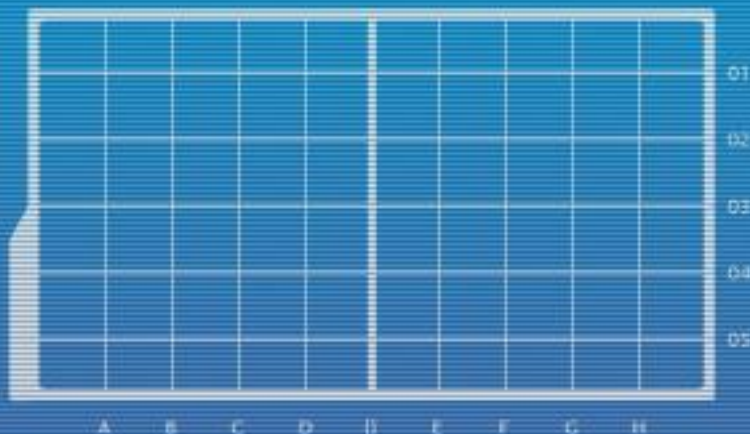




DEPARTMENT OF INFORMATION SYSTEMS AND COMPUTER SCIENCE



```
001011100100011110111100100110101110100100101  
11010101101010100001010101010010101010101010  
10100101001001001010101010101010101010101010  
11100001111010110000000111101010101010000010101  
11101010111100101000100101111010100010100100111010  
101010010100100100100001010101101010101010100101111  
00101010010101001010100000001010101001111101000011001  
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001001010100101001001010010001010101010101001010010  
10010100100001010100100101010010100101010010010  
10010100101010101010101010101010101010101001001001  
10010100101010101010101010101010101010101010101010
```



Quadtrees

Hierarchy + Collision Checking

Lecture Time!

- ▶ Size: Matters
- ▶ Quadtrees: Multiple Layers of Uniform Grids?
- ▶ Implementation: Lists Again?

```
0010101001010100001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010010110
1001010010001010100100101001010
100101001010100101001010010101
```



DISCS

Size Does Matter

- ▶ Uniform grids can still work for games with objects of varying sizes
 - ▶ They just don't work that well



Space Patrol Luluco, episode 5

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
10010100101010010100101001010101



Size Does Matter

- ▶ Logic dictates that larger objects run a higher risk of colliding with other objects
 - ▶ Large objects occupy more cells in in a uniform grid

0010101001010100001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
00100101010010100100101001001001010
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Size Does Matter

- ▶ Logic also dictates that small objects are less likely to be colliding with other small objects but they are more likely to collide with larger objects anyway
 - ▶ Small objects occupy fewer cells, possibly those also occupied also by large objects

0010101001010100011110010010010101
1000110010001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



Back to Uniform Grid

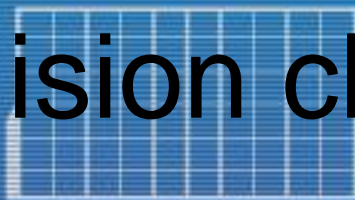
- ▶ Assume only one cell to cover the entire game world
 - ▶ In other words, ye olde brute force pairwise collision checking
 - ▶ We will call it grid A
- ▶ Assume another uniform grid, this time with 4 cells
 - ▶ We will call it grid B

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



Back to Uniform Grid

- ▶ Assume that objects can only:
 - ▶ Occupy only a single cell in grid B (it's relatively small) or
 - ▶ Occupy the single cell in grid A (it's relatively large... or poorly placed)
- ▶ Assume both grids A and B are active
 - ▶ For an object in each case above, what condition/s must another object satisfy in order to be considered for pairwise collision checking with that object?



