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GRAPHS AND NETWORKS



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- Slides in this course courtesy of
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 - ▣ Dr. Yun Jang (Sejong Univ.)
 - ▣ Dr. Ross Maciejewski (ASU)
 - ▣ Dr. Niklas Elmqvist (UMD)
 - ▣ Dr. David Ebert (Purdue)

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Connections

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- Past lectures, we've talked about multivariate data
 - ▣ Time series (line plots, cyclical, control chart, prediction)
- In these data, we're seeing connections between events, locations and time
- However, there are other ways to represent these sorts of connections
- We can model a set of connections as a graph

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What is a Graph?

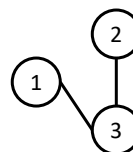
4

- **Vertices** (nodes) connected by **Edges** (links)
- We have several ways to represent a graph

- ▣ Adjacency list

Adjacency List

1:3
2:3
3:1,2



- ▣ Adjacency matrix

	1	2	3
1	0	0	1
2	0	0	1
3	1	1	0

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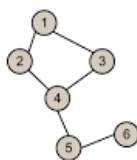
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Graph Representations

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- Adjacency list representation is usually preferred
 - ▣ The most compact way to represent *sparse* graphs
- Adjacency matrix representation may be preferred
 - ▣ A highly connected graph

Undirected Graph & Adjacency Matrix



Undirected Graph

	1	2	3	4	5	6
1	0	1	1	0	0	0
2	1	0	0	1	0	0
3	1	0	0	1	0	0
4	0	1	1	0	1	0
5	0	0	0	1	0	1
6	0	0	0	0	1	0

Adjacency Matrix

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Graph Terminology

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- Graphs can have ?? cycle
 - ▣ You can follow a path from one node and return back to the same node
- Graph edges can be *directed* (uni-, bi-) or *undirected*
- The ?? is the ^{degree} number of ?? ^{edge} connected to it
 - ▣ For a directed graph, you have an *In-Degree* and an *Out-Degree*
- Graph edges can have values (weights) on them and these values can be measures like we've discussed in our multivariate data (nominal, ordinal or quantitative)

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Some details from this slide borrowed from John Stasko's Graph lecture: <http://www.cc.gatech.edu/~stasko/7450/Notes/graph1.pdf>

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Graph Drawing Research Overview

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- There is a whole research community that focuses on the creation of graph layout techniques:
- <http://www.graphdrawing.org/>
- **1970s**
 - ▣ Begin to visualize graphs on a computer
 - ▣ *Key Ideas:*
 - Aesthetics in the graph layouts
 - Can we mathematically optimize these “aesthetics”???

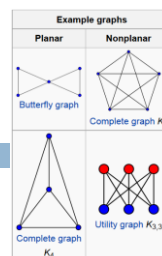
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Graph Drawing

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- **1980s**
 - ▣ Exciting algorithms and geometry
 - Many fundamental graph layout algorithms were developed
 - ▣ Planarity became a key concept
 - A **planar** graph is a graph that can be embedded in a plane so that **no edges intersect**
 - The problem of determining if a graph is planar can be solved in linear time with a simple algorithm
 - ▣ Fary's Theorem (1948) – any simple planar graph can be drawn without crossings so that its edges are straight line segments



Fáry, István (1948), "On straight-line representation of planar graphs", *Acta Sci. Math. (Szeged)* 11: 229–233

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Graph Drawing

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1990s

- ▣ Graph drawing matured as a discipline with the advent of the graph drawing conference
- ▣ Information visualization emerges as a discipline

2000s

- ▣ More demand for graph drawing
- ▣ Data volumes become larger – data deluge
- ▣ More usable products, faster computers
- ▣ New customers (social networks, systems biology, security)

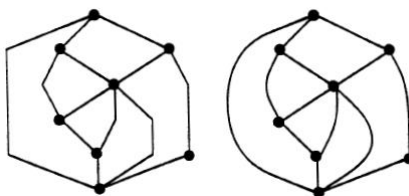
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How to Draw a Graph?

