

PFSS

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# Chapter 1

## Main Page

This PFSS computation suite computes the PFSS solution using photospheric magnetograms from MDI, HMI, G $\leftrightarrow$ ONG, and WSO. It can also create maps of the magnetic configuration and the expansion factor at arbitrary heights between photosphere and source surface. Commands are given via command line arguments to the PFSS suite. For an example how to use the command-line interface see below. Several solar observatories are supported and automatically recognized for supplying the photospheric magnetogram.

### 1.1 Building the documentation (optional)

A PDF containing the documentation of this program is included in the GIT repository. The documentation is implemented via doxygen. In order to obtain the most current documentation, you first need to install doxygen

```
apt install doxygen
```

and then build the documentation:

```
cd pfss
make documentation
```

The documentation will then be produced both as HTML and PDF in the directory PFSS/doc.

### 1.2 Optimizations (optional)

Several optimizations can be adjusted in the Makefile. If a CUDA-capable device is present, setting the variable CUDA to '1' will build the program to employ the CUDA device, which might decrease computation time substantially. For this optimization the CUDA runtime environment needs to be installed (please consult NVIDIA's webpage for instructions).

The variable NUMTHREADS limits the number of threads to be utilized for multithreaded execution of the program. For optimal performance it should be the same number as CPU cores in the system.

Default parameters for the computation can also be set in the Makefile. The corresponding build variables start with DEFAULT\_.

## 1.3 Building the binary

This program utilizes several third-party libraries which need to be installed in order for the binary to be built. These libraries are very common so there is a good chance that they can be found in your distributions repositories. If you are on a debian system, try installing them via

```
apt install libfreeimage-dev libcfitsio-dev libboost-dev libboost-filesystem-dev libboost-regex-dev
```

If successful the PFSS computation suite can be built via

```
cd pfss
make
```

The binary will be placed in pfss/bin.

## 1.4 Running the program

If you used make to build the PFSS computation suite, the binary file will be stored in pfss/bin/.

### 1.4.1 Configuration and model output files

Upon execution the binary reads a configuration file, which specifies the data and configuration directories. The configuration directory contains information about start and stop times of Carrington rotations. The data directory contains all the output from the PFSS computation suite. If you run the binary from the pfss/bin/ directory without specifying a configuration file, the default file pfss/config/config will be used. The default data directory is then pfss/data. Please consult this default config file to set your own data directory at a location with enough disk space if the default location is not suitable. Absolute paths in your config file allows the binary to be executed from arbitrary shell locations. Manipulation of the configuration file is only necessary if you have special needs for the location of the computed solutions.

### 1.4.2 Command line options and arguments

The syntax to run the PFSS computation suite is

```
pfss --option0 [argument0] --option1 [argument1] ...
```

The following options and arguments are supported. Default values for not specified options can be adjusted in the Makefile.

-- **config** *filename*

*filename* is path to configuration file [default: --config ../config/config]

-- **compute** *filename*

Invokes the PFSS solver for given photospheric magnetogram at path *filename*. For additional arguments see below.

-- **map** *filename*

Computes the magnetic configuration at specified height [default: photosphere and source surface]. *filename* points to the configuration file of the computed solution (ending in *\*config.cfg*). For additional options see below.

-- **batchcompute** *directory*

Invokes the PFSS solver for all magnetic magnetograms found in *directory* (non-recursive).

-- **batchmap**

Invokes mapper for all solutions computed in data directory.

#### Additional options for compute

-- **rss** *value* source surface height (multiples of solar radius), *value* is floating point  
 -- **ell** *value* ellipticity of source surface, *value* is floating point, [default: 1.0 (spheric)]  
 -- **resCompR** *value* computational grid resolution in radial direction, other directions are determined automatically, *value* is unsigned integer  
 -- **method** *value* solution method to be used for PFSS computation. *value* is either 'shc' for the classic spherical harmonic coefficient approach or 'numeric' for the finite difference solver  
 -- **order** *value* maximum principal order to be used with the SHC approach, *value* is unsigned integer

#### Additional options for map

-- **resMapTheta** *value* resolution of mapping in meridional direction, *value* is unsigned integer  
 -- **resMapPhi** *value* resolution of mapping in zonal direction, *value* is unsigned integer  
 -- **height** *value* height between phot. and source surface to be mapped, *value* is multiple of solar radius

## 1.5 Supported photospheric magnetograms

The following photospheric synoptic magnetogram sources are supported. The PFSS computation suite identifies the source instrument and necessary pre-processing steps by filename, meaning you cannot alter them or the program will not be able to handle the containing data.

observatory name	filename example	resolution	URL
WSO	WSO.2066.F.txt	72 x 30	<a href="http://wso.stanford.edu/synoptic1.html">http://wso.stanford.edu/synoptic1.html</a>
SOHO-MDI	synop_MI_0.2066.fits	3600 x 1080	<a href="http://sun.stanford.edu/synop/">http://sun.stanford.edu/synop/</a>
SDO-HMI	hmi.Synoptic_MI.2100.fits	3600 x 1440	<a href="http://hmi.stanford.edu/data/synoptic.html">http://hmi.stanford.edu/data/synoptic.html</a>
NSO-GONG	mrmqs080208t0128c2066_000.↵ fits	360 x 180	<a href="https://gong.nso.edu/data/magmap/crmap.↵html">https://gong.nso.edu/data/magmap/crmap.↵html</a>

## 1.6 Example use cases

All examples are executed from the pfss/bin-directory, so change there:

```
cd pfss/bin
```

To perform a PFSS model evaluation with default parameters for the synoptic photospheric magnetogram found at `pfss/data/input/synop_Ml_0.2066.fits` (not included in the repository, you need to download the magnetogram and place it at that location):

```
./pfss --compute ../data/input/synop_Ml_0.2066.fits
```

To generate magnetic mappings at the photosphere and source surface of the computed solution in the previous example:

```
./pfss --map ../data/2066/2066_MDI_Kiel_PFSS2.50_GridSph_35x87x175_config.cfg
```

To generate a magnetic mappings of the same solution at height  $r=2.4 r_{\text{sol}}$  with a resolution of 130 x 200 pixels:

```
./pfss --map ../data/2066/2066_MDI_Kiel_PFSS2.50_GridSph_35x87x175_config.cfg --height 2.4 \
--resMapTheta 130 --resMapPhi 200
```

To evaluate the PFSS model for all photospheric magnetic maps found in directory `pfss/data/batchinput` with a radial grid resolution of 40 grid points and a source surface radius of  $r=3.1 r_{\text{sol}}$ :

```
./pfss --batchcompute ../data/input/ --resCompR 40 --rss 3.1
```

## Chapter 2

# Hierarchical Index

### 2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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## Chapter 3

# Class Index

### 3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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## Chapter 4

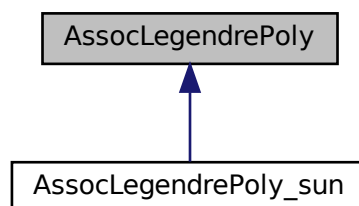
# Class Documentation

### 4.1 AssocLegendrePoly Class Reference

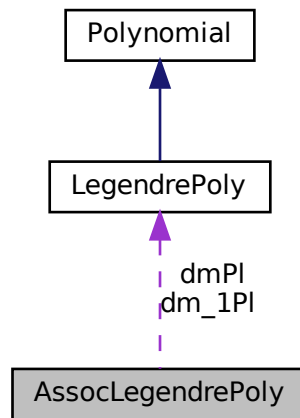
conventional associated Legendre polynomials (as described by, e.g., Wikipedia)

```
#include <hcFunction.h>
```

Inheritance diagram for AssocLegendrePoly:



Collaboration diagram for AssocLegendrePoly:



## Public Member Functions

- [AssocLegendrePoly](#) (uint l=0, uint m=0)  
*std constructor*
- [AssocLegendrePoly](#) (const [AssocLegendrePoly](#) &other)  
*cpy constructor*
- virtual [~AssocLegendrePoly](#) ()  
*destructor*
- [AssocLegendrePoly](#) & [operator=](#) (const [AssocLegendrePoly](#) &other)  
*assignment op*
- virtual hcFloat [operator\(\)](#) (hcFloat x)  
*evaluator*
- void **initNULL** ()
- void **clear** ()
- void **init** (uint l, uint m)
- virtual hcFloat [getDeriv](#) (hcFloat theta)  
*returns first derivative at cos(theta)*
- void **dump** ()

## Public Attributes

- uint **l**
- uint **m**
- [LegendrePoly](#) **dmPI**

*m*'th derivative of the Legendre polynomial

- [LegendrePoly dm\\_1PI](#)

*the (m+1)st derivative of the Legendre polynomial (necessary for theta component)*

### 4.1.1 Detailed Description

conventional associated Legendre polynomials (as described by, e.g., Wikipedia)

The documentation for this class was generated from the following files:

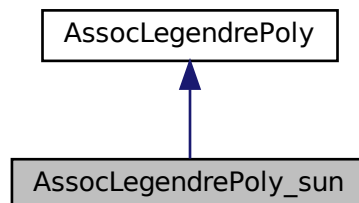
- engine/math/hcFunction.h
- engine/math/hcFunction.cpp

## 4.2 AssocLegendrePoly\_sun Class Reference

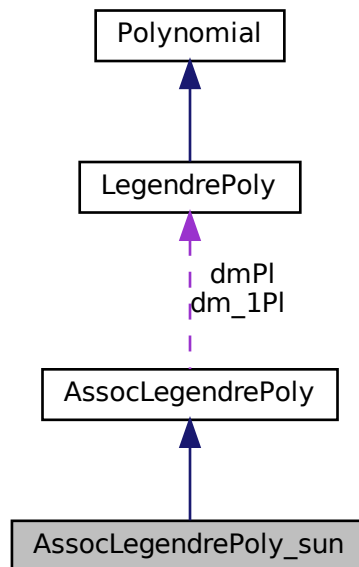
associated Legendre polynomial as used by Xudong Sun for WSO data

```
#include <hcFunction.h>
```

Inheritance diagram for AssocLegendrePoly\_sun:



Collaboration diagram for AssocLegendrePoly\_sun:



## Public Member Functions

- [AssocLegendrePoly\\_sun](#) (uint l=0, uint m=0)  
*std constructor*
- [AssocLegendrePoly\\_sun](#) (const [AssocLegendrePoly\\_sun](#) &other)  
*cpy constructor*
- virtual [~AssocLegendrePoly\\_sun](#) ()  
*destructor*
- [AssocLegendrePoly\\_sun](#) & [operator=](#) (const [AssocLegendrePoly\\_sun](#) &other)  
*assignment operator*
- virtual hcFloat [operator\(\)](#) (hcFloat x)  
*evaluator*
- virtual hcFloat [getDeriv](#) (hcFloat theta)  
*returns first derivative at cos(theta)*

## Additional Inherited Members

### 4.2.1 Detailed Description

associated Legendre polynomial as used by Xudong Sun for WSO data

The documentation for this class was generated from the following files:

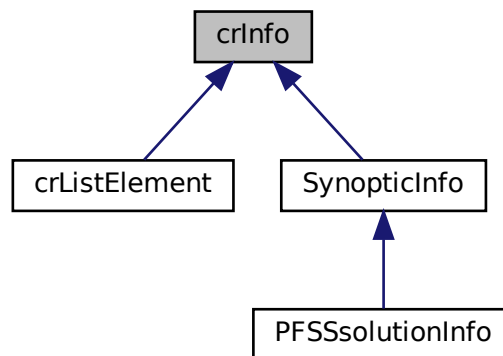
- engine/math/hcFunction.h
- engine/math/hcFunction.cpp

## 4.3 crInfo Class Reference

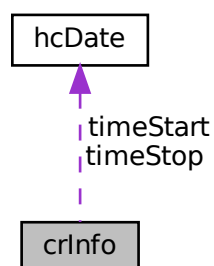
information on specific Carrington rotation

```
#include <carRotInfo.h>
```

Inheritance diagram for crInfo:



Collaboration diagram for crInfo:



## Public Member Functions

- [crInfo](#) (uint crNum=0)  
*std constructor*
- [crInfo](#) (const [crInfo](#) &other)  
*cpy constructor*
- virtual [~crInfo](#) ()  
*destructor*
- [crInfo](#) & [operator=](#) (const [crInfo](#) &other)  
*assignment operator*
- bool [operator==](#) (const [crInfo](#) &other)  
*comparison operator*
- bool [operator>](#) (const [crInfo](#) &other)  
*comparison operator*
- bool [operator<](#) (const [crInfo](#) &other)  
*comparison operator*
- bool [operator>=](#) (const [crInfo](#) &other)  
*comparison operator*
- bool [operator<=](#) (const [crInfo](#) &other)  
*comparison operator*
- bool **exportBinary** (std::ofstream &stream)
- bool **importBinary** (std::ifstream &stream)
- void **initNULL** ()
- void **clear** ()
- void **init** (uint [CRnum](#))
- void [dump](#) (uint indent=0) const  
*dumps information on this instance to stdout with optional indendttation*

## Public Attributes

- uint [CRnum](#)  
*number of Carrington Rotation*
- [hcDate](#) timeStart  
*start date of Carrington Rotation*
- [hcDate](#) timeStop  
*stop date of Carrington Rotation*

### 4.3.1 Detailed Description

information on specific Carrington rotation

The documentation for this class was generated from the following files:

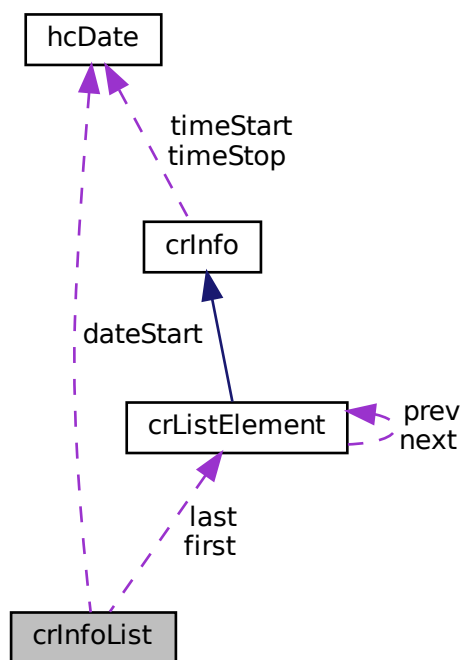
- src/carRotInfo.h
- src/carRotInfo.cpp

## 4.4 crInfoList Class Reference

list of carrington rotation numbers and corresponding start times

```
#include <carRotInfo.h>
```

Collaboration diagram for crInfoList:



### Public Member Functions

- **crInfoList** (const [crInfoList](#) &other)
- [crInfoList](#) & **operator=** (const [crInfoList](#) &other)
- void **clear** ()
- void **initNULL** ()
- void **init** ()

- `crListElement * getListElement (uint carRotNum)`  
*returns the list element representing the specified carRotNum or NULL, if non-existent*
- `bool appendObservation (uint carRotNum, originID origin, int pos)`
- `void dump () const`  
*dumps information on this instance to stdout with optional indendtation*

## Static Public Member Functions

- `static bool initStaticMembers ()`
- `static void clearStaticMembers ()`
- `static hcDate getStartDate (int carRotNum)`  
*computes start date of specific Carrington rotation*
- `static hcDate getStopDate (int carRotNum)`  
*computes stop date of specific Carrington rotation*
- `static int getCRnumber (const hcDate &date)`  
*computes the Carrington rotation number of a specific date*

## Public Attributes

- `crListElement * first`  
*first element in list*
- `crListElement * last`  
*last element in list*

## Static Public Attributes

- `static uint numCRinList = 0`  
*number of carrington rotations stored in list*
- `static int * listCRNum = NULL`  
*list of carrington rotation numbers*
- `static long int * listJulianDayNum = NULL`  
*list of corresponding start times (JD integer part)*
- `static double * listJulianDayFrac = NULL`  
*list of corresponding start times (JD fractional part)*
- `static hcDate * dateStart = NULL`  
*list of start dates*



### 4.4.1 Detailed Description

list of carrington rotation numbers and corresponding start times

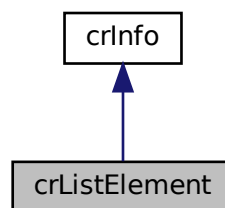
The documentation for this class was generated from the following files:

- src/carRotInfo.h
- src/carRotInfo.cpp

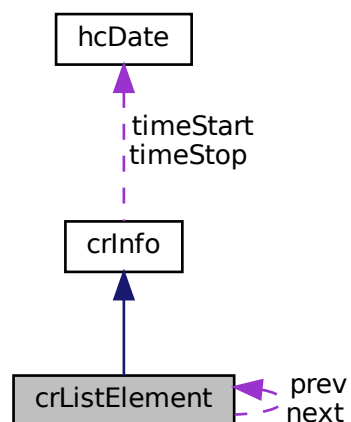
## 4.5 crListElement Class Reference

```
#include <carRotInfo.h>
```

Inheritance diagram for crListElement:



Collaboration diagram for crListElement:



## Public Member Functions

- [crListElement](#) (int carRotNum=0)  
*std-constructor*
- [crListElement](#) (const [crListElement](#) &other)  
*cpy constructor*
- [~crListElement](#) ()  
*destructor*
- [crListElement](#) & **operator=** (const [crListElement](#) &other)
- void **clear** ()
- void **initNULL** ()
- void **init** (int carRotNum)
- void [addElementToArray](#) (int \*\*array, uint &numEntries, uint newValue)  
*expands array by one and appends newValue at the end*
- bool [appendObservatory](#) (originID origin, int pos)  
*appends the position in solutions-set of the new observation to element*
- void [dump](#) ()  
*dumps information on this instance to stdout with optional indendtation*

## Public Attributes

- [crListElement](#) \* **prev**
- [crListElement](#) \* **next**
- int \* **WSO\_solution**
- int \* **KPVT\_solution**
- int \* **MDI\_solution**
- int \* **MDIDAILY\_solution**
- int \* **GONG\_solution**
- int \* **HMI\_solution**
- int \* **OWN\_solution**
- uint **numWSO**
- uint **numKPVT**
- uint **numMDI**
- uint **numMDIDAILY**
- uint **numGONG**
- uint **numHMI**
- uint **numOWN**

### 4.5.1 Detailed Description

information on which instrument has been used to compute the magnetic field of Carrington Rotation carRotNum

the integer values XXX\_solution are either -1 if no solution has been computed using that instrument or the positional number in the solutions-set of HelioMagfield

The documentation for this class was generated from the following files:

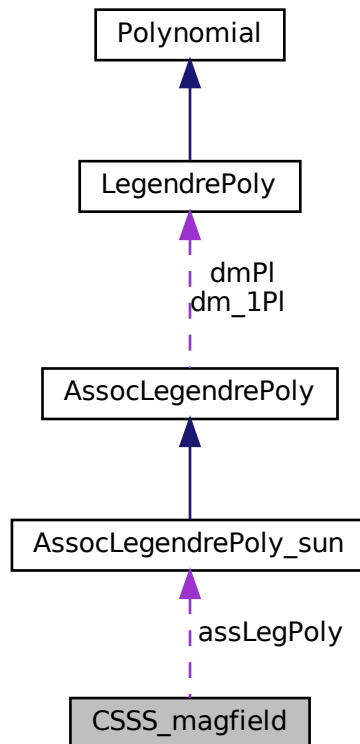
- src/carRotInfo.h
- src/carRotInfo.cpp

## 4.6 CSSS\_magfield Class Reference

solution of the CSSS model (not fully implemented/not working!!)

```
#include <pfss.h>
```

Collaboration diagram for CSSS\_magfield:



### Public Member Functions

- [CSSS\\_magfield](#) ()  
*std constructor*
- [CSSS\\_magfield](#) (const [CSSS\\_magfield](#) &other)  
*cpy constructor*
- **CSSS\_magfield** (const char \*filename)
- [~CSSS\\_magfield](#) ()  
*destructor*
- [CSSS\\_magfield](#) & **operator=** (const [CSSS\\_magfield](#) &other)  
*assignment operator*

- void **initNULL** ()
- void **clear** ()
- void **init** (uint **order**)
- void **eval** (const **Vec3D** &pos, **Vec3D** &result)
- bool **load** (const char \*filename)
- void **exportCoefficients** (const char \*filename)
- void **dump** ()

## Public Attributes

- **AssocLegendrePoly\_sun** \*\* **assLegPoly**  
*contains all the associated Legendre polynomials required for the solution*
- uint **order**  
*highest order of assoc. Legendre **Polynomial** utilized*
- double \*\* **g**  
*coefficients*
- double \*\* **h**  
*coefficients*
- double **sourceSurfaceFactor**  
*location of source surface in multiples of **r\_sol***

### 4.6.1 Detailed Description

solution of the CSSS model (not fully implemented/not working!!)

