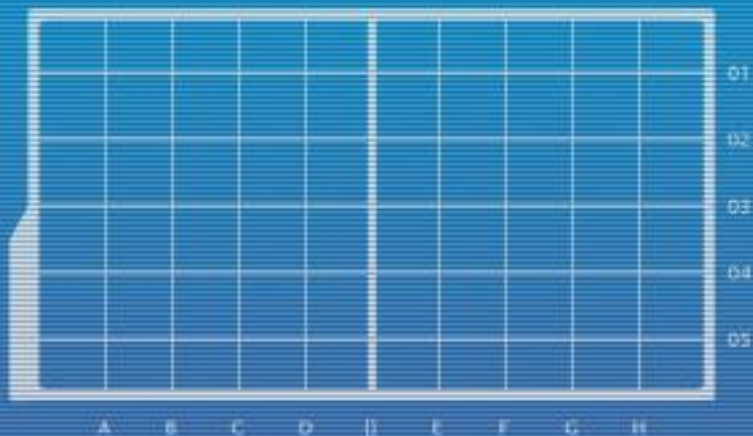




DEPARTMENT OF INFORMATION SYSTEMS AND COMPUTER SCIENCE



```
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```



Bounding Boxes

Axis-aligned and Oriented

Lecture Time!

- ▶ Collision Requirements: Bounding Volumes
- ▶ Bounding Boxes: Axis-Aligned and Oriented

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
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DISCS

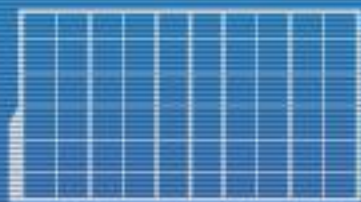
Circles Are Cool, But...

- ▶ What about other geometrical shapes?
- ▶ How do we check for collision?
 - ▶ What values do we need to store?
 - ▶ What are the conditions to check?
 - ▶ What if the two shapes being checked are different?
- ▶ What about collision responses?

Bounding Volumes

- ▶ Circle (sphere if 3D) → fastest test, lowest memory requirements
- ▶ AABB (axis-aligned bounding box)
- ▶ OBB (oriented bounding box)
- ▶ 8-DOP (eight-direction discrete orientation polytope)
- ▶ Convex hull → best bounding and culling

001010100101010001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
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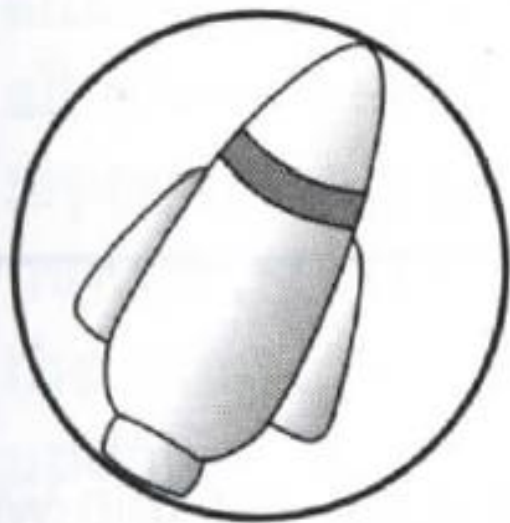


DISCS

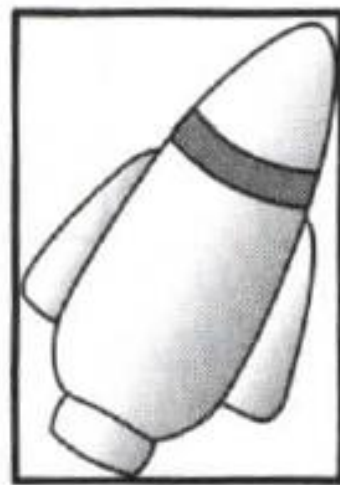
Bounding Volumes

→ **BETTER BOUND, BETTER CULLING**

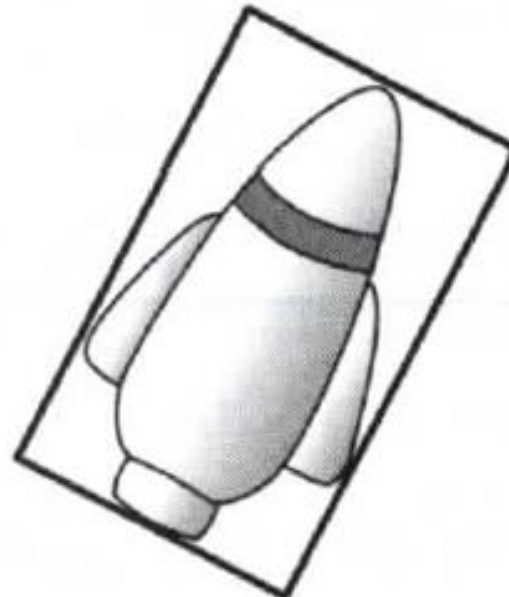
← **FASTER TEST, LESS MEMORY**



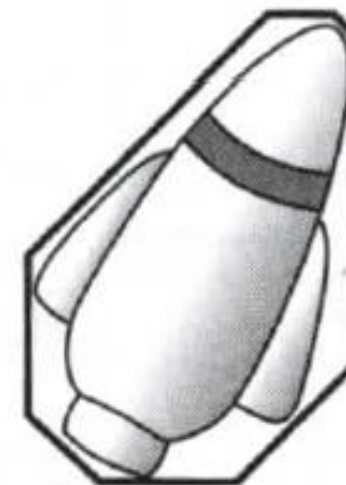
SPHERE



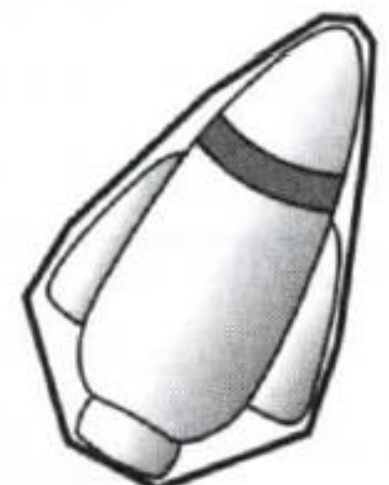
AABB



OBB



8-DOP



CONVEX HULL

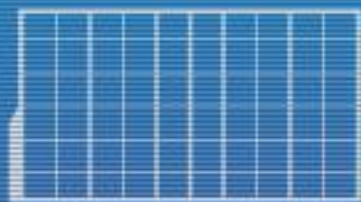
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10010100100001010100100101001010
100101001010100101001010010101



Bounding Volumes

- ▶ Can use bounding volume tests for several purposes:
 - ▶ For an "early out" or to allow collision test to exit early without needing to run the expensive/super-accurate geometric tests
 - ▶ Queries such as point inclusion, ray intersection with the volume, and intersection with planes and polygons

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