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- ▣ Various graphic standards for the representations
 - ▣ Vertices: typically circles or boxes
 - ▣ Edges: a simple curve
- ▣ So, a graph drawing algorithm
 - ▣ takes edges and vertices of a graph
 - ▣ outputs a pictorial representation based on some algorithmic graphic standard



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How to Draw a Graph?

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- A graph has infinitely many ways to be laid out
- What we are concerned
 - ▣ the **usefulness of the drawing**
 - ▣ the capability of **conveying the meaning and relationships**
- These are often expressed by means of **aesthetics**
 - ▣ A fundamental and classic aesthetic
 - the **minimization of ??** **edge crossings**
 - ▣ Might want to **??** on the screen that the graph takes up
minimize the area
 - ▣ May want to optimize displays of **??**
symmetry

P Eades and R Tamassia, "Algorithms for Drawing Graphs: An Annotated Bibliography," *Technical Report No. CS-89-09*, Brown University, October 1989.

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Aesthetic Considerations

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crossings

total edge length

area

maximum edge length

uniform edge length

total bends

- ?? – minimize towards planar
- ?? – minimize towards proper scale
- ?? – minimize towards efficiency
- ?? – minimize longest edge
- ?? – minimize variance
- ?? – minimize orthogonal towards straight-line

Some details from this slide borrowed from John Stasko's Graph lecture: <http://www.cc.gatech.edu/~stasko/7450/Notes/graph1.pdf>

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Experimenting with Aesthetics-Based Graph Layout

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- Automatic graph layout algorithms are typically judged
 - ▣ Speed
 - ▣ Extent to which they conform to an aesthetic
 - ▣ E.g., minimized crossings, maximized symmetry, etc.
- However, we want to understand if humans can use these
 - ▣ Helen Purchase experiments
 - showed that ?? is the **most important aesthetic** to consider
reducing the number of crossing

Purchase, H.C.; Carrington, D.; Alder, J.-A. Experimenting with aesthetics-based graph layout. In: Anderson, M.; Cheng, P.; Haarslev, V. editors. Vol. LNAI 1889, Theory and Application of Diagrams Conference: Springer Verlag; 2000. p. 498-501

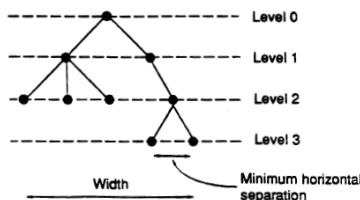
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Rooted Trees

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- A graph might be used to represent some **hierarchy**, so we often utilize a tree metaphor
- Typically these utilize the following aesthetics
 - ▣ Vertices are placed along horizontal lines according to their level (distance from root)
 - ▣ There is a minimum separation distance between two consecutive vertices on the same level
 - ▣ The width of the drawing is as small as possible



P Eades and R Tamassia, "Algorithms for Drawing Graphs: An Annotated Bibliography," *Technical Report No. CS-89-09*, Brown University, October 1989.

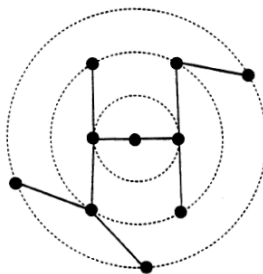
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Free Trees

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- We can have trees that do not represent hierarchy
- Modify rooted trees to produce radial drawing by arranging the vertices of each level on a concentric circle
- It is NP-complete to construct a planar orthogonal grid drawing of a tree such that the maximum edge length is minimized



P Eades and R Tamassia, "Algorithms for Drawing Graphs: An Annotated Bibliography," *Technical Report No. CS-89-09*, Brown University, October 1989.

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Planarity Testing

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line crossing

- Clearly, one aesthetic is to **remove ??**, thus planarity is a desirable graph feature
- This is a well-studied problem, and many methods exist that run in $O(n)$ time where n is the number of edges (or vertices) in a graph
 - ▣ *Classic path addition method*¹
 - ▣ *PQ tree vertex addition method*²
 - ▣ *Edge addition method*³

1 - Hopcroft, John; Tarjan, Robert E. (1974), "Efficient planarity testing", *Journal of the Association for Computing Machinery* **21** (4): 549–568

2 - Lempel, A.; Even, S.; Cederbaum, I. (1967), "An algorithm for planarity testing of graphs", in Rosenstiehl, P., *Theory of Graphs*, New York: Gordon and Breach, pp. 215–232.