Gets as parameter a file with coefficients for associated Legendre polynomials. Returns on request the solution (magnetic field strength B) at a specific location in spherical (preferred) or cartesian coordinates

The documentation for this class was generated from the following files:

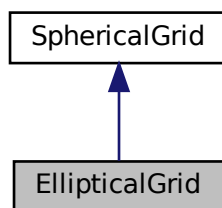
- src/pfss.h
- src/pfss.cpp

## 4.7 EllipticalGrid Class Reference

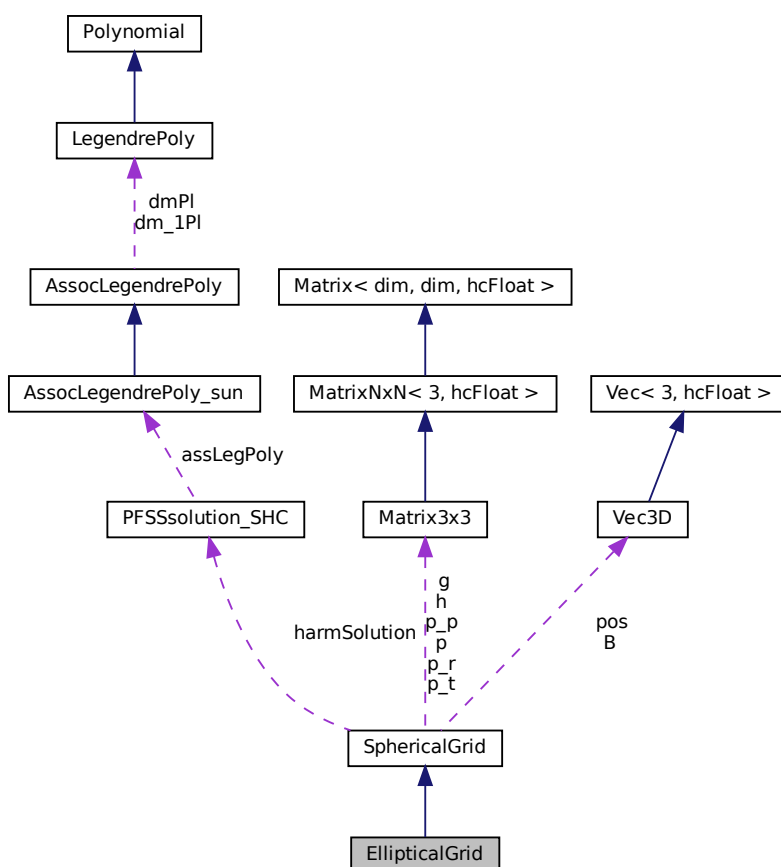
grid structure for numerical computation in 3D space

```
#include <ellipticalGrid.h>
```

Inheritance diagram for EllipticalGrid:



Collaboration diagram for EllipticalGrid:



## Public Member Functions

- virtual bool `isElliptical` () const

*determine whether the grid is spherical or elliptical*

- virtual **Vec3D** **getPos** (uint index, bool ellipticCoords=false) const
- virtual **Vec3D** **getB** (uint index, bool ellipticCoords=false) const
- virtual void **setB** (uint index, **Vec3D** value, bool ellipticCoords=false)
- **Vec3D** **getSphericalPos** (uint index)

*returns position in spherical coordinates, same as getPos, but not virtual*

- hcFloat \* **getEllArray** () const

*parameter a of ellipsis*

- hcFloat **getEllA** (uint index) const

- **EllipticalGrid** ()

*std constructor*

- **EllipticalGrid** (const **EllipticalGrid** &grid)

*cpy constructor*

- virtual **~EllipticalGrid** ()

*destructor*

- **EllipticalGrid** & **operator=** (const **EllipticalGrid** &other)

*assignment operator*

- **EllipticalGrid** & **operator=** (const **SphericalGrid** &other)

*assignment operator*

- void **initNULL\_CPU** ()

- void **initNULL** ()

- void **clear\_CPU** ()

- void **clear** ()

- void **dump** () const

- hcFloat **getEllParamsFromPos** (**Vec3D** pos, bool posElliptic) const

*computes elliptic parameters a for arbitrary position pos*

- void **convertMagMapping** (**MagMapping** &map)

- virtual void **init** (bool **sinLatGrid**, hcFloat **maxSinLat**, hcFloat **minSinLat**, hcFloat **lowerR**, hcFloat **upperR**, uint **numR**, bool clearGPU=true, hcFloat **a**=1.0)

- bool **getGradientVectors** (**Vec3D** cartPos, **Vec3D** &er, **Vec3D** &et, **Vec3D** &ep, bool prolate) const

*returns cartesian gradient (contravariant) basis vectors in physical domain*

- bool **getTangentVectors** (**Vec3D** cartPos, **Vec3D** &er, **Vec3D** &et, **Vec3D** &ep, bool prolate) const

*returns cartesian tangent (covariant) basis vectors in physical domain*

## Public Attributes

- bool **prolate**

## Protected Attributes

- hcFloat \* **a**

*parameter a of ellipsis*

## Additional Inherited Members

### 4.7.1 Detailed Description

grid structure for numerical computation in 3D space

### 4.7.2 Member Function Documentation

#### 4.7.2.1 init()

```
void EllipticalGrid::init (
    bool sinLatGrid,
    hcFloat maxSinLat,
    hcFloat minSinLat,
    hcFloat lowerR,
    hcFloat upperR,
    uint numR,
    bool clearGPU = true,
    hcFloat ell = 1.0 ) [virtual]
```

additional information like different domains (block regular) and distribution of grid points have to be supplied

#### Parameters

<i>rDistribution</i>	(0 - equally spaced, 1 - geometric series)
----------------------	--

Reimplemented from [SphericalGrid](#).

The documentation for this class was generated from the following files:

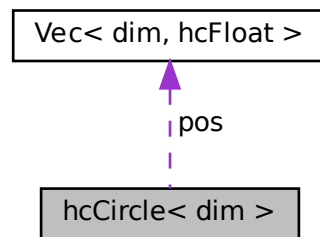
- src/ellipticalGrid.h
- src/ellipticalGrid.cpp

## 4.8 hcCircle< dim > Class Template Reference

mathematical model and functions for circles in nD-space

```
#include <hcCircle.h>
```

Collaboration diagram for `hcCircle< dim >`:



## Public Member Functions

- `hcCircle ()`  
*std constructor*
- `hcCircle (const hcCircle &other)`  
*cpy constructor*
- `hcCircle (const Vec< dim, hcFloat > &pos, hcFloat radius)`  
*constructor*
- `~hcCircle ()`  
*destructor*
- `hcCircle< dim > & operator= (const hcCircle< dim > &other)`  
*assignment operator*
- `void init (const Vec< dim, hcFloat > &pos, hcFloat radius)`
- `void dump () const`

## Public Attributes

- `Vec< dim, hcFloat > pos`
- `float radius`

### 4.8.1 Detailed Description

```
template<uint dim>
class hcCircle< dim >
```

mathematical model and functions for circles in nD-space

The documentation for this class was generated from the following file:

- `engine/math/hcCircle.h`

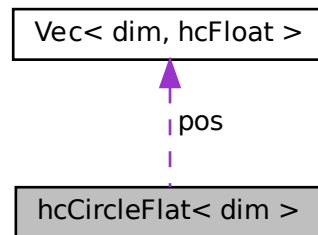


## 4.9 hcCircleFlat< dim > Class Template Reference

mathematical model and functions for circles in 2D-space

```
#include <hcCircle.h>
```

Collaboration diagram for hcCircleFlat< dim >:



### Public Member Functions

- `hcCircleFlat` (const `Vec2D` &pos=`Vec2D`(0.0, 0.0), float radius=1.0)
- `hcCircleFlat` (const `hcCircleFlat` &other)  
*cpy constructor*
- `hcCircleFlat` & **operator=** (const `hcCircleFlat` &other)
- void **init** (const `Vec2D` &pos, float radius)
- void **set** (const `Vec2D` &pos, float radius)
- int **intersectsL2D** (const `hcLine2D` &line, `Vec2D` &result0, `Vec2D` &result1) const  
*computes the intersections point(s) with a line for the std-norm*
- int **intersectsC2D** (const `hcCircleFlat` &circle, `Vec2D` &result1, `Vec2D` &result2, `hcLine2D` &resultline) const
- int **getTangentVecForced** (const `Vec2D` &in, `Vec2D` &result) const  
*computes the tangent vector to a point on the circle*

### Public Attributes

- `Vec< dim, hcFloat >` **pos**
- float **radius**

#### 4.9.1 Detailed Description

```
template<uint dim>
class hcCircleFlat< dim >
```

mathematical model and functions for circles in 2D-space

this class is not fit for circles oriented in nD-space

## 4.9.2 Constructor & Destructor Documentation

### 4.9.2.1 hcCircleFlat()

```
template<uint dim>
hcCircleFlat< dim >::hcCircleFlat (
    const Vec2D & pos = Vec2D(0.0, 0.0),
    float radius = 1.0 )
```

#### Parameters

<i>pos</i>	std constructor
------------	-----------------

## 4.9.3 Member Function Documentation

### 4.9.3.1 getTangentVecForced()

```
template<uint dim>
int hcCircleFlat< dim >::getTangentVecForced (
    const Vec2D & in,
    Vec2D & result ) const
```

computes the tangent vector to a point on the circle

No checks are made during computation. This speeds up the process and gets rid of numerical artifacts, though it has to be assured beforehand that the point really lies on the circle. Otherwise following computations might yield rubbish

### 4.9.3.2 intersectsC2D()

```
template<uint dim>
int hcCircleFlat< dim >::intersectsC2D (
    const hcCircleFlat< dim > & circle,
    Vec2D & result0,
    Vec2D & result1,
    hcLine2D & resultline ) const
```

computes the intersection of 2 circles in 2D-space (std-norm)

#### Return values

0	no intersection / areas disjunct or one circle in the other
1	two intersection points, stored in result1 and result2, the line produced by these two points is stored in resultline
2	tangential point, stored in result1

### 4.9.3.3 intersectsL2D()

```
template<uint dim>
int hcCircleFlat< dim >::intersectsL2D (
    const hcLine2D & line,
    Vec2D & result0,
    Vec2D & result1 ) const
```

computes the intersections point(s) with a line for the std-norm

Return values

0	no intersection of line with circle
1	two intersections, stored in result1 and result2
2	line tangential, tangential point stored in result1

The documentation for this class was generated from the following file:

- engine/math/hcCircle.h

## 4.10 hcDate Class Reference

### Public Member Functions

- [hcDate](#) ()  
*std constructor*
- [hcDate](#) (const [hcDate](#) &other)  
*cpy constructor*
- **hcDate** (long int [year](#), uint [month](#), uint day, uint [hour](#), uint [minute](#), uint [second](#), hcTimeStandard timeID=HC\_← C TT, hcCalendarID [calendarID](#)=HC\_GREGORIAN)
- **hcDate** (long int [year](#), uint [doy](#), uint [hour](#), uint [minute](#), uint [second](#), hcTimeStandard timeID=HC\_← C TT, hcCalendarID [calendarID](#)=HC\_GREGORIAN)
- **hcDate** (double [year](#), hcTimeStandard timeID=HC\_← C TT, hcCalendarID [calendarID](#)=HC\_GREGORIAN)
- **hcDate** (string timestamp)
- void **initNULL** ()
- [hcDate](#) & **operator=** (const [hcDate](#) &other)
- [hcDate](#) & **operator+=** (int128 timeDiff)
- [hcDate](#) & **operator-=** (int128 timeDiff)
- int128 **operator-** (const [hcDate](#) &other) const
- bool **operator>** (const [hcDate](#) &other) const  
*determines if this comes after other*
- bool **operator>=** (const [hcDate](#) &other) const  
*determines if this comes after other*
- bool **operator<** (const [hcDate](#) &other) const

*determines if other comes after this*

- bool `operator<=` (const `hcDate` &other) const  
*determines if other comes after this*
- bool `operator==` (const `hcDate` &other) const  
*determines equality*
- void `setFromSystemTime` ()  
*reads the time from the system and converts it to `hcDate`*
- bool `setFromTimeStamp` (const string &timestamp)  
*reads time from string produced by `toString`*
- void `set` (long int `year`, uint `doy`, uint `hour`, uint `minute`, uint `second`, `hcTimeStandard` timeID=HC\_TT, `hcCalendarID` `calendarID`=HC\_GREGORIAN)  
*set to a specific point in time*
- bool `set` (long int `year`, uint `month`, uint `day`, uint `hour`, uint `minute`, uint `second`, `hcTimeStandard` timeID=HC\_TT, `hcCalendarID` `calendarID`=HC\_GREGORIAN)  
*set to a specific point in time (Relative to me. Eat that, Einstein!!)*
- void `setFromTT` (int128 `absoluteTime`)  
*set date from absolute TT time since J2000*
- void `setFromJD` (long int `julianDay`, double `frac`)  
*convert `julienDay.frac` to `hcDate`*
- void `setFromUnix` (int128 `unixTime`)  
*set date from UNIX time (seconds since 1970-01-01, 00:00:00 UTC)*
- void `setFromCarringtonTime` (const double &`crTime`)  
*set date from Carrington time*
- bool `isLeapYear` ()  
*tells if this year is a leap year*
- uint `monthLength` (uint `numMonth`)  
*returns the length of the given month in days*
- void `computeInternalTT` ()
- void `getJulianDate` (long &`julianDayNum`, double &`frac`) const
- void `getModifiedJulianDate` (long &`mjd`, double &`mjd_frac`) const
- int128 `getUnixTime` () const  
*get UNIX time seconds \* facsec since Jan. 01, 1970 00:00:00 UTC*
- double `getCarringtonLongitude` () const  
*get Carrington Longitude in degrees (sub-earth point, measured from 0° at TODO ???)*
- double `getCarringtonTime` () const  
*get Carrington Longitude in degrees (sub-earth point, measured from 0° at TODO ???)*
- string `getTOD` () const  
*returns human readable time of day*

- uint [getCarringtonRotationNum](#) () const
- [hcDate](#) [getCarringtonRotStartDate](#) ()  
*find start time of Carrington rotation number crNum*
- [hcDate](#) [getCarringtonRotEndDate](#) ()  
*find end time of Carrington rotation number crNum*
- uint [computeDOY](#) ()  
*computes day of year from values set in the fields year, month and day*
- void [computeDayAndMonthFromDOY](#) ()  
*computes day and month from the fields doy and year*
- void [setFromInternalTT](#) ()
- void [convert2](#) (hcTimeStandard std)
- uint [numLsSinceBeginning](#) () const
- bool [isLeapSec](#) () const
- uint [getWeekDay](#) () const
- string [toString](#) () const
- string [toSpiceString](#) () const
- bool [exportBinary](#) (std::ofstream &stream)
- bool [importBinary](#) (std::ifstream &Sstream)
- void [str](#) (char \*out)
- void [dump](#) () const

## Public Attributes

- hcCalendarID [calendarID](#)  
*type of calendar used (Gregorian, Julian,...)*
- hcTimeStandard [timeStandard](#)  
*time standard used to express the date (TT, UTC,...)*
- int128 [absoluteTime](#)  
*Absolute time in seconds from epoch J2000.0, Jan. 01, 2000 : 12:00:00 given in Terrestrial Time.*
- int128 [equTTtime](#)  
*what the TT clock would show at this date*
- int128 [timeSinceJ2000](#)  
*seconds \* facSec from epoch in timeStandard*
- long int [year](#)  
*christian year*
- uint [doy](#)  
*day of year*
- uint [month](#)  
*month of year*
- uint [dom](#)  
*day of month*

- uint [hour](#)  
*hour of day*
- uint [minute](#)  
*minute of hour*
- uint [second](#)  
*second of minute*
- uint [millisec](#)  
*ms of second*
- uint [microsec](#)  
*us of ms*
- uint [nanosec](#)  
*ns of us*

## Static Public Attributes

- static const int128 [facSec](#) = 1000000000  
*time is stored with nano-second accuracy*

## 4.10.1 Member Function Documentation

### 4.10.1.1 [getCarringtonRotationNum\(\)](#)

```
uint hcDate::getCarringtonRotationNum ( ) const
```

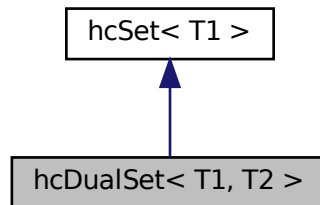
brief get Carrington rotation number corresponding to this date

The documentation for this class was generated from the following files:

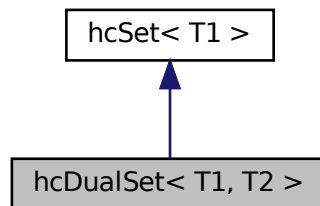
- engine/hcTime.h
- engine/hcTime.cpp

## 4.11 hcDualSet< T1, T2 > Class Template Reference

Inheritance diagram for hcDualSet< T1, T2 >:



Collaboration diagram for hcDualSet< T1, T2 >:



### Public Member Functions

- **hcDualSet** (uint numMaxSlots=1)
- void **clear** ()
- void **initNULL** ()
- void **init** (uint numMaxSlots)
- T2 \* **getOtherObject** (const T1 &object)
- int **appendElement** (T1 &object, T2 &otherObject)
- int **removeElement** (T1 &object)  
*remove given object from this set*

### Public Attributes

- T2 \*\* **otherElements**

### 4.11.1 Member Function Documentation

#### 4.11.1.1 removeElement()

```
template<class T1 , class T2 >
int hcDualSet< T1, T2 >::removeElement (
    T1 & object ) [virtual]
```

remove given object from this set

#### Returns

position where object has been found and removed or -1 on failure

Reimplemented from [hcSet< T1 >](#).

The documentation for this class was generated from the following file:

- engine/hcSet.h

## 4.12 hclmage< T > Class Template Reference

### Public Member Functions

- [hclmage](#) ()  
*std constructor*
- [hclmage](#) (const [hclmage](#)< T > &other)  
*cpy constructor*
- **hclmage** (uint width, uint height)
- [hclmage](#) & **operator=** (const [hclmage](#) &other)  
*assignment operator*
- T & **operator()** (uint x, uint y)  
*returns manipulatable reference to contents*
- T **content** (uint x, uint y) const  
*returns copy of contents*
- void **initNULL** ()
- void **clear** ()
- void **init** (uint width, uint height)  
*allocates memory for an image of the according dimenstions*
- [hclmage](#) **extractSubimage** (int extractPosX, int extractPosY, uint width, uint height)



*extracts subimage of (width \* height) from the specified position*

- bool `extractSubimage` (int extractPosX, int extractPosY, `hclImage`< T > &retval)  
*see above*
- void `shiftXdirection` (int numPixels)  
*shifts image numPixels in positive x-direction, pixels leaving right boundary enter from the left*
- void `pushToArray` (T \*\*array, uint &width, uint &height)  
*saves data to array and reports back width and height*
- T \* `getData` ()
- void `dump` () const

## Public Attributes

- uint `width`
- uint `height`

## Protected Attributes

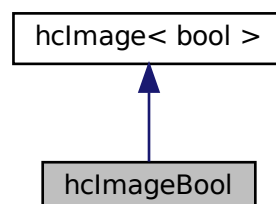
- T \* `data`

The documentation for this class was generated from the following file:

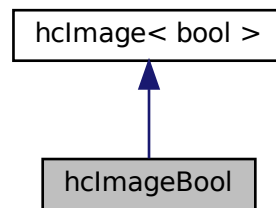
- engine/hclImage.h

## 4.13 hclImageBool Class Reference

Inheritance diagram for hclImageBool:



Collaboration diagram for `hclImageBool`:



## Public Member Functions

- `hclImageBool ()`  
*std constructor*
- `hclImageBool (const hclImageBool &other)`  
*cpy constructor*
- `hclImageBool (uint width, uint height)`
- `hclImageBool & operator= (const hclImageBool &other)`
- `void init (uint width, uint height)`
- `void dump () const`

## Additional Inherited Members

The documentation for this class was generated from the following files:

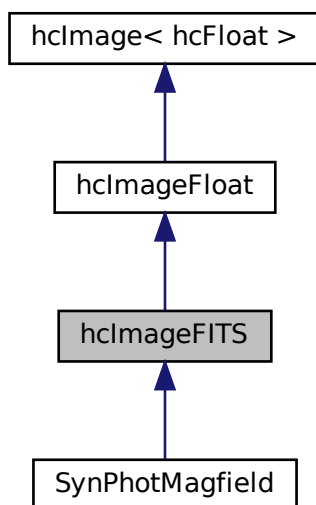
- `engine/hclImage.h`
- `engine/hclImage.cpp`

## 4.14 hclImageFITS Class Reference

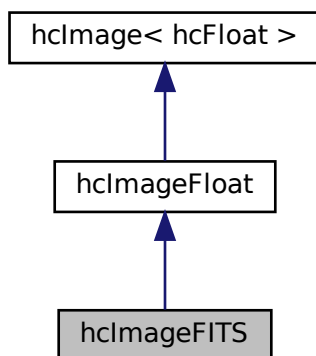
handler for 2D FITS image files

```
#include <hcImageFITS.h>
```

Inheritance diagram for hclmageFITS:



Collaboration diagram for hclmageFITS:



## Public Member Functions

- [hclmageFITS](#) ()
- [hclmageFITS](#) (const [hclmageFITS](#) &other)
- **hclmageFITS** (uint width, uint height)
- [hclmageFITS](#) (const string &filename)
- virtual [~hclmageFITS](#) ()
- [hclmageFITS](#) & [operator=](#) (const [hclmageFITS](#) &other)

- void **clear** ()
- void **initNULL** ()
- virtual bool **load** (const string &filename)  
*load FITS image from file*
- virtual bool **save** (const string &filename)  
*write FITS image to file*
- bool **dumpAllKeys** ()  
*print all stored keys to screen*
- bool **readKeyString** (const string &keyname, string &retval)  
*read key keyname and give back as string*
- bool **readKeyFloat** (const string &keyname, hcFloat &value)  
*read key keyname and convert to floating point value before returning*
- bool **writeKeyFloat** (const string &keyname, const string &comment, hcFloat value)  
*write key keyname with content value*
- bool **writeKeyString** (const string &keyname, const string &comment, const string &value)  
*write key keyname with content value*
- bool **writeKeyComment** (const string &comment)
- hcFloat **getHistogramMaximum** (uint numBins)
- **ImageStatistics** **getImageStatistics** () const
- **percentileDataStruct** **getPercentiles** () const
- void **normalize** ()
- void **rescale** (uint newWidth, uint newHeight)
- hcFloat **crosscor** (const **hclImageFITS** &other, uint i, uint j)

## Static Public Member Functions

- static void **initStaticMembers** ()

## Public Attributes

- string **filename**
- fitsfile \* **filePtr**

## Static Public Attributes

- static pthread\_mutex\_t **mutexFits**

## Additional Inherited Members

### 4.14.1 Detailed Description

handler for 2D FITS image files

## 4.14.2 Constructor & Destructor Documentation

### 4.14.2.1 hcImageFITS() [1/3]

```
hcImageFITS::hcImageFITS ( )
```

std constructor

### 4.14.2.2 hcImageFITS() [2/3]

```
hcImageFITS::hcImageFITS (
    const hcImageFITS & other )
```

cpy constructor

### 4.14.2.3 hcImageFITS() [3/3]

```
hcImageFITS::hcImageFITS (
    const string & filename )
```

creates handler by opening a file

### 4.14.2.4 ~hcImageFITS()

```
hcImageFITS::~~hcImageFITS ( ) [virtual]
```

destructor

## 4.14.3 Member Function Documentation

### 4.14.3.1 operator=()

```
hcImageFITS & hcImageFITS::operator= (
    const hcImageFITS & other )
```

assignment operator

#### 4.14.4 Member Data Documentation

##### 4.14.4.1 filePtr

```
fitsfile* hcImageFITS::filePtr
```

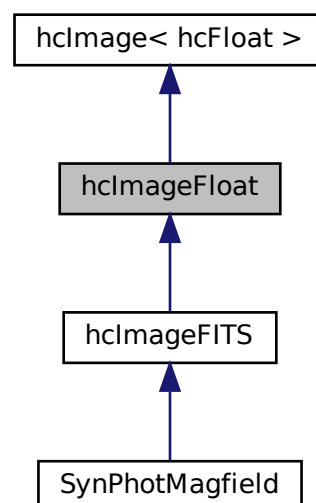
pointer to input FITS file

The documentation for this class was generated from the following files:

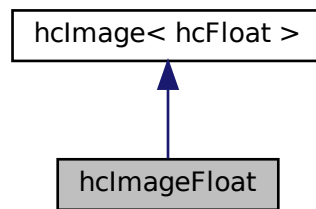
- engine/hcImageFITS.h
- engine/hcImageFITS.cpp
- main.cpp

#### 4.15 hcImageFloat Class Reference

Inheritance diagram for hcImageFloat:



Collaboration diagram for hclImageFloat:



## Public Member Functions

- [hclImageFloat](#) ()  
*std constructor*
- [hclImageFloat](#) (const [hclImageFloat](#) &other)  
*cpy constructor*
- **hclImageFloat** (uint width, uint height)
- **hclImageFloat** (uint width, uint height, float color)
- [hclImageFloat](#) & **operator=** (const [hclImageFloat](#) &other)
- void **init** (uint width, uint height)
- void **init** (uint width, uint height, float color)  
*allocates memory for an image of the specified dimensions and paints it according to color*
- virtual bool **load** (const string &filename)  
*loads an image from filename*
- virtual bool **save** (const string &filename)  
*saves to filename*
- void **reldiffImage** (const [hclImageFloat](#) &img0, const [hclImageFloat](#) &img1)  
*computes pixelwise relative difference between img0 and img1*
- void **diffImage** (const [hclImageFloat](#) &img0, const [hclImageFloat](#) &img1)  
*compute pixelwise difference between img0 and img1*
- float **absMean** ()  
*sums up all absolute pixel values and divides by number of pixels*
- void **setBackgroundColor** (float bgColor, int insertPosX=0, int insertPosY=0, uint subWidth=0, uint subHeight=0)  
*paints the entire image or parts of it in bgColor*
- bool **insertSubimage** (const [hclImageFloat](#) &src, int insertPosX, int insertPosY)  
*inserts a image into this one at the specified location*

