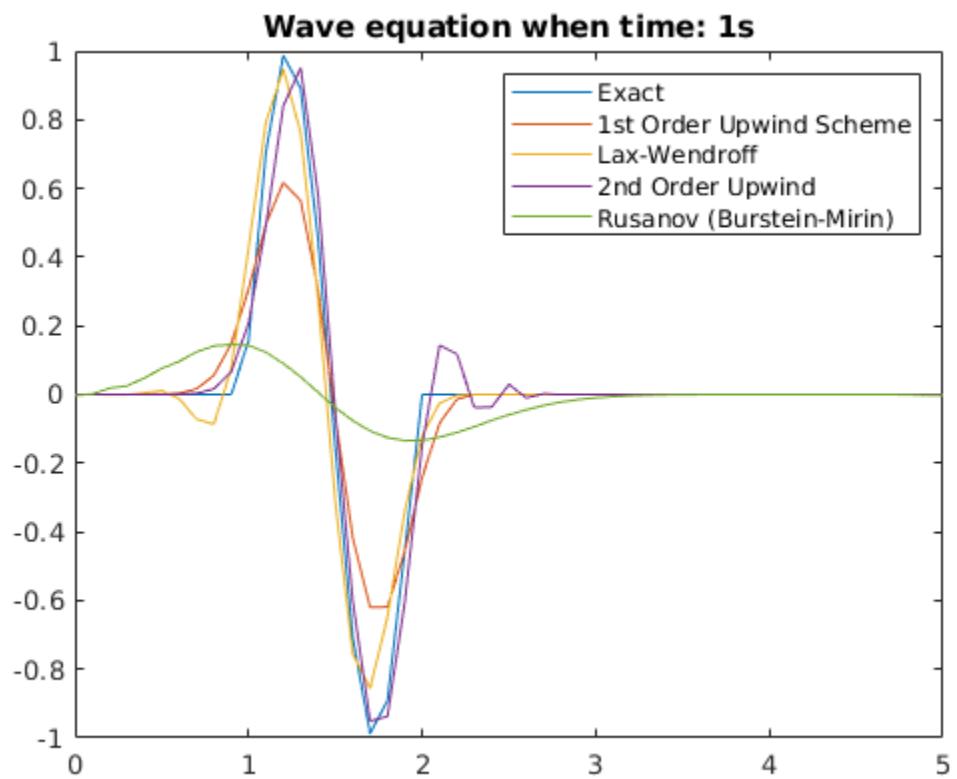
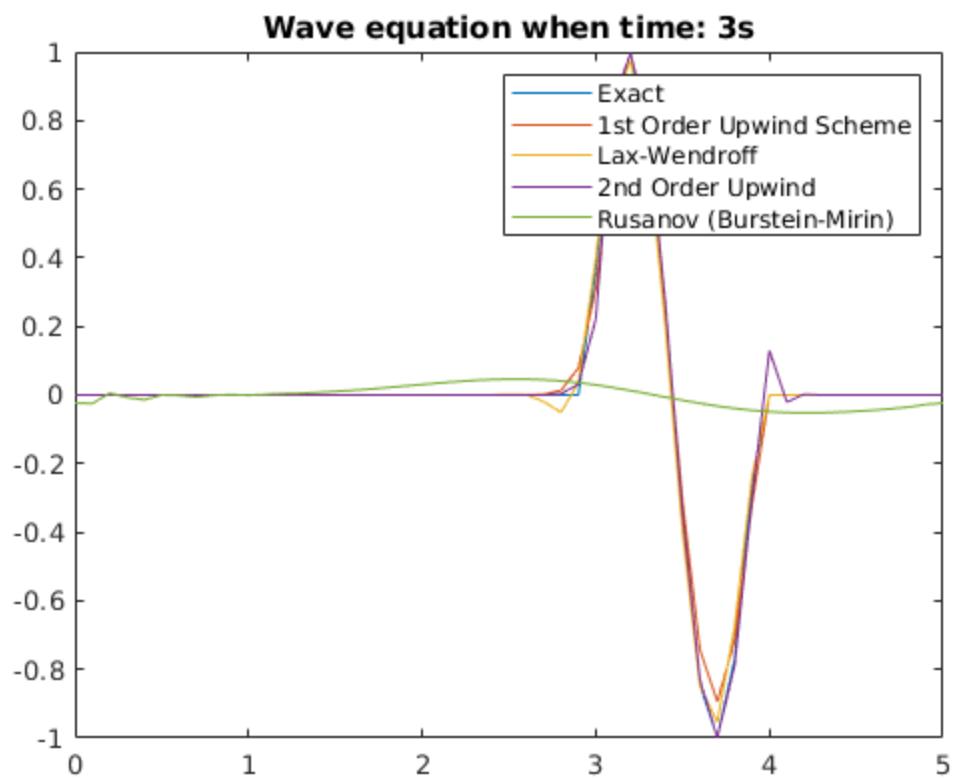
% for Y = 0.75
wave_methods(0.1,0.75,1,4);
wave_methods(0.1,0.75,2,5);
wave_methods(0.1,0.75,3,6);

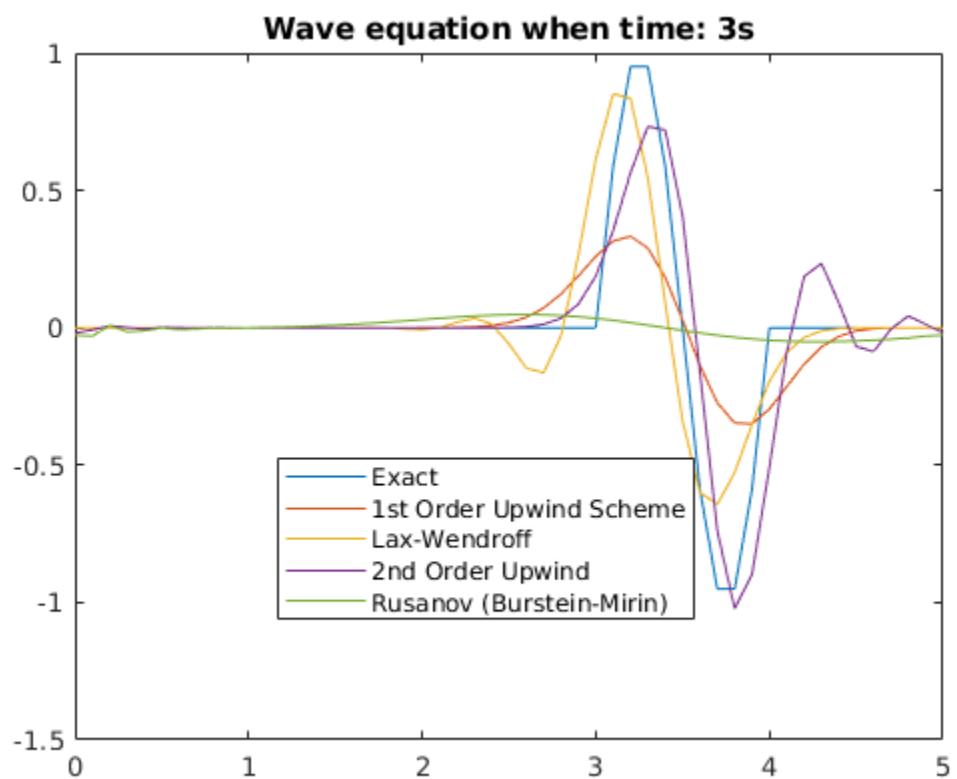
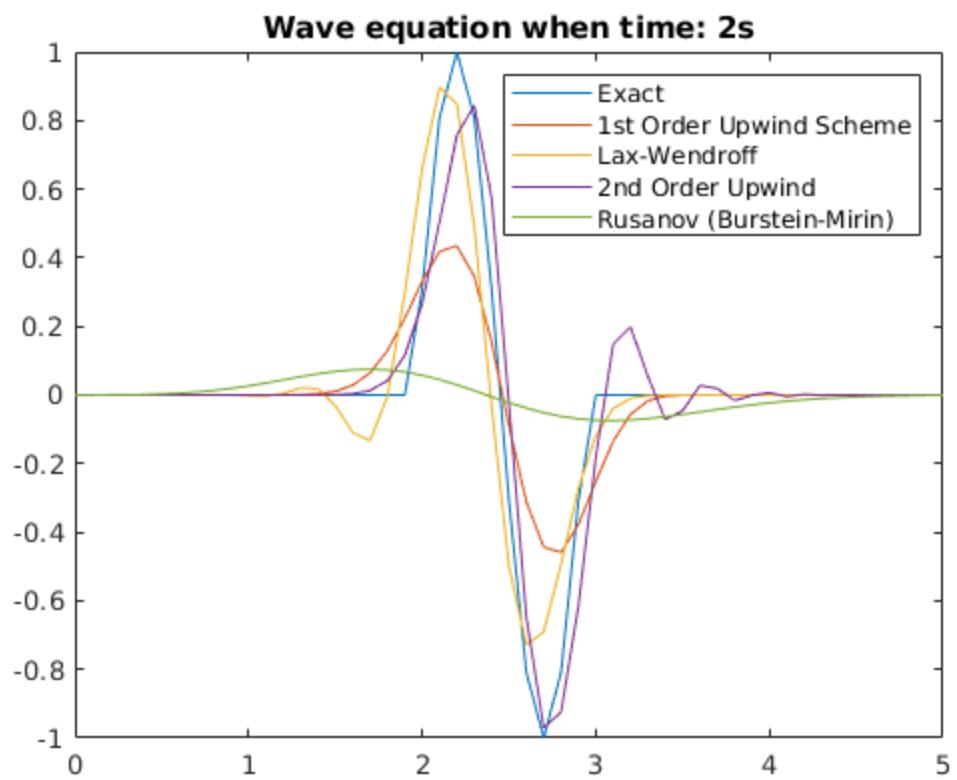
% tabulate the tables for L's of the numerical solution
% using v = 0.75, dx = 0.1, dx = 0.05, dx = 0.01 at t = 3. (wave)
% wave_methods_tabulation(0.1,0.75,3)
% wave_methods_tabulation(0.05,0.75,3)
% wave_methods_tabulation(0.01,0.75,3)