3 - Boyer & Myrvold (2004), p. 243: "Its implementation in LEDA is slower than LEDA implementations of many other $O(n)$ -time planarity algorithms."

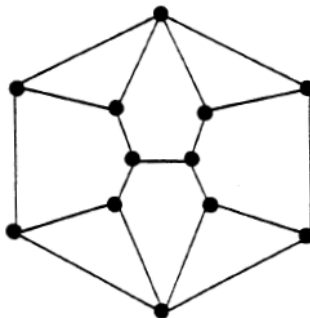
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Straight Line Graph Drawings

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- Tutte's Algorithm
 - ▣ The result is a non-crossing, convex drawing



William T. Tutte. How to draw a graph. *Proc. London Math. Society*, 13(52):743–768, 1963.

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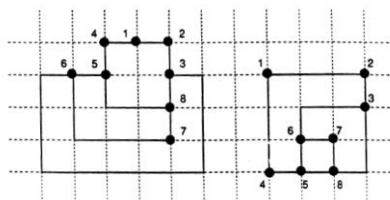
Orthogonal Grid Drawings

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- Planar orthogonal grid drawings were first studied in connection with circuit layout
- With this graphic standard, goal is **to minimize the** **??** (good for readability and for VLSI)
- Any planar graph of **??** admits a planar orthogonal grid drawing with area $O(n^2)$

number of bends

degree at most 4



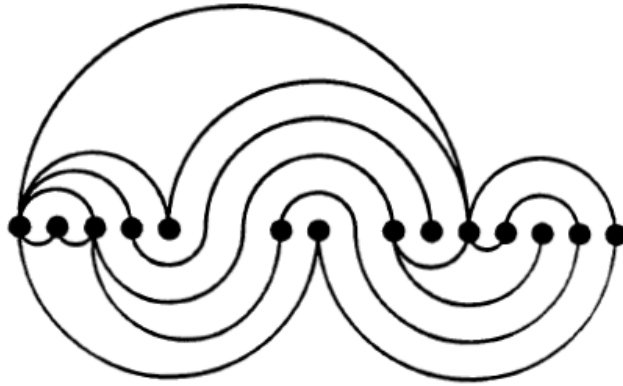
P Eades and R Tamassia, "Algorithms for Drawing Graphs: An Annotated Bibliography," *Technical Report No. CS-89-09*, Brown University, October 1989.

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Planar Drawings on a Line

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P Eades and R Tamassia, "Algorithms for Drawing Graphs: An Annotated Bibliography," *Technical Report No. CS-89-09*, Brown University, October 1989.

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Force-Directed Methods

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- Use a physical analogy to draw graphs
- View a graph as a system of objects with **forces** acting between them
- Assumption is that **a balanced system gives a good layout**
- Specifically, a system configuration with locally minimum energy
 - ▣ The sum of forces on each object is zero
- <https://observablehq.com/@d3/force-directed-graph>

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Force-Directed Methods

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- Consider each node/vertex to be the object of the system
 - ▣ **Nodes** interact with each other based on some **forces**
 - ▣ **links** do not interact with each other, instead, they add new forces to each node
- Equilibrium configuration is when
 - ▣ the **sum of forces on each node is zero**
- Methods typically have two parts
 - ▣ Model – a force system defined by nodes and links
 - ▣ Algorithm – a technique for finding equilibrium

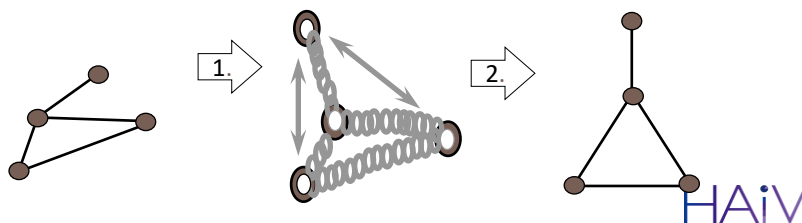
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Spring Methods

