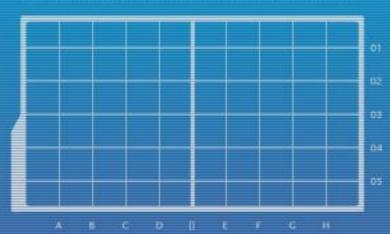


DEPARTMENT OF INFORMATION SYSTEMS AND COMPUTER SCIENCE





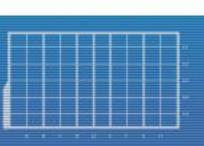
Polygons

Convex Shapes and the Separating Axis Theorem

Lecture Time!

- ► Polygons: In SFML
- ► Separating Axis Theorem: Convex Shapes Only







- A convex shape in SFML defined by a collection of points in local coordinate space
 - ► Two consecutive points, as well as the last and first points, form an edge
 - Can define points in either clockwise or counterclockwise order
 - ▶ But stick to one order for all polygons in your code/data
- ► Also has position and rotation

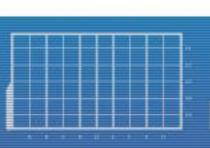


```
sf::ConvexShape poly;
// set number of points
// (ex. 3 for a triangle)
poly.setPointCount( NUM POINTS );
for ( int i = 0; i < NUM POINTS; <math>i++ )
    // use vectors to set points
    // in local space
    sf::Vector2f vect;
    poly.setPoint(i, vect);
```



```
// assuming you want a hollow shape
poly.setFillColor(
    sf::Color(0,0,0,0));
poly.setOutlineColor(
    sf::Color(255, 255, 255));
poly.setOutlineThickness( -1);
// drawing is still the same
window.draw(poly);
```

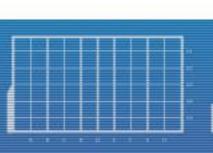






- ► A convex polygon has interior angles that are all less than 180 degrees
- ► A concave polygon is not convex
 - ► Has at least one interior angle that is more than 180 degrees







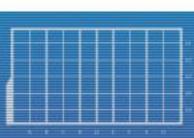
Separating Axis Theorem

- Project both polygons on the normal of each edge of both polygons
 - ▶ If the projections do not overlap for at least one edge, then there is no overlap
 - Otherwise, the polygons overlap
- Requires several operations even if it has early exit possibilities
 - Use AABB or any other "cheap" overlap test first before using SAT

Separating Axis Theorem

- SFML only takes note of a polygon's position, rotation, and point coordinates in local space
- ► However, using the SAT for an overlap test requires the points to be in world space coordinates
 - ► Apply rotation then position
 - ► Note: SAT works with convex shapes only

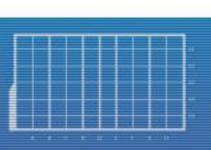




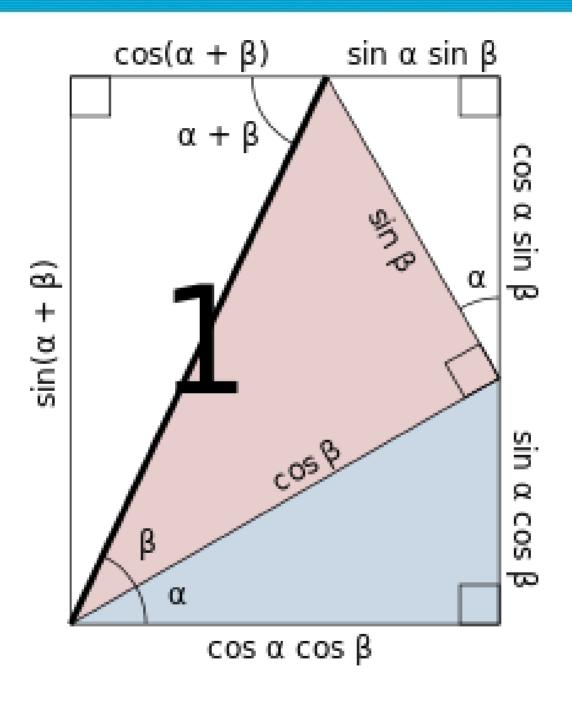


- ► Given a unit vector (x, y)
 - \rightarrow x = cos θ
 - y = sin θ
- Rotating it by α degrees around the origin means new point (x', y')
 - \rightarrow x' = cos $(\theta + \alpha)$
 - \rightarrow y' = sin $(\theta + \alpha)$



