Assignment - 1

Karthik Kurugodu

Abstract—This document contains the solution to Exercise 2.36 (a) of Oppenheim.

Problem 1. The system L in figure P2.36-1 is known to be linear. Shown are three output signals $y_1[n], y_2[n], y_3[n]$ in response to the input signals $x_1[n], x_2[n], x_3[n]$ respectively

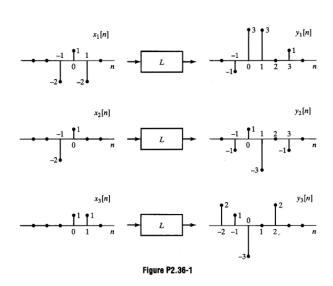


Fig. 1: $|H(e^{j\omega})|$

Solution:

Impulse equation: $\delta[n] = x_3[n] + \frac{1}{2}x_1[n] - \frac{1}{2}x_2[n]$ Shifted Impulse equation: $\delta[n-1] = \frac{1}{2}x_2[n] - \frac{1}{2}x_1[n]$ Given system is linear.

$$\therefore L[\delta[n]] = y_3[n] + \frac{1}{2}y_1[n] - \frac{1}{2}y_2[n]$$
 (1)

$$\therefore L[\delta[n-1]] = \frac{1}{2}y_2[n] - \frac{1}{2}y_1[n]$$
 (2)

Since $(1) \neq (2)$.

:. Given system is not time invariant