10010100101010010100101001010101



DISCS

Bounding Volumes

- ▶ Bounding volumes are typically computed in a preprocessing step instead of at runtime
- ▶ However, some BVs must be realigned at runtime when their contained objects move
 - ▶ Realigning the BV is usually cheaper than recomputing it from scratch

0010101001010100011110100001100
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11100001111010110000000111101001
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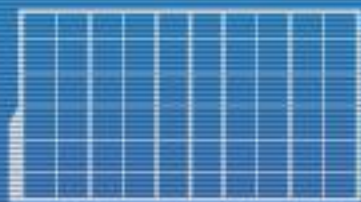


DISCS

Axis-Aligned Bounding Box

- ▶ Rectangular box with faces oriented such that its face normals are at all times parallel with the axes of a given coordinate system
 - ▶ Fast overlap check
 - ▶ Low storage requirements

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Axis-Aligned Bounding Box

- ▶ Three common representations of AABB:
 - ▶ Min-max
 - ▶ Min-widths
 - ▶ Center-radius

0010101001010100001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010010110
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Min-Max Representation

- For min-max, simply get the minimum and maximum coordinate values along each axis
 - In other words, the two opposing corner points



Min-Max Overlap

- ▶ Overlap test involves checking each coordinate axis for two AABB's a and b
 - ▶ If, for any axis, the minimum coordinate value of one is greater than the maximum coordinate of the other, then there is no intersection
 - ▶ Overlapping on all axes means there is an intersection

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
10010100101010010100101001010101



DISCS

Min-Max Exercise

- ▶ Check each pair of AABBs to see if they intersect:
 - ▶ Min: (0, 0) ; Max: (8, 8)
 - ▶ Min: (4, -1) ; Max: (5, 2)
 - ▶ Min: (-3, 3) ; Max: (1, 5)

0010101001010100011110100001100
10001100100001111001101010010101
110010101010101000010011001010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
100101001010100101001010010101



Min-Width Representation