% % for Y = 1
% 0.98 was needed in order to be able to distinguish, still 0.98->1
% wave_methods_linear(0.1,0.98,1,7);
% wave_methods_linear(0.1,0.98,2,8);
% wave_methods_linear(0.1,0.98,3,9);
%
% % for Y = 0.75
% wave_methods_linear(0.1,0.75,1,10);
% wave_methods_linear(0.1,0.75,2,11);
% wave_methods_linear(0.1,0.75,3,12);

% tabulate the tables for L's of the numerical solution
% using v = 0.75, dx = 0.1, dx = 0.05, dx = 0.01 at t = 3.
% wave_methods_linear_tabulation(0.1,0.75,3)
% wave_methods_linear_tabulation(0.05,0.75,3)
% wave_methods_linear_tabulation(0.01,0.75,3)
```









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% The following code is for the wave equation
% using 1st order upwind scheme

function L_A = wave_methods_tabulation(dx,Y,time)

dt = Y*dx;

% rows in the matrix
t = 0:dt:time;
% columns in the matrix
L = 0:dx:5;

%initial condition in wavelength
IC1 = sin(2*pi*(0:dx:1));
%secondary initial condition in wavelength
IC2 = 0*((1+dx):dx:5);

u1 = zeros(length(t),length(L));
u1(size(u1,1),:) = [IC1,IC2];

% This is the 1st order upwind scheme
for w = length(t)-1:-1:1

    for i=2:1:length(L)
        u1(w,i) = (Y)*(-u1(w+1,i)+u1(w+1,i-1))+u1(w+1,i);
    end

    u1(w,length(L)) = u1(w+1,length(L)-1);
    u1(w,1) = u1(w+1,length(L)-1);

end

%
-----  

% The following code is for the wave equation
% using lax-wendroff method

u2 = zeros(length(t),length(L));
u2(size(u1,1),:) = [IC1,IC2];

for w = length(t)-1:-1:1
    for i=2:1:length(L)-1
        u2(w,i) = u2(w+1,i)-(1/2)*(Y)*(u2(w+1,i+1)-u2(w+1,i-1))...
        +(1/2)*(Y)^2*(u2(w+1,i+1)-2*u2(w+1,i)+u2(w+1,i-1));
    end

    u2(w,length(L)) = u2(w+1,length(L)-1);
    u2(w,1) = u2(w+1,length(L)-1);
end

```

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```

%
-----  

% The following code is for the wave equation  

% using second order upwind  

% a predictor is used and then the other values are iterated  

% using a 1 step algorithm  

u3 = zeros(length(t),length(L));  

u3(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    u3(w,2) = u3(w+1,2)-(Y)*(u3(w+1,2)-u3(w+1,1));  

    for i=3:1:length(L)  

        u3(w,i) = u3(w+1,i)-(dt/dx)*(u3(w+1,i)-u3(w+1,i-1))+...  

            (1/2)*(dt/dx)*((dt/dx)-1)*(u3(w+1,i)-...  

                2*u3(w+1,i-1)+u3(w+1,i-2));  

    end  

    u3(w,length(L)) = u3(w+1,length(L)-1);  

    u3(w,1) = u3(w+1,length(L)-1);  

end  

%
-----  

% The following code is for the wave equation  

% using Rusanov method  

u4 = zeros(length(t),length(L));  

u4(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    %for the 1st step before n+1  

    for i=1:1:length(L)-1  

        u4_1(1,i) = (1/2)*(u4(w+1,i+1)+u4(w+1,i))-...  

            (1/3)*Y*(u4(w+1,i+1)-u4(w+1,i));  

    end  

    %for the 2nd step before n+1  

    for i=2:1:length(L)-1  

        u4_2(1,i) = u4(w+1,i)-(2/3)*Y*(u4_1(1,i)-u4_1(1,i-1));  

    end  

    for i=3:1:length(L)-2  

        u4(w,i)=u4(w+1,i)-(1/24)*Y*(-2*u4(w+1,i+2)+7*u4(w+1,i+1)-...  

            7*u4(w+1,i-1)+2*u4(w+1,i-2))-...  

            (6/8)*Y*(u4_2(1,i-1)-u4_2(1,i-2))-...  

            ((4*Y^2-Y^4)/24)*(u4(w+1,i+2)-4*u4(w+1,i+1)+6*u4(w+1,i)...  

                -4*u4(w+1,i-1)+u4(w+1,i-2));  

    end  

    u4(w,length(L)-1)=u4(w+1,length(L)-1)-(1/24)*Y*(-2*u4(w+1,2)+7*u4(w+1,length(L))-...)

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7*u4(w+1,length(L)-2)+2*u4(w+1,length(L)-3))-...
(3/8)*Y*(u4_2(1,length(L)-2)-u4_2(1,length(L)-3))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2)-4*u4(w+1,length(L))+6*u4(w
+1,length(L)-1))-...
-4*u4(w+1,length(L)-2)+u4(w+1,length(L)-3));

u4(w,2)=u4(w+1,2)-(1/24)*Y*(-2*u4(w+1,2+2)+7*u4(w+1,2+1)-...
7*u4(w+1,2-1)+2*u4(w+1,length(L)-1))-...
(3/8)*Y*(u4_2(1,2-1)-u4_2(1,length(u4_2)))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2+2)-4*u4(w+1,2+1)+6*u4(w+1,2)...
-4*u4(w+1,2-1)+u4(w+1,length(L)-1));

u4(w,length(L)) = u4(w+1,length(L)-1);
u4(w,1) = u4(w+1,length(L)-1);
end

%
-----%
% The following code is for the wave equation
% using the exact solution
% so u(x) = sin(2*pi*x) from 0,x,1
% u(x) = 0 for 1,x,5
% hence, for the exact solution, u(x,t) = F(x-ct)

u_exact = zeros(length(t),length(L));

for w = length(t):-1:1
    for i=1:1:length(L)
        if ((L(i)-t(w))>=0) && (((L(i)-t(w)))<=1)
            u_exact(w,i) = sin(2*pi*(L(i)-t(w)));
        else
            u_exact(w,i) = 0;
        end
    end
end

%
-----%
% Now lets tabulate the table for L_inf, L_1, L_2
% for the 1st order upwind scheme

L1 = zeros(3,length(L));

for i=1:1:length(L)
    L1(1,i) = abs(u1(1,i)-u_exact(length(t),i));
end
L_A(1,1) = max(L1(1,:));

for i=1:1:length(L)
    L1(2,i) = abs(u1(1,i)-u_exact(length(t),i));
end
L_A(1,2) = sum(L1(2,:))/length(L);

for i=1:1:length(L)

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        L1(3,i) = abs(u1(1,i)-u_exact(length(t),i))^2;
end
L_A(1,3) = (sum(L1(3,:))/length(L))^(1/2);

%
-----  

% Now lets tabulate the table for L_inf, L_1, L_2
% using lax-wendroff method

for i=1:1:length(L)
    L1(1,i) = abs(u2(1,i)-u_exact(length(t),i));
end
L_A(2,1) = max(L1(1,:));

L1(2,1) = abs(u2(1,1)-u_exact(length(t),1));
for i=2:1:length(L)
    L1(2,i) = abs(u2(1,i)-u_exact(length(t),i))+L1(2,i-1);
end
L_A(2,2) = L1(2,length(L))/length(L);

L1(3,1) = (abs(u2(1,1)-u_exact(length(t),1))^2)/length(L);
for i=2:1:length(L)
    L1(3,i) = abs(u2(1,i)-u_exact(length(t),i))^2+L1(3,i-1);
end
L_A(2,3) = (L1(3,length(L))/length(L))^(1/2);

%
-----  

% Now lets tabulate the table for L_inf, L_1, L_2
% using second order upwind

for i=1:1:length(L)
    L1(1,i) = abs(u3(1,i)-u_exact(length(t),i));
end
L_A(3,1) = max(L1(1,:));

L1(3,1) = abs(u3(1,1)-u_exact(length(t),1));
for i=2:1:length(L)
    L1(2,i) = abs(u3(1,i)-u_exact(length(t),i))+L1(2,i-1);
end
L_A(3,2) = L1(2,length(L))/length(L);