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- Node
 - ▣ Thought of as an **electrically charge particle** that **repels each other**
- Link
 - ▣ Thought of as **a spring that connects the particles**
 - ▣ So there is an attraction force when longer than the natural length, and repulsion when shorter



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Springs and Electrical Forces

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- Use a combination of spring & electrical forces
 - ▢ Node: modeled as spring
 - ▢ Link: equally charged particles which repel each other
- The force on v : $F(v) = \sum f_{u,v} + \sum g_{u,v}$
- $f_{u,v}$: force on v by the spring between u and v
 - : follow Hook's law (proportional to the difference between the distance between u and v and the zero-energy length of the spring)
- $g_{u,v}$: Electrical repulsion exerted on v by vertex u
 - : follow inverse square law

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Springs and Electrical Forces

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- $d(p,q)$: Euclidean distance between points p and q
- $p_v = (x_v, y_v)$: position of vertex v
- x component of the force on v

$$\sum_{(u,v) \in E} k_{uv}^1 (d(p_u, p_v) - l_{uv}) \frac{x_v - x_u}{d(p_u, p_v)} + \sum_{(u,v) \in V \times V} \frac{k_{uv}^2}{(d(p_u, p_v))^2} \cdot \frac{x_v - x_u}{d(p_u, p_v)}$$
- $l_{u,v}$: natural (zero energy) length of the spring between u and v
 - : if the spring has natural length $l_{u,v}$, no force is exerted;
- $k_{u,v}^1$: stiffness of the spring between u and v
 - : the larger $k_{u,v}^1$, the more tendency for the distance between u and v to be close to $l_{u,v}$
- $k_{u,v}^2$: the strength of the electrical repulsion between u and v

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Springs and Electrical Forces

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Aim of the force model design:

- Spring force:
 - ▣ Ensure the distance between adjacent nodes u and v is approximately equal to $l_{u,v}$
- Electrical force:
 - ▣ Ensure nodes not too close to each other.
- One may choose parameters l_{uv} $k^1_{u,v}$ $k^2_{u,v}$ to customize for specific applications.

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Finding Equilibrium

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- There are many techniques to find an equilibrium configuration (or minimum energy).
- Simple algorithm
 - ▣ Initially at random location
 - ▣ At each iteration:
 - Force $F(v)$ on each node is computed
 - Each node v is moved in the direction of $F(v)$ by a small amount proportional to the magnitude of $F(v)$
 - ▣ Stops when equilibrium is achieved or some conditions are met.
- **Not the fastest**, but allow smooth animation.
- Calculating attractive forces only between neighbors: $O(|L|)$
- Calculating repulsive forces between all pair of vertices: $O(|N|^2)$
 - ▣ **Bottleneck of the algorithm in general**

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Force directed methods

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- Many experiments in this area, but the open problem is, “Why do these methods work?”
 - ▣ Many experiments, some theorems
- Theorem: If a graph has the right automorphisms, then there is a local minimum of a spring drawing that is symmetric
- Theories
 - ▣ Combinatorial rigidity theory
 - ▣ Theory of multidimensional scaling

Details from this slide borrowed from Peter Eades’ “The Future of Graph Drawing – and a rhapsody” lecture:
<http://sydney.edu.au/engineering/it/~peter/downloads.html>

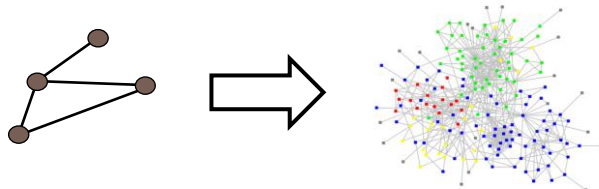
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Scale Challenge

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- So, what happens when we get a lot of nodes and edges?
- We run out of space for nodes and links so we get a hairball
- Can slow down the algorithm!