- For min-width, get the minimum corner point and the dimensions of the box



Min-Width Overlap

- ▶ Overlap test involves checking each coordinate axis for two AABB's a and b
- ▶ For each axis, solve for difference of minimum coordinate values (the next slide assumes computation is $a.\text{min}[\text{axis}] - b.\text{min}[\text{axis}]$)

001010100101010000111100101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
00100101010010100100101001001010110
10010100100001010100100101001010
1001010010101001010010100101010101



Min-Width Overlap

- ▶ If the difference is greater than the corresponding dimension of b , then there is no intersection
- ▶ If the negative of the difference is greater than the corresponding dimension of a , then there is no intersection
- ▶ Computed for all axes but no early out?
Then there is an intersection

00101010010101000111100101010010101
10001100100001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
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10010100101010010100101001010101



DISCS

Min-Width Exercise

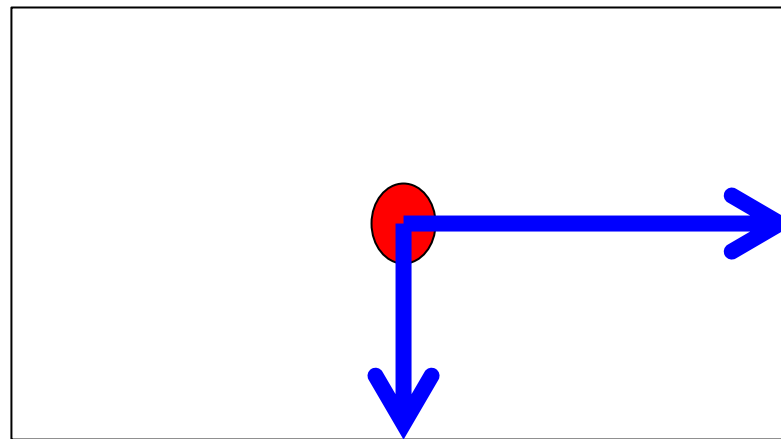
- ▶ Check each pair of AABBs to see if they intersect:
 - ▶ Min: (0, 0) ; Dimensions: (8, 8)
 - ▶ Min: (4, -1) ; Dimensions: (1, 3)
 - ▶ Min: (-3, 3) ; Dimensions: (4, 2)

0010101001010100001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
100101001010100101001010010101



Center-Radius Representation

- For center-radius, get the center point and half the dimensions of the box



Center-Radius Overlap

- ▶ Overlap test involves checking each coordinate axis for two AABB's a and b
- ▶ For each axis, solve for absolute value of difference of center coordinate values (the next slide assumes computation is $\text{abs}(a.c[\text{axis}] - b.c[\text{axis}])$)

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



Center-Radius Overlap

- ▶ If this value is greater than the sum of the corresponding half-dimensions of the boxes, then there is no intersection
- ▶ Computed for all axes but no early out?
