0.0.1 Importing necessary libraries

```
[1]: import numpy as np
  from sklearn.datasets import make_spd_matrix
  import matplotlib.pyplot as plt
```

0.1 Problem 1

0.1.1 Problem 1 (a)

```
f(x) = x^{T}Ax + b
\Rightarrow \nabla f(x) = 2Ax
where A = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & 0 \\ -1 & 0 & 1 \end{bmatrix}, b = \begin{bmatrix} 1 \end{bmatrix}
```

By setting the gradient to zero $\Rightarrow 2Ax = 0$ $\Rightarrow x = 0$

```
[2]: A_a = np.matrix([[2, -1, -1], [-1, 2, 0], [-1, 0, 1]])
     b_a = np.matrix([[1]])
     def f_a(x):
         return x.T @ A_a @ x + b_a
     def gradient_f_a(x):
         return 2* A_a @ x
     def gradient_descent(x0, learning_rate, num_iterations):
         x = x0
         for i in range(num_iterations):
             x = x - learning rate * gradient f a(x)
         return x
     N = 1000
     t = 0.02
     x0 = np.random.rand(3,1)
     result_gradient_descent = gradient_descent(x0, t, N)
     print("Minimizer using gradient descent:", result_gradient_descent)
     print("Value of f_a at minimizer:", f_a(result_gradient_descent)[0,0])
     result_gradient_zero = (1/2) * A_a.I @ np.matrix([[0],[0],[0]])
     print("Minimizer using gradient zero:", result_gradient_zero)
     print("Value of f_a at minimizer using gradient zero:", __

¬f_a(result_gradient_zero)[0,0])
```

```
Minimizer using gradient descent: [[1.54960309e-04] [8.59964837e-05] [1.93232345e-04]]
Value of f_a at minimizer: 1.000000013616153
```

```
Minimizer using gradient zero: [[0.]
      [0.]
      [0.]]
     Value of f_a at minimizer using gradient zero: 1.0
     0.1.2 Problem 1 (b)
     f(x) = ||Ax - b||^2
     \Rightarrow \nabla f(x) = 2A^T(Ax - b)
     where A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 3 & 1 \end{bmatrix}, b = \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}
     By setting the gradient to zero \Rightarrow 2A^T(Ax - b) = 0
     \Rightarrow A^T(Ax - b) = 0
     \Rightarrow A^T A x = A^T b
     \Rightarrow x = (A^T A)^{-1} A^T b
[3]: A_b = np.matrix([[1,2],[2,4],[3,1]])
      b_b = np.matrix([[1],[3],[1]])
      def f_b(x):
            \texttt{return} \ \ \texttt{x.T} \ \ @ \ \ \texttt{A\_b.T} \ \ @ \ \ \texttt{A\_b} \ \ @ \ \ \texttt{x} \ - \ \ \texttt{x.T} \ \ @ \ \ \texttt{A\_b.T} \ \ @ \ \ \texttt{b\_b} \ + \ \ \texttt{b\_b.T_{\sqcup}}  
        →@ b_b
      def gradient_f_b(x):
           return 2* A_b.T @ (A_b @ x - b_b)
      def gradient_descent(x0, learning_rate, num_iterations):
           x = x0
           for i in range(num_iterations):
                x = x - learning_rate * gradient_f_b(x)
           return x
      N = 1000
      t = 0.02
      x0 = np.random.rand(2,1)
      result_gradient_descent = gradient_descent(x0, t, N)
      print("Minimizer using gradient descent:", result_gradient_descent)
      print("Value of f_b at minimizer:", f_b(result_gradient_descent)[0,0])
      result_gradient_zero = (A_b.T @ A_b).I @ A_b.T @ b_b
      print("Minimizer using gradient zero:", result_gradient_zero)
      print("Value of f_b at minimizer using gradient zero:", 

¬f_b(result_gradient_zero)[0,0])

     Minimizer using gradient descent: [[0.12]
      [0.64]]
     Value of f_b at minimizer: 0.2000000000000107
```