Back to Uniform Grid

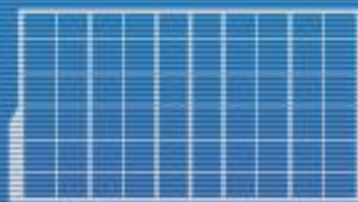
- ▶ Let's go further and assume another uniform grid with 16 cells
 - ▶ We will call it grid C
- ▶ An object can only occupy a single cell in only one of the three grids
- ▶ Assume grid C is now also active
 - ▶ How should we handle collision checking?



Quadrees

- ▶ The quadtree is a tree-based, axis-aligned hierarchical spatial partitioning method of an area of 2D world space
- ▶ As the name suggests, each parent node in the quadtree has four children
- ▶ The root node is generally the smallest axis-aligned square that covers the entire game world

```
00101010010101000011110010010001000
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
10010100101010010100101001010101
```



Quadrees

- ▶ The area occupied by the root node is subdivided into four smaller equal-size squares (aka cells or quads)
- ▶ These four smaller areas are the child nodes of the root node
- ▶ These child nodes are also subdivided in the same way, and so on
 - ▶ Typically stops when the tree reaches a maximum depth or when the squares become smaller than a certain size

0010101001010001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
1110000111101011000000011110000
0010010101001010010010010101010101
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1001010010101010101010101010101010



DISCS

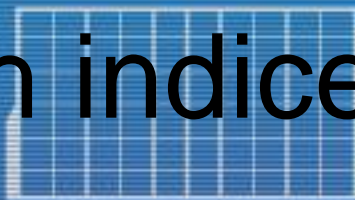
Quadrees

- ▶ A node in a quadtree usually contains the following information (or there should be an easy way to derive this information):
 - ▶ Center (center point of the AABB representing the node)
 - ▶ Half-width (or "radius" of the AABB)
 - ▶ Pointers to its 4 children nodes and to its parent node
 - ▶ List of objects in this node (same as a cell in uniform grid)



Quadrees

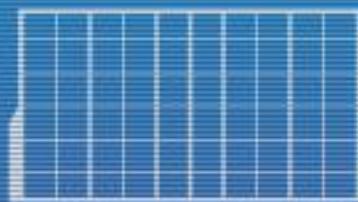
- ▶ Remember that there are many ways to implement a tree
- ▶ Since we know that each node in a quadtree has exactly 4 children (or 0 if the node is at a certain depth), you can also use an array-based implementation for the quadtree
 - ▶ This removes the need for pointers to children nodes but requires you to work with indices instead



Quadrees

- ▶ An object can only be placed in a node that covers them completely
 - ▶ If an object is larger than a particular node or it is overlapping that node's edge, that object should not be placed in that node's list
 - ▶ It is possible for a very small object to be placed in the root node if that object is situated in or near the center of the world

0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
10010100101010010100101010010101



Example

- ▶ Assume a quadtree of depth 3 (like our theoretical example earlier with grids A, B, and C)
- ▶ World size is 320x240
 - ▶ Size of root node? (Note: Square shape preferred)
 - ▶ Size and number of cells in second layer?
 - ▶ Size and number of cells in third layer?

001010100101010001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
10010100101010010100101010010101

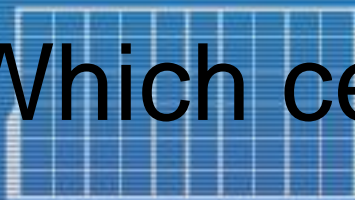


DISCS

Example

- ▶ Note: Changing world size to 320x320 to keep things simple; assume (0, 0) is upper-left corner of world
 - ▶ Object #1 is a rectangle of size (30, 20) and its center is located in (120, 130)
 - ▶ Object #2 is a rectangle of size (240, 100) and its center is located in (159, 160)
 - ▶ Object #3 is a rectangle of size (60, 20) and its center is located in (70, 40)

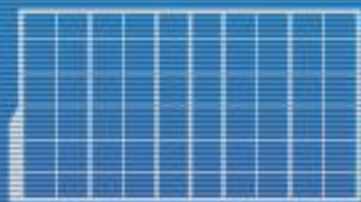
▶ Which cell should each object be placed?