Then there is an intersection

0010101001010100001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
00100101010010100100101001001010110
1001010010001010100100101001010
1001010010101001010010101010101



Center-Radius Exercise

- ▶ Check each pair of AABBs to see if they intersect:
 - ▶ Center: (4, 4) ; Radii: (4, 4)
 - ▶ Center: (4.5, 0.5) ; Radii: (0.5, 1.5)
 - ▶ Center: (-1, 4) ; Radii: (2, 1)

0010101001010100011110100001100
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
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100101001010100101001010010101



DISCS

Computing AABBs

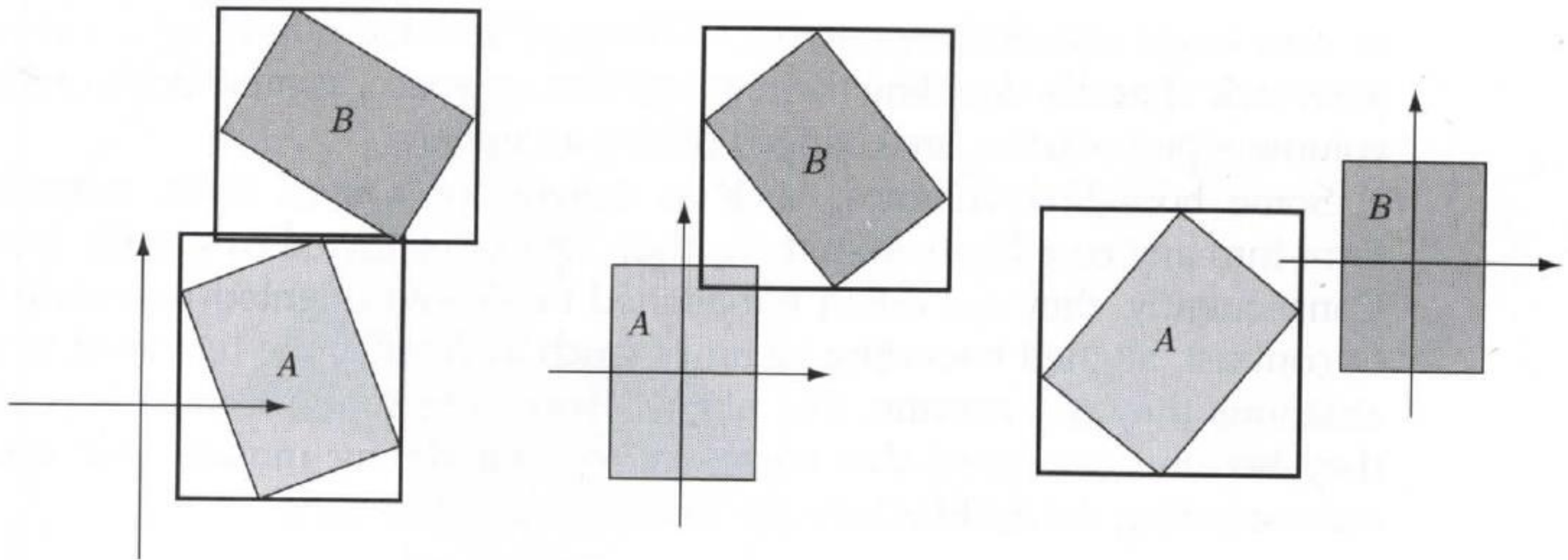
- ▶ Both BVs must use the same coordinate system
 - ▶ Transform both BVs into world space (better if high number of overlap checks)
 - ▶ Transform one BV into the local space of the other (half the work and usually a tighter BV result)

001010100101010001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
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100101001010100101001010010101



DISCS

Computing AABBs



00101010010101000011110010000100
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110010101010100001001100101010100
1001010010010010101010101010101
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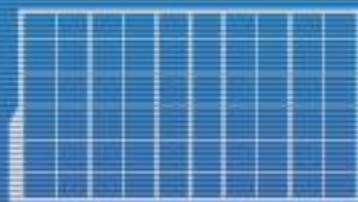


DISCS

Computing AABBs

- ▶ If the containing object rotates, the AABBB must be recomputed
- ▶ Here are two of several strategies that can be used:
 - ▶ Computing a tight dynamic reconstruction from the original point set
 - ▶ Computing an approximate dynamic reconstruction from the rotated AABBB

0010101001010100011110100001100
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1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
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100101001010100101001010010101



From Original Point Set

- ▶ Simply create another AABB that contains the object in its current orientation
 - ▶ Find minimum and maximum coordinate values along all axes
 - ▶ Will make more sense when we get to polygons

0010101001010100011110100001100
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11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



From Rotated AABB

- ▶ Same as above, but use the original AABB with the given rotation
 - ▶ The original AABB must be used, otherwise this strategy will result in an object's AABB growing indefinitely

0010101001010100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010010110
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Recitation

- ▶ Assuming no rotation applied yet:
 - ▶ What is the AABB of a square?
 - ▶ What is the AABB of a rectangle?

00110101001010100001111001101010010101
10001100100001111001101010010101
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100101001001001010101010101010101