L1(3,1) = (abs(u3(1,1)-u_exact(length(t),1))^2)/length(L);
for i=2:1:length(L)
    L1(3,i) = abs(u3(1,i)-u_exact(length(t),i))^2+L1(3,i-1);
end
L_A(3,3) = (L1(3,length(L))/length(L))^(1/2);

%
-----  

% Now lets tabulate the table for L_inf, L_1, L_2
% using Rusanov method

for i=1:1:length(L)

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```
L1(1,i) = abs(u4(1,i)-u_exact(length(t),i));
end
L_A(4,1) = max(L1(1,:));

L1(3,1) = abs(u4(1,1)-u_exact(length(t),1));
for i=2:1:length(L)
    L1(2,i) = abs(u4(1,i)-u_exact(length(t),i))+L1(2,i-1);
end
L_A(4,2) = L1(2,length(L))/length(L);

L1(3,1) = (abs(u4(1,1)-u_exact(length(t),1))^2)/length(L);
for i=2:1:length(L)
    L1(3,i) = abs(u4(1,i)-u_exact(length(t),i))^2+L1(3,i-1);
end
L_A(4,3) = (L1(3,length(L))/length(L))^(1/2);

end
```

*Not enough input arguments.*

*Error in wave\_methods\_tabulation (line 6)*  
dt = Y\*dx;

*Published with MATLAB® R2018a*

```

ans =
0.6780    0.1064    0.2180
0.6140    0.0842    0.1709
0.5084    0.0802    0.1525
0.8801    0.1385    0.2818

ans =
0.4828    0.0744    0.1563
0.2909    0.0331    0.0689
0.2372    0.0288    0.0587
0.7781    0.1207    0.2455

ans =
0.1974    0.0225    0.0502
0.0696    0.0030    0.0098
0.0607    0.0027    0.0088
0.3443    0.0534    0.1136

>>

```

Using these values in order to get the slope of the L's

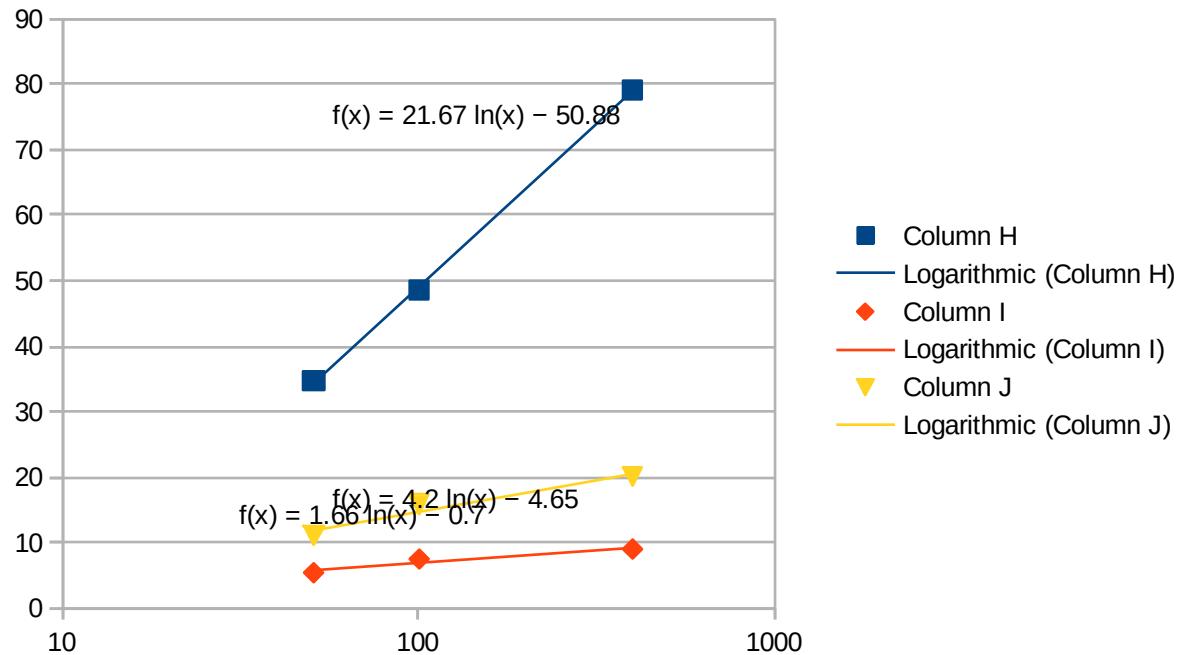
	Upwind – Linf		
M	Linf	L1	L2
51	34.577966429	5.4279125162	11.119936455
101	48.759412042	7.5125015888	15.788160254
401	79.138082958	9.0353392455	20.136115703

	Lax		
M	Linf	L1	L2
51	31.313618464	4.2939984685	8.7135391091
101	29.382984056	3.3388532795	6.9607505166
401	27.893939147	1.2032953899	3.9097815544

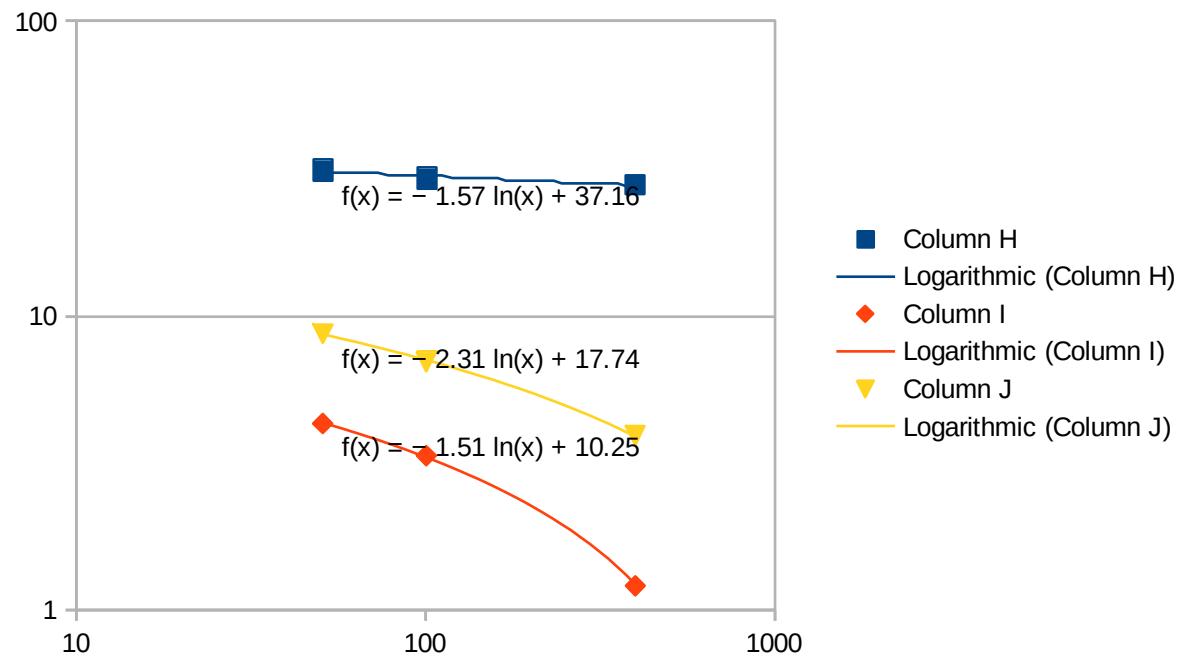
	2 <sup>nd</sup> order		
M	Linf	L1	L2
51	25.928333112	4.0907952592	7.77669035
101	23.95786242	2.9061410655	5.9246052886
401	24.338135305	1.0997843945	3.5245526333

	Rusanov		
M	Linf	L1	L2
51	44.883125621	7.0628945728	14.372560867
101	78.583731008	12.193095747	24.798719762
401	138.07996363	21.412916523	45.570274082

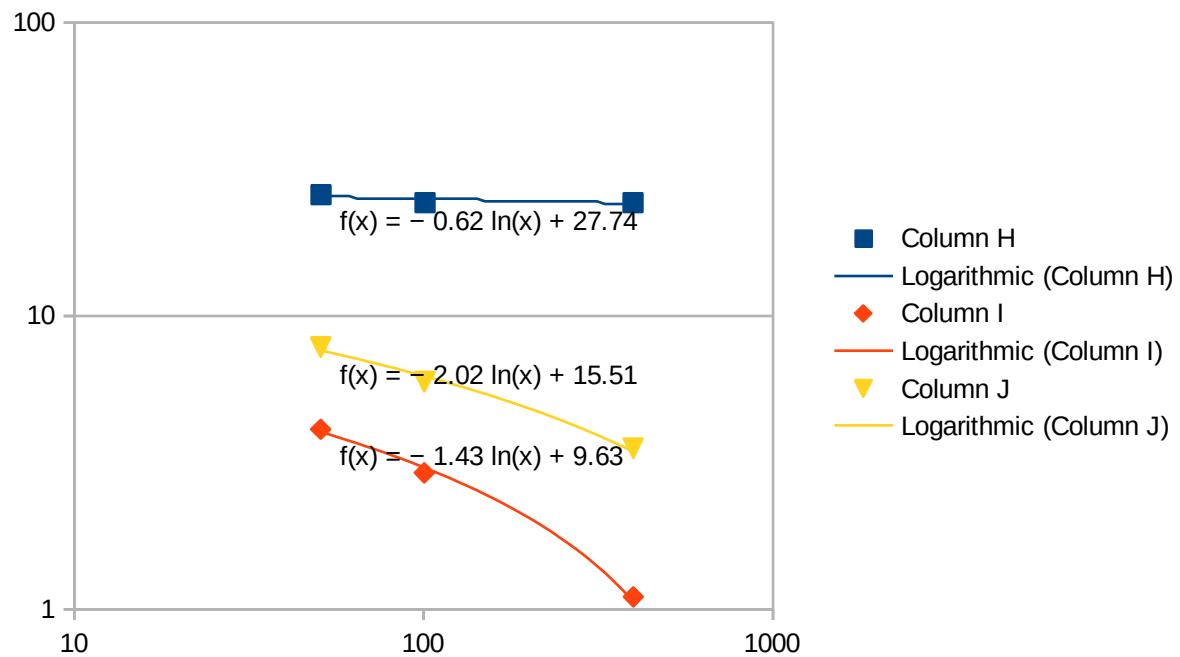
x values and the mesh points and y value is the L\*M



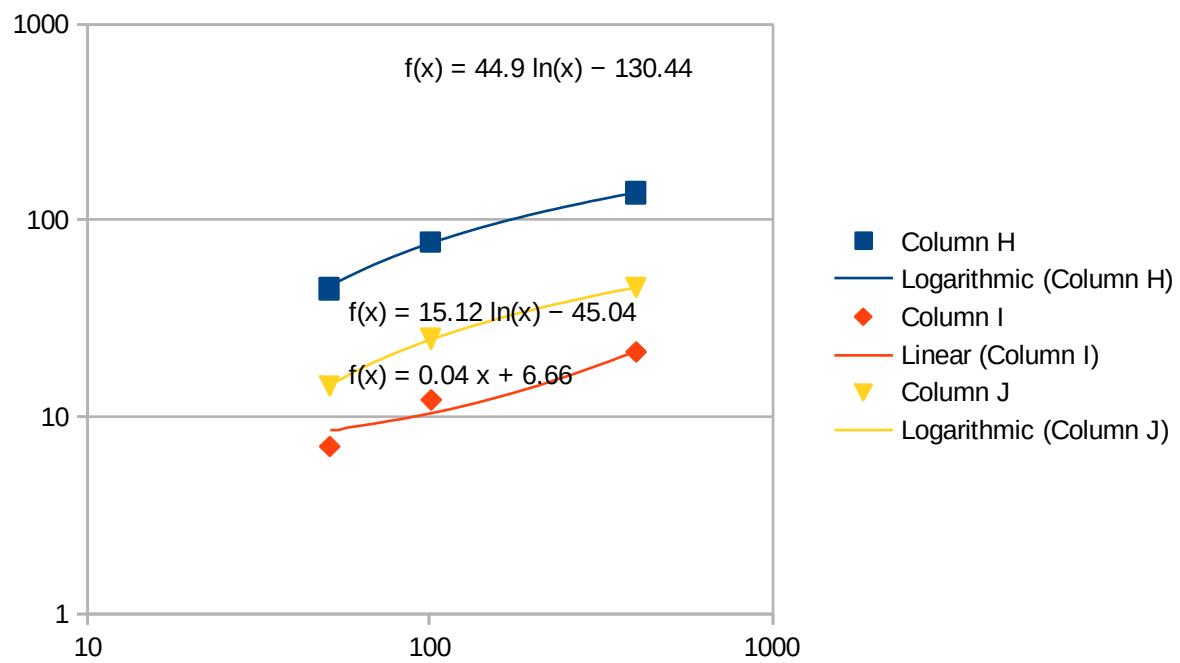
1<sup>st</sup> order upwind (slopes are variable)



Lax method (slopes are variable)



2<sup>nd</sup> order upwind (slopes are variable)



Rusanov

---