- bool `loadFromArray` (float \*array, uint width, uint height)  
*loads image data from array*
- hcFloat `meanSquaredDiff` (hcImage &other)
- void `meanFilter` (uint windowWidth, bool circular)  
*applies mean filter to picture, x-coordinate may be circular*
- void `medianFilter` (uint windowWidth, bool circular)  
*applies median filter to picture, x-coordinate may be circular*
- void `dump` () const  
*rescales image to new dimensions*

## Additional Inherited Members

### 4.15.1 Member Function Documentation

#### 4.15.1.1 dump()

```
void hcImageFloat::dump ( ) const
```

rescales image to new dimensions

<

#### 4.15.1.2 insertSubimage()

```
bool hcImageFloat::insertSubimage (
    const hcImageFloat & src,
    int insertPosX,
    int insertPosY )
```

inserts a image into this one at the specified location

inserts image supplied by src at the supplied positions by replacing the data stored at these positions in this (opaque, no transparency)

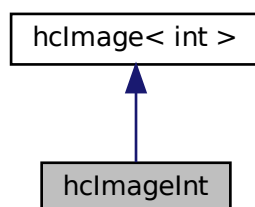
The documentation for this class was generated from the following files:

- engine/hcImage.h
- engine/hcImage.cpp

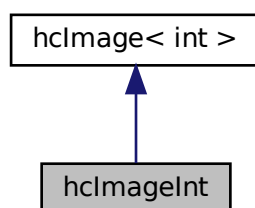


## 4.16 hclmageInt Class Reference

Inheritance diagram for hclmageInt:



Collaboration diagram for hclmageInt:



### Public Member Functions

- [hclmageInt](#) ()  
*std constructor*
- [hclmageInt](#) (const [hclmageInt](#) &other)  
*cpy constructor*
- **hclmageInt** (uint width, uint height)
- [hclmageInt](#) & **operator=** (const [hclmageInt](#) &other)
- void **init** (uint width, uint height)
- void **dump** () const

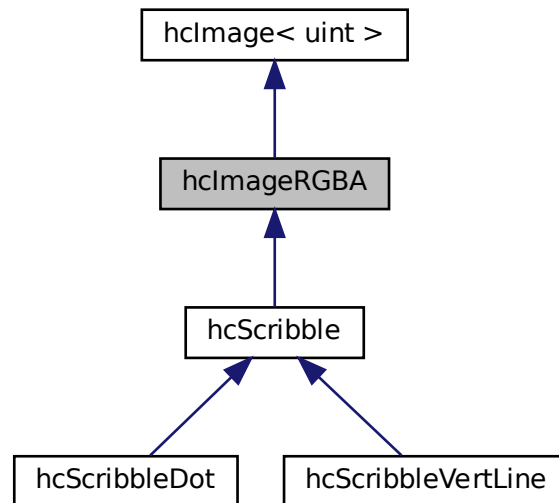
### Additional Inherited Members

The documentation for this class was generated from the following files:

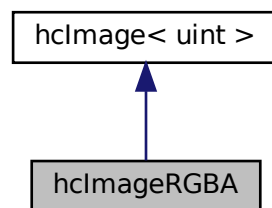
- engine/hclmage.h
- engine/hclmage.cpp

## 4.17 hclImageRGBA Class Reference

Inheritance diagram for hclImageRGBA:



Collaboration diagram for hclImageRGBA:



### Public Member Functions

- `hclImageRGBA()`  
*std constructor*
- `hclImageRGBA(const hclImageRGBA &other)`  
*cpy constructor*
- `hclImageRGBA(uint width, uint height)`

- **hclImageRGBA** (uint width, uint height, uint color)
- **hclImageRGBA & operator=** (const **hclImageRGBA** &other)
- void **init** (uint width, uint height)
- void **init** (uint width, uint height, uint color)  
*allocates memory for an image of the specified dimensions and paints it according to color*
- virtual bool **save** (const string &filename)  
*saves to filename*
- uint **numNotBlackPixels** () const
- void **magDiff** (**hclImage** &img1, **hclImage** &img2)
- void **setBackgroundColor** (uint bgColor, int insertPosX=0, int insertPosY=0, uint subWidth=0, uint subHeight=0)  
*paints the entire image or parts of it in bgColor*
- bool **insertSubimage** (**hclImage** &src, int insertPosX, int insertPosY)  
*inserts a image into this one at the specified location*
- bool **loadFromArray** (uint \*array, uint width, uint height)  
*loads image data from array*
- bool **interpolateRectangularImage** (uint width\_out, uint height\_out)  
*interpolates image to the requested dimension*
- void **dump** () const

## Additional Inherited Members

### 4.17.1 Member Function Documentation

#### 4.17.1.1 interpolateRectangularImage()

```
bool hclImageRGBA::interpolateRectangularImage (
    uint width_out,
    uint height_out )
```

interpolates image to the requested dimension

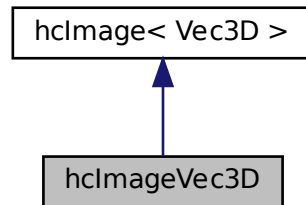
resizes a rectangular image via bilinear interpolation TODO: redo this function!

The documentation for this class was generated from the following files:

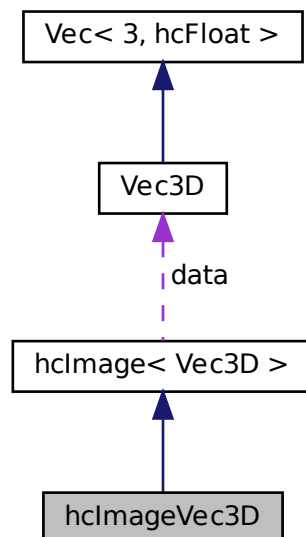
- engine/hclImage.h
- engine/hclImage.cpp

## 4.18 hclImageVec3D Class Reference

Inheritance diagram for hclImageVec3D:



Collaboration diagram for hclImageVec3D:



### Public Member Functions

- [hclImageVec3D \(\)](#)  
*std constructor*
- [hclImageVec3D \(const hclImageVec3D &other\)](#)  
*cpy constructor*

- **hclImageVec3D** (uint width, uint height)
- **hclImageVec3D** & **operator=** (const **hclImageVec3D** &other)
- void **init** (uint width, uint height)
- void **dump** () const

### Additional Inherited Members

The documentation for this class was generated from the following files:

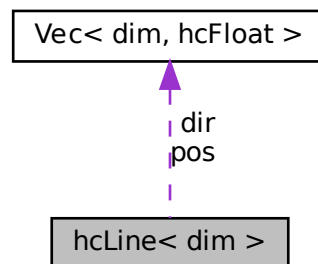
- engine/hclImage.h
- engine/hclImage.cpp

## 4.19 hcLine< dim > Class Template Reference

contains mathematical model and functions for nD lines

```
#include <hcLine.h>
```

Collaboration diagram for hcLine< dim >:



### Public Member Functions

- **hcLine** ()  
*std-constructor*
- **hcLine** (const **hcLine**< dim > &other)  
*cpy-constructor*
- **hcLine** (const **Vec**< dim, hcFloat > &pos, const **Vec**< dim, hcFloat > &dir)  
*direction constructor*
- **~hcLine** ()  
*destructor*

- `hcLine< dim > & operator= (const hcLine< dim > &other)`  
*assignment operator*
- `int intersectsL (const hcLine< dim > &l, Vec< dim, hcFloat > &result) const`  
*tests the intersectio of this line with another line*
- `int intersectsP (const Vec< dim, hcFloat > &vec, float &result) const`  
*tests if a point lies on this line*
- `int createLineThroughPoints (const Vec< dim, hcFloat > &point1, const Vec< dim, hcFloat > &point2)`  
*creates a line through point1 and point2*
- `float pointProjection (const Vec< dim, hcFloat > &point) const`
- `void set (const Vec< dim, hcFloat > &vec1, const Vec< dim, hcFloat > &vec2)`
- `int setV1 (const Vec< dim, hcFloat > &vec)`
- `int setV2 (const Vec< dim, hcFloat > &vec)`
- `Vec< dim, hcFloat > getPos (hcFloat lambda) const`  
*computes the nD-Vetor obtained by inserting lambda in this Line equation*
- `void dump () const`

## Public Attributes

- `Vec< dim, hcFloat > pos`
- `Vec< dim, hcFloat > dir`

## 4.19.1 Detailed Description

```
template<uint dim>
class hcLine< dim >
```

contains mathematical model and functions for nD lines

The nD-Line is parametrized by by two nD-vectors (position and direction vectors):  $\text{line} = \text{pos} + \text{lambda} * \text{dir}$  lambda is element of [0,1] if line is initialized by giving two points to be connected by the line

## 4.19.2 Member Function Documentation

### 4.19.2.1 createLineThroughPoints()

```
template<uint dim>
int hcLine< dim >::createLineThroughPoints (
    const Vec< dim, hcFloat > & point1,
    const Vec< dim, hcFloat > & point2 )
```

creates a line through point1 and point2

creates ND-line through two ND-points, if they are not too close to each other

## Return values

0	points too close or dimension mismatch
1	line successfully created

## 4.19.2.2 intersectsL()

```
template<uint dim>
int hcLine< dim >::intersectsL (
    const hcLine< dim > & l,
    Vec< dim, hcFloat > & result ) const
```

tests the intersection of this line with another line

computes the intersection with another nD-line

## Return values

0	no intersection found
1	exactly one intersection found
2	lines are identical

the Vector result contains the intersection point in case 1 and the position vector of this Line in the case 2

## 4.19.2.3 intersectsP()

```
template<uint dim>
int hcLine< dim >::intersectsP (
    const Vec< dim, hcFloat > & vec,
    float & result ) const
```

tests if a point lies on this line

checks if the nD-point denoted by vec is on this Line

## Return values

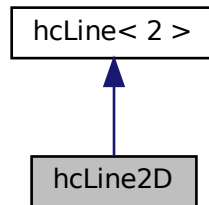
0	point not on Line
1	point on Line, line parameter is returned in result

The documentation for this class was generated from the following file:

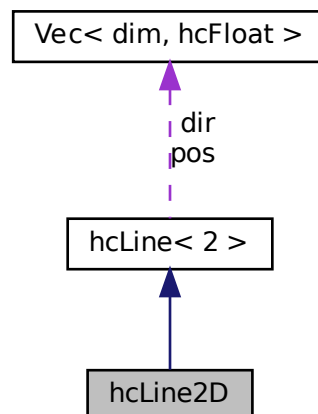
- engine/math/hcLine.h

## 4.20 hcLine2D Class Reference

Inheritance diagram for hcLine2D:



Collaboration diagram for hcLine2D:



### Public Member Functions

- `hcLine2D` (const `Vec2D` &pos=`Vec2D`(0.0, 0.0), const `Vec2D` &dir=`Vec2D`(1.0, 1.0))  
*std constructor*
- `hcLine2D` (const `hcLine2D` &other)  
*cpy constructor*
- `hcLine2D` (float x1, float y1, float x2, float y2)
- `hcLine2D` & `operator=` (const `hcLine2D` &other)



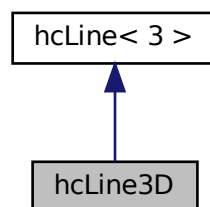
## Additional Inherited Members

The documentation for this class was generated from the following files:

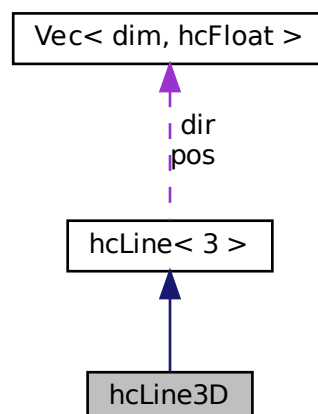
- engine/math/hcLine.h
- engine/math/hcLine.cpp

## 4.21 hcLine3D Class Reference

Inheritance diagram for hcLine3D:



Collaboration diagram for hcLine3D:



## Public Member Functions

- `hcLine3D` (const `Vec3D` &pos0=`Vec3D`(0.0, 0.0, 0.0), const `Vec3D` &pos1=`Vec3D`(1.0, 1.0, 1.0))
- `hcLine3D` (const `hcLine3D` &other)  
*cpy constructor*
- `~hcLine3D` ()  
*destructor*
- `hcLine3D` & `operator=` (const `hcLine3D` &other)  
*assignment operator*
- void `init` (const `Vec3D` &pos0, const `Vec3D` &pos1)
- int `intersectsSphere3D` (const `hcSphere`< 3 > &sphere, `hcFloat` &result0, `hcFloat` &result1, bool getInside↔Pos)  
*returns the parameter of the line where it intersects the sphere*
- `Vec3D` `intersectsPlane3D` (const `hcPlane3D` &plane, uint &result)  
*returns the point of intersection*
- int `getIntersectionsWithSphere` (const `hcSphere`< 3 > &sphere, `Vec3D` &result0, `Vec3D` &result1, bool get↔InsidePos=false)  
*gives the two points where the line pirces the sphere (or the point where it touches the sphere)*

## Additional Inherited Members

### 4.21.1 Constructor & Destructor Documentation

#### 4.21.1.1 `hcLine3D()`

```
hcLine3D::hcLine3D (
    const Vec3D & pos0 = Vec3D(0.0, 0.0, 0.0),
    const Vec3D & pos1 = Vec3D(1.0, 1.0, 1.0) )
```

##### Parameters

<code>pos0</code>	std constructor
-------------------	-----------------

### 4.21.2 Member Function Documentation

#### 4.21.2.1 `getIntersectionsWithSphere()`

```
int hcLine3D::getIntersectionsWithSphere (
    const hcSphere< 3 > & sphere,
```

```

    Vec3D & result0,
    Vec3D & result1,
    bool getInsidePos = false )

```

gives the two points where the line pierces the sphere (or the point where it touches the sphere)

returns the positions where the line pierces the sphere

#### Parameters

<i>sphere</i>	the sphere to be pierced
<i>result0</i>	first intersection or tangential point of sphere and line
<i>result1</i>	second intersection point of sphere and line
<i>getInsidePos</i>	numerical parameter, determines if result0/1 shall be slightly above or below sphere surface

#### Return values

0	no intersection of line with sphere
1	line tangential, tangential point stored in result0
2	two intersections, stored in result0 and result1

#### 4.21.2.2 intersectsPlane3D()

```

Vec3D hcLine3D::intersectsPlane3D (
    const hcPlane3D & plane,
    uint & result )

```

returns the point of intersection

returns the point of intersection (if existing, zero-vec otherwise)

#### Parameters

<i>plane</i>	the plane to be pierced
<i>result</i>	0 -> no intersection, 1 -> one intersection, 2 -> line lies in plane

#### 4.21.2.3 intersectsSphere3D()

```

int hcLine3D::intersectsSphere3D (
    const hcSphere< 3 > & sphere,
    hcFloat & result0,
    hcFloat & result1,
    bool getInsidePos )

```

returns the parameter of the line where it intersects the sphere

returns the line parameter lambda0 and lambda1 where the line pierces the sphere

## Parameters

<i>sphere</i>	the sphere to be pierced
<i>result0</i>	first intersection or tangent parameter of sphere and line
<i>result1</i>	second intersection parameter of sphere and line
<i>getInsidePos</i>	numerical parameter, determines if result0/1 shall be slightly above or below sphere surface this parameter affects only the pircing (retval = 1) and not not the tangent (retval = 2) case

## Return values

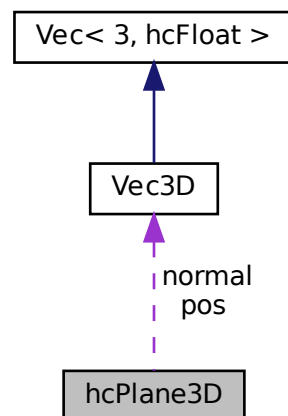
0	no intersection of line with sphere
1	line tangential, tangential point stored in result0
2	two intersections, stored in result0 and result1

The documentation for this class was generated from the following files:

- engine/math/hcLine.h
- engine/math/hcLine.cpp

## 4.22 hcPlane3D Class Reference

Collaboration diagram for hcPlane3D:



### Public Member Functions

- `hcPlane3D` (const `Vec3D` &pos=`Vec3D`(0.0, 0.0, 0.0), const `Vec3D` &normal=`Vec3D`(0.0, 0.0, 1.0))  
*std constructor*

- [hcPlane3D](#) (const [hcPlane3D](#) &other)  
*cpy constructor*
- **hcPlane3D** (const [Vec3D](#) &pos0, const [Vec3D](#) &pos1, const [Vec3D](#) &pos2)
- [hcPlane3D](#) & **operator=** (const [hcPlane3D](#) &other)
- bool **operator==** (const [hcPlane3D](#) &other)  
*tests identity of this plane with another*
- void **clear** ()
- void **initNULL** ()
- bool **init** (const [Vec3D](#) &pos, const [Vec3D](#) &normal)  
*initializes plane by giving position and normal vectors*
- bool **init** (const [Vec3D](#) &pos0, const [Vec3D](#) &pos1, const [Vec3D](#) &pos2)  
*initializes plane by giving three points on the plane*
- void **dump** () const

## Public Attributes

- [Vec3D](#) **pos**
- [Vec3D](#) **normal**

The documentation for this class was generated from the following files:

- engine/math/hcPlane.h
- engine/math/hcPlane.cpp

## 4.23 hcPlaneND Class Reference

The documentation for this class was generated from the following file:

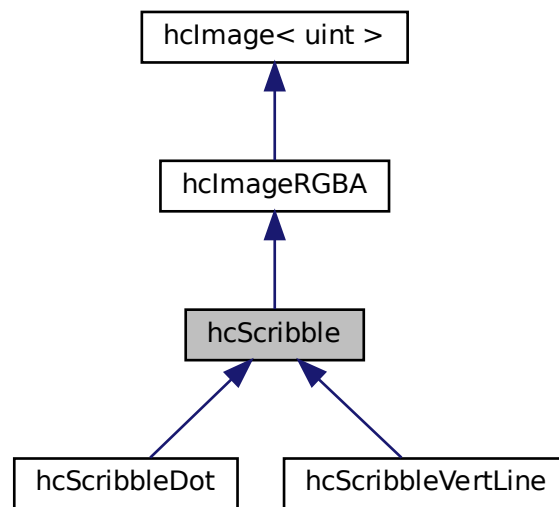
- engine/math/hcPlane.h

## 4.24 hcScribble Class Reference

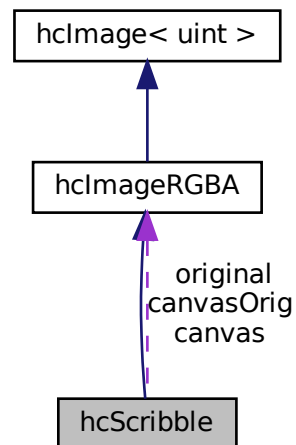
implements objects (lines, points, crosses, whatever) for scribbling in hcImages

```
#include <hcImage.h>
```

Inheritance diagram for `hcScribble`:



Collaboration diagram for `hcScribble`:



## Public Member Functions

- **hcScribble** (const [hcScribble](#) &other)
- [hcScribble](#) & **operator=** (const [hcScribble](#) &other)
- void **initNULL** ()

- virtual void **clear** ()
- void **init** (double **relWidth**, double **relPosX**, double **relPosY**, **hclImageRGBA** \***canvas**)
- void **setCanvas** (**hclImageRGBA** \***canvas**)  
*sets canvas to be painted upon*
- void **reinit** ()  
*this function empties canvasOrig so that a new canvas can be loaded without parts of the old one be dumped in it*
- bool **updateScaledScribble** ()  
*adjusts this **hclImageRGBA** according to relative position / width*
- bool **updatePosition** ()  
*recomputes the insertPos of the scribble according to relPos*
- bool **draw** ()  
*draws this scribble at the specified position*
- bool **redrawOrig** ()  
*redraws the original part of the image where the scribble was drawn*
- void **dump** () const

## Public Attributes

- **hclImageRGBA** \* **canvas**  
*not-owning pointer to the image to be scribbled in*
- **hclImageRGBA** **canvasOrig**  
*canvas content that has been overdrawn by this scribble (TODO: this allows scribbles to think other scribbles are the original image)*
- **hclImageRGBA** **original**  
*not scaled image to be scribbled in canvas*
- int **insertPosX**  
*x-pos of this in canvas*
- int **insertPosY**  
*y-pos of this in canvas*
- double **relPosX**  
*relative  $(-1 < x < 1)$  x-pos of this in canvas*
- double **relPosY**  
*relative  $(-1 < x < 1)$  y-pos of this in canvas*
- double **newRelPosX**  
*where to draw when draw-function is called next time*
- double **newRelPosY**  
*where to draw when draw-function is called next time*
- double **relWidth**  
*relative width of this scribble in canvas*

## Additional Inherited Members

### 4.24.1 Detailed Description

implements objects (lines, points, crosses, whatever) for scribbling in hclmages

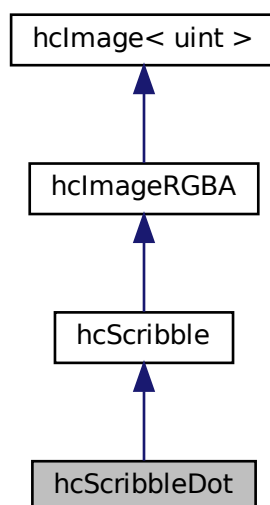
<

The documentation for this class was generated from the following files:

- engine/hclImage.h
- engine/hclImage.cpp

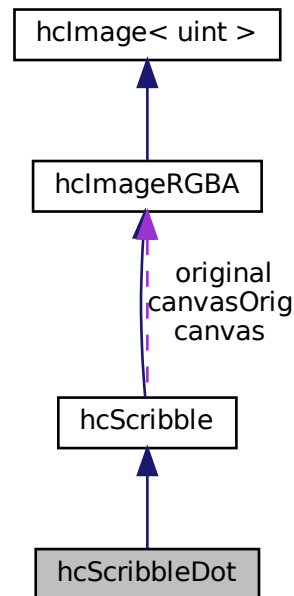
## 4.25 hcScribbleDot Class Reference

Inheritance diagram for hcScribbleDot:





Collaboration diagram for hcScribbleDot:



## Public Member Functions

- [hcScribbleDot](#) ()  
*std constructor*
- [hcScribbleDot](#) (const [hcScribbleDot](#) &other)  
*cpy constructor*
- **hcScribbleDot** (uint color, double [relWidth](#), double [relPosX](#), double [relPosY](#), [hclmageRGBA](#) \*canvas)
- [hcScribbleDot](#) & **operator=** (const [hcScribbleDot](#) &other)
- void **initNULL** ()
- virtual void **clear** ()
- void **init** (uint color, double [relWidth](#), double [relPosX](#), double [relPosY](#), [hclmageRGBA](#) \*canvas)
- void **dump** () const

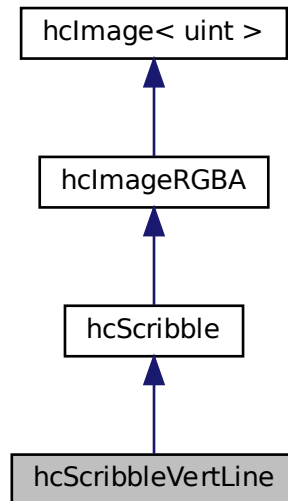
## Additional Inherited Members

The documentation for this class was generated from the following files:

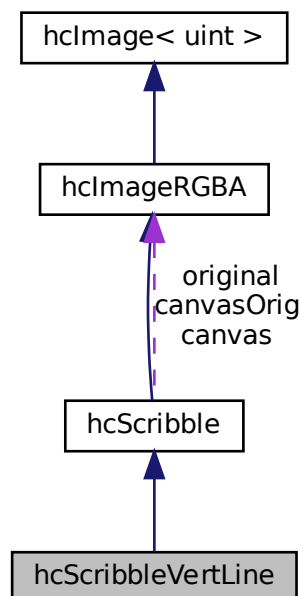
- engine/hclmage.h
- engine/hclmage.cpp

## 4.26 hcScribbleVertLine Class Reference

Inheritance diagram for hcScribbleVertLine:



Collaboration diagram for hcScribbleVertLine:



## Public Member Functions

- [hcScribbleVertLine](#) ()  
*std constructor*
- [hcScribbleVertLine](#) (const [hcScribbleVertLine](#) &other)  
*cpy constructor*
- **hcScribbleVertLine** (uint color, double [relWidth](#), double [relPosX](#), double [relPosY](#), [hclImageRGBA](#) \*canvas)
- [hcScribbleVertLine](#) & **operator=** (const [hcScribbleVertLine](#) &other)
- void **initNULL** ()
- virtual void **clear** ()
- void **init** (uint color, double [relWidth](#), double [relPosX](#), double [relPosY](#), [hclImageRGBA](#) \*canvas)
- void **dump** () const

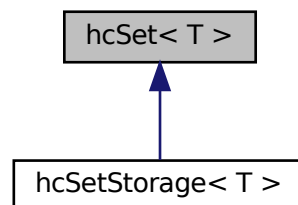
## Additional Inherited Members

The documentation for this class was generated from the following files:

- engine/hclImage.h
- engine/hclImage.cpp

## 4.27 hcSet< T > Class Template Reference

Inheritance diagram for hcSet< T >:



## Public Member Functions

- **hcSet** (uint numMaxSlots=4)
- **hcSet** (const [hcSet](#)< T > &other)
- [hcSet](#)< T > & **operator=** (const [hcSet](#)< T > &other)
- T & **operator[]** (uint i) const
- void **clear** ()
- void **initNULL** ()
- void **init** (uint numMaxSlots)

- virtual void **expand** (uint numNewElements)
- virtual int **findElement** (const T &object)
- virtual bool **hasElement** (const T &object)
- virtual bool **isSlotOccupied** (uint n) const  
*is slot n occupied?*
- int **appendElement** (T &object)  
*appends given object to this set*
- bool **appendElementAtPos** (T &object, uint pos)  
*appends element at a specific position if possible*
- virtual int **removeElement** (T &object)  
*remove given object from this set*
- T & **elementAt** (uint num)  
*returns reference to element at position num*
- void **dump** () const

## Public Attributes

- uint **numMaxSlots**
- uint **numOccupiedSlots**
- uint **numFreeSlots**
- uint **firstFreeSlot**
- uint **lastOccSlot**
- T \*\* **elements**
- bool \* **occupied**

## 4.27.1 Member Function Documentation

### 4.27.1.1 appendElement()

```
template<class T >
int hcSet< T >::appendElement (
    T & object )
```

appends given object to this set

#### Returns

position where object is stored

### 4.27.1.2 removeElement()

```
template<class T >
int hcSet< T >::removeElement (
    T & object ) [virtual]
```

remove given object from this set

#### Returns

position where object has been found and removed or -1 on failure

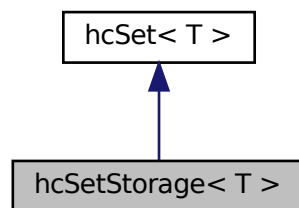
Reimplemented in [hcDualSet< T1, T2 >](#), and [hcSetStorage< T >](#).

The documentation for this class was generated from the following file:

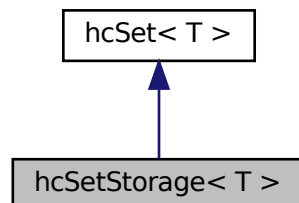
- engine/hcSet.h

## 4.28 hcSetStorage< T > Class Template Reference

Inheritance diagram for hcSetStorage< T >:



Collaboration diagram for hcSetStorage< T >:



## Public Member Functions

- [hcSetStorage](#) (uint numMaxSlots=1)  
*std constructor*
- [hcSetStorage](#) (const [hcSetStorage](#) &other)  
*cpy constructor*
- [hcSetStorage](#)< T > & **operator=** (const [hcSetStorage](#)< T > &other)
- virtual int [removeElement](#) (T &object)  
*removes and destroys an element*
- bool [extractElement](#) (T &object)  
*removes an element and transfers ownership*

## Additional Inherited Members

The documentation for this class was generated from the following file:

- engine/hcSet.h

## 4.29 hcSortedList< T > Class Template Reference

### Public Member Functions

- **hcSortedList** (uint numMaxSlots=128)
- **hcSortedList** (const [hcSortedList](#)< T > &other)
- [hcSortedList](#)< T > & **operator=** (const [hcSortedList](#)< T > &other)
- [hcSortedList](#)< T > & **operator=** (const [hcSortedListStorage](#)< T > &other)
- T & **operator[]** (uint i) const
- void **clear** ()
- void **initNULL** ()
- void **init** (uint numMaxSlots=1024)
- virtual void **expand** (uint numNewElements)
- virtual int **findElement** (const T &object)
- virtual bool **hasElement** (const T &object)
- uint [insertElement](#) (T &object)  
*appends given object to this list*
- virtual int [removeElement](#) (T &object)  
*remove given object from this set*
- bool **sort** ()
- void **dump** () const

### Public Attributes

- uint **numElements**
- uint **numMaxSlots**
- T \*\* **elements**

### 4.29.1 Member Function Documentation

#### 4.29.1.1 insertElement()

```
template<class T >
uint hcSortedList< T >::insertElement (
    T & object )
```

appends given object to this list

##### Returns

position where object is stored

#### 4.29.1.2 removeElement()

```
template<class T >
int hcSortedList< T >::removeElement (
    T & object ) [virtual]
```

remove given object from this set

##### Returns

position where object has been found and removed or -1 on failure

The documentation for this class was generated from the following file:

- engine/hcSortedList.h

## 4.30 hcSortedListStorage< T > Class Template Reference

### Public Member Functions

- [hcSortedListStorage](#) (uint numMaxSlots=128)  
*std constructor*
- [hcSortedListStorage](#) (const [hcSortedListStorage](#) &other)  
*cpy constructor*
- [hcSortedListStorage](#)< T > & **operator=** (const [hcSortedListStorage](#)< T > &other)
- virtual int [removeElement](#) (T &object)  
*removes and destroys an element*
- bool [extractElement](#) (T &object)  
*removes an element and transfers ownership*

The documentation for this class was generated from the following file:

- engine/hcSortedList.h

## 4.31 hcSphere< dim > Class Template Reference

mathematical model and functions for nD-spheres

```
#include <hcSphere.h>
```

### Public Member Functions

- [hcSphere](#) ()  
*std constructor*
- [hcSphere](#) (const [hcSphere](#)< dim > &sphere)  
*cpy constructor*
- [hcSphere](#) (const [Vec](#)< dim, hcFloat > &pos, float radius)  
*constructor*
- [~hcSphere](#) ()  
*destructor*
- [hcSphere](#)< dim > & [operator=](#) (const [hcSphere](#)< dim > &other)  
*assignment operator*
- void [init](#) (const [Vec](#)< dim, hcFloat > &pos, float radius)
- void [dump](#) () const

#### 4.31.1 Detailed Description

```
template<uint dim>
class hcSphere< dim >
```

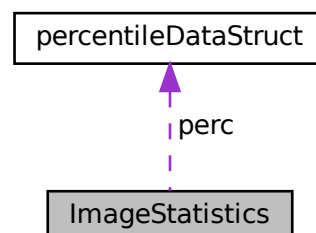
mathematical model and functions for nD-spheres

The documentation for this class was generated from the following files:

- engine/math/hcLine.h
- engine/math/hcSphere.h

## 4.32 ImageStatistics Class Reference

Collaboration diagram for ImageStatistics:





## Public Member Functions

- **ImageStatistics** (const [ImageStatistics](#) &other)
- **ImageStatistics** ([percentiles perc](#), uint [numPixels](#), hcFloat [mean](#), hcFloat [stddev](#))
- [ImageStatistics](#) & **operator=** (const [ImageStatistics](#) &other)  
*assignment operator*
- void **operator+=** (const [ImageStatistics](#) &other)  
*operator for computing "average" statistics*
- void **operator/=** (hcFloat factor)  
*operator for computing "average" statistics*
- void **initNULL** ()
- string **toString** () const
- void **dump** () const

## Public Attributes

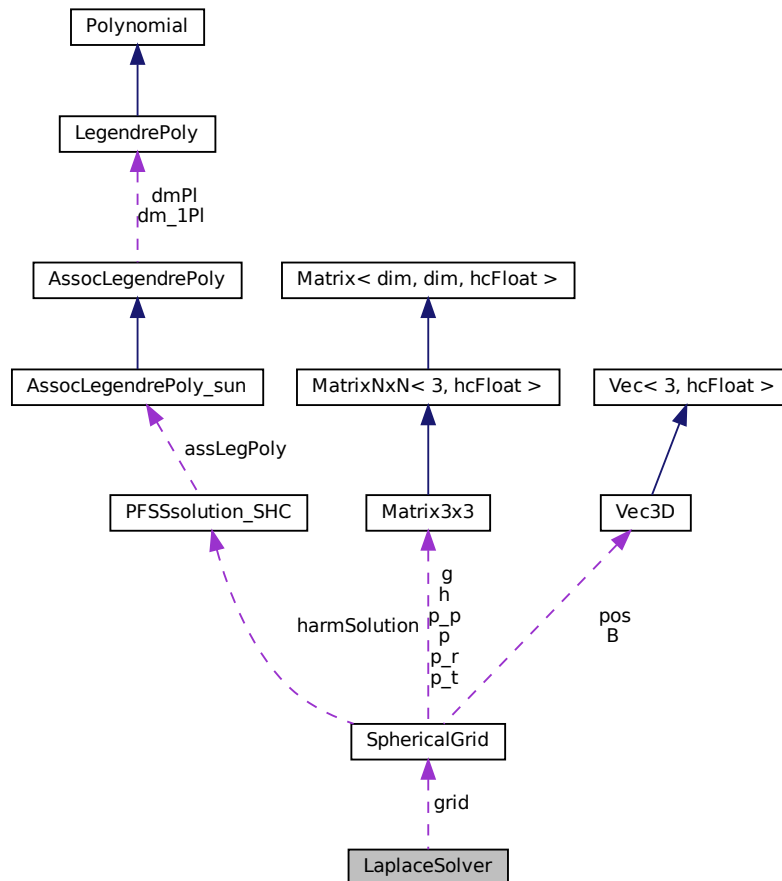
- uint [numPixels](#)  
*number of non-zero pixels*
- [percentiles perc](#)  
*percentiles of content*
- hcFloat [mean](#)  
*mean value of image content*
- hcFloat [stddev](#)  
*standard deviation of mean of image content*

The documentation for this class was generated from the following files:

- src/imageStatistics.h
- src/imageStatistics.cpp

## 4.33 LaplaceSolver Class Reference

Collaboration diagram for LaplaceSolver:



### Public Member Functions

- [LaplaceSolver](#) ()  
*std constructor*
- [LaplaceSolver](#) (const [LaplaceSolver](#) &solver)  
*cpy constructor*
- [LaplaceSolver](#) & **operator=** (const [LaplaceSolver](#) &other)
- bool **init** (bool sinLatGrid, hcFloat maxSinLat, hcFloat r\_ss, uint numR, hcFloat ell)
- void [iterateSpheric](#) ()
- void [iterateElliptic\\_MT](#) ()
- void [iterateElliptic\\_ST](#) ()
- void [iterateElliptic](#) ()
- void [iterate\\_CPU](#) ()
- int [computeSolution](#) (hcImageFITS &photImage)  
*computes solution of Laplace's equation via finite differences*
- void **dump** () const

## Static Public Member Functions

- static void \* [iterateElliptic\\_threadEntry](#) (void \*parameter)  
*thread entry point forelliptic iteration*

## Public Attributes

- [SphericalGrid](#) \* **grid**
- bool [solutionComputed](#)  
*has some computation been done on this?*

### 4.33.1 Member Function Documentation

#### 4.33.1.1 `iterate_CPU()`

```
void LaplaceSolver::iterate_CPU ( )
```

iteration switcher for spheric/elliptic grid with unit/non-unit base vectors

#### 4.33.1.2 `iterateElliptic()`

```
void LaplaceSolver::iterateElliptic ( )
```

iteration procedure for general spheric/elliptic grid with general (non-unit) base vectors

#### 4.33.1.3 `iterateElliptic_MT()`

```
void LaplaceSolver::iterateElliptic_MT ( )
```

iteration procedure for general spheric/elliptic grid with general (non-unit) base vectors, multi-threaded

#### 4.33.1.4 `iterateElliptic_ST()`

```
void LaplaceSolver::iterateElliptic_ST ( )
```

iteration procedure for general spheric/elliptic grid with general (non-unit) base vectors, single-threaded

#### 4.33.1.5 `iterateElliptic_threadEntry()`

```
void * LaplaceSolver::iterateElliptic_threadEntry (
    void * parameter ) [static]
```

thread entry point forelliptic iteration

entry function for multicore PFSS iteration function

#### 4.33.1.6 `iterateSpheric()`

```
void LaplaceSolver::iterateSpheric ( )
```

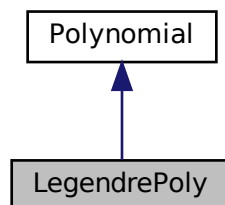
iteration procedure only for spherical grid with unit base vectors

The documentation for this class was generated from the following files:

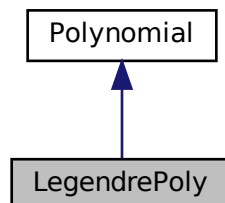
- `src/laplaceSolver.h`
- `src/laplaceSolver.cpp`

## 4.34 LegendrePoly Class Reference

Inheritance diagram for LegendrePoly:



Collaboration diagram for LegendrePoly:



## Public Member Functions

- [LegendrePoly](#) (uint order=0)  
*std constructor*
- [LegendrePoly](#) (const [LegendrePoly](#) &other)  
*cpy constructor*
- [~LegendrePoly](#) ()  
*destructor*
- [LegendrePoly](#) & [operator=](#) (const [LegendrePoly](#) &other)  
*assignment operator*
- void **initNULL** ()
- void **clear** ()
- void **init** (uint n)

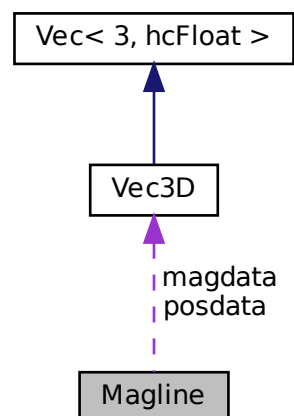
## Additional Inherited Members

The documentation for this class was generated from the following files:

- engine/math/hcFunction.h
- engine/math/hcFunction.cpp

## 4.35 Magline Class Reference

Collaboration diagram for Magline:



## Public Member Functions

- [Magline](#) ()  
*std constructor*
- [Magline](#) (const [Magline](#) &other)  
*cpy constructor*
- virtual [~Magline](#) ()  
*destructor*
- [Magline](#) & [operator=](#) (const [Magline](#) &other)  
*assignment operator*
- void [init](#) ()
- void [initNULL](#) ()
- void [clear](#) ()
- [Vec3D](#) [getMagVec](#) (uint num)  
*returns magnetic vector at given numerical position in array*
- [Vec3D](#) [getPosVec](#) (uint num)  
*returns positional vector (spherical coordinates) at given numerical position in array*
- bool [getValuesAtHeight](#) (hFloat height, [Vec3D](#) &posData, [Vec3D](#) &magData)  
*(linearly) interpolates values at sample points to obtain intermediate values at a specific height*
- int [getAllValuesAtHeight](#) (hFloat height, [Vec3D](#) \*posData, [Vec3D](#) \*magData)  
*returns number of positions where this maglines pierces through a specific height*
- unsigned char [createMaglineThroughPos](#) ([SphericalGrid](#) &grid, const [Vec3D](#) &posParam, bool debug, hFloat epsMin=1E1, hFloat epsMax=1E2)  
*tracks a magnetic field line through a specific position*
- bool [lowerDistLTupperDist](#) (const [Magline](#) &other)  
*checks if the distance between the lower endings of two lines is less than their upper distance*
- bool [isInSameFluxtubeAs](#) (const [Magline](#) &other)  
*calls lowerDistLTupperDist, this criterion is just sufficient*
- bool [exportBinary](#) (std::ofstream &stream)  
*dumps instance into stream*
- bool [importBinary](#) (std::ifstream &stream)  
*imports instance from stream*
- void [dump](#) () const  
*dump data structure to screen*

## Static Public Member Functions

- static void [initStaticMembers](#) ()  
*initialize static member variables*

## Public Attributes

- uint `numSamples`  
*number of points where the magline has been sampled*
- `Vec3D` \* `magdata`  
*array of magnetic field strengths where magline has been sampled (spherical)*
- `Vec3D` \* `posdata`  
*array of positions where magline has been sampled (spherical)*
- bool `closed`  
*does the magline connect two points on the phtotosphere?*
- bool `valid`  
*are there valid values in magdata and posdata?*
- bool `polarity`  
*true if coming out of surface, false if going in, don't care if valid=false*

## Static Public Attributes

- static uint `colorInvalid`
- static uint `colorClosed`
- static uint `colorPositive`
- static uint `colorNegative`

### 4.35.1 Member Function Documentation

#### 4.35.1.1 createMaglineThroughPos()

```
unsigned char Magline::createMaglineThroughPos (
    SphericalGrid & grid,
    const Vec3D & posParam,
    bool debug,
    hcFloat epsMin = 1E1,
    hcFloat epsMax = 1E2 )
```

tracks a magnetic field line through a specific position

produces the magnetic and positional values of a magnetic field line.

#### Parameters

<i>grid</i>	utilized for tracking field line
<i>posParam</i>	position through which to draw the magline (spherical/elliptical coordinates)
<i>debug</i>	gives debugging information throughout computation
<i>stepSize</i>	distance between two data samples in the visualization

**Returns**

error value (see below)

(1 << 0) = 1 maglineDown empty (1 << 1) = 2 maglineDown has too many samples

(1 << 2) = 4 maglineUp empty (1 << 3) = 8 maglineUp has too many samples

(1 << 4) = 16 both directions have no samples (except first point) (1 << 5) = 32 both directions combined have too many samples

(1 << 6) = 64 magline connects two points on the source surface (1 << 7) = 128 start position not valid

**4.35.1.2 getAllValuesAtHeight()**

```
int Magline::getAllValuesAtHeight (
    hcFloat height,
    Vec3D * posData,
    Vec3D * magData )
```

returns number of positions where this maglines pierces through a specific height

**Parameters**

<i>height</i>	heliocentric height where this magline is to be sampled
<i>posData</i>	positions of sampled magline (spherical coordinates)
<i>magData</i>	magnetic direction vectors at height (spherical coordinates)

**Return values**

<i>number</i>	of positions where magline pierces through height if more than MAGLINE_NUM_POSITIONS positions exist, only the first MAGLINE_NUM_POSITIONS will be reported
---------------	---

posData and magData are pre-allocated arrays of size MAGLINE\_NUM\_POSITIONS

**4.35.1.3 getValuesAtHeight()**

```
bool Magline::getValuesAtHeight (
    hcFloat height,
    Vec3D & posData,
    Vec3D & magData )
```

(linearly) interpolates values at sample points to obtain intermediate values at a specific height

**Parameters**

<i>height</i>	heliocentric height where this magline is to be sampled
<i>posData</i>	position of sampled magline (spherical coordinates)
<i>magData</i>	magnetic direction vector at height (spherical coordinates)



#### 4.35.1.4 lowerDistLTupperDist()

```
bool Magline::lowerDistLTupperDist (
    const Magline & other )
```

checks if the distance between the lower endings of two lines is less than their upper distance

lower distance between maglines is less than (LT) the upper distance of the same maglines

##### Parameters

<i>other</i>	Magline to be compared to
--------------	---------------------------

##### Returns

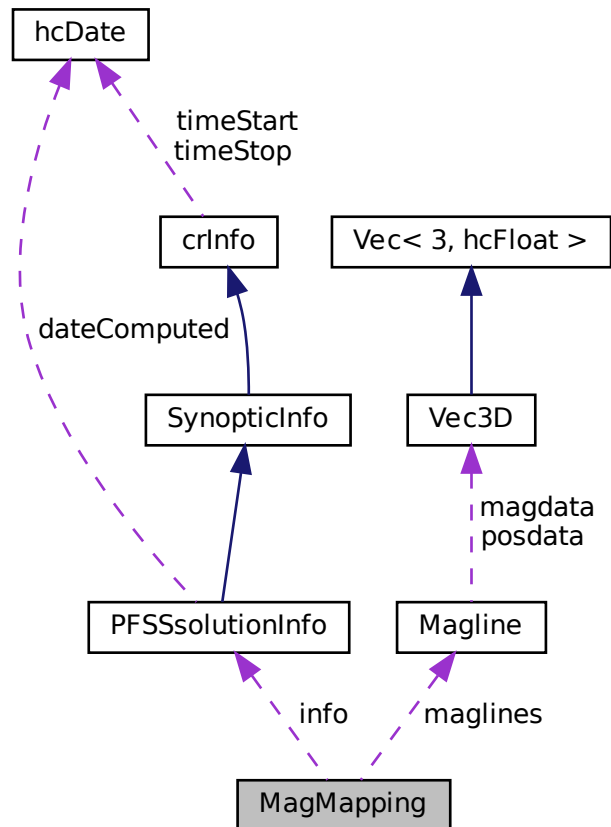
true, if distance at the lower boundary is less than distance at upper boundary, false otherwise

The documentation for this class was generated from the following files:

- src/magline.h
- main.cpp
- src/magline.cpp

## 4.36 MagMapping Class Reference

Collaboration diagram for MagMapping:



### Public Member Functions

- [MagMapping](#) ()  
*std constructor*
- [MagMapping](#) (const [MagMapping](#) &other)  
*cpy constructor*
- [MagMapping](#) (const [PFSSsolutionInfo](#) &info, bool [sinLatFormat](#), bool [compCoords](#), [hcFloat](#) [maxSinLat](#), uint [numTheta](#), uint [numPhi](#), [hcFloat](#) [height](#))  
*constructor*
- virtual [~MagMapping](#) ()  
*destructor*
- [MagMapping](#) & [operator=](#) (const [MagMapping](#) &other)