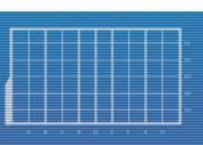






https://en.wikipedia.org/wiki/File:AngleAdditionDiagramSine.svg

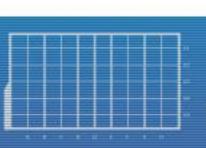






- ► Back to the new point (x', y')
- $x' = \cos \theta \cos \alpha \sin \theta \sin \alpha$
 - $= x \cos \alpha y \sin \alpha$
- y' = sin θ cos α + cos θ sin α
 - = $y \cos \alpha + x \sin \alpha$





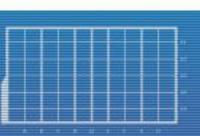


- ▶ But SFML uses screen coordinates
- ► Shouldn't we negate y?

$$-y = \sin O$$

$$-y' = \sin(O + M)$$



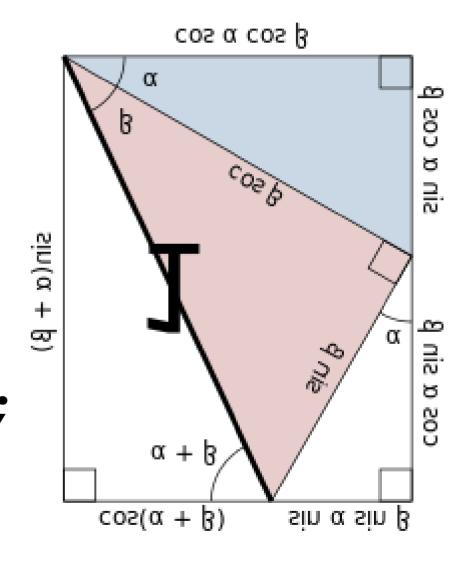


- ► Rotation in SFML is clockwise
- ► You shouldn't negate y!

$$-y = \sin O$$

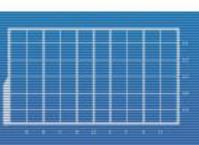
$$-y' = \sin (O + M)$$

aShape.rotate(deg);



https://en.wikipedia.org/wiki/File:AngleAdditionDiagramSine.svg



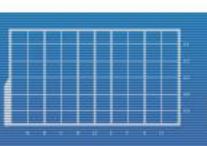




2-D Translation

- After applying rotation, you can now apply position
 - Which is just a simple addition operation



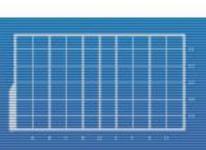




Edge Normal

- Assuming you defined your polygon in CCW order, an edge's normal is obtained by:
 - ► First getting the vector that points from one point to the next (the edge itself)
 - Then getting the vector that is CW perpendicular to it (the normal)



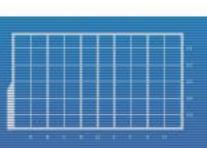




Edge Normal

- However, the SAT overlap test will still work even if the normal is facing the wrong way
 - ► Towards the inside of the polygon and not away from it







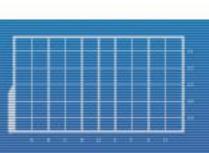
Projection

- Now you just need to project all the points of each polygon on the edge normal
 - ► The end result should be two line segments along the edge normal
- Check if they overlap
 - ▶ If they do, repeat the test for the next edge or conclude that the polygons overlap if all edges have already been tested
 - If they do not, the polygons do not overlap

Overlap

- ► How do you check if the line segments overlap?
 - ► Hint: Minimum definition of line segment simply requires 2 points
 - Hint#2: All points are being projected on the same normal
 - ► Hint#3: Check slide set #5







- Create a program that creates polygons based on text received via standard input
 - All input separated by whitespace characters
 - Input begins with a positive integer N indicating how many shapes to create
 - ► Input for N shapes follows
 - Note: The program does not check if the shapes are convex



- ► For each shape:
 - ► Input starts with a positive integer P indicating how many points the shape has
 - ▶ Input for P+1 points follows
- ► For each point:
 - ▶ Input consists of 2 numbers a point's local coordinates (x then y)
 - The last "point" is the shape's position (also x then y)



- ► There should be a button to toggle rotation on and off
 - ➤ Off at the start
 - When toggled on, each shape should rotate at a constant speed
 - But the speed for each shape should be different
- The first polygon should also be movable using the WASD keys

- ➤ Your program should render the convex polygons in one of three different colors:
 - First color if polygon is actually intersecting with another polygon
 - Second color if polygon's AABB is intersecting with another polygon's AABB but polygons themselves are not intersecting
 - ► Third color if polygons' AABBs do not