Creating the Quadtree

- ▶ While it is possible to dynamically create quadtree nodes whenever they are needed, let us assume an easier static implementation
- ▶ Quadtree creation can be done using a recursive function
 - ▶ Start by defining the root node

```
001010100101010001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101
```



DISCS

Creating the Quadtree

- ▶ Root node parameters:
 - ▶ Center is the center of the screen
 - ▶ Half-width is half the screen width or height, whichever is greater
 - ▶ Pointers to parent and child nodes may be necessary except in an array-based implementation
 - ▶ List is initially empty (obviously)

```
0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
10010100101010010100101001010101
```



Creating the Quadtree

- ▶ Each child node's parameters:
 - ▶ Center is \pm half of the root's half-width to root's center's x and y
 - ▶ Ex. $+$ to x and $-$ to y to get the upper-right quad
 - ▶ Half-width is half of the root's half-width
 - ▶ Solved for that already; see above

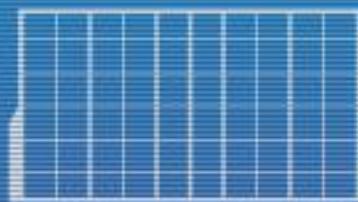
0010101001010100001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
0010010101001010010010100100100110
1001010010001010100100101001010
100101001010100101001010010101



Creating the Quadtree

- ▶ Each child node is another quadtree with different parameters for its "root"
 - ▶ Center and half-width already defined (see previous slide)
 - ▶ Pointers to parent and child nodes may be necessary except in an array-based implementation
 - ▶ List is initially empty (obviously)

```
0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
10010100101010010100101001010101
```



Creating the Quadtree

- ▶ You may then pretend that a node is the root for its own children
 - ▶ Refer to the previous 2 slides
- ▶ But you have to stop somewhere eventually
 - ▶ Limit depth to 8 (6 for octrees used in 3D)

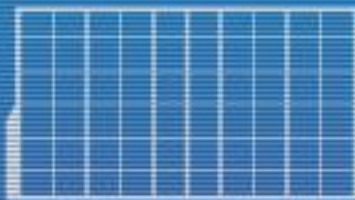
0010101001010100011110100001100
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



Updating the Quadtree

- ▶ Given an object, where should it be placed in the quadtree?
- ▶ Updating the quadtree lists can also be done recursively
 - ▶ Start by setting the root node as the "current" node

0010101001010100001111001001001001
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101

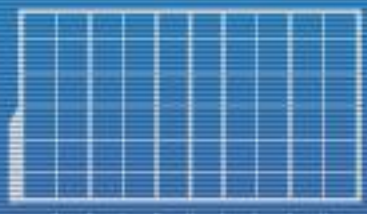


DISCS

Updating the Quadtree

- ▶ At the current node, check if the object can be contained completely in one of its child nodes
 - ▶ How?
 - ▶ Assume that all objects can be contained completely in the root node

00101010010101000011110100001100
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Updating the Quadtree

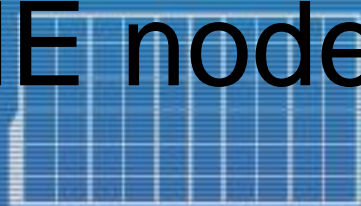
- ▶ If it cannot be contained in any of the child nodes OR you are already at one of the leaf nodes, add it to the list of the current node
 - ▶ The leaf check should be done first :P
- ▶ If it can AND you are NOT at one of the leaf nodes, set that child as the "current" node and repeat the process
 - ▶ Refer to the previous slide



Updating the Quadtree

- ▶ An object should also contain a pointer to or the index of the quadtree node it occupies
 - ▶ This allows you to:
 - ▶ Easily remove the object from its quadtree node list if it has to change nodes and
 - ▶ Skip adding the object to a list that it is already in
 - ▶ Remember: An object should only occupy