*assignment operator*

- **Magline & operator()** (uint indTheta, uint indPhi)  
*returns magline at position*
- void **init** (const **PFSSsolutionInfo** &info, bool **sinLatFormat**, bool **compCoords**, hcFloat **maxSinLat**, uint **numTheta**, uint **numPhi**, hcFloat height)  
*initializer*
- bool **isComputed** () const  
*true if mapping has been computed*
- uint **getNumTheta** ()
- uint **getNumPhi** ()
- **Vec3D getCoords** (uint j, uint k)  
*returns the coordinates for pixel (j,k)*
- bool **setCoords** (uint j, uint k, const **Vec3D** &coord)  
*sets the coordinates for pixel (j,k)*
- hcFloat **getHeight** () const
- bool **exportBinary** (const string &filename)  
*exports mapping to binary file*
- bool **importBinary** (const string &filename)  
*imports mapping from binary file*
- hcFloat **diffFootpoints** (**MagMapping** &other)  
*computes averaged squared distance of photospheric footpoints*
- hcFloat **getOpenFlux** ()  
*computes the open magnetic flux through mapping*
- virtual bool **createAtHeight** (const **PFSSsolutionInfo** &info, **LaplaceSolver** &solver, hcFloat height, uint num↔ThetaIn, uint numPhiIn, hcFloat maxSinLatIn, bool **sinLatFormat**, bool **compCoords**)  
*create Mapping at desired height level*
- bool **createAtHeight\_SP** (const **PFSSsolutionInfo** &info, **LaplaceSolver** &solver, hcFloat height, uint num↔ThetaIn, uint numPhiIn, hcFloat maxSinLatIn, bool **sinLatFormat**, bool **compCoords**)  
*single core version of magnetic field line creation*
- bool **createAtHeight\_MP** (const **PFSSsolutionInfo** &info, **LaplaceSolver** &solver, hcFloat height, uint num↔ThetaIn, uint numPhiIn, hcFloat maxSinLatIn, bool **sinLatFormat**, bool **compCoords**)  
*multi core version of magnetic field line creation*
- void **createMappingHeader** (char \*header, hcFloat height, hcFloat \*otherHeights, uint numHeights, hcFloat lowerR, hcFloat upperR)  
*gives human readable explanation of what is in exported ASCII file*
- string **getExpansionFactorComment** ()
- bool **exportImagePolarity** ()  
*creates polarity image of this mapping*
- bool **exportImageFootpoint** (string filename)

*creates polarity image of photospheric footpoints for each magline in this mapping*

- bool [exportASCII](#) (string filename, hcFloat \*heights, uint numHeights, hcFloat lowerR, hcFloat source↔SurfaceR)  
*exports mag mapping with connection to several height levels to txt- and image-file*
- bool [exportImageExpansionFactor](#) ()  
*export expansion factor of magnetic field lines in this map*
- bool [exportImageExpansionFactorMax](#) ()  
*export maximum expansion factor of magnetic field lines in this map*
- bool [exportImageMagfield](#) ()  
*export magnetic field at this height*
- void [dump](#) (uint indent=0)  
*dumps information on instance to stdout with optional indentation*

## Static Public Member Functions

- static void \* [createAtHeight\\_threadEntryPoint](#) (void \*parameter)  
*thread entry point for createAtHeight\_MP*

## Public Attributes

- [PFSSsolutionInfo](#) **info**
- bool [sinLatFormat](#)  
*azimuthal spacing linear in latitude (false, TODO not working) or sine(latitude) (true)*
- hcFloat [maxSinLat](#)  
*sinLat-Boundary in case of sinLatFormat==true*
- bool [compCoords](#)  
*height level in computationalCoords*
- uint [numTheta](#)  
*number of "pixels" in meridional direction*
- uint [numPhi](#)  
*number of "pixels" in zonal direction*
- [Magline](#) \*\* [maglines](#)  
*array of magnetic field lines this mapping consists of*

### 4.36.1 Member Function Documentation

#### 4.36.1.1 createAtHeight()

```
bool MagMapping::createAtHeight (
    const PFSSsolutionInfo & info,
    LaplaceSolver & solver,
    hcFloat height,
    uint numThetaIn,
    uint numPhiIn,
    hcFloat maxSinLatIn,
    bool sinLatFormatIn,
    bool compCoords ) [virtual]
```

create Mapping at desired height level

computed and stored entirely in computational coordinates(vectors, transformation to physical coordinates/vectors is done afterwards when re-importing data

##### Parameters

<i>solver</i>	gives the environment in which maglines shall be created
<i>height</i>	the height above photosphere where equidistant "pixels" are evaluated
<i>numTheta</i>	the number of pixels in theta direction (if 0, the entire mapping is computed in the native grid of solver)
<i>numPhi</i>	the number of pixels in phi direction
<i>maxSinLat</i>	the highest point in mapping
<i>minSinLat</i>	the lowest point in mapping
<i>sinLatGrid</i>	evenly spaced in sinLat or in lat?
<i>compCoords</i>	height given in computational coordinates (true) or world coordinates (false)

##### Returns

success

#### 4.36.1.2 createAtHeight\_MP()

```
bool MagMapping::createAtHeight_MP (
    const PFSSsolutionInfo & info,
    LaplaceSolver & solver,
    hcFloat height,
    uint numTheta,
    uint numPhi,
    hcFloat maxSinLat,
    bool sinLatFormat,
    bool compCoords )
```

multi core version of magnetic field line creation

multi-threaded version of magnetic field line creation

#### 4.36.1.3 createAtHeight\_threadEntryPoint()

```
void * MagMapping::createAtHeight_threadEntryPoint (
    void * parameter ) [static]
```

thread entry point for createAtHeight\_MP

entry function for multicore creation of magnetic field lines

#### 4.36.1.4 diffFootpoints()

```
hcFloat MagMapping::diffFootpoints (
    MagMapping & other )
```

computes averaged squared distance of photospheric footpoints

compares photospheric footpoints of back mapped magnetic field lines

This function only makes sense if it is a backmapping from source surface down to the photosphere

#### 4.36.1.5 exportASCII()

```
bool MagMapping::exportASCII (
    string filename,
    hcFloat * heights,
    uint numHeights,
    hcFloat lowerR,
    hcFloat upperR )
```

exports mag mapping with connection to several height levels to txt- and image-file

outputs textfiles where every line corresponds to one pixel position of the map

the output format is described in the header of the output file

#### 4.36.1.6 getExpansionFactorComment()

```
string MagMapping::getExpansionFactorComment ( )
```

create comment to add to FITS files

#### 4.36.1.7 getHeight()

```
hcFloat MagMapping::getHeight ( ) const
```

returns base height of this map

The documentation for this class was generated from the following files:

- src/magMapping.h
- src/magMapping.cpp

## 4.37 Matrix< rows, cols, T > Class Template Reference

implementation of the mathematical matrix construct, only float values supported so far

```
#include <hcMatrix.h>
```

### Public Member Functions

- [Matrix](#) ()  
*std constructor*
- template<class S >  
[Matrix](#) (const [Matrix](#)< rows, cols, S > &other)  
*copy constructor*
- [Matrix](#) (const [Vec](#)< rows, T > &v1, const [Vec](#)< rows, T > &v2)  
*create column-matrix*
- [Matrix](#) (const [Vec](#)< rows, T > &v1, const [Vec](#)< rows, T > &v2, const [Vec](#)< rows, T > &v3)  
*create column-matrix*
- [~Matrix](#) ()  
*destructor*
- template<class S >  
[Matrix](#) & **operator=** (const [Matrix](#)< rows, cols, S > &other)
- [Matrix](#) & **operator\*=** (T [scale](#))  
*scales the matrix*
- [Matrix](#) & **operator/=** (T [scale](#))  
*scales the matrix*
- [Matrix](#) & **operator+=** (const [Matrix](#)< rows, cols, T > &other)  
*adds another matrix to this*
- [Matrix](#) & **operator-=** (const [Matrix](#)< rows, cols, T > &other)  
*adds another matrix to this*
- [Vec](#)< rows, T > **operator\*** (const [Vec](#)< cols, T > &vec)  
*this \* vec*
- T & **operator()** (uint i, uint j)  
*access to element in matrix at row j, column j*
- T **operator[]** (uint i) const  
*access to content in row-major ordering*
- T **getElement** (uint i, uint j) const  
*access to element in matrix at row j, column j*
- void **loadIdentity** ()  
*load identity matrix*

- void **loadZeroes** ()  
*initialize matrix with zeros*
- void **loadTransMat** (const **Vec**< rows-1, T > &vec)  
*creates a translation matrix in homogeneous coordinates*
- void **switchRows** (uint i, uint j)  
*changes rows i and j*
- void **addRow** (uint dest, uint source, T **scale**)
- void **scale** (T scale)  
*add scale \* row(source) to row(dest)*
- void **scaleRow** (uint row, T **scale**)  
*scales a specific row by scale*
- uint **solveSLE** (**Vec**< rows, hcFloat > &result)  
*solves a system of linear equations using gauss' method*
- int **translate** (const **Vec**< rows-1, T > &vec)  
*assumes homogeneous TF-matrix, translates scene by vec*
- **Matrix**< cols, rows, T > **transpose** ()  
*transposes matrix*
- void **dump** () const
- void **subdump** ()
- template<class S >  
**Matrix**< rows, cols, T > & **operator=** (const **Matrix**< rows, cols, S > &other)

## Public Attributes

- T **content** [rows \*cols]  
*contains the entries of the matrix in row-major ordering*

### 4.37.1 Detailed Description

```
template<uint rows, uint cols, class T>
class Matrix< rows, cols, T >
```

implementation of the mathematical matrix construct, only float values supported so far

Stores entries of a matrix in row-major ordering in array content

### 4.37.2 Member Function Documentation



**4.37.2.1 scale()**

```
template<uint rows, uint cols, class T >
void Matrix< rows, cols, T >::scale (
    T scale )
```

add scale \* row(source) to row(dest)

scales every entry

**4.37.2.2 solveSLE()**

```
template<uint rows, uint cols, class T >
uint Matrix< rows, cols, T >::solveSLE (
    Vec< rows, hCFloat > & result )
```

solves a system of linear equations using gauss' method

Solves a System of Linear Equations ( $Ax=y$ ) posed by the matrix "Ay" for x, where the rightmost column is interpreted as the solution vector y. The Gaussian elimination algorithm is used. So far, only unique solutions are stored in the vector result. The matrix Ay is not altered but copied to a local object

**Return values**

0	there is no solution or ill posed problem
1	unique solution, stored now in result
2	there is an infinte number of solution

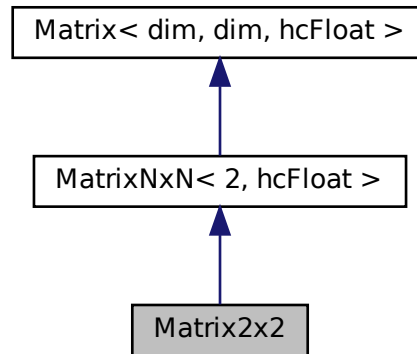
only in case 1 does the result vector contain useful data

The documentation for this class was generated from the following file:

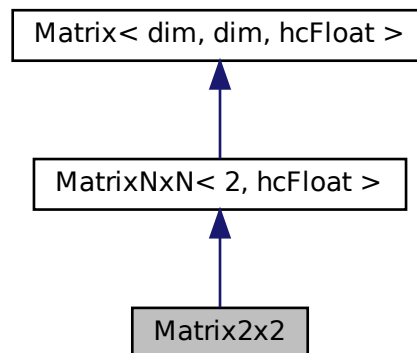
- engine/math/hcMatrix.h

## 4.38 Matrix2x2 Class Reference

Inheritance diagram for Matrix2x2:



Collaboration diagram for Matrix2x2:



### Public Member Functions

- [Matrix2x2](#) ()  
*std constructor*
- [Matrix2x2](#) (const [Matrix2x2](#) &other)  
*cpy constructor*
- template<class S >  
[Matrix2x2](#) (const [MatrixNxN](#)< 2, S > &other)

*pseudo cpy constructor*

- [Matrix2x2](#) & **operator=** (const [Matrix2x2](#) &other)
- template<class S >  
[Matrix2x2](#) & **operator=** (const [MatrixNxN](#)< 2, S > &other)
- template<class S >  
[Matrix2x2](#) & **operator=** (const [Matrix](#)< 2, 2, S > &other)
- template<class S >  
void **scalex** (S scale)
- template<class S >  
void **scaley** (S scale)
- template<class S >  
void **scale** (S scalex, S scaley)

## Additional Inherited Members

The documentation for this class was generated from the following files:

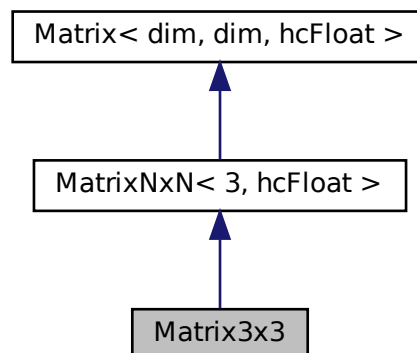
- engine/math/hcMatrix.h
- engine/math/hcMatrix.cpp

## 4.39 Matrix3x3 Class Reference

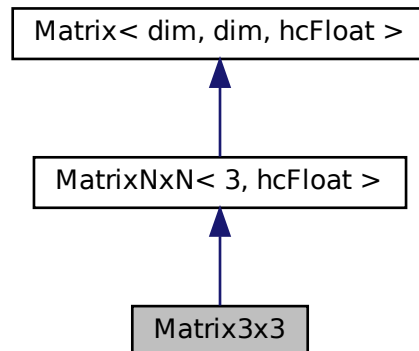
implements a 3x3 matrix for use, e.g., with homogeneous 2D space

```
#include <hcMatrix.h>
```

Inheritance diagram for Matrix3x3:



Collaboration diagram for Matrix3x3:



## Public Member Functions

- **Matrix3x3** (const [Matrix3x3](#) &other)
- template<class S >  
**Matrix3x3** (const [MatrixNxN](#)< 3, S > &other)
- template<class S >  
**Matrix3x3** (const [Vec](#)< 3, S > &vec1, const [Vec](#)< 3, S > &vec2, const [Vec](#)< 3, S > &vec3)
- [Matrix3x3](#) & **operator=** (const [Matrix3x3](#) &other)
- template<class S >  
[Matrix3x3](#) & **operator=** (const [MatrixNxN](#)< 3, S > &other)
- void **convertSphericalToCartesian** (const [Vec3D](#) &cartPos)
- void **convertCartesianToSpherical** (const [Vec3D](#) &cartPos)
- template<class S >  
void [scalex](#) (S scale)  
*loads the conversion matrix to convert from cartesian coords to spherical coords*
- template<class S >  
void **scaley** (S scale)
- template<class S >  
void **scalez** (S scale)
- template<class S >  
void **scale** (S [scalex](#), S scaley, S scalez)
- template<class S >  
void **loadRotationX** (S theta)
- template<class S >  
void **loadRotationY** (S theta)
- template<class S >  
void **loadRotationZ** (S theta)
- template<class S >  
void **rotateAroundAxis** ([Vec3D](#) axis, S angle)
- template<class S >  
void **loadEulerTransform** (S omega, S theta, S phi)

## Additional Inherited Members

### 4.39.1 Detailed Description

implements a 3x3 matrix for use, e.g., with homogeneous 2D space

The documentation for this class was generated from the following files:

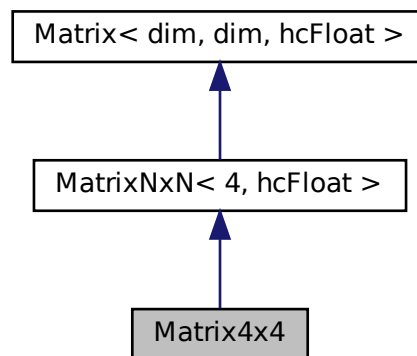
- engine/math/hcMatrix.h
- engine/math/hcMatrix.cpp

## 4.40 Matrix4x4 Class Reference

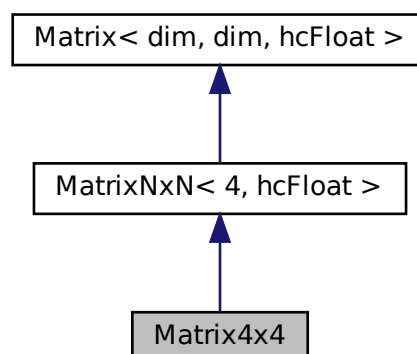
implements a 4x4 matrix for use, e.g., with homogeneous 3D space

```
#include <hcMatrix.h>
```

Inheritance diagram for Matrix4x4:



Collaboration diagram for Matrix4x4:



## Public Member Functions

- [Matrix4x4](#) ()  
*std constructor*
- [Matrix4x4](#) (const [Matrix4x4](#) &other)  
*cpy constructor*
- template<class S >  
[Matrix4x4](#) (const [MatrixNxN](#)< 4, S > &other)  
*pseudo-cpy constructor*
- [~Matrix4x4](#) ()  
*std constructor*
- [Matrix4x4](#) & **operator=** (const [Matrix4x4](#) &other)
- template<class S >  
[Matrix4x4](#) & **operator=** (const [MatrixNxN](#)< 4, S > &other)
- void **loadTFMatrix** (const [Vec3D](#) &right, const [Vec3D](#) &up, const [Vec3D](#) &back, const [Vec3D](#) &pos)
- template<class S >  
void **scalex** (S scale)
- template<class S >  
void **scaley** (S scale)
- template<class S >  
void **scalez** (S scale)
- template<class S >  
void **scalew** (S scale)
- template<class S >  
void **scale** (S scalex, S scaley, S scalez, S scalew)
- template<class S >  
void **rotatex** (S phi)
- template<class S >  
void **rotatey** (S phi)
- template<class S >  
void **rotatez** (S phi)
- void **rotateAtoB** (const [Vec3D](#) a, const [Vec3D](#) b)  
*creates a rotation matrix that rotates a onto b*
- template<class S >  
void **translate** (S x, S y, S z)
- void **translate** (const [Vec](#)< dim-1, T > &v)  
*assumes homogeneous TF-matrix, translates along vec v in N-1 dimensions*

## Additional Inherited Members

### 4.40.1 Detailed Description

implements a 4x4 matrix for use, e.g., with homogeneous 3D space

The documentation for this class was generated from the following files:

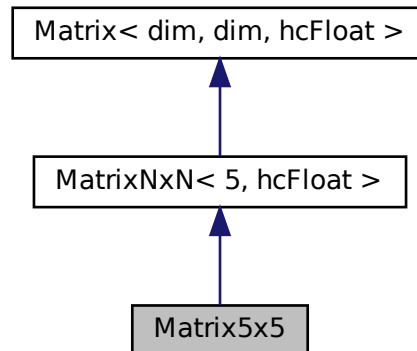
- engine/math/hcMatrix.h
- engine/math/hcMatrix.cpp

## 4.41 Matrix5x5 Class Reference

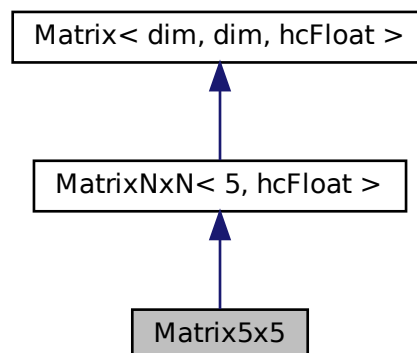
implements a 5x5 matrix for use, e.g., with homogeneous 4D space

```
#include <hcMatrix.h>
```

Inheritance diagram for Matrix5x5:



Collaboration diagram for Matrix5x5:



### Public Member Functions

- **Matrix5x5** (const [Matrix5x5](#) &other)
- template<class S >  
**Matrix5x5** (const [MatrixNxN](#)< 5, S > &other)
- [Matrix5x5](#) & **operator=** (const [Matrix5x5](#) &other)

- `template<class S >`  
`Matrix5x5 & operator=` (const `MatrixNxN< 5, S >` &other)
- `void loadTFMatrix` (const `Vec4D` &right, const `Vec4D` &up, const `Vec4D` &back, const `Vec4D` &over, const `Vec4D` &pos)
- `template<class S >`  
`void rotateXY` (S phi)
- `template<class S >`  
`void rotateXZ` (S phi)
- `template<class S >`  
`void rotateYZ` (S phi)
- `template<class S >`  
`void rotateXW` (S phi)
- `template<class S >`  
`void rotateYW` (S phi)
- `template<class S >`  
`void rotateZW` (S phi)
- `template<class S >`  
`void translate` (S x, S y, S z)

## Additional Inherited Members

### 4.41.1 Detailed Description

implements a 5x5 matrix for use, e.g., with homogeneous 4D space

TODO: not tested

The documentation for this class was generated from the following files:

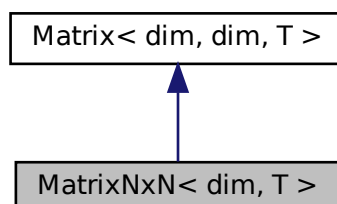
- `engine/math/hcMatrix.h`
- `engine/math/hcMatrix.cpp`

## 4.42 `MatrixNxN< dim, T >` Class Template Reference

implementation of a square matrix

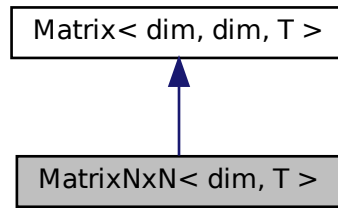
```
#include <hcMatrix.h>
```

Inheritance diagram for `MatrixNxN< dim, T >`:





Collaboration diagram for MatrixNxN< dim, T >:



## Public Member Functions

- `MatrixNxN ()`  
*std constructor*
- `template<class S > MatrixNxN (const MatrixNxN< dim, S > &other)`  
*cpy constructor*
- `~MatrixNxN ()`  
*destructor*
- `MatrixNxN< dim, T > & operator= (const MatrixNxN< dim, T > &other)`  
*assignment operator*
- `double det ()`  
*computes determinant of matrix (double precision)*
- `int invert ()`  
*computes inverse of matrix*
- `void loadIdentity ()`  
*initializes matrix with ones on main diagonal*
- `void scaleAllDim (T scale)`  
*applies a scale operation on all dimensions*
- `void scaleHom (T scale)`  
*assumes homogeneous TF-matrix, scales the scene isotropically*
- `void scaleAxis (uint n, T scale)`  
*assumes homogeneous TF-matrix, scales along a specific axis*
- `void translate (const Vec< dim-1, T > &v)`  
*assumes homogeneous TF-matrix, translates along vec v in N-1 dimensions*
- `void dump () const`

## Additional Inherited Members

### 4.42.1 Detailed Description

```
template<uint dim, class T>
class MatrixNxN< dim, T >
```

implementation of a square matrix

The documentation for this class was generated from the following file:

- engine/math/hcMatrix.h

## 4.43 percentileDataStruct Struct Reference

### Public Member Functions

- **percentileDataStruct** (const string &perc00, const string &perc01, const string &perc02, const string &perc05, const string &perc10, const string &perc20, const string &perc25, const string &perc30, const string &perc40, const string &perc50, const string &perc60, const string &perc70, const string &perc75, const string &perc80, const string &perc90, const string &perc95, const string &perc98, const string &perc99, const string &perc100)
- [percentileDataStruct](#) & **operator=** (const [percentileDataStruct](#) &other)
- void **operator+=** (const [percentileDataStruct](#) &other)
- void **operator/=** (hcFloat factor)
- string **toString** () const
- void **dump** ()