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Expanding Graph Drawing

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- If we want to improve the visual capacity for graph drawing we need to think of extensions
 - ▣ 3D
 - ▣ Interaction
 - ▣ Clustering

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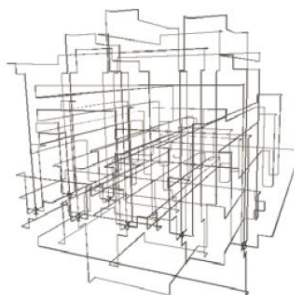
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3D Graph Drawing

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- 1990-2005
 - ▣ Many theorems on 3D
 - ▣ New metaphors introduced
 - ▣ New research grants and start-up company
 - ▣ However, 3D mostly failed

3D orthogonal
drawing of K_7



Maurizio Patrignani

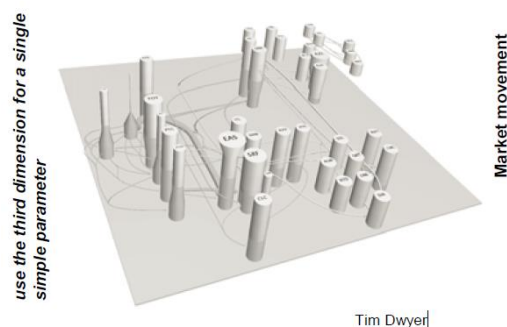
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2.5D Graph Drawing

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- Colin Ware: “Use 3D with a 2D attitude”
- Tim Dwyer: “use the third dimension for a single parameter”



Tim Dwyer and David R. Gallagher. Visualising changes in fund manager holdings in two and a half-dimensions. *Information Visualization*, 3(4):227-244, 2004

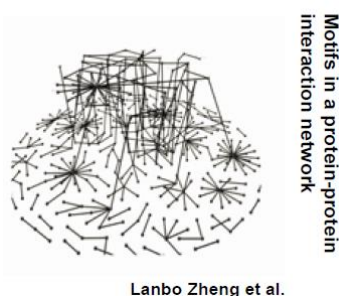
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Multiplane Method

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- Partition the graph
- Draw each part on a 2D manifold in 3D
- Connect the parts with inter-manifold edges



Weidong Huang, Colin Murray, Xiaobin Shen, Le Song, Ying Xin Wu, Lanbo Zheng: Visualisation and Analysis of Network Motifs. IV 2005, 697-702

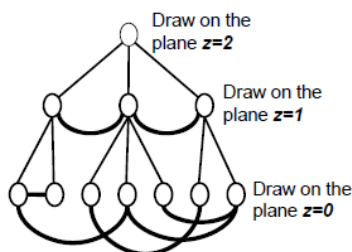
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Multilevel Visualization of Clustered Graphs

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- Draw the clusters on height l of the cluster tree on the plane $z=i$



P. Eades and Q. Feng. Multilevel Visualization of Clustered Graphs. In *Proc. 6th Int. Symp. Graph Drawing*, volume 1190 of *LNCS*, pages 101-112. Springer, 1996.

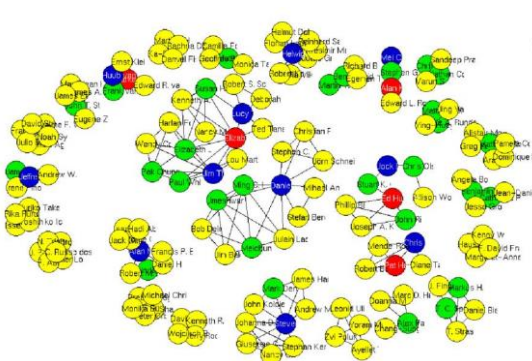


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Thinking Back on our Visual Variables

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- If we think back onto our early lectures, we need to make decisions on what the appropriate visual variables will be
- **For a node**, we have
 - ▣ Shape
 - ▣ Color
 - ▣ Size
 - ▣ Location
 - ▣ Label