```

% The following code is for the wave equation
% using 1st order upwind scheme

function wave_methods_linear(dx,Y,time,n)

dt = Y*dx;

% rows in the matrix
t = 0:dt:time;
% columns in the matrix
L = 0:dx:5;

%initial condition in wavelength
%IC1 = sin(2*pi*(0:dx:1));
IC1 = ones(1,length(0:dx:1));
%secondary initial condition in wavelength
IC2 = 0*((1+dx):dx:5);

u1 = zeros(length(t),length(L));
u1(size(u1,1),:) = [IC1,IC2];

% This is the 1st order upwind scheme
for w = length(t)-1:-1:1

    for i=2:1:length(L)
        u1(w,i) = (Y)*(-u1(w+1,i)+u1(w+1,i-1))+u1(w+1,i);
    end

    u1(w,length(L)) = u1(w+1,length(L)-1);
    u1(w,1) = u1(w+1,length(L)-1);

end

%
-----%
% The following code is for the wave equation
% using lax-wendroff method

u2 = zeros(length(t),length(L));
u2(size(u1,1),:) = [IC1,IC2];

for w = length(t)-1:-1:1
    for i=2:1:length(L)-1
        u2(w,i) = u2(w+1,i)-(1/2)*(Y)*(u2(w+1,i+1)-u2(w
+1,i-1))+...
                    (1/2)*(Y)^2*(u2(w+1,i+1)-2*u2(w+1,i)+u2(w+1,i-1));
    end

    u2(w,length(L)) = u2(w+1,length(L)-1);
    u2(w,1) = u2(w+1,length(L)-1);
end

```

---

---

```

%
-----  

% The following code is for the wave equation  

% using second order upwind  

% a predictor is used and then the other values are iterated  

% using a 1 step algorithm  

u3 = zeros(length(t),length(L));  

u3(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    u3(w,2) = u3(w+1,2)-(Y)*(u3(w+1,2)-u3(w+1,1));  

    for i=3:1:length(L)  

        u3(w,i) = u3(w+1,i)-(dt/dx)*(u3(w+1,i)-u3(w+1,i-1))+...  

            (1/2)*(dt/dx)*((dt/dx)-1)*(u3(w+1,i)-...  

                2*u3(w+1,i-1)+u3(w+1,i-2));  

    end  

    u3(w,length(L)) = u3(w+1,length(L)-1);  

    u3(w,1) = u3(w+1,length(L)-1);  

end  

%
-----  

% The following code is for the wave equation  

% using Rusanov method  

u4 = zeros(length(t),length(L));  

u4(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    %for the 1st step before n+1  

    for i=1:1:length(L)-1  

        u4_1(1,i) = (1/2)*(u4(w+1,i+1)+u4(w+1,i))-...  

            (1/3)*Y*(u4(w+1,i+1)-u4(w+1,i));  

    end  

    %for the 2nd step before n+1  

    for i=2:1:length(L)-1  

        u4_2(1,i) = u4(w+1,i)-(2/3)*Y*(u4_1(1,i)-u4_1(1,i-1));  

    end  

    for i=3:1:length(L)-2  

        u4(w,i)=u4(w+1,i)-(1/24)*Y*(-2*u4(w+1,i+2)+7*u4(w+1,i+1)-...  

            7*u4(w+1,i-1)+2*u4(w+1,i-2))-...  

            (6/8)*Y*(u4_2(1,i-1)-u4_2(1,i-2))-...  

            ((4*Y^2-Y^4)/24)*(u4(w+1,i+2)-4*u4(w+1,i+1)+6*u4(w+1,i)...  

            -4*u4(w+1,i-1)+u4(w+1,i-2));  

    end  

    u4(w,length(L)-1)=u4(w+1,length(L)-1)-(1/24)*Y*(-2*u4(w+1,2)+7*u4(w+1,length(L))-...)

```

---

---

```

7*u4(w+1,length(L)-2)+2*u4(w+1,length(L)-3))-...
(3/8)*Y*(u4_2(1,length(L)-2)-u4_2(1,length(L)-3))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2)-4*u4(w+1,length(L))+6*u4(w
+1,length(L)-1))-...
-4*u4(w+1,length(L)-2)+u4(w+1,length(L)-3));

u4(w,2)=u4(w+1,2)-(1/24)*Y*(-2*u4(w+1,2+2)+7*u4(w+1,2+1)-...
7*u4(w+1,2-1)+2*u4(w+1,length(L)-1))-...
(3/8)*Y*(u4_2(1,2-1)-u4_2(1,length(u4_2)))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2+2)-4*u4(w+1,2+1)+6*u4(w+1,2)...
-4*u4(w+1,2-1)+u4(w+1,length(L)-1));

u4(w,length(L)) = u4(w+1,length(L)-1);
u4(w,1) = u4(w+1,length(L)-1);
end

%
-----%
% The following code is for the wave equation
% using the exact solution
% so u(x) = sin(2*pi*x) from 0,x,1
% u(x) = 0 for 1,x,5
% hence, for the exact solution, u(x,t) = F(x-ct)

u_exact = zeros(length(t),length(L));

for w = length(t):-1:1
    for i=1:1:length(L)
        if ((L(i)-t(w))>=0) && (((L(i)-t(w)))<=1)
            u_exact(w,i) = 1;
        else
            u_exact(w,i) = 0;
        end
    end
end

figure(n)
plot(L,u_exact(length(t),:),L,u1(1,:),L,u2(1,:),L,u3(1,:),L,u4(1,:));
title(['Wave equation when time: ', num2str(time),'s'])
legend('Exact','1st Order Upwind Scheme','Lax-Wendroff','2nd Order
Upwind',...
'Rusanov (Burstein-Mirin)')

end

Not enough input arguments.

