

Typing Assumptions Improve Identification in Causal Discovery



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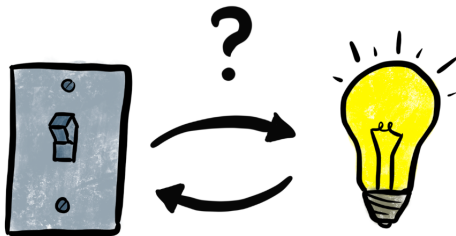
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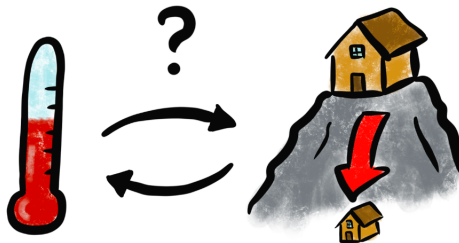
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Motivation

Can a light bulb change the state of a switch?



Can the temperature of a city alter its altitude?

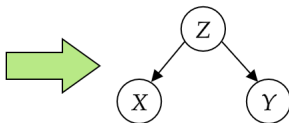


- As humans, we understand the implausibility of causal relationships between certain types of entities.
- In fact, most of the time, we use prior knowledge to generalize causal relation between similar entities.
[Griffiths et al., 2011, Schulz & Gopnik, 2004, Gopnik & Sobel, 2000]

Causal Discovery

The task of causal discovery consists of learning the structure of G based on observations from P_X .

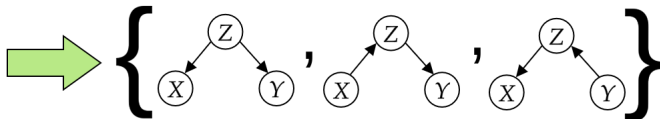
X	Y	Z
1.21	1.58	0.33
1.50	1.84	0.51
\vdots	\vdots	\vdots
\vdots	\vdots	\vdots
0.96	1.07	0.11



Markov Equivalence Class

Unfortunately, from observational data, one can only retrieve a set of equivalent DAGs called the **Markov Equivalence Class** (MEC).

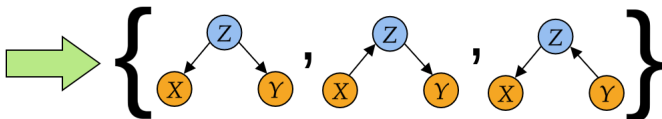
X	Y	Z
1.21	1.58	0.33
1.50	1.84	0.51
⋮	⋮	⋮
⋮	⋮	⋮
0.96	1.07	0.11



Variable types

In our new setting, each vertex has an associated type (that might have been given by an expert). We call these graphs **t-DAGs**.

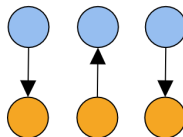
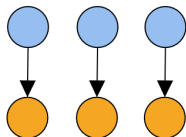
X	Y	Z
1.21	1.58	0.33
1.50	1.84	0.51
⋮	⋮	⋮
0.96	1.07	0.11



Type consistency: constraints on type interactions

Assumption: all edges between a pair of types are oriented in the same direction.

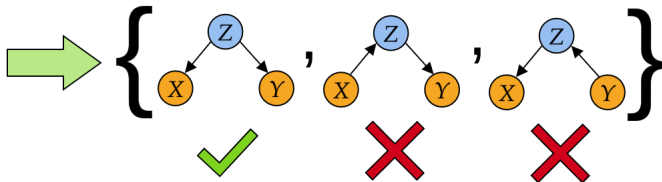
We call t-DAGs that satisfy this condition **consistent t-DAGs**.



t-MEC: an equivalence class for consistent t-DAGs

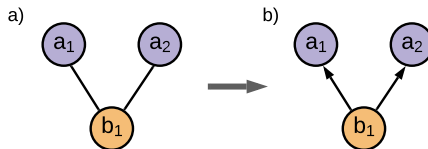
With this assumption, the size of the MEC can be greatly reduced by removing t-DAGs that violate type consistency. We call this equivalence class a **t-MEC**.

X	Y	Z
1.21	1.58	0.33
1.50	1.84	0.51
⋮	⋮	⋮
⋮	⋮	⋮
0.96	1.07	0.11



Theorem: identification guarantees for random graphs

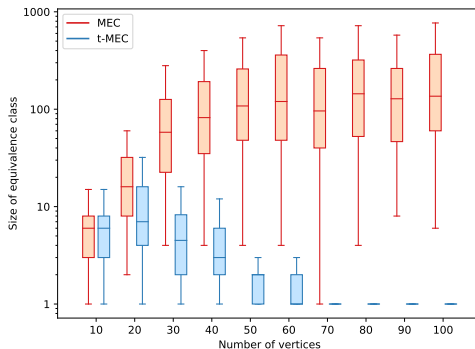
- We show that there exists conditions under which our assumptions lead to benefits in identification.
- For a random sequence of t-DAGs with a fixed number of types, the size of the t-MEC **converge to a singleton** exponentially fast with **the number of vertices** (measured variables).
- **Proof sketch:** There exists a structure, called a two-type fork, that forces the orientation of edges due to type consistency. As the graph grows, the probability of observing it converges to 1 and thus all edges of the t-DAG are oriented.



Two-type fork

Experiments

As the number of vertices increase, $|t\text{-MEC}|$ decreases while $|\text{MEC}|$ increases.



This work shows that our typing assumptions can help reduce the size of the MEC and thus help in causal discovery when our assumptions hold.

Future work:

- Explore practical applications (tiered background knowledge [Andrews, 2020])
- Relax our assumption for more realistic settings
- Learn types automatically from metadata related to each variable

Thank you!



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Come to our poster to learn more about:

- our assumptions based on variable types.
- a simple algorithm to incorporate these assumptions in causal discovery.
- the theoretical result that guarantee convergence of the equivalence class to a singleton.

References

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