Minimizer using gradient zero: [[0.12]

```
[0.64]]
     Value of f_b at minimizer using gradient zero: 0.20000000000000107
     0.1.3 Problem 1 (c)
     f(x) = ||Ax - b||^2
     \Rightarrow \nabla f(x) = 2A^T(Ax - b)
                  \lceil 1 \quad 2 \quad 1 \rceil
     where A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 3 & 1 & 9 \\ 4 & 1 & 0 \\ 2 & 1 & 4 \end{bmatrix}, b = \begin{bmatrix} 3 \\ 1 \\ 0 \\ 9 \end{bmatrix}
     By setting the gradient to zero \Rightarrow 2A^T(Ax - b) = 0
     \Rightarrow A^T(Ax - b) = 0
     \Rightarrow A^T A x = A^T b
     \Rightarrow x = (A^T A)^{-1} A^T b
[4]: A_c = np.matrix([[1,2,1],[2,4,2],[3,1,9],[4,1,0],[2,1,4]])
      b_c = np.matrix([[1],[3],[1],[0],[9]])
      def f_c(x):
           \texttt{return} \ \texttt{x.T} \ @ \ \texttt{A\_c.T} \ @ \ \texttt{A\_c} \ @ \ \texttt{x} \ - \ \texttt{b\_c.T} \ @ \ \texttt{A\_c.T} \ @ \ \texttt{b\_c} \ + \ \texttt{b\_c.T}_{\sqcup}
        →@ b_c
      def gradient_f_c(x):
           return 2* A_c.T @ (A_c @ x - b_c)
      def gradient_descent(x0, learning_rate, num_iterations):
           x = x0
           for i in range(num_iterations):
                x = x - learning_rate * gradient_f_c(x)
           return x
      N = 1000
      t = 0.002 # learning rate is made smaller than previous problems due to out of
       ⇒bound errors
      x0 = np.random.rand(3,1)
      result_gradient_descent = gradient_descent(x0, t, N)
      print("Minimizer using gradient descent:", result_gradient_descent)
      print("Value of f_c at minimizer:", f_c(result_gradient_descent)[0,0])
      result_gradient_zero = (A_c.T @ A_c).I @ A_c.T @ b_c
      print("Minimizer using gradient zero:", result_gradient_zero)
      print("Value of f_c at minimizer using gradient zero:", __

¬f_c(result_gradient_zero)[0,0])
     Minimizer using gradient descent: [[0.05744939]
       [0.65686105]
       [0.33915902]]
```

```
Value of f_c at minimizer: 56.990482782488314

Minimizer using gradient zero: [[0.05744939]

[0.65686105]

[0.33915902]]

Value of f_c at minimizer using gradient zero: 56.99048278248832
```

0.2 Problem 2

Generating A randomly using $sklearn.datasets.make_spd_matrix, and generate <math>b$ and c using np.random.rand function of numpy.

```
[5]:  \begin{bmatrix} A = \text{np.matrix}(\text{make\_spd\_matrix}(10)) \\ b = \text{np.matrix}(\text{np.random.randn}(10,1)) \\ c = \text{np.matrix}(\text{np.random.randn}(1,1)) \\  \end{bmatrix}   f(x) = x^T A x - 2b^T x + c \\ \Rightarrow \nabla f(x) = 2Ax - 2b \\ \Rightarrow \nabla^2 f(x) = 2A \\ \nabla^2 f(x) \geq 0 \Rightarrow f \text{ is convex} \\ 2 * A \geq 0 \Rightarrow A \geq 0 \Rightarrow A \text{ is positive semi definite} \Rightarrow f \text{ is convex or not.}  So we need to check if A is positive semi definite or not to know if f is convex or not.
```

```
[6]: def f(x):
    return x.T @ A @ x -2 * b.T @ x + c

def gradient_f(x):
    return 2 * A @ x - 2 * b

def grad_grad_f(x):
    return 2 * A

def is_pos_sem_def(x):
    return np.all(np.linalg.eigvals(x) >= 0)
```