Error in wave_methods_linear (line 6)
dt = Y*dx;

```

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---

```
clc
clear all

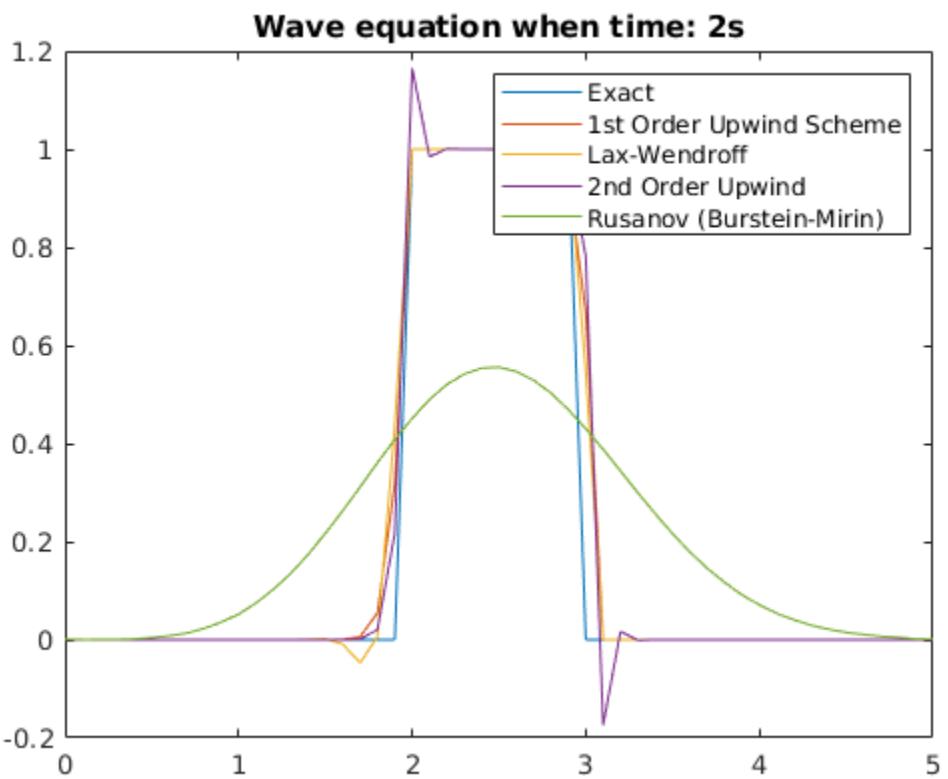
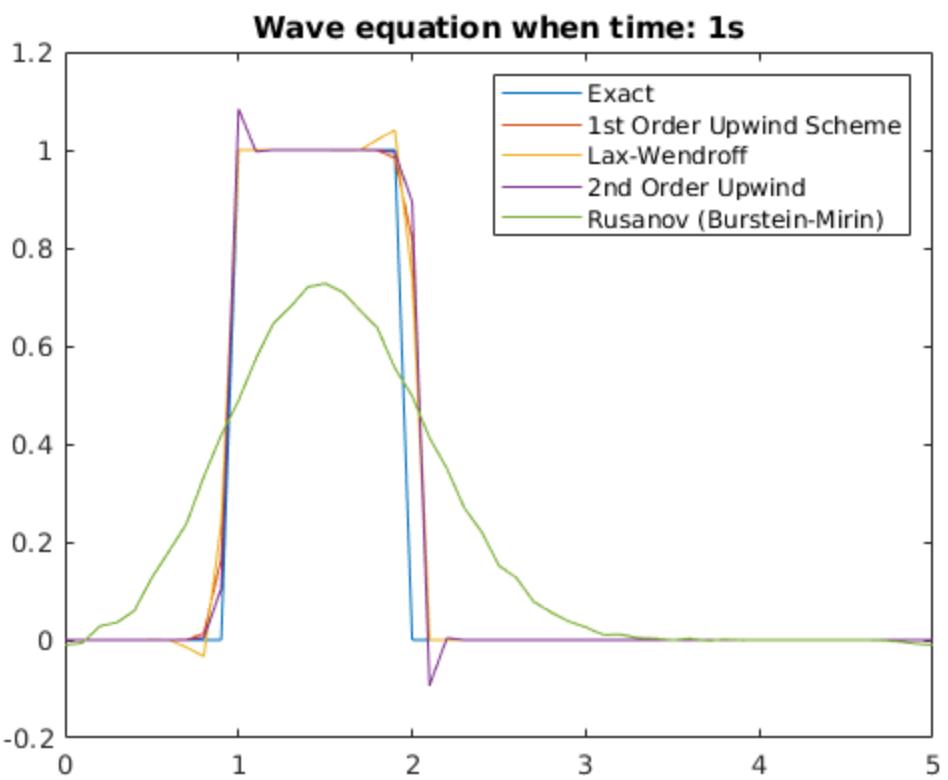
% for Y = 1
% 0.98 was needed in order to be able to distinguish, still 0.98->1
% wave_methods(0.1,0.98,1,1);
% wave_methods(0.1,0.98,2,2);
% wave_methods(0.1,0.98,3,3);

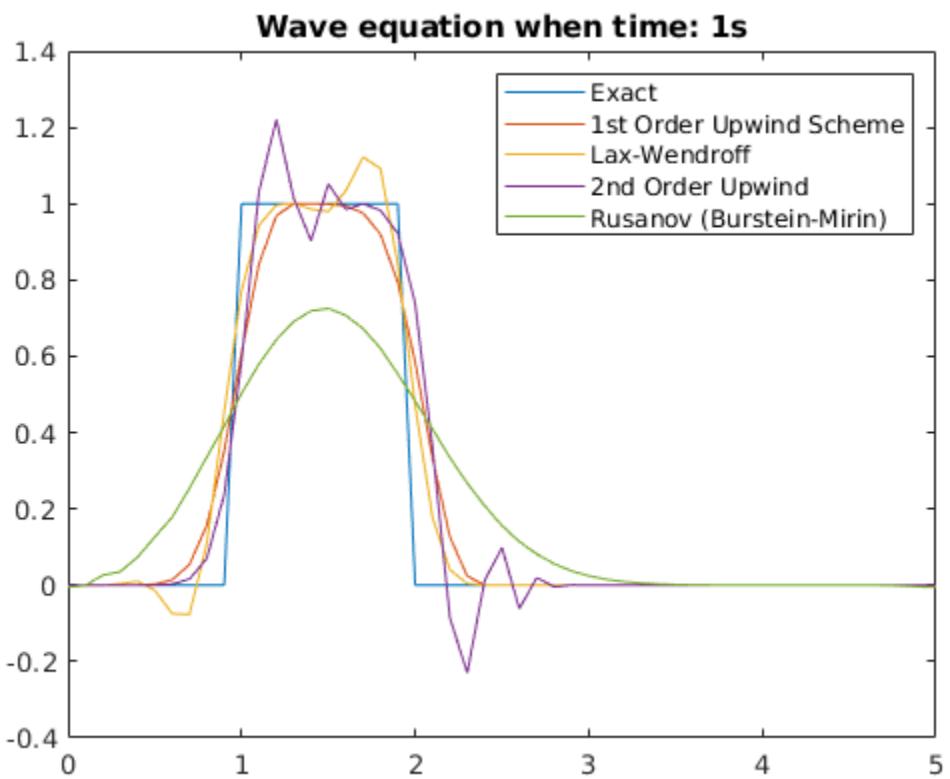
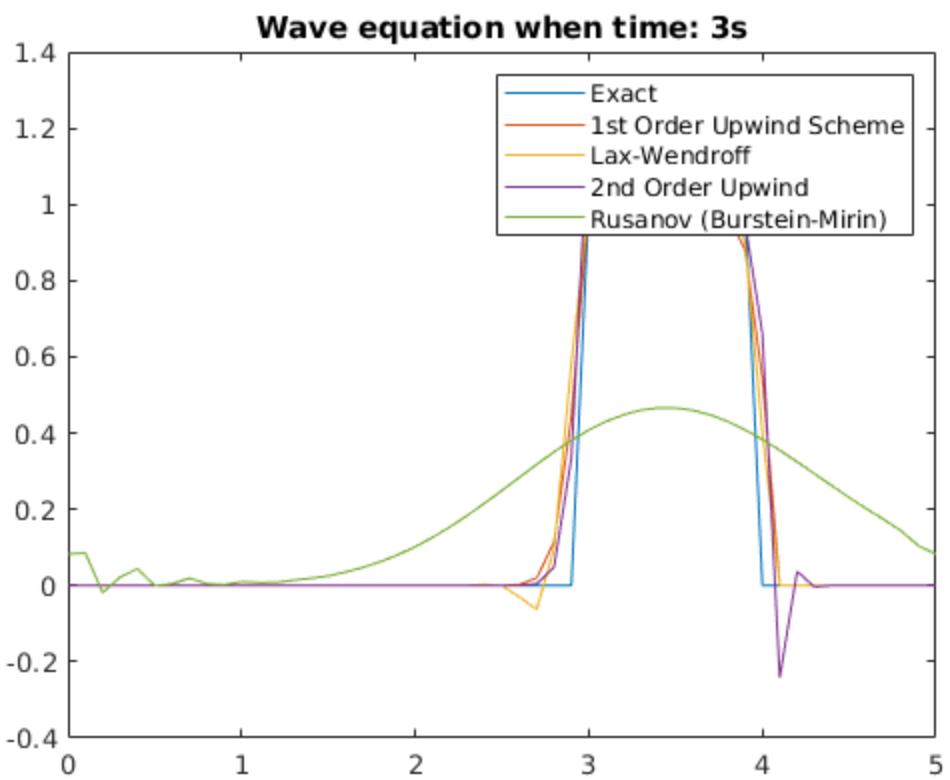
% for Y = 0.75
% wave_methods(0.1,0.75,1,4);
% wave_methods(0.1,0.75,2,5);
% wave_methods(0.1,0.75,3,6);