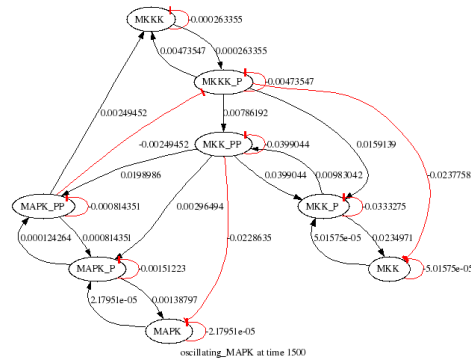
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Thinking Back on our Visual Variables

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□ For a link, we have

- Color
- Size
- Label
- Form
 - Polyline
 - Straight
 - Orthogonal grid



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Network Visualization Nirvana

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- What would be our dream situation for network/graph visualization?
 - ?? Every node is visible
 - ?? For every node we can count its degree
 - ?? For every link...
 - ??

B Shneiderman and A Aris. Network Visualization by Semantic Substrates. *IEEE Transactions on Visualization and Computer Graphics*, 12(5): 733-740, 2006.

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Graph Visualization Task Taxonomy

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□ Topology-based tasks

- ?? **Adjacency**
 - Find the set of nodes adjacent to a node
- ?? **Accessibility**
 - Find the set of nodes accessible to a node
- ?? **Common connection**
 - Given nodes, find the set of nodes connected to all
- ?? **Connectivity**
 - Find shortest path
 - Identify clusters
 - Identify connected components

B. Lee, C. Plaisant, C. Sims Parr, J.-D. Fekete, N. Henry, "Task Taxonomy for Graph Visualization", Proc. of BELIV '06, April '06, pp. 1-5.
Some details from this slide borrowed from John Stasko's Graph lecture: <http://www.cc.gatech.edu/~stasko/7450/Notes/graph1.pdf>

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Graph Visualization Task Taxonomy

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□ Attribute-based tasks

- ?? **On the nodes**
 - Find the nodes having a specific attribute value
- ?? **On the edges**
 - Given a node, find the nodes connected only by certain kinds of edges

□ Browsing tasks

- ?? **Follow path**
- ?? **Revisit**

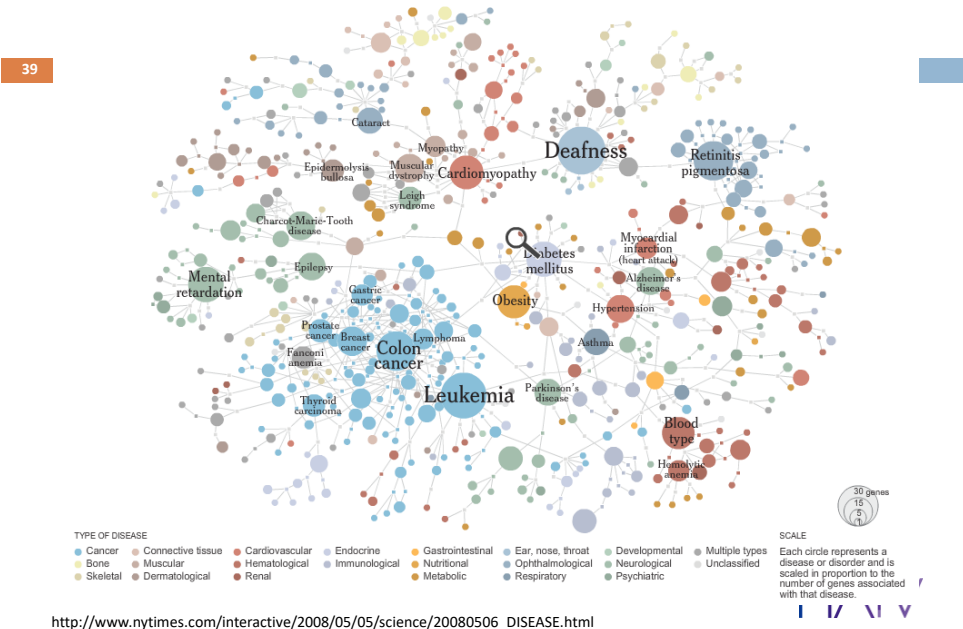
□ Overview task

- ?? **Compound exploratory task**
 - Estimate size of a network
 - Find patterns