### Public Attributes

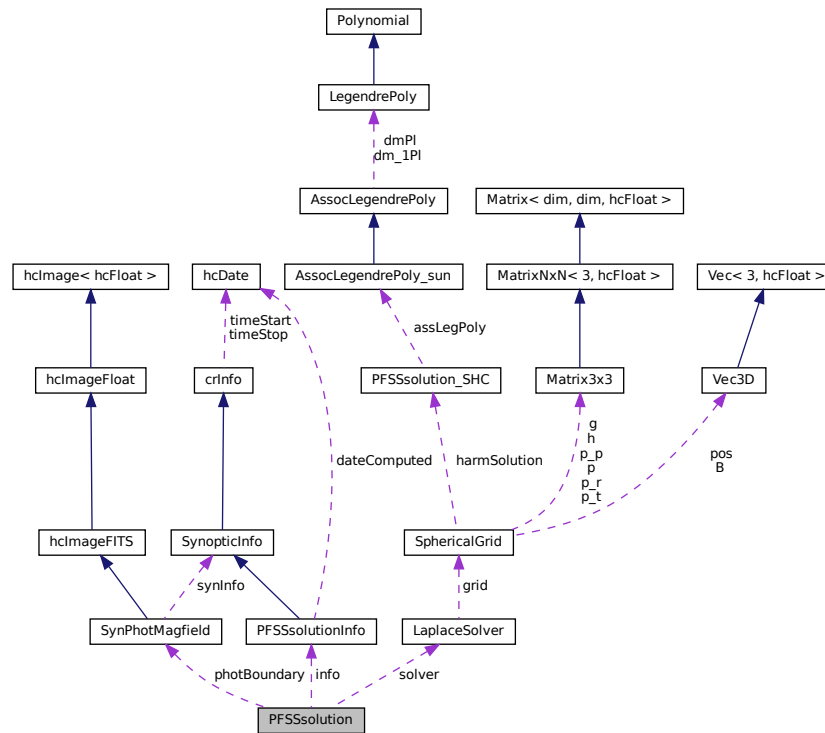
- hcFloat **perc00**
- hcFloat **perc01**
- hcFloat **perc02**
- hcFloat **perc05**
- hcFloat **perc10**
- hcFloat **perc20**
- hcFloat **perc25**
- hcFloat **perc30**
- hcFloat **perc40**
- hcFloat **perc50**
- hcFloat **perc60**
- hcFloat **perc70**
- hcFloat **perc75**
- hcFloat **perc80**
- hcFloat **perc90**
- hcFloat **perc95**
- hcFloat **perc98**
- hcFloat **perc99**
- hcFloat **perc100**

The documentation for this struct was generated from the following file:

- engine/hcTools.h

## 4.44 PFSSsolution Class Reference

Collaboration diagram for PFSSsolution:



### Public Member Functions

- `PFSSsolution ()`  
*std constructor*
- `PFSSsolution (const PFSSsolution &other)`  
*cpy constructor*
- `void initNULL ()`
- `void clear ()`
- `void init ()`
- `bool isDirSet ()`  
*checks if output directory is set*
- `string getFilenamePhotMagfield ()`  
*get filename for photospheric synoptic magfield file*
- `string getFilenameGrid ()`  
*get filename for binary grid data*
- `string getFilenameConfig ()`  
*get filename for configuration file*

- [PFSSsolution](#) & [operator=](#) (const [PFSSsolution](#) &other)  
*assignment operator*
- [LaplaceSolver](#) & [getSolver](#) ()  
*returns reference to solver member variable*
- bool [loadPhotBoundary](#) (const string &filename, uint scaleMethod=7)  
*loads magnetic map of photosphere and initializes this object*
- bool [save](#) ()  
*stores solution computed by solver into file located at path*
- bool [load](#) (const string &cfgFN)  
*loads precomputed solution into this object*
- bool [computeKielSHC](#) (const string &filename, uint order, hcFloat r\_ss, uint resCompR)  
*compute solution according to Spherical Harmonic Coefficient approach*
- bool [computeKielGrid](#) (const string &filename, const string &optionalID, hcFloat r\_ss, uint compResR, hcFloat surfShapeA, uint scaleMethod=7)  
*computes finite difference laplace equation via GPU or CPU*
- bool [mapHeightLevel](#) (hcFloat height, hcFloat maxSinLat, uint numTheta, uint numPhi, bool sinLatFormat=true, bool computationalCoords=true)  
*routine for computing magnetic height maps in memory*
- string [getMagneticMappingFilename](#) (const [MagMapping](#) &magmap)  
*getting filename for export/import of magnetic mappings*
- bool [multiMapSolution](#) (uint numTheta, uint numPhi, bool computeIntermediateHeightLevels, bool sinLatFormat, bool computationalCoords)  
*computes magnetic field line maps to several height levels*
- bool [computeAndMapKielSHC](#) (const string &filename, uint order, hcFloat r\_ss, uint compResR, uint mapResTheta, uint mapResPhi, bool mapIntermediateHeights)  
*computes spherical harmonic coefficients for given photospheric magfield*
- bool [computeAndMapKielGrid](#) (const string &filename, const char \*optionalID, hcFloat r\_ss, uint compResR, uint mapResTheta, uint mapResPhi, bool mapIntermediateHeights, hcFloat ellipticity, uint scaleMethod=7)  
*computes and maps Kiel grid approach*
- bool [loadAndMapKielGrid](#) (const string &filename, uint mapResTheta, uint mapResPhi, hcFloat height=0.0)  
*loads Kiel grid solution and computes mapping*
- bool [loadAndMapStanfordSHC](#) (const char \*photFilename, const char \*StanfordCoeffFilename, uint compResR, uint imgThetaRes, uint imgPhiRes, bool mapIntermediateHeights)  
*loads Stanford SHC file and computes mapping*
- bool [batchKielSHC](#) (const string &inDir, hcFloat r\_ss, uint resCompR, uint order)  
*computes and maps Kiel SHC approach for all files in inDir*
- bool [batchKielGrid](#) (const string &inDir, hcFloat r\_ss, uint resCompR, hcFloat ellipticity=1.0)  
*computes and maps Kiel grid approach for all files in inDir*
- bool [batchMap](#) (uint resMapTheta, uint resMapPhi, hcFloat height=0.0)

*compute maps for all computes solutions in dirData*

- void [paramStudyThresh](#) (const char \*inDir, uint compRadialRes, uint compThetaRes, uint compPhiRes, uint imgThetaRes, uint imgPhiRes)  
*analyses impact of solver threshold level on results*
- void [paramStudyRss](#) (const char \*inDir, uint compRadialRes, uint compThetaRes, uint compPhiRes, uint imgThetaRes, uint imgPhiRes)  
*analyses impact of source surface height on results*
- void [paramStudyRes](#) ()  
*analyzes impact of grid point numbers on results*
- void [paramStudyScaleMethod](#) (const char \*filename)  
*analyses impact on image scaling algorithm on results*
- void [paramStudyRadialRes](#) (const char \*filename)  
*parameter study regarding radial resolution of computational grid*
- void [compareAnaInter](#) (const char \*inDir)  
*comparison study regarding analytical and interpolated magnetic field line tracking*
- void [compareSHCorders](#) (const string &inDir, hcFloat r\_ss, uint compRadialRes, uint imgThetaRes, uint imgPhiRes, bool mapIntermediateHeights=false)
- void [compareRdist](#) (const char \*inDir, uint compRadialRes, uint compThetaRes, uint compPhiRes, uint imgThetaRes, uint imgPhiRes)
- void [compare2Stanford](#) (const char \*photFilename, const char \*StanfordCoeffFilename, uint compRadialRes, uint compThetaRes, uint compPhiRes, bool rDistribution, hcFloat geometricFactor, uint imgThetaRes, uint imgPhiRes, bool mapIntermediateHeights)  
*computes grid method, shc method and loads Stanford file for comparison*
- bool [footpointAnalysis](#) (hcFloat latThresh=INFINITY)
- bool [batchFootpointAnalysis](#) (const string &inDir, hcFloat r\_ss, uint compResR, methodID [method](#), hcFloat ellipticity, uint orderSHC, hcFloat latThresh=INFINITY)  
*computes PFSS according to SHC approach and performs footpoint analysis on EIT maps*
- bool [batchFootpointAnalysisAllComputed](#) (hcFloat latThresh=INFINITY)  
*(re-)computes footpoint analysis for all solutions stored in outDir*
- void [dump](#) () const

## Public Attributes

- methodID [method](#)  
*TODO: info? SHC, numeric spheric or numeric elliptic*
- [LaplaceSolver](#) [solver](#)  
*the actual solver*
- [PFSSsolutionInfo](#) [info](#)  
*information about solution*
- [SynPhotMagfield](#) [photBoundary](#)  
*boundary condition for solver*

### 4.44.1 Member Function Documentation

#### 4.44.1.1 batchKielGrid()

```
bool PFSSsolution::batchKielGrid (
    const string & inDir,
    hcFloat r_ss,
    uint resCompR,
    hcFloat ellipticity = 1.0 )
```

computes and maps Kiel grid approach for all files in inDir

opens inDir and computes PFSS model for each photospheric map as well as magnetic field line maps. This function only does the computational work, for the GUI version please see HelioMagfield::batchRotationComputing

##### Parameters

<i>inDir</i>	direcory to be worked upon
<i>r_ss</i>	heliocentric position of source surface (m)
<i>resCompR</i>	radial resolution of computational grid
<i>ellipticity</i>	ellipticity of source surface (default: 1.0 - spherical)

#### 4.44.1.2 batchKielSHC()

```
bool PFSSsolution::batchKielSHC (
    const string & inDir,
    hcFloat r_ss,
    uint resCompR,
    uint order )
```

computes and maps Kiel SHC approach for all files in inDir

##### Parameters

<i>inDir</i>	direcory to be worked upon
<i>r_ss</i>	heliocentric position of source surface (m)
<i>resCompR</i>	radial resolution of computational grid
<i>order</i>	maximum principal order of SHC approach

#### 4.44.1.3 computeAndMapKielGrid()

```
bool PFSSsolution::computeAndMapKielGrid (
```

```

const string & filename,
const char * optionalID,
hcFloat r_ss,
uint compResR,
uint mapResTheta,
uint mapResPhi,
bool mapIntermediateHeights,
hcFloat ellipticity,
uint scaleMethod = 7 )

```

computes and maps Kiel grid approach

#### Parameters

<i>filename</i>	filename of the photospheric magnetogram to be analyzed
<i>optionalID</i>	optional identifier to be used in output filenames
<i>r_ss</i>	heliocentric position of surce surface
<i>compResR</i>	radial resolution of computational grid
<i>compResTheta</i>	meridional resolutions of computational grid
<i>compResPhi</i>	zonal resolution of computational grid
<i>rDist</i>	distribution of radial grid shells (use 0 for equidistant spacing in r-direction)
<i>geomIncFactor</i>	geometric increment factor for non-equidistant r-spacing
<i>mapResTheta</i>	meridional resolution of magnetic mapping
<i>mapResPhi</i>	zonal resolution of magnetic mapping
<i>mapIntermediateHeights</i>	true, if for each r-shell of the comp grid a magnetic mapping is to be computed
<i>surfaceShape</i>	0 - spherical grid, 1 - elliptical grid
<i>surfShapeA</i>	stretching parameter for elliptical grid
<i>scaleMethod</i>	rescaling algorithm for photospheric data

#### 4.44.1.4 computeAndMapKielSHC()

```

bool PFSSsolution::computeAndMapKielSHC (
    const string & filename,
    uint order,
    hcFloat r_ss,
    uint compResR,
    uint mapResTheta,
    uint mapResPhi,
    bool mapIntermediateHeights )

```

computes spherical harmonic coefficients for given photospheric magfield

Even though the magnetic field is to be computed analytically employing the spherical harmonic coefficient approach, further processing (like mapping of magnetic field lines from source surface down to the photosphere) is done on a 3D grid.

#### Parameters

<i>filename</i>	synoptic photospheric magnetogram to be loaded
-----------------	--

## Parameters

<i>order</i>	maximum order of coefficients to be computed
<i>r_ss</i>	heliocentric distance of source surface (in m)
<i>compResR</i>	radial resolution of computational grid
<i>compResTheta</i>	meridional resolutions of computational grid
<i>compResPhi</i>	zonal resolution of computational grid
<i>rDist</i>	distribution of radial grid shells (use 0 for equidistant spacing in r-direction)
<i>geomIncFactor</i>	geometric increment factor for non-equidistant r-spacing
<i>mapResTheta</i>	meridional resolution of magnetic mapping
<i>mapResPhi</i>	zonal resolution of magnetic mapping
<i>mapIntermediateHeights</i>	true, if for each r-shell of the comp grid a magnetic mapping is to be computed

## Returns

true, if computation of PFSS and mapping successful

**4.44.1.5 load()**

```
bool PFSSsolution::load (
    const string & cfgFN )
```

loads precomputed solution into this object

given a rotation/instrument-cfg filename and a path where the solution is stored, this function imports a previously computed solution from disk \*

**4.44.1.6 loadAndMapKielGrid()**

```
bool PFSSsolution::loadAndMapKielGrid (
    const string & filename,
    uint mapResTheta,
    uint mapResPhi,
    hcFloat height = 0.0 )
```

loads Kiel grid solution and computes mapping

## Parameters

<i>filename</i>	configuration file to be loaded
<i>mapResTheta</i>	meridional resolution of magnetic mapping
<i>mapResPhi</i>	zonal resolution of magnetic mapping
<i>mapIntermediateHeights</i>	true, if for each r-shell of the comp grid a magnetic mapping is to be computed *
<i>height</i>	height to be mapped or 0.0 for source surface and photosphere



#### 4.44.1.7 loadAndMapStanfordSHC()

```
bool PFSSsolution::loadAndMapStanfordSHC (
    const char * photFilename,
    const char * StanfordCoeffFilename,
    uint compResR,
    uint mapResTheta,
    uint mapResPhi,
    bool mapIntermediateHeights )
```

loads Stanford SHC file and computes mapping

A computational grid is necessary for mapping magnetic field lines

##### Parameters

<i>photFilename</i>	Photospheric synoptic magnetogram
<i>StanfordCoeffFilename</i>	Spherical harmonic coefficients to be evaluated
<i>compResR</i>	radial resolution of computational grid
<i>compResTheta</i>	meridional resolutions of computational grid
<i>compResPhi</i>	zonal resolution of computational grid
<i>rDist</i>	distribution of radial grid shells (use 0 for equidistant spacing in r-direction)
<i>geomIncFactor</i>	geometric increment factor for non-equidistant r-spacing
<i>mapResTheta</i>	meridional resolution of magnetic mapping
<i>mapResPhi</i>	zonal resolution of magnetic mapping
<i>mapIntermediateHeights</i>	true, if for each r-shell of the comp grid a magnetic mapping is to be computed

#### 4.44.1.8 mapHeightLevel()

```
bool PFSSsolution::mapHeightLevel (
    hcFloat height,
    hcFloat maxSinLat,
    uint numTheta,
    uint numPhi,
    bool sinLatFormat = true,
    bool compCoords = true )
```

routine for computing magnetic height maps in memory

Magnetic field lines are invoked at a given height in a quasi equidistant manner (sine-latitude grid). The field lines are then traced through the heliosphere and sampled at other given heights. This way we can track the "evolution" of the magnetic field from different starting points.

**Parameters**

<i>height</i>	at which quasi-equidistant field lines are to be invoked
<i>maxSinLat</i>	highest sine(latitude)
<i>numTheta</i>	number of grid points in latitudinal direction
<i>numPhi</i>	number of grid points in azimuthal direction

**4.44.1.9 multiMapSolution()**

```
bool PFSSsolution::multiMapSolution (
    uint numTheta,
    uint numPhi,
    bool computeIntermediateHeightLevels,
    bool sinLatFormat,
    bool compCoords )
```

computes magnetic field line maps to several height levels

creates magnetic field maps with footpoints at several heights and mapped to all other heights in this list.

**4.44.1.10 paramStudyRes()**

```
void PFSSsolution::paramStudyRes ( )
```

analyzes impact of grid point numbers on results

conducts a parameter study of the resolution of the numerical grid

**4.44.1.11 paramStudyRss()**

```
void PFSSsolution::paramStudyRss (
    const char * inDir,
    uint compRadialRes,
    uint compThetaRes,
    uint compPhiRes,
    uint imgThetaRes,
    uint imgPhiRes )
```

analyses impact of source surface height on results

conducts a parameter study of the height of the source surface on files in directory inDir

**4.44.1.12 paramStudyThresh()**

```
void PFSSsolution::paramStudyThresh (
    const char * filename,
    uint compRadialRes,
    uint compThetaRes,
    uint compPhiRes,
    uint imgThetaRes,
    uint imgPhiRes )
```

analyses impact of solver threshold level on results

conducts a parameter study of the solver threshold level on input file named filename

**4.44.1.13 save()**

```
bool PFSSsolution::save ( )
```

stores solution computed by solver into file located at path

stores computed PFSS solution to disk and stores meta-information into cfg-files (cfg file for information on this specific solution and one entry in super-cfg so that the program knows that there is a solution for this specific Carrington rotation and instrument)

The documentation for this class was generated from the following files:

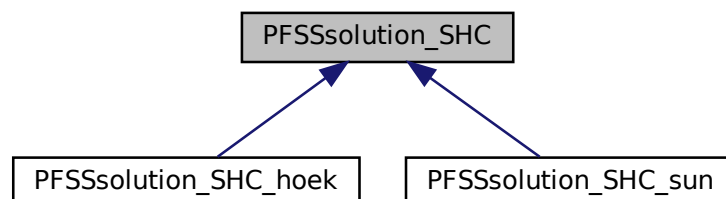
- src/pfssSolution.h
- src/pfssSolution.cpp
- src/pfssSolution\_batches.cpp

**4.45 PFSSsolution\_SHC Class Reference**

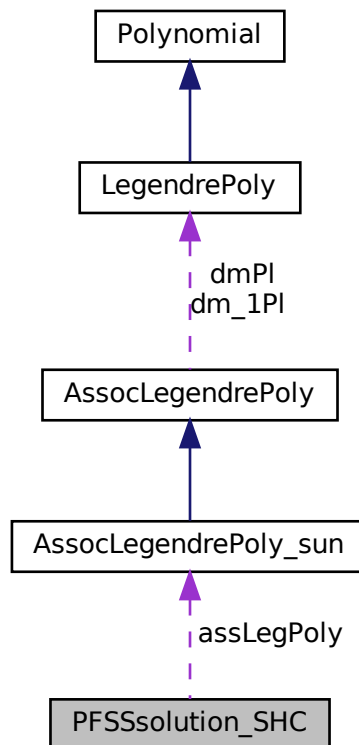
solution of the PFSS model via spherical harmonic coefficients (SHC)

```
#include <pfss.h>
```

Inheritance diagram for PFSSsolution\_SHC:



Collaboration diagram for PFSSsolution\_SHC:



## Public Member Functions

- [PFSSsolution\\_SHC](#) (const char \*filename, bool WSOfile, hcFloat r\_ss)  
*constructor*
- [PFSSsolution\\_SHC](#) ()  
*std constructor*
- [PFSSsolution\\_SHC](#) (const [PFSSsolution\\_SHC](#) &other)  
*cpy constructor*
- virtual [~PFSSsolution\\_SHC](#) ()  
*destructor*
- [PFSSsolution\\_SHC](#) & [operator=](#) (const [PFSSsolution\\_SHC](#) &other)  
*assignment operator*
- void **initNULL** ()
- void **clear** ()
- virtual void **init** (uint order, hcFloat r\_ss)=0
- virtual void [eval](#) (const [Vec3D](#) &pos, [Vec3D](#) &result)=0

*evaluates the magnetic field at spherical position pos*

- bool [importCoefficients](#) (const char \*filename, bool WSOfile, hcFloat r\_ss)  
*reads coefficients from human readable file*
- void [exportCoefficients](#) (const char \*filename)  
*writes coefficients to human readable file*
- void [determineCoefficientsFromPhotMagfield](#) (uint order, hcFloat r\_ss, [SynPhotMagfield](#) &photMagfield)  
*computes spherical harmonic coefficients from synoptic magnetogram*

## Public Attributes

- [AssocLegendrePoly\\_sun](#) \*\* [assLegPoly](#)  
*contains all the associated Legendre polynomials required for the solution*
- uint [coeffOrder](#)  
*highest order of assoc. Legendre [Polynomial](#) utilized*
- hcFloat \*\* [g](#)  
*g coefficients*
- hcFloat \*\* [h](#)  
*h coefficients*
- hcFloat [sourceSurfaceFactor](#)  
*location of source surface in multiples of r\_sol*

### 4.45.1 Detailed Description

solution of the PFSS model via spherical harmonic coefficients (SHC)

### 4.45.2 Member Function Documentation

#### 4.45.2.1 [determineCoefficientsFromPhotMagfield\(\)](#)

```
void PFSSsolution_SHC::determineCoefficientsFromPhotMagfield (
    uint order,
    hcFloat r_ss,
    SynPhotMagfield & photMagfield )
```

computes spherical harmonic coefficients from synoptic magnetogram

computes spherical harmonic coefficients from synoptic magnetogram

## Parameters

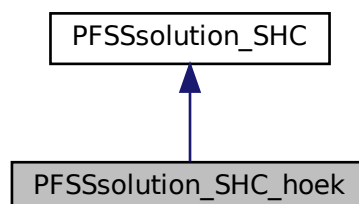
<i>order</i>	maximum order of coefficients to be computed
<i>r_ss</i>	heliocentric position of source surface (in m)
<i>photMagfield</i>	data structure containing synoptic photospheric (LOS) magnetic field strength

The documentation for this class was generated from the following files:

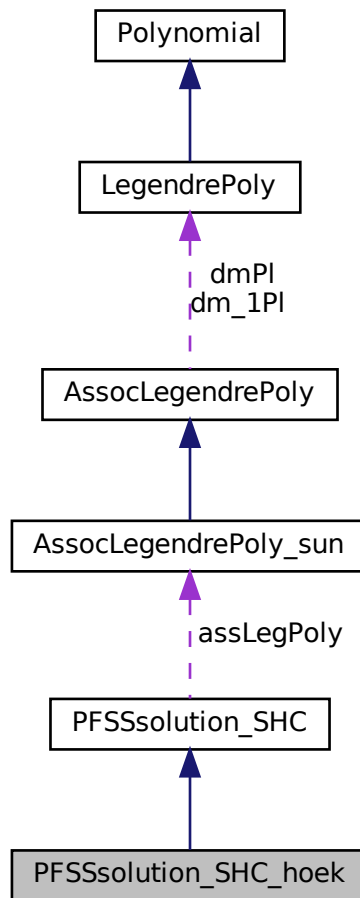
- src/pfss.h
- src/pfss.cpp

## 4.46 PFSSsolution\_SHC\_hoek Class Reference

Inheritance diagram for PFSSsolution\_SHC\_hoek:



Collaboration diagram for PFSSsolution\_SHC\_hoek:



## Public Member Functions

- `PFSSsolution_SHC_hoek` (const `PFSSsolution_SHC_hoek` &other)
- `PFSSsolution_SHC_hoek` & **operator=** (const `PFSSsolution_SHC_hoek` &other)
- `PFSSsolution_SHC_hoek` **operator-** (const `PFSSsolution_SHC_hoek` &other)  
*difference between two solutions (difference of coefficients)*
- virtual void **init** (uint order, hcFloat r\_ss)
- virtual void **eval** (const `Vec3D` &pos, `Vec3D` &result)  
*evaluates the magnetic field at spherical position pos*

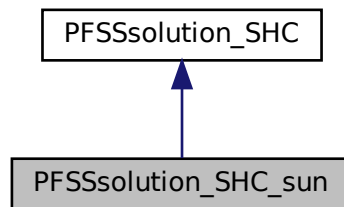
## Additional Inherited Members

The documentation for this class was generated from the following files:

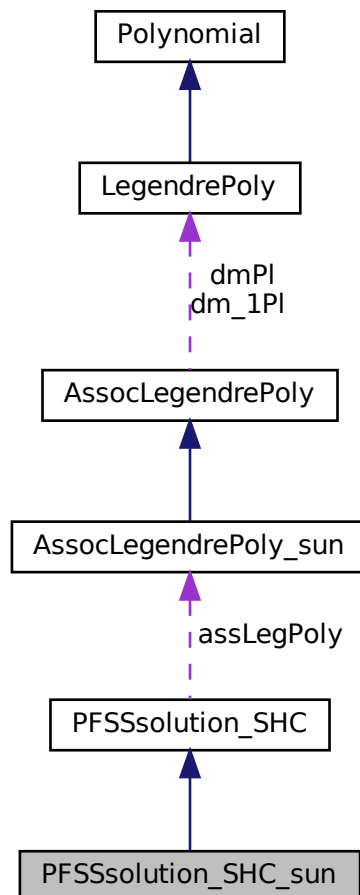
- `src/pfss.h`
- `src/pfss.cpp`

## 4.47 PFSSsolution\_SHC\_sun Class Reference

Inheritance diagram for PFSSsolution\_SHC\_sun:



Collaboration diagram for PFSSsolution\_SHC\_sun:





## Public Member Functions

- [PFSSsolution\\_SHC\\_sun](#) ()  
*std constructor*
- [PFSSsolution\\_SHC\\_sun](#) (const [PFSSsolution\\_SHC\\_sun](#) &other)  
*cpy constructor*
- [~PFSSsolution\\_SHC\\_sun](#) ()  
*destructor*
- [PFSSsolution\\_SHC\\_sun](#) & [operator=](#) (const [PFSSsolution\\_SHC\\_sun](#) &other)  
*assignment operator*
- [PFSSsolution\\_SHC\\_sun](#) [operator-](#) (const [PFSSsolution\\_SHC\\_sun](#) &other)  
*difference between two solutions (difference of coefficients)*
- virtual void [init](#) (uint order, hcFloat r\_ss)
- virtual void [eval](#) (const [Vec3D](#) &pos, [Vec3D](#) &result)  
*evaluates the magnetic field at spherical position pos*

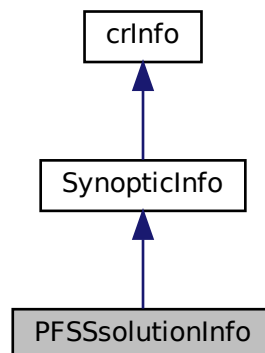
## Additional Inherited Members

The documentation for this class was generated from the following files:

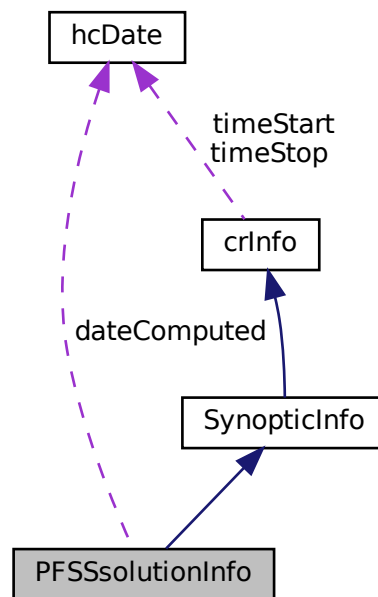
- src/pfss.h
- src/pfss.cpp

## 4.48 PFSSsolutionInfo Class Reference

Inheritance diagram for PFSSsolutionInfo:



Collaboration diagram for PFSSsolutionInfo:



## Public Member Functions

- `PFSSsolutionInfo ()`  
*std constructor*
- `PFSSsolutionInfo (const PFSSsolutionInfo &other)`  
*cpy constructor*
- `PFSSsolutionInfo (SynopticInfo synInf, uint sizeofFloat, modelID model, methodID method, groupID group, hcFloat rss, hcFloat ell, uint orderSHC, uint numR, uint numTheta, uint numPhi)`  
*constructor*
- `PFSSsolutionInfo & operator= (const PFSSsolutionInfo &other)`  
*assignment operator*
- `bool operator== (const PFSSsolutionInfo &other)`  
*comparison operator*
- `bool operator> (const PFSSsolutionInfo &other)`  
*comparison operator*
- `bool operator< (const PFSSsolutionInfo &other)`  
*comparison operator*
- `void initNULL ()`
- `void clear ()`

- void **init** ([SynopticInfo](#) synInf, uint [sizeofFloat](#), modelID [model](#), methodID [method](#), groupID [group](#), hcFloat [rss](#), hcFloat [ell](#), uint [orderSHC](#), uint [numR](#), uint [numTheta](#), uint [numPhi](#))
- bool **exportBinary** (ofstream &stream)  
*export instance to binary stream*
- bool **importBinary** (ifstream &stream)  
*imports instance from binary stream*
- string **toString** () const  
*returns information on this instance in string*
- void **dump** (uint indent=0) const  
*dumps information on this instance to stdout with optional indendtation*

## Public Attributes

- uint [sizeofFloat](#)  
*floating point type used for computation 4=float, 8=double*
- modelID [model](#)  
*model employed for magnetic computation*
- methodID [method](#)  
*method applied for (PFSS) computation*
- groupID [group](#)  
*working group which computed this solution*
- hcFloat [rss](#)  
*source surface radius (m)*
- hcFloat [ell](#)  
*ellipticity of source surface (if method==METH\_ELLIPTICAL)*
- uint [orderSHC](#)  
*maximum principal order of SHC solution (if method==METH\_SHC)*
- uint [numR](#)  
*number of grid points in radial direction*
- uint [numTheta](#)  
*number of grid points in meridional direction*
- uint [numPhi](#)  
*number of grid points in zonal direction*
- hcDate [dateComputed](#)  
*date when the solution was computed*
- uint [computationTime](#)  
*time in seconds it took to compute*
- uint [solutionSteps](#)

*number of solution steps to fall below accuracy threshold*

The documentation for this class was generated from the following files:

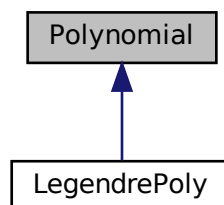
- src/pfssSolutionInfo.h
- src/pfssSolutionInfo.cpp

## 4.49 Polynomial Class Reference

loads coefficients for Spherical functions computed by Bala via CSSS

```
#include <hcFunction.h>
```

Inheritance diagram for Polynomial:



### Public Member Functions

- **Polynomial** (uint order=0)  
*std constructor*
- **Polynomial** (const **Polynomial** &other)  
*cpy constructor*
- **Polynomial** (double \*factor, uint n)
- **~Polynomial** ()  
*destructor*
- **Polynomial** & **operator=** (const **Polynomial** &other)  
*assignment operator*
- void **initNULL** ()
- void **clear** ()
- void **init** (uint n)
- double **operator()** (double x)
- void **derivative** (uint m)  
*transforms this to its m'th derivative*
- void **scale** (double scale)
- void **dump** ()

## Public Attributes

- double \* **factor**
- uint **n**

### 4.49.1 Detailed Description

loads coefficients for Spherical functions computed by Bala via CSSS

<

polynomial of order n

The documentation for this class was generated from the following files:

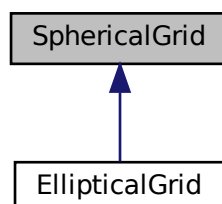
- engine/math/hcFunction.h
- engine/math/hcFunction.cpp

## 4.50 SphericalGrid Class Reference

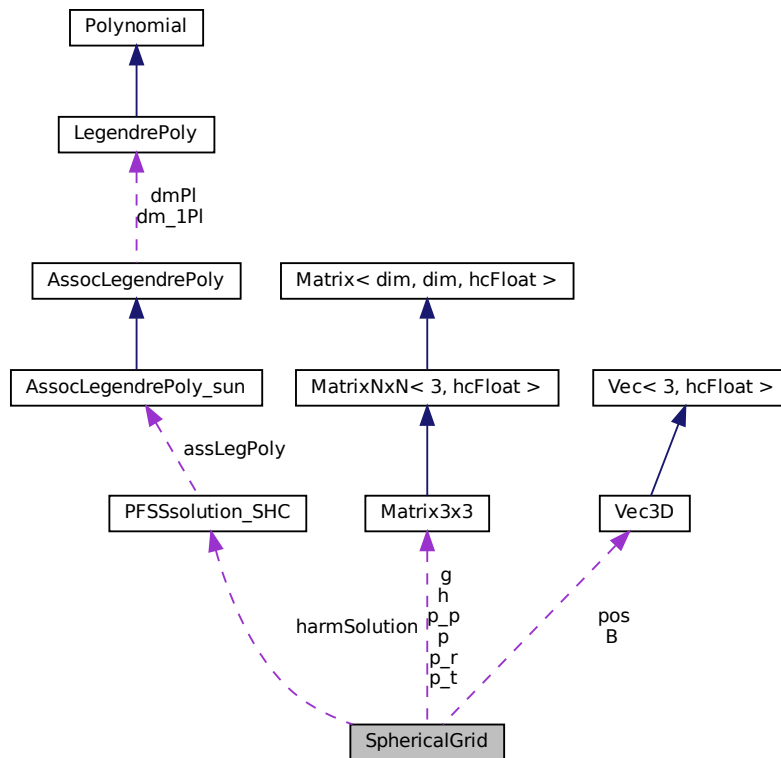
grid structure for numerical computation in 3D space

```
#include <grids.h>
```

Inheritance diagram for SphericalGrid:



Collaboration diagram for SphericalGrid:



## Public Member Functions

- [SphericalGrid](#) ()  
*std constructor*
- [SphericalGrid](#) (const [SphericalGrid](#) &grid)  
*cpy constructor*
- virtual [~SphericalGrid](#) ()  
*destructor*
- virtual [SphericalGrid](#) & [operator=](#) (const [SphericalGrid](#) &other)  
*assignment operator*
- virtual void **initNULL** ()
- virtual void **initNULL\_CPU** ()
- virtual void **clear** ()
- virtual void **clear\_CPU** ()
- virtual void **init** (bool [sinLatGrid](#), hcFloat [maxSinLat](#), hcFloat [minSinLat](#), hcFloat [lowerR](#), hcFloat [upperR](#), uint [numR](#), bool clearGPU=true, hcFloat a=1.0)  
*initializes the grid*
- void **initMembers** (uint [numR](#), uint numT, uint numP, bool [sinLatGrid](#), hcFloat [maxSinLat](#), hcFloat [minSinLat](#), hcFloat [lowerR](#), hcFloat [upperR](#))

*initializes member variables, usable by elliptical and spherical grid*

- void [getScalingFactors](#) ()  
*computes scaling factors to be used by the Laplace solver*
- void [clearValues](#) ()  
*clears the values (B\_r, relError, temp, etc.) not the positions (pos)*
- void [diff](#) (const [SphericalGrid](#) &other)  
*computes difference in psi array*
- [hcFloat](#) [maxSpacingR](#) (uint &index)  
*returns index of grid point where spacing in r-direction is tallest*
- [hcFloat](#) [maxSpacingTheta](#) (uint &index)  
*returns index of grid point where spacing in theta-direction is tallest*
- [hcFloat](#) [maxSpacingPhi](#) (uint &index)  
*returns index of grid point where spacing in phi-direction is tallest*
- virtual bool [isElliptical](#) () const  
*determine whether the grid is spherical or elliptical*
- virtual [Vec3D](#) [getPos](#) (uint index, bool ellipticCoords) const
- virtual [Vec3D](#) [getB](#) (uint index, bool ellipticCoords=false) const
- virtual void [setB](#) (uint index, [Vec3D](#) value, bool ellipticCoords=false)
- virtual void [dumpCoords](#) (uint fixed=0, bool ellipticCoords=false) const
- void [iterateElliptic\\_gridPoint](#) (uint i, uint j, uint k)  
*solve Laplace equation on a single grid point according to the elliptic computation scheme*
- [hcFloat](#) [getPsi](#) (uint index) const
- void [setPsi](#) (uint index, [hcFloat](#) value)
- void [setRelError](#) (uint index, [hcFloat](#) value)
- [hcFloat](#) [getTemp](#) (uint index) const
- void [setTemp](#) (uint index, [hcFloat](#) value)
- [hcFloat](#) [getRelError](#) (uint index) const
- [hcFloat](#) \* [getPsiArray](#) () const  
*scalar potential*
- [hcFloat](#) \* [getRelErrorArray](#) () const  
*relative error compered to preciding step*
- [Vec3D](#) \* [getPosArray](#) () const  
*position in world coordinates (spherical)*
- [Vec3D](#) \* [getBArray](#) () const  
*magnetic field components (spherical)*
- [hcFloat](#) \* [getTempArray](#) () const  
*temp value for computations on spec. grid point*
- float [getStepSize](#) () const  
*returns the optimal step size for following values (e.g., Magnetic field lines) throughout the grid*

- uint **getIndex** (uint i, uint j, uint k) const
- uint **getIndexPhiPlus** (uint ind)
- void **getIndicesFromIndex** (uint ind, uint &i, uint &j, uint &k) const  
*if ind = k \* numR \* numTheta + j \* numR + i is given, computes i, j, k*
- void **printGridIndicesFromIndex** (uint ind)
- void **computeLowerBoundaryPsi** (float \*image)
- virtual unsigned char **getNearestNeighbors** (Vec3D &pos, Vec< 8, hcFloat > &indices, bool debug=false) const  
*computes the nearest grid cells in the grid*
- virtual bool **getInterpolatedB** (Vec3D &B, Vec3D &pos, unsigned char &error, bool debug=false) const  
*computes an interpolated value for B from the surrounding grid points via trilinear interpolation (r->theta->phi)*
- Vec3D **getBFromPsi** (uint r, uint t, uint p)
- void **compDerivR** (Matrix3x3 \*arr, Matrix3x3 \*deriv)  
*computes derivative w.r.t. r of quantity stored at arr*
- void **compDerivT** (Matrix3x3 \*arr, Matrix3x3 \*deriv)  
*computes derivative w.r.t. theta of quantity stored at arr*
- void **compDerivP** (Matrix3x3 \*arr, Matrix3x3 \*deriv)  
*computes derivative w.r.t. phi of quantity stored at arr*
- bool **exportEntireGrid** (const char \*filename)  
*export grid to binary file*
- bool **importEntireGrid** (const char \*filename)  
*import grid from binary file*
- bool **evaluateCSSS** (const char \*filename)
- virtual void **dump** () const

## Static Public Member Functions

- static void **getOptimalGridParameters** (uint numR, hcFloat lowerR, hcFloat upperR, hcFloat &geometricFactor, uint &numT, uint &numP, bool high=false)  
*computes parameters so that distances in all directions between grid points are more or less equal*

## Public Attributes

- uint **sizeofFloat**  
*4-single, 8-double, 16-long double(not supported in CUDA yet)*
- uint **numR**  
*number of r-steps*
- uint **numTheta**  
*number of theta-steps*
- uint **numPhi**  
*number of phi-steps*



- uint [numGridPoints](#)  
*overall grid points*
- bool [sinLatGrid](#)  
*is the grid equally spaced in latitude (=false) or sin(lat) (=true)*
- hcFloat [maxSinLat](#)  
*sin(latitude) of northernmost pixel border*
- hcFloat [minSinLat](#)  
*sin(latitude) of southernmost pixel border*
- hcFloat [lowerR](#)  
*lowest radial coordinate (photosphere)*
- hcFloat [upperR](#)  
*uppermost radial coordinate (source surface)*
- hcFloat [geometricFactor](#)  
*factor by which radial spacing increases from shell to shell*
- [PFSSsolution\\_SHC](#) \* [harmSolution](#)  
*PFSS solution via spherical harmonic function approach, temporary testing variable*
- [Vec3D](#) \* [pos](#)  
*position in computational coordinates (spherical)*
- [Vec3D](#) \* [B](#)  
*magnetic field components (spherical)*
- hcFloat \* [psi](#)  
*scalar potential*
- hcFloat \* [relError](#)  
*relative error compered to preciding step*
- hcFloat \* [temp](#)  
*temp value for computations on spec. grid point*
- [Matrix3x3](#) \* [g](#)  
*metric coefficients*
- [Matrix3x3](#) \* [h](#)  
*dual metric coefficients*
- [Matrix3x3](#) \* [p](#)  
*metric helper variable (sqrt(g)\*g)*
- [Matrix3x3](#) \* [p\\_r](#)  
*derivative of p w.r.t. r*
- [Matrix3x3](#) \* [p\\_t](#)  
*derivative of p w.r.t. theta*

- [Matrix3x3 \\* p\\_p](#)  
*derivative of p w.r.t. phi*
- hcFloat \* **s\_ijk**
- hcFloat \* **s\_imjk**
- hcFloat \* **s\_ipjk**
- hcFloat \* **s\_ijmk**
- hcFloat \* **s\_ijpk**
- hcFloat \* **s\_ijkm**
- hcFloat \* **s\_ijkp**
- hcFloat \* **s\_imjmk**
- hcFloat \* **s\_imjpk**
- hcFloat \* **s\_ipjmk**
- hcFloat \* **s\_ipjpk**
- hcFloat \* **s\_imjkm**
- hcFloat \* **s\_imjpk**
- hcFloat \* **s\_ipjkm**
- hcFloat \* **s\_ipjpk**
- hcFloat \* **s\_ijmkm**
- hcFloat \* **s\_ijmkp**
- hcFloat \* **s\_ijpkm**
- hcFloat \* **s\_ijppk**
- hcFloat \* **s\_ijmmk**
- hcFloat \* **s\_imjmmk**
- hcFloat \* **s\_ipjmmk**
- hcFloat \* **s\_ijmmkm**
- hcFloat \* **s\_ijmmkp**
- hcFloat \* **s\_ijppk**
- hcFloat \* **s\_imjppk**
- hcFloat \* **s\_ipjppk**
- hcFloat \* **s\_ijppkm**
- hcFloat \* **s\_ijppkp**

### 4.50.1 Detailed Description

grid structure for numerical computation in 3D space

### 4.50.2 Member Function Documentation

#### 4.50.2.1 getInterpolatedB()

```
bool SphericalGrid::getInterpolatedB (
    Vec3D & B_out,
    Vec3D & position,
    unsigned char & error,
    bool debug = false ) const [inline], [virtual]
```

computes an interpolated value for B from the surrounding grid points via trilinear interpolation (r->theta->phi)

## Parameters

<i>B</i>	(out) the magnetic field at pos (spherical coordinate system)
<i>position</i>	(in/out) the position (spherical/computational coordinates) where the magnetic field is requested
<i>error</i>	(out) error code (see below)

returns true only if a valid magnetic field vector has been found

The error codes returned in error are:

(1 << 0) = 1 pos.r below lower boundary (1 << 1) = 2 pos.r above upper boundary

(1 << 7) = 128 different error, should not be possible to reach

#### 4.50.2.2 getNearestNeighbors()

```
unsigned char SphericalGrid::getNearestNeighbors (
    Vec3D & position,
    Vec< 8, hFloat > & indices,
    bool debug = false ) const [inline], [virtual]
```

computes the nearest grid cells in the grid

## Parameters

<i>position</i>	for which nearest neighbors shall be found (spherical/computational coordinates)
<i>indices</i>	vector containing grid indices for nearest neighbors

returns bit-coded clipping id if pos is outside grid:

(1 << 0) = 1 pos.r below lower boundary (1 << 1) = 2 pos.r above upper boundary

(1 << 2) = 4 pos.theta above highest latitude (north pole) in these two cases, nearest neighbors are being computed in accordance with the (1 << 3) = 8 pos.theta below lowest latitude (south pole) polar boundary conditions

(1 << 7) = 128 different error, should not be possible to reach

indices has to be 8-dim vector, numbering is done just like with the grid:

indices[0] -> rm, tm, pm indices[1] -> rp, tm, pm indices[2] -> rm, tp, pm indices[3] -> rp, tp, pm

indices[4] -> rm, tm, pp indices[5] -> rp, tm, pp indices[6] -> rm, tp, pp indices[7] -> rp, tp, pp

#### 4.50.2.3 getStepSize()

```
float SphericalGrid::getStepSize ( ) const [inline]
```

returns the optimal step size for following values (e.g., Magnetic field lines) throughout the grid

for now assumes equidistant grid! this should probably be amended sometime

#### 4.50.2.4 init()

```
void SphericalGrid::init (
    bool sinLatGrid,
    hcFloat maxSinLat,
    hcFloat minSinLat,
    hcFloat lowerR,
    hcFloat upperR,
    uint numR,
    bool clearGPU = true,
    hcFloat a = 1.0 ) [virtual]
```

initializes the grid

additional information like different domains (block regular) and distribution of grid points have to be supplied

##### Parameters

<i>rDistribution</i>	(false - equally spaced, true - geometric series)
----------------------	---

Reimplemented in [EllipticalGrid](#).

The documentation for this class was generated from the following files:

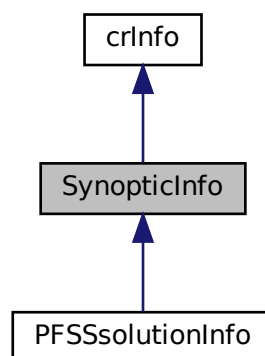
- src/grids.h
- src/ellipticalGrid.cpp
- src/grids.cpp
- src/laplaceSolver.cpp

## 4.51 SynopticInfo Class Reference

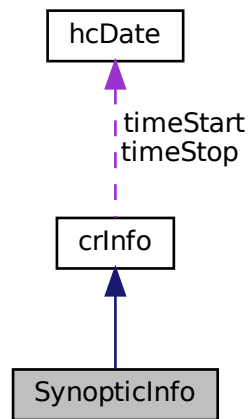
information on photospheric magnetic field data such as instrument which was used, sin(latitude)-format, ...

```
#include <synPhotMagfield.h>
```

Inheritance diagram for SynopticInfo:



Collaboration diagram for SynopticInfo:



## Public Member Functions

- [SynopticInfo](#) ()
- [SynopticInfo](#) (const [SynopticInfo](#) &other)
- **SynopticInfo** (originID id, hcFloat [maxSinLat](#), uint [CRnum](#), uint [dailyID](#)=0)
- virtual [~SynopticInfo](#) ()
- [SynopticInfo](#) & [operator=](#) (const [SynopticInfo](#) &other)
- bool [operator==](#) (const [SynopticInfo](#) &other)  
*comparison operator*
- bool [operator>](#) (const [SynopticInfo](#) &other)  
*comparison operator*
- bool [operator<](#) (const [SynopticInfo](#) &other)  
*comparison operator*
- bool [exportBinary](#) (ofstream &stream)  
*export instance to stream*
- bool [importBinary](#) (ifstream &stream)  
*import instance from stream*
- void **initNULL** ()
- void **clear** ()
- void **init** (originID id, hcFloat [maxSinLat](#), uint [CRnum](#), uint [dailyID](#))
- void [dump](#) (uint indent=0) const  
*dumps information on this instance to stdout*

## Public Attributes

- originID [instrument](#)
- uint [dailyID](#)
- bool [sinLatFormat](#)
- hcFloat [maxSinLat](#)

### 4.51.1 Detailed Description

information on photospheric magnetic field data such as instrument which was used, sin(latitude)-format, ...

### 4.51.2 Constructor & Destructor Documentation

#### 4.51.2.1 SynopticInfo() [1/2]

```
SynopticInfo::SynopticInfo ( )
```

std constructor

#### 4.51.2.2 SynopticInfo() [2/2]

```
SynopticInfo::SynopticInfo (
    const SynopticInfo & other )
```

cpy constructor

#### 4.51.2.3 ~SynopticInfo()

```
SynopticInfo::~~SynopticInfo ( ) [virtual]
```

destructor

### 4.51.3 Member Function Documentation

#### 4.51.3.1 operator=()

```
SynopticInfo & SynopticInfo::operator= (
    const SynopticInfo & other )
```

assignment operator

## 4.51.4 Member Data Documentation

### 4.51.4.1 dailyID

```
uint SynopticInfo::dailyID
```

identification for daily synoptic maps

### 4.51.4.2 instrument

```
originID SynopticInfo::instrument
```

instrument used for synoptic map

### 4.51.4.3 maxSinLat

```
hcFloat SynopticInfo::maxSinLat
```

sin(latitude) of northern grid boundary

### 4.51.4.4 sinLatFormat

```
bool SynopticInfo::sinLatFormat
```

y-Axis in synoptic map given in sin(latitude)?