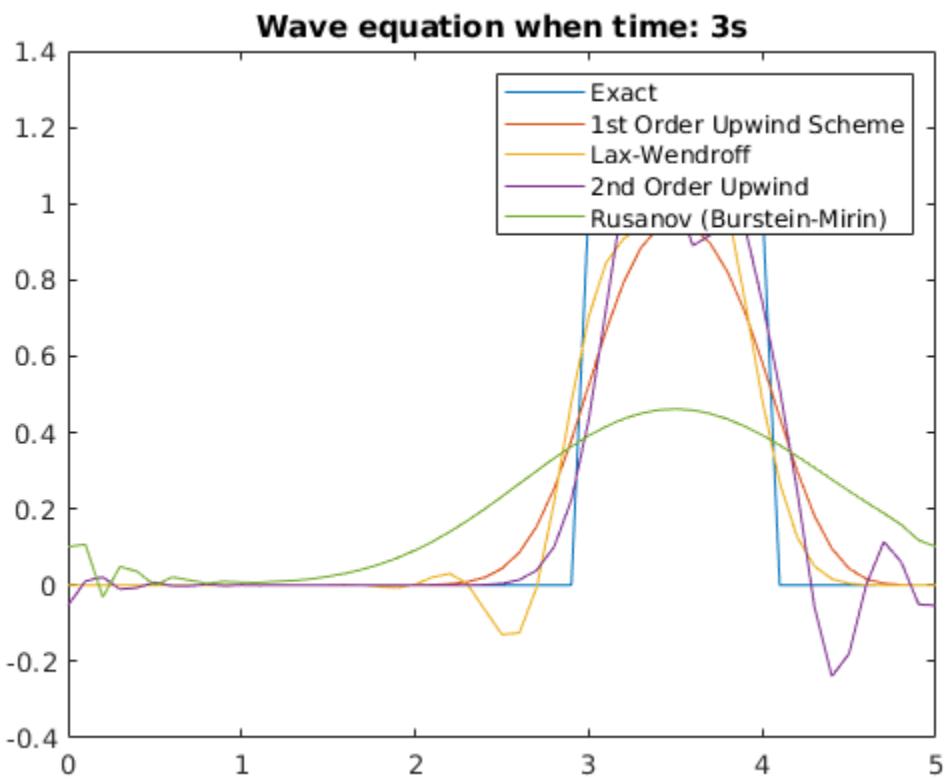
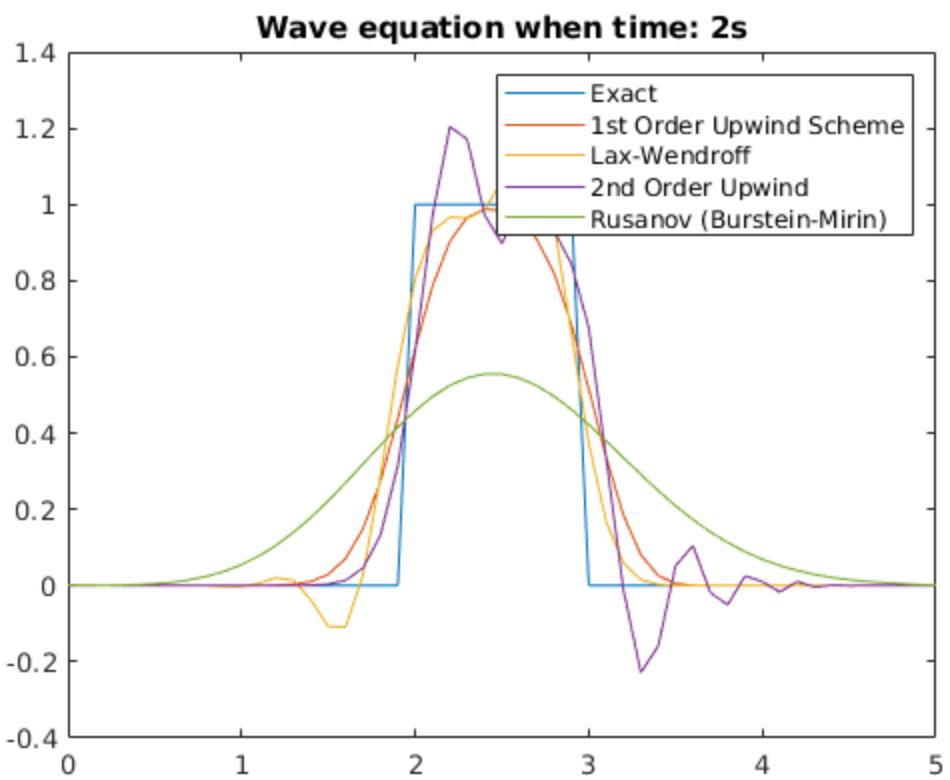
% tabulate the tables for L's of the numerical solution
% using v = 0.75, dx = 0.1, dx = 0.05, dx = 0.01 at t = 3. (wave)
% wave_methods_tabulation(0.1,0.75,3)
% wave_methods_tabulation(0.05,0.75,3)
% wave_methods_tabulation(0.01,0.75,3)

% % for Y = 1
% 0.98 was needed in order to be able to distinguish, still 0.98->1
wave_methods_linear(0.1,0.98,1,7);
wave_methods_linear(0.1,0.98,2,8);
wave_methods_linear(0.1,0.98,3,9);
%
% % for Y = 0.75
wave_methods_linear(0.1,0.75,1,10);
wave_methods_linear(0.1,0.75,2,11);
wave_methods_linear(0.1,0.75,3,12);

% tabulate the tables for L's of the numerical solution
% using v = 0.75, dx = 0.1, dx = 0.05, dx = 0.01 at t = 3.
% wave_methods_linear_tabulation(0.1,0.75,3)
% wave_methods_linear_tabulation(0.05,0.75,3)
% wave_methods_linear_tabulation(0.01,0.75,3)
```









---

```

% The following code is for the wave equation
% using 1st order upwind scheme

function L_A = wave_methods_linear_tabulation(dx,Y,time)

dt = Y*dx;

% rows in the matrix
t = 0:dt:time;
% columns in the matrix
L = 0:dx:5;

%initial condition in wavelength
%IC1 = sin(2*pi*(0:dx:1));
IC1 = ones(1,length(0:dx:1));
%secondary initial condition in wavelength
IC2 = 0*((1+dx):dx:5);

u1 = zeros(length(t),length(L));
u1(size(u1,1),:) = [IC1,IC2];

% This is the 1st order upwind scheme
for w = length(t)-1:-1:1

    for i=2:1:length(L)
        u1(w,i) = (Y)*(-u1(w+1,i)+u1(w+1,i-1))+u1(w+1,i);
    end

    u1(w,length(L)) = u1(w+1,length(L)-1);
    u1(w,1) = u1(w+1,length(L)-1);

end

%
-----%
% The following code is for the wave equation
% using lax-wendroff method

u2 = zeros(length(t),length(L));
u2(size(u1,1),:) = [IC1,IC2];

for w = length(t)-1:-1:1
    for i=2:1:length(L)-1
        u2(w,i) = u2(w+1,i)-(1/2)*(Y)*(u2(w+1,i+1)-u2(w
+1,i-1))+...
                    (1/2)*(Y)^2*(u2(w+1,i+1)-2*u2(w+1,i)+u2(w+1,i-1));
    end

    u2(w,length(L)) = u2(w+1,length(L)-1);
    u2(w,1) = u2(w+1,length(L)-1);
end

```

---

---

```

%
-----  

% The following code is for the wave equation  

% using second order upwind  

% a predictor is used and then the other values are iterated  

% using a 1 step algorithm  

u3 = zeros(length(t),length(L));  

u3(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    u3(w,2) = u3(w+1,2)-(Y)*(u3(w+1,2)-u3(w+1,1));  

    for i=3:1:length(L)  

        u3(w,i) = u3(w+1,i)-(dt/dx)*(u3(w+1,i)-u3(w+1,i-1))+...  

            (1/2)*(dt/dx)*((dt/dx)-1)*(u3(w+1,i)-...  