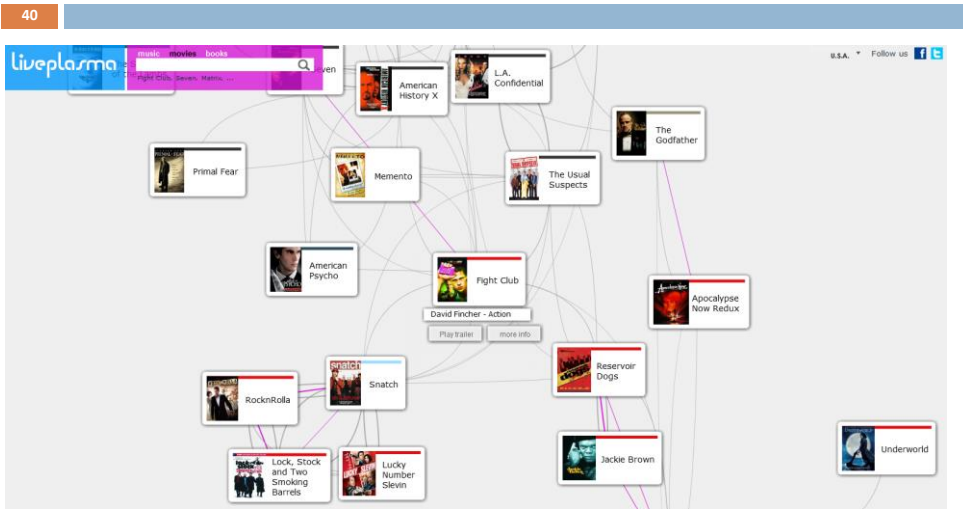
B. Lee, C. Plaisant, C. Sims Parr, J.-D. Fekete, N. Henry, "Task Taxonomy for Graph Visualization", Proc. of BELIV '06, April '06, pp. 1-5.
Some details from this slide borrowed from John Stasko's Graph lecture: <http://www.cc.gatech.edu/~stasko/7450/Notes/graph1.pdf>

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Mapping the Human ‘Diseasome’
Researchers created a map linking different diseases, represented by circles, to the genes they have in common, represented by squares.
Related Article: [Redefining Disease, Genes and All](#)

