

onnectors		STM32F103C8T6
	Power Regulation	
	File: power_regulation.kicad_sch	
le: connectors.kicad_sch		File: STM32F103C8T6.kicad_sch

Author: Shirley Lam
Author: Kurtis Dinelle
OSU DAM Robotics
Sheet: /
File: stm32-can-do.kicad_sch

 Title:
 STM32
 CAN-Do!

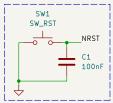
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 Date:
 2024-11-02

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 Date: 2024-11-02
 Rev: v0.1

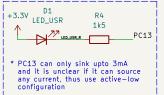
 KiCad E.D.A. 8.0.6
 Id: 1/4

STM32 Microcontroller & Supporting Circuitry

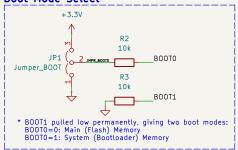
Reset Button



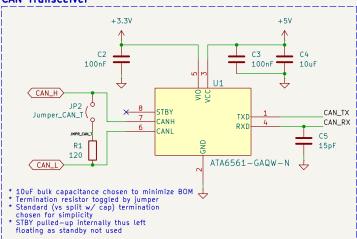
User LED



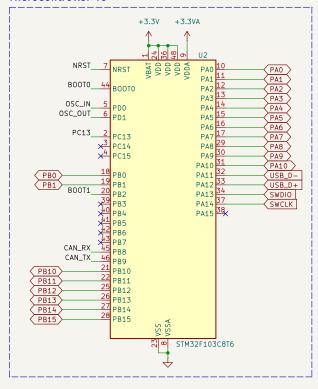
Boot Mode Select



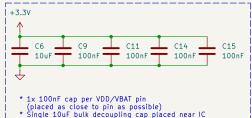
CAN Transceiver



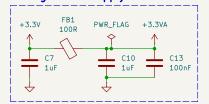
Microcontroller IC



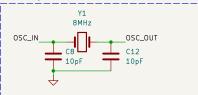
Power Supply



Analog Power Supply



HSE Crystal



* The calculation for these external load capacitors is supposed to follow a rough formula of:

 $C_{ext1} = C_{ext2} = 2(C_{load} - C_{stray})$

Where C_load is model dependent (found in datasheet) and C_stray depends on several factors which are really hard to calculate...

A typical rule of thumb is to assume 3–5pF for C_stray, and using a crystal with 8pF C_load, that gives us roughly 6–10pF for C_ext. This crystal is used with Nucleo boards which uses 10pF C_ext, so go with that.

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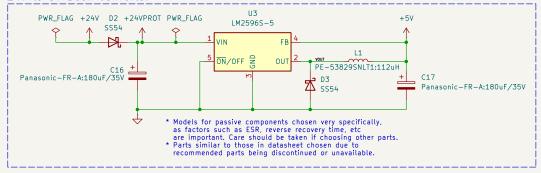
Title: STM32 Microcontroller

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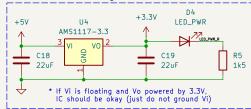
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Power Regulation

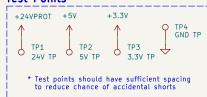
24V to 5V Buck Converter



5V to 3.3V LDO Regulator



Test Points



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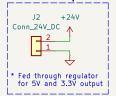
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 Size: A4
 Date: 2024-11-03
 Rev: v0.1

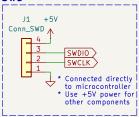
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 Id: 3/4

Connectors & Header Pins

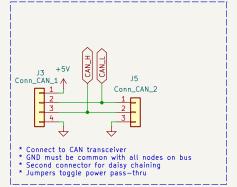
+24V DC Input



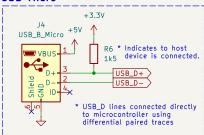
SWD



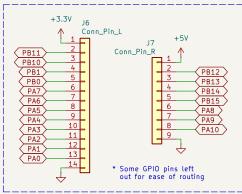
CAN Bus



USB Micro



Pin Breakout



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