ONE node

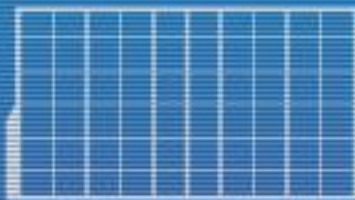


DISCS

Collision Checking

- ▶ For each object, collision checking involves traversing the quadtree either towards the root (easier) or towards the leaves:
 - ▶ Start by setting the node occupied by the object to be the "current" node
 - ▶ Do a pairwise collision check with each object in the list of the current node

0010101001010100011110100001100
10001100100001111001101010010101
110010101010101000010011001010100
1001010010010010101010101010101
11100001111010110000000111101001
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1001010010001010100100101001010
100101001010100101001010010101

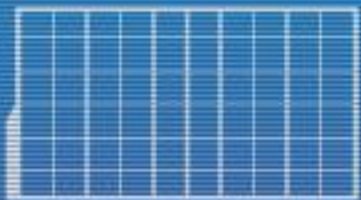


DISCS

Collision Checking

- ▶ For each object, collision checking involves traversing the quadtree... (continued):
 - ▶ Assuming traversal towards the root, set the parent node as the "current" node and go back to the previous step
 - ▶ Stop if you're at the root node already

001010100101010001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
00100101010010100100101001001010110
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Collision Checking

- While the quadtree helps immensely, there are still redundant/useless collision checks that you should NOT perform



Bananya, episode 10

00101010010101000111100101010010101
10001100100001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
100101001010100101001010010101



DISCS

Collision Checking

- ▶ Given an object, when going through the list in the node that the object itself occupies:
 - ▶ That object should NOT check for collision with itself
 - ▶ That object should also NOT check for collision with other objects located in an "earlier" address or index in the overall list of objects

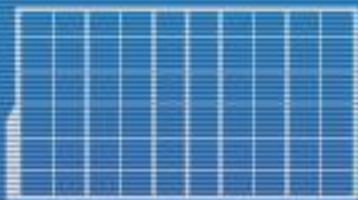
0010101001010100011110100001100
10001100100001111001101010010101
110010101010100001001100101010100
1001010010010010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
10010100100001010100100101001010
1001010010101001010010101010101



Homework

- ▶ Create a program that can simulate a LOT of "air hockey pucks" (1000+)
 - ▶ Circle information will be obtained via standard input
 - ▶ First line contains number of circles N
 - ▶ Each of the next N lines contains the circle's x-coordinate, y-coordinate, and radius (in that order)

```
001010100101010001111001101010010101
10001100100001111001101010010101
11001010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101
```

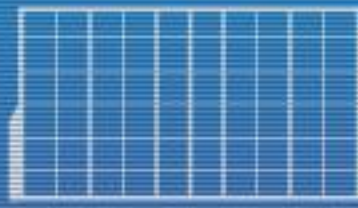


DISCS

Homework

- ▶ It's pretty much the physics collision homework on steroids
 - ▶ Each circle should have a mass equal to its area (radius * radius * pi)
 - ▶ Hint: You should also store the reciprocal of the mass of each circle for easy access (the mass itself is usually not stored)
 - ▶ Friction toggle is OPTIONAL

001010100101010001111001101010010101
110010101010100001001100101010100
100101001001001010101010101010101
11100001111010110000000111101001
001001010100101001001010010010110
1001010010001010100100101001010
100101001010100101001010010101



DISCS

Homework

- ▶ All circles should be the same color
- ▶ A circle can be selected by left-clicking it
 - ▶ The selected circle should have a different color
 - ▶ This will also deselect any previously selected circle
- ▶ The selected circle can be accelerated using keyboard input
 - ▶ By holding down WASD or directional keys



Homework

- ▶ Note that you may have to perform other optimizations
 - ▶ Reduce number of arithmetic operations per frame
- ▶ If you notice circles "melding" into each other, it is highly likely that there is something wrong with the way you handle quadtree traversal
 - ▶ Double-check using brute force