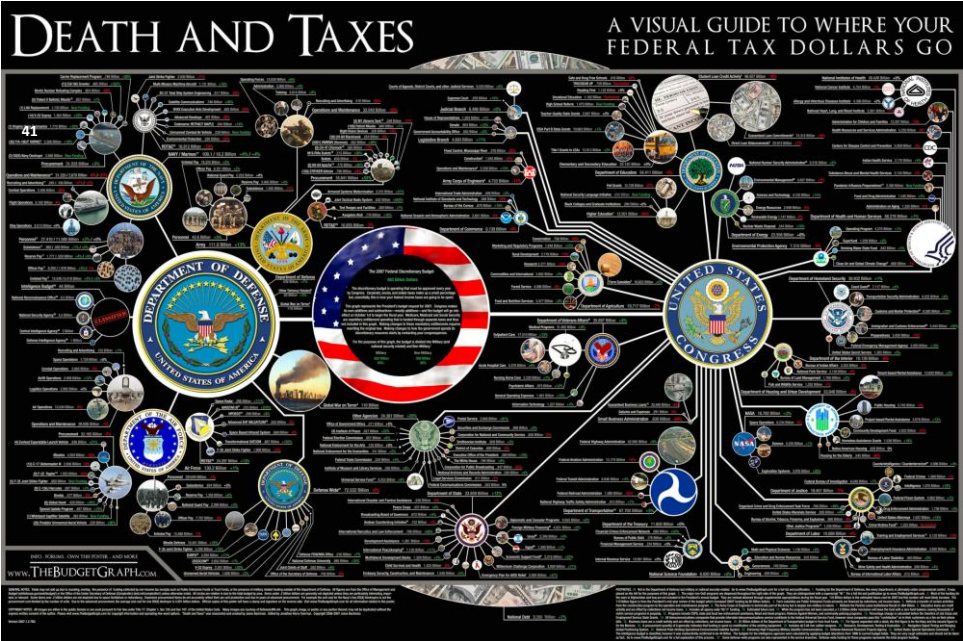


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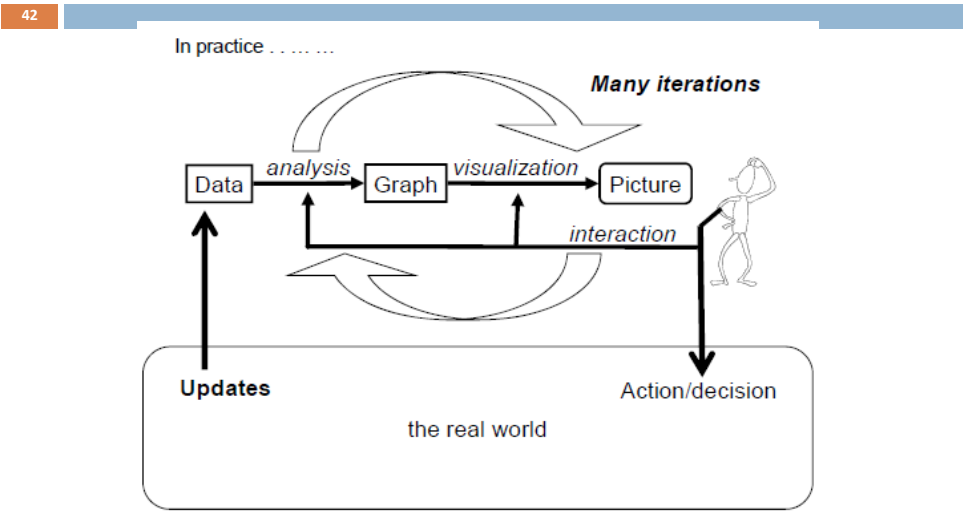


<http://www.deathandtaxesposter.com/>

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Interaction Flow in Graphs



Details from this slide borrowed from Peter Eades' "The Future of Graph Drawing – and a rhapsody" lecture:
<http://sydney.edu.au/engineering/it/~peter/downloads.html>

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Using Interaction

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- By using interaction, we can **reduce ??**
 - ▣ The layout is only computed for the key frame (can be a relatively small graph in comparison)
 - ▣ Can use the time that the user is thinking about the visual to compute
- This also **reduces the ??**
- However, this **can increase the ??**
 - ▣ The user must remember things from key frame to key frame

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Implications of Interaction

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- Drilling down changes the size of a node (zooms in)
- Drilling up is performed by the system, but needs to preserve mental model
- Nodes must move to accommodate these changes in size
- The new picture must also conform to all the aesthetic constraints
- The mental map must be preserved
 - ▣ Preserve ordering
 - ▣ Preserve proximity
 - ▣ Preserve topology

Details from this slide borrowed from Peter Eades' "The Future of Graph Drawing – and a rhapsody" lecture:
<http://sydney.edu.au/engineering/it/~peter/downloads.html>

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Readings

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□ Required Reading:

- ▣ Ivan Herman, Guy Melanon, and M. Scott Marshall. 2000. Graph Visualization and Navigation in Information Visualization: A Survey. *IEEE Transactions on Visualization and Computer Graphics* 6, 1 (January 2000), 24-43
- ▣ Adam Perer and Ben Shneiderman: Integrating Statistics and Visualization for Exploratory Power: From Long-Term Case Studies to Design Guidelines, *IEEE Computer Graphics & Applications* 29, 3 (May/June 2009), 39-51
- ▣ M. Wattenberg, "Visual exploration of multivariate graphs," *Proceedings of ACM CHI '06*, Montreal, Canada, April 2006, pp. 811-819.

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