                2*u3(w+1,i-1)+u3(w+1,i-2));  

    end  

    u3(w,length(L)) = u3(w+1,length(L)-1);  

    u3(w,1) = u3(w+1,length(L)-1);  

end  

%
-----  

% The following code is for the wave equation  

% using Rusanov method  

u4 = zeros(length(t),length(L));  

u4(size(u1,1),:) = [IC1,IC2];  

for w = length(t)-1:-1:1  

    %for the 1st step before n+1  

    for i=1:1:length(L)-1  

        u4_1(1,i) = (1/2)*(u4(w+1,i+1)+u4(w+1,i))-...  

            (1/3)*Y*(u4(w+1,i+1)-u4(w+1,i));  

    end  

    %for the 2nd step before n+1  

    for i=2:1:length(L)-1  

        u4_2(1,i) = u4(w+1,i)-(2/3)*Y*(u4_1(1,i)-u4_1(1,i-1));  

    end  

    for i=3:1:length(L)-2  

        u4(w,i)=u4(w+1,i)-(1/24)*Y*(-2*u4(w+1,i+2)+7*u4(w+1,i+1)-...  

            7*u4(w+1,i-1)+2*u4(w+1,i-2))-...  

            (6/8)*Y*(u4_2(1,i-1)-u4_2(1,i-2))-...  

            ((4*Y^2-Y^4)/24)*(u4(w+1,i+2)-4*u4(w+1,i+1)+6*u4(w+1,i)...  

                -4*u4(w+1,i-1)+u4(w+1,i-2));  

    end  

    u4(w,length(L)-1)=u4(w+1,length(L)-1)-(1/24)*Y*(-2*u4(w+1,2)+7*u4(w+1,length(L))-...)

```

---

---

```

7*u4(w+1,length(L)-2)+2*u4(w+1,length(L)-3))-...
(3/8)*Y*(u4_2(1,length(L)-2)-u4_2(1,length(L)-3))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2)-4*u4(w+1,length(L))+6*u4(w
+1,length(L)-1))-...
-4*u4(w+1,length(L)-2)+u4(w+1,length(L)-3));

u4(w,2)=u4(w+1,2)-(1/24)*Y*(-2*u4(w+1,2+2)+7*u4(w+1,2+1)-...
7*u4(w+1,2-1)+2*u4(w+1,length(L)-1))-...
(3/8)*Y*(u4_2(1,2-1)-u4_2(1,length(u4_2)))-...
((4*Y^2-Y^4)/24)*(u4(w+1,2+2)-4*u4(w+1,2+1)+6*u4(w+1,2)...
-4*u4(w+1,2-1)+u4(w+1,length(L)-1));

u4(w,length(L)) = u4(w+1,length(L)-1);
u4(w,1) = u4(w+1,length(L)-1);
end

%
-----%
% The following code is for the wave equation
% using the exact solution
% so u(x) = sin(2*pi*x) from 0,x,1
% u(x) = 0 for 1,x,5
% hence, for the exact solution, u(x,t) = F(x-ct)

u_exact = zeros(length(t),length(L));

for w = length(t):-1:1
    for i=1:1:length(L)
        if ((L(i)-t(w))>=0) && (((L(i)-t(w)))<=1)
            u_exact(w,i) = sin(2*pi*(L(i)-t(w)));
        else
            u_exact(w,i) = 0;
        end
    end
end

%
-----%
% Now lets tabulate the table for L_inf, L_1, L_2
% for the 1st order upwind scheme

L1 = zeros(3,length(L));

for i=1:1:length(L)
    L1(1,i) = abs(u1(1,i)-u_exact(length(t),i));
end
L_A(1,1) = max(L1(1,:));

for i=1:1:length(L)
    L1(2,i) = abs(u1(1,i)-u_exact(length(t),i));
end
L_A(1,2) = sum(L1(2,:))/length(L);

for i=1:1:length(L)

```

---

---

```

        L1(3,i) = abs(u1(1,i)-u_exact(length(t),i))^2;
end
L_A(1,3) = (sum(L1(3,:))/length(L))^(1/2);

%
-----  

% Now lets tabulate the table for L_inf, L_1, L_2
% using lax-wendroff method

for i=1:1:length(L)
    L1(1,i) = abs(u2(1,i)-u_exact(length(t),i));
end
L_A(2,1) = max(L1(1,:));

L1(2,1) = abs(u2(1,1)-u_exact(length(t),1));
for i=2:1:length(L)
    L1(2,i) = abs(u2(1,i)-u_exact(length(t),i))+L1(2,i-1);
end
L_A(2,2) = L1(2,length(L))/length(L);

L1(3,1) = (abs(u2(1,1)-u_exact(length(t),1))^2)/length(L);
for i=2:1:length(L)
    L1(3,i) = abs(u2(1,i)-u_exact(length(t),i))^2+L1(3,i-1);
end
L_A(2,3) = (L1(3,length(L))/length(L))^(1/2);

%
-----  

% Now lets tabulate the table for L_inf, L_1, L_2
% using second order upwind

for i=1:1:length(L)
    L1(1,i) = abs(u3(1,i)-u_exact(length(t),i));
end
L_A(3,1) = max(L1(1,:));

L1(3,1) = abs(u3(1,1)-u_exact(length(t),1));
for i=2:1:length(L)
    L1(2,i) = abs(u3(1,i)-u_exact(length(t),i))+L1(2,i-1);
end
L_A(3,2) = L1(2,length(L))/length(L);

L1(3,1) = (abs(u3(1,1)-u_exact(length(t),1))^2)/length(L);
for i=2:1:length(L)
    L1(3,i) = abs(u3(1,i)-u_exact(length(t),i))^2+L1(3,i-1);
end
L_A(3,3) = (L1(3,length(L))/length(L))^(1/2);

%
-----  

% Now lets tabulate the table for L_inf, L_1, L_2
% using Rusanov method

for i=1:1:length(L)

```

---

---

```
L1(1,i) = abs(u4(1,i)-u_exact(length(t),i));
end
L_A(4,1) = max(L1(1,:));

L1(3,1) = abs(u4(1,1)-u_exact(length(t),1));
for i=2:1:length(L)
    L1(2,i) = abs(u4(1,i)-u_exact(length(t),i))+L1(2,i-1);
end
L_A(4,2) = L1(2,length(L))/length(L);

L1(3,1) = (abs(u4(1,1)-u_exact(length(t),1))^2)/length(L);
for i=2:1:length(L)
    L1(3,i) = abs(u4(1,i)-u_exact(length(t),i))^2+L1(3,i-1);
end
L_A(4,3) = (L1(3,length(L))/length(L))^(1/2);

end
```

*Not enough input arguments.*

*Error in wave\_methods\_linear\_tabulation (line 6)*  
dt = Y\*dx;

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```

ans =
1.8465    0.2196    0.5016
2.0838    0.2284    0.5506
1.9465    0.2364    0.5338
1.6676    0.2334    0.4626


ans =
1.9195    0.2090    0.5122
2.1756    0.2173    0.5506
1.9970    0.2228    0.5387
1.7867    0.2197    0.4824


ans =
|
1.9980    0.2011    0.5306
2.0235    0.2060    0.5468
2.0000    0.2083    0.5456
1.9580    0.2026    0.5169

```

Using these values in order to get the slope of the L's

Upwind – Linf

M	Linf	L1	L2
51	94.1715	11.1996	25.5816
101	193.8695	21.109	51.7322
401	801.198	80.6411	212.7706

Lax

M	Linf	L1	L2
51	106.2738	11.6484	28.0806
101	219.7356	21.9473	55.6106
401	811.4235	82.606	219.2668

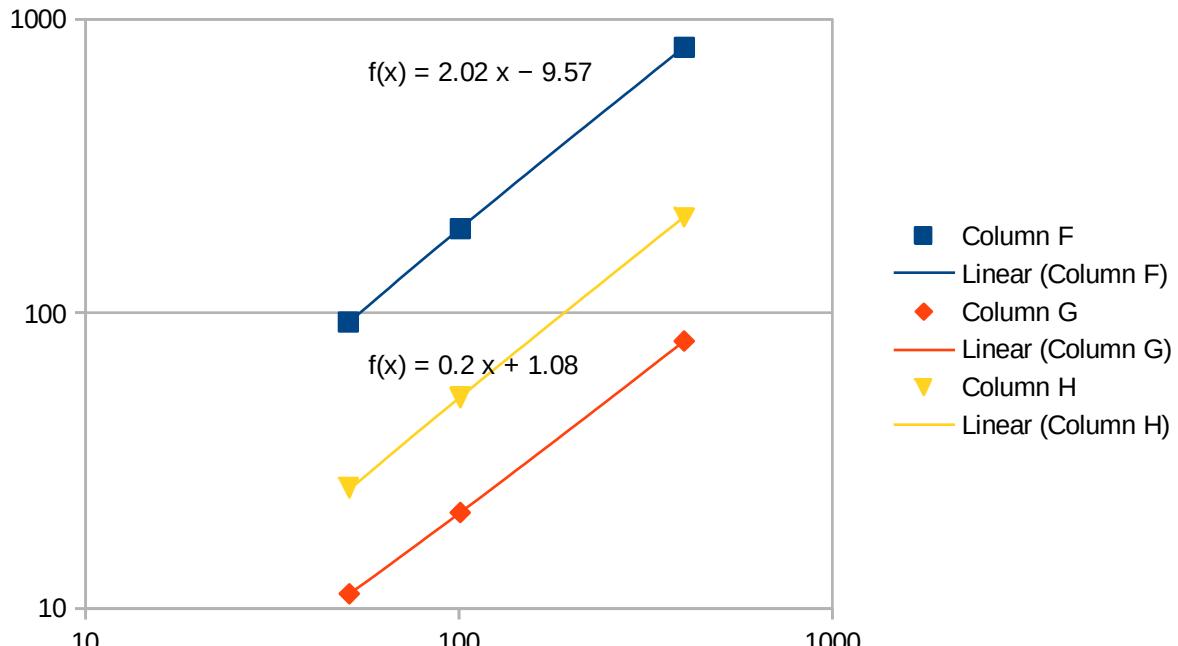
2<sup>nd</sup> order

M	Linf	L1	L2
51	97.325	12.0564	27.2238
101	201.697	22.5028	54.4087
401	802	83.5283	218.7856