11100001111010110000000111101001
0010010101001010010010100100101010
10010100100001010100100101001010
100101001010101001010010101010101



DISCS

Recitation

- ▶ What is the AABB of a circle?
- ▶ What happens to the AABB when the circle rotates?
 - ▶ Do you have to recompute the AABB?

0010101001010100001111001101010010101
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100101001001001010101010101010101
11100001111010110000000111101001
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DISCS

Exercises

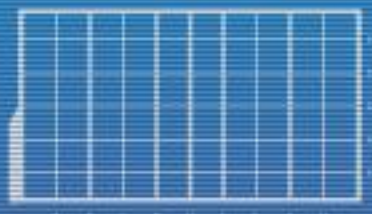
- ▶ Create a program that renders 2 rectangles that rotate at different speeds
- ▶ In addition, render each rectangle's AABB
- ▶ Allow input to move the two rectangles and change their colors to indicate whether or not their AABBs are overlapping



Exercises

- ▶ Add a circle and render its AABB
- ▶ Change the color of any shape when its AABB intersects another shape's AABB

```
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11001010101010100001001100101010100  
100101001001001010101010101010101  
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00100101010010100100101001001010110  
10010100100001010100100101001010  
10010100101010010100101001010101
```



DISCS

Oriented Bounding Box

- ▶ An OBB is like an AABB but has an arbitrary orientation
- ▶ Testing for overlap between two OBBs does NOT require both of them to use the same coordinate system
 - ▶ That would be just AABB all over again

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1001010010010010101010101010101
111000011101011000000011101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Computing OBBs

- ▶ OBB representation needs:
 - ▶ OBB's center point
 - ▶ Local axes
 - ▶ Halfwidth extents of OBB along each axis
 - ▶ In other words, half the dimensions of the OBB

001010100101010000111100100001100
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10010100101010010100101010010101



DISCS

Computing OBBs

- ▶ Can construct an AABB for each OBB and use AABB intersection test
 - ▶ Not really much of a point except as a cheap early out
- ▶ Can use the separating axis test
 - ▶ To be covered when we get to polygons
 - ▶ Up next: Polygons

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1001010010010010101010101010101
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10010100100001010100100101001010
10010100101010010100101001010101



Homework

- ▶ Create a program that displays 5 RectangleShapes that have the same color but are of different dimensions and not initially overlapping
- ▶ Then, give each of these shapes a different speed of rotation
- ▶ Render each shape's AABB as it rotates
- ▶ Shapes with AABBs that are intersecting should be displayed with a different color