The documentation for this class was generated from the following files:

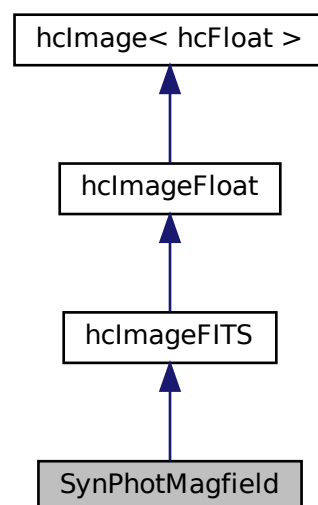
- src/synPhotMagfield.h
- src/synPhotMagfield.cpp

## 4.52 SynPhotMagfield Class Reference

handles synoptic photospheric magnetograms stored in GAUSS

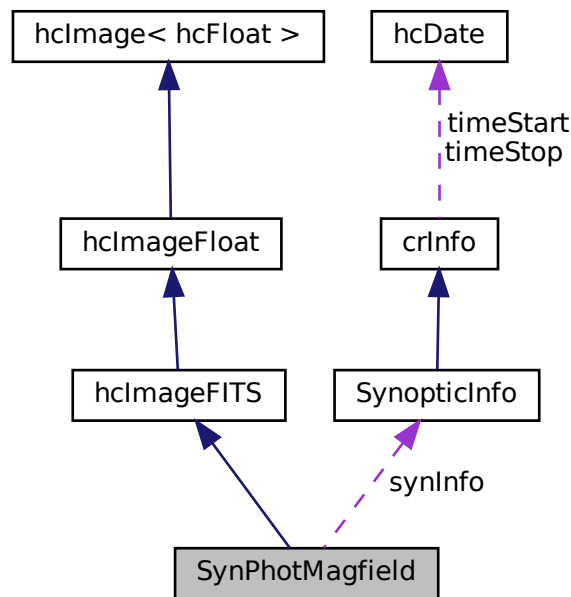
```
#include <synPhotMagfield.h>
```

Inheritance diagram for SynPhotMagfield:





Collaboration diagram for SynPhotMagfield:



## Public Member Functions

- [SynPhotMagfield](#) ()  
*std constructor*
- [SynPhotMagfield](#) (const [SynPhotMagfield](#) &other)  
*cpy constructor*
- [SynPhotMagfield](#) & [operator=](#) (const [SynPhotMagfield](#) &other)  
*assignment operator*
- void [initNULL](#) ()
- virtual bool [load](#) (const string &filename)  
*load FITS image from file*
- bool [openKPVT](#) (const string &filename)
- bool [openWSO](#) (const string &filename)
- bool [openWSOconverted](#) (const string &filename)
- bool [openSOHOMDI](#) (const string &filename)
- bool [openSOHOMDI\\_DAILY](#) (const string &filename)
- bool [openNSOGONG](#) (const string &filename)
- bool [openSDOHMI](#) (const string &filename)
- bool [openVerDAILY](#) (const string &filename)
- bool [openOwnFormat](#) (const string &filename)
- bool [createLOSfromGrid](#) ([SphericalGrid](#) &grid)

*computes line-of-sight magnetogram from magnetic field values of grid*

- bool [loadDipole](#) (hFloat dipole, uint numTheta, uint numPhi, hFloat maxSinLat=0.0, hFloat minSinLat=-0.0)

*loads artificial dipole to line-of-sight magnetogram*

- void [removeMonopole](#) ()

*removes monopole component from magnetogram*

- bool [remeshImage](#) (uint newWidth, uint newHeight, uint scaleMethod)

*rescales magnetogram*

- void [cropPolesFromImage](#) (uint numPixelsToCrop)

*remove north-most and south-most lines from magnetogram*

- bool [convertWSOtxtToWSOfits](#) (const string &infile, const string &outfile)

*converts Stanford ASCII files to FITS files*

- virtual bool [save](#) (const string &filename)

*stores photospheric magfield in FITS format to be re-imported later on*

- void [dump](#) () const

*dumps information on this instance to stdout*

## Public Attributes

- [SynopticInfo synInfo](#)

*information on the synoptic data*

## Additional Inherited Members

### 4.52.1 Detailed Description

handles synoptic photospheric magnetograms stored in GAUSS

1G = 1E-4T = 100uT

### 4.52.2 Member Function Documentation

## 4.52.2.1 remeshImage()

```
bool SynPhotMagfield::remeshImage (
    uint newWidth,
    uint newHeight,
    uint scaleMethod )
```

rescales magnetogram

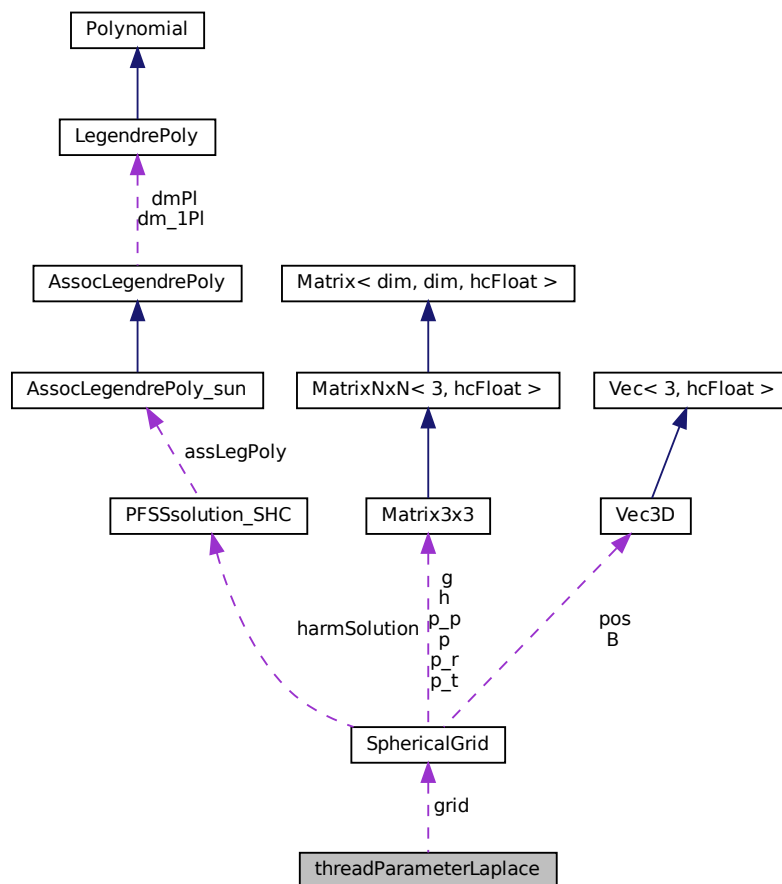
Note: maxSinLat and minSinLat only relevant if scaleMethod=0 or scaleMethod=1

The documentation for this class was generated from the following files:

- src/synPhotMagfield.h
- src/synPhotMagfield.cpp

## 4.53 threadParameterLaplace Struct Reference

Collaboration diagram for threadParameterLaplace:



## Public Member Functions

- void **init** (uint threadID=0, volatile \_\_Atomic\_word \*numRunningThreads=NULL, pthread\_mutex\_t \*runningMutex=NULL, volatile \_\_Atomic\_word \*threadRunning=NULL, [SphericalGrid](#) \*grid=NULL)
- void **set** (const uint &idx, const uint &gppt)

## Public Attributes

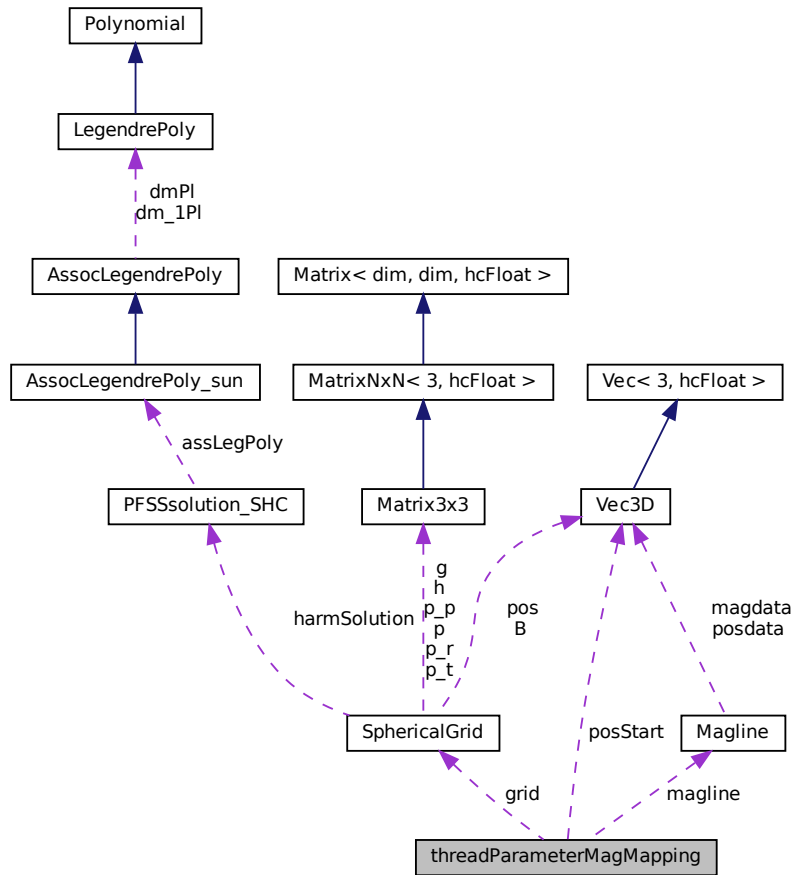
- uint **threadID**
- pthread\_mutex\_t \* **runningMutex**
- [SphericalGrid](#) \* **grid**
- volatile \_\_Atomic\_word \* **numRunningThreads**
- volatile \_\_Atomic\_word \* **threadRunning**
- uint [idx](#)  
*id of grid point to be computed, as in CUDA version*
- uint [gppt](#)  
*grid points per thread*

The documentation for this struct was generated from the following file:

- src/laplaceSolver.h

## 4.54 threadParameterMagMapping Struct Reference

Collaboration diagram for threadParameterMagMapping:



### Public Member Functions

- void **init** (uint threadID, volatile \_Atomic\_word \*numRunningThreads, pthread\_mutex\_t \*runningMutex, volatile \_Atomic\_word \*threadRunning, [SphericalGrid](#) \*grid)
- void **set** ([Magline](#) \*magline, [Vec3D](#) \*posStart)

### Public Attributes

- uint **threadID**
- pthread\_mutex\_t \* **runningMutex**
- [SphericalGrid](#) \* **grid**
- volatile \_Atomic\_word \* **numRunningThreads**
- volatile \_Atomic\_word \* **threadRunning**
- [Magline](#) \* **magline**

*pointer to magline to be worked upon*

- [Vec3D \\* posStart](#)  
*pointer to position from which to start tracking field line, in computational coordinates*

The documentation for this struct was generated from the following file:

- `src/magMapping.h`

## 4.55 `Vec< dim, T >` Class Template Reference

implementation of the mathematical (finite dimensionality) vector concept

```
#include <hcVec.h>
```

### Public Member Functions

- [Vec \(\)](#)  
*std constructor*
- `template<class S >`  
[Vec](#) (const [Vec](#)< dim, S > &other)  
*cpy constructor*
- [~Vec \(\)](#)  
*destructor*
- `T & operator() (uint n)`
- `T operator[] (uint n) const`
- `template<class S >`  
[Vec](#)< dim, T > & [operator=](#) (const [Vec](#)< dim, S > &other)  
*assignment operator*
- [Vec & operator\\*=](#) (T [scale](#))
- [Vec & operator/=](#) (T [scale](#))
- [Vec & operator+=](#) (const [Vec](#) &other)
- [Vec & operator-=](#) (const [Vec](#) &other)
- [Vec operator-](#) ()
- `bool operator==` (const [Vec](#) &vec) const
- `bool isAlmostEqual` (const [Vec](#)< dim, T > &other, T eps=1E-6)  
*checks if vectors are the same within numerical uncertainty bounds*
- [Vec](#)< dim, T > & [normalize](#) ()
- `void loadZeroes ()`
- `void loadHom` (const [Vec](#)< dim-1, T > &vec)
- `T sp` (const [Vec](#) &v) const  
*std-scalar product with other vector*
- `double sp_double` (const [Vec](#) &other) const
- `T dist` (const [Vec](#) &other)  
*distance to point in std-norm*

- T **length** () const  
*distance to origin in std-norm / length of vector*
- void **scale** (T factor)  
*scales the vector by factor*
- void **zero** ()  
*sets all components to 0*
- bool **isNullVector** () const
- bool **isValid** () const  
*checks if some element is INF or NAN*
- bool **exportBinary** (std::ofstream &stream)
- bool **importBinary** (std::ifstream &stream, uint sizeofFloat=0)
- void **dump** () const

## Public Attributes

- T **content** [dim]  
*elements of the vector*

### 4.55.1 Detailed Description

```
template<uint dim, class T>
class Vec< dim, T >
```

implementation of the mathematical (finite dimensionality) vector concept

### 4.55.2 Member Function Documentation

#### 4.55.2.1 isNullVector()

```
template<uint dim, class T >
bool Vec< dim, T >::isNullVector
```

< copies components from Vector and overwrites the dimensionality of this

The documentation for this class was generated from the following file:

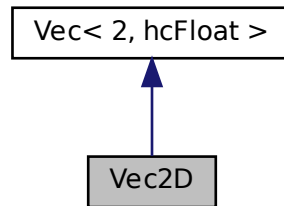
- engine/math/hcVec.h

## 4.56 Vec2D Class Reference

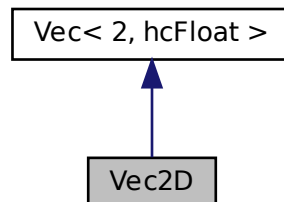
3D Vectors

```
#include <hcVec.h>
```

Inheritance diagram for Vec2D:



Collaboration diagram for Vec2D:



### Public Member Functions

- [Vec2D](#) ()  
*std constructor*
- `template<class S >`  
**Vec2D** (S x, S y)
- [Vec2D](#) (const [Vec2D](#) &other)  
*cpy constructor*
- `template<class S >`  
[Vec2D](#) (const [Vec](#)< 2, S > &other)  
*pseudo-cpy constructor*



- `~Vec2D()`  
*destructor*
- `Vec2D & operator= (const Vec2D &other)`
- `template<class S >`  
`Vec2D & operator= (const Vec< 2, S > &other)`
- `template<class S >`  
`void rotate (S phi)`
- `template<class S >`  
`void set (S x, S y)`

## Additional Inherited Members

### 4.56.1 Detailed Description

3D Vectors

The documentation for this class was generated from the following files:

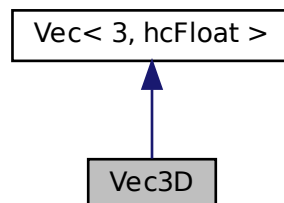
- `engine/math/hcVec.h`
- `engine/math/hcVec.cpp`

## 4.57 Vec3D Class Reference

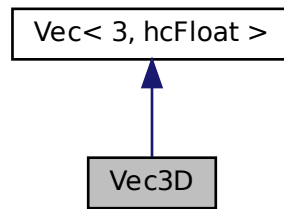
3D Vectors

```
#include <hcVec.h>
```

Inheritance diagram for Vec3D:



Collaboration diagram for Vec3D:



## Public Member Functions

- [Vec3D](#) ()  
*std constructor*
- [Vec3D](#) (const [Vec3D](#) &other)  
*cpy constructor*
- template<class S >  
[Vec3D](#) (const [Vec](#)< 3, S > &other)  
*pseudo-cpy constructor*
- template<class S >  
**Vec3D** (S x, S y, S z)
- [~Vec3D](#) ()  
*destructor*
- [Vec3D](#) & **operator=** (const [Vec3D](#) &other)
- template<class S >  
[Vec3D](#) & **operator=** (const [Vec](#)< 3, S > &other)
- template<class S >  
void [rotateX](#) (S angle)  
*rotate around x-axis in global cartesian coordinate system*
- template<class S >  
void [rotateY](#) (S angle)  
*rotate around y-axis in global cartesian coordinate system*
- template<class S >  
void [rotateZ](#) (S angle)  
*rotate around z-axis in global cartesian coordinate system*
- void [stereoProjUnitSphere](#) ([Vec2D](#) tangent)  
*stereographic projection of this (in cartCoords ) onto plane tangent at unit sphere in spherical coordinates ([Vec2D](#) tangent)*
- void [convertEllipticalCoordsToCartesian](#) (hcFloat a, bool prolate)  
*transforms elliptical coordinates to cartesian coordinates*
- void [convertCartesianCoordsToElliptical](#) (hcFloat a, bool prolate)  
*transforms cartesian coordinates to elliptical coordinates*

- [Vec3D](#) **convCoordSpher2Cart** () const
- [Vec3D](#) **convCoordCart2Spher** () const
- [Vec3D](#) **convCoordCart2Ell** (const [EllipticalGrid](#) &grid) const
- [Vec3D](#) **convCoordEll2Cart** (const [EllipticalGrid](#) &grid) const
- [Vec3D](#) **convCoordSpher2Ell** ([EllipticalGrid](#) &grid) const
- [Vec3D](#) **convCoordEll2Spher** ([EllipticalGrid](#) &grid) const
- [Vec3D](#) **convVecSpher2Cart** (const [Vec3D](#) &cartPos) const
- [Vec3D](#) **convVecCart2Spher** (const [Vec3D](#) &cartPos)
- [Vec3D](#) **convCoordCart2Cart** ([Vec3D](#) e1x, [Vec3D](#) e1y, [Vec3D](#) e1z, [Vec3D](#) e2x, [Vec3D](#) e2y, [Vec3D](#) e2z) const  
*convert position vector from cartesian coordinate system 1 to cartesian coordinate system 2*
- [Vec3D](#) **convVecSpher2Ell** (const [Vec3D](#) &posSpher, const [EllipticalGrid](#) &grid) const
- [Vec3D](#) **convVecEll2Spher** (const [Vec3D](#) &posEll, const [EllipticalGrid](#) &grid) const
- [Vec3D](#) **convVecEll2Cart** (const [Vec3D](#) &cartPos, const [EllipticalGrid](#) &grid) const
- [Vec3D](#) **convVecCart2Ell** (const [Vec3D](#) &cartPos, const [EllipticalGrid](#) &grid) const
- [Vec3D](#) **convVecCart2Ell2** (const [Vec3D](#) &cartPos, [EllipticalGrid](#) &grid) const
- [Vec3D](#) **convVecHAE2GSE** (const [hcDate](#) &date)  
*convert vector in Heliocentric Aries Ecliptic cartesian coordinates to Geocentric Solar Ecliptic cartesian coordinates*
- [Vec3D](#) **convVecGSE2HAE** (const [hcDate](#) &date)  
*convert vector in Geocentric Solar Ecliptic cartesian coordinates to Heliocentric Aries Ecliptic cartesian coordinates*
- [Vec3D](#) **convVecHAE2SW** (const [Vec3D](#) &pos\_HAE\_c, [hcFloat](#) swSpeed, [hcFloat](#) lowerR, const [hcDate](#) &date) const  
*convert vector from Heliocentric Aries Ecliptic cartesian coordinates to solar wind frame*
- template<class S >  
void **transformSphericalCoordSystem** (S theta, S phi)  
*transforms point given in spherical coordinates into another spherical system*
- template<class S >  
void **transformSphericalCoordSystemBack** (S theta, S phi)  
*transform back point given in spherical coordinates (see transformSphericalCoordSystem)*
- void **cp** (const [Vec3D](#) &v, [Vec3D](#) \*res) const  
*cross product of two [Vec3D](#)*
- [Vec3D](#) **cp** (const [Vec3D](#) &other) const  
*cross product of two [Vec3D](#)*
- [hcFloat](#) **getAngle** (const [Vec3D](#) &other) const
- [hcFloat](#) **getAngle2** (const [Vec3D](#) &other) const
- void **dumpSphericalCoords** ()

## Additional Inherited Members

### 4.57.1 Detailed Description

3D Vectors

The documentation for this class was generated from the following files:

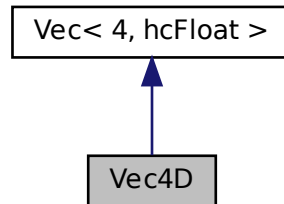
- engine/math/hcVec.h
- engine/math/hcVec.cpp
- src/ellipticalGrid.cpp

## 4.58 Vec4D Class Reference

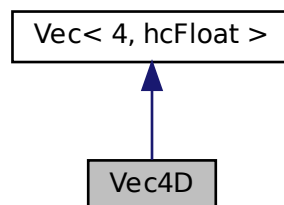
4D Vectors

```
#include <hcVec.h>
```

Inheritance diagram for Vec4D:



Collaboration diagram for Vec4D:



### Public Member Functions

- [Vec4D](#) ()  
*std constructor*
- [Vec4D](#) (const [Vec4D](#) &other)  
*cpy constructor*
- [Vec4D](#) (const [Vec3D](#) &other)  
*homogen-cpy constructor*
- template<class S >  
[Vec4D](#) (const [Vec](#)< 4, S > &other)

*pseudo-cpy constructor*

- `template<class S >`  
**Vec4D** (S x, S y, S z, S w)
- `~Vec4D ()`

*destructor*

- **Vec4D** & **operator=** (const **Vec4D** &other)
- `template<class S >`  
**Vec4D** & **operator=** (const **Vec**< 4, S > &other)
- `template<class S >`  
void **set** (S x, S y, S z, S w)
- `template<class S >`  
void **setPos** (S x, S y)
- `template<class S >`  
void **setTex** (S u, S v)

## Additional Inherited Members

### 4.58.1 Detailed Description

4D Vectors

The documentation for this class was generated from the following files:

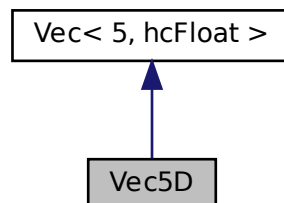
- `engine/math/hcVec.h`
- `engine/math/hcVec.cpp`

## 4.59 Vec5D Class Reference

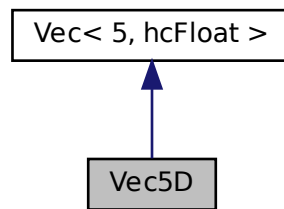
5D Vectors

```
#include <hcVec.h>
```

Inheritance diagram for Vec5D:



Collaboration diagram for Vec5D:



## Public Member Functions

- `template<class S >`  
**Vec5D** (S x, S y, S z, S u, S v)
- `template<class S >`  
void **set** (S x, S y, S z, S u, S v)

## Additional Inherited Members

### 4.59.1 Detailed Description

5D Vectors

The documentation for this class was generated from the following files:

- `engine/math/hcVec.h`
- `engine/math/hcVec.cpp`

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