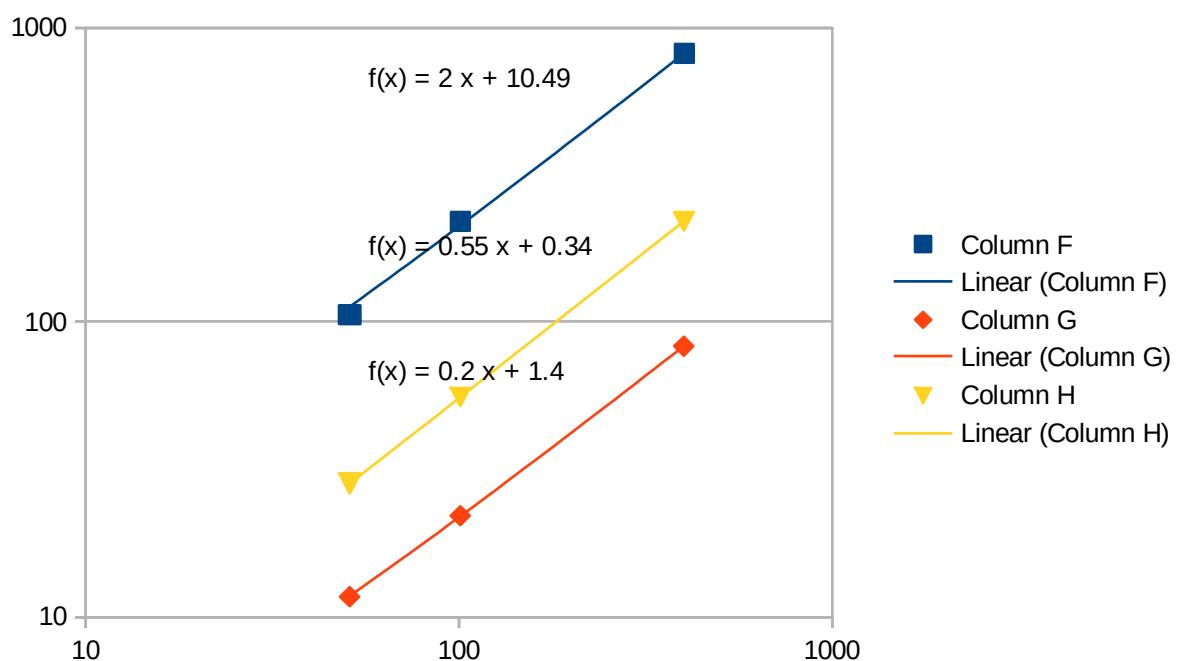
Rusanov

M	Linf	L1	L2
51	85.0476	11.9034	23.5926
101	180.4567	22.1897	48.7224
401	785.158	81.2426	207.2769

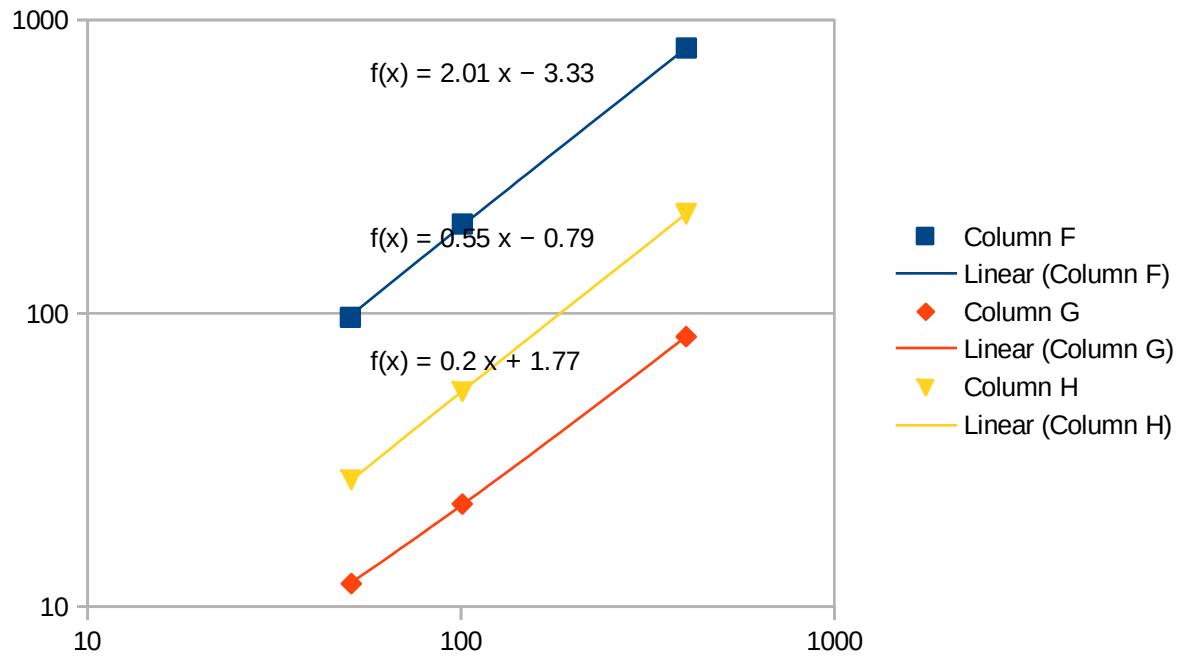
x values and the mesh points and y value is the L\*M



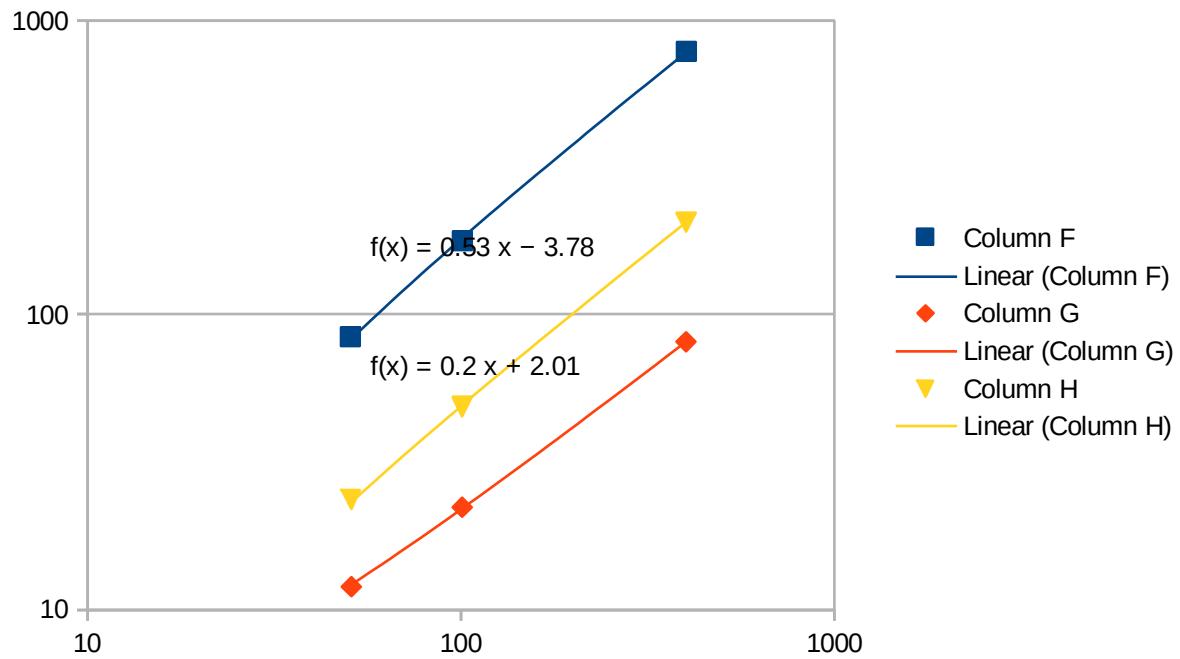
1<sup>st</sup> order upwind (slopes are variable)



Lax method (slopes are variable)



2<sup>nd</sup> order upwind (slopes are variable)



Rusanov