0.2.1 Problem 2 (a)

Analytical solution

```
[7]: if is_pos_sem_def(A):
    print("A is semi positive definite, hence f is convex")
```

A is semi positive definite, hence f is convex

By setting the gradient of f to zero, we can find the analytical solution $\Rightarrow \nabla f(x) = 0$ $\Rightarrow 2Ax - 2b = 0$ $\Rightarrow x = A^{-1}b$

```
[8]: result_gradient_zero = np.matrix(A.I @ b)
```

```
[10]: print("Minimizer using gradient zero:", result_gradient_zero)
               print("Analytical solution by setting gradient to zero:", analytical_solution)
             Minimizer using gradient zero: [[-9.15256852]
                [ 2.78083746]
                [-1.18661204]
                [ 1.32064519]
                [-7.09335175]
                [13.35628316]
                [-3.38601289]
                [ 2.42614784]
                [-0.79290161]
                [ 9.7378983 ]]
             Analytical solution by setting gradient to zero: -28.24615806045249
             0.2.2 Problem 2 (b)
             Gradient descent Initial point x_0 = [1/10, 1/10, 1/10, 1/10, 1/10, 1/10, 1/10, 1/10, 1/10]^T
             where x_0 \in \mathbb{R}^{10}
[11]: x0 = np.matrix([[1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10]
                  →10],[1/10]])
             Step size l_{GD} = \frac{1}{2||A||+||b||_2} where ||A|| is the spectral norm of A and ||b||_2 is the 2-norm of b
[12]: a_norm = np.linalg.norm(A, ord=2)
               b norm = np.linalg.norm(b)
               step\_size = 1 / ((2*a\_norm) + b\_norm)
[13]: def gradient_descent(x0, step_size, num_iterations):
                          11 11 11
                         Gradient descent algorithm
                          :param x0: np.matrix - Initial point
                          :param step_size: float - step size
                          :param num_iterations: int - number of iterations
                          :return: value of x after num iterations, list of objective values
                          HHHH
                         x = x0
                         f_list = []
                         for i in range(num_iterations):
                                   x = x - step_size * gradient_f(x)
                                    f list.append(f(x).tolist()[0][0])
                         return x, f_list
[14]: result_gradient_descent, f_list = gradient_descent(x0, step_size, 1000)
               optimal_solution = f(result_gradient_descent)[0,0]
[15]:
```

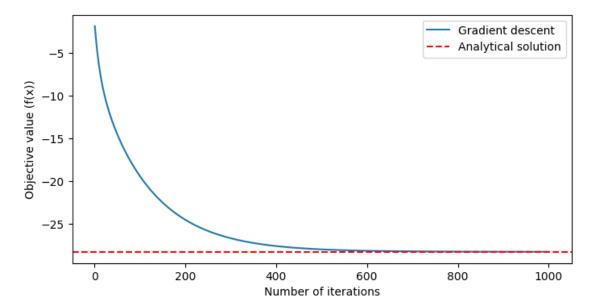
```
[16]: print("Minimizer using gradient descent:", result_gradient_descent)
print("Optimal Solution by using gradient descent:", optimal_solution)
```

```
Minimizer using gradient descent: [[-9.03581218]
  [ 2.72650626]
  [-1.14045911]
  [ 1.29836243]
  [-6.98249168]
  [13.19409598]
  [-3.3210739 ]
  [ 2.37920814]
  [-0.77443266]
  [ 9.6221097 ]]
```

Optimal Solution by using gradient descent: -28.242278949955974

In the following plot, the blue line shows the objective value after each iteration and the red dashed line shows the analytical solution.

```
[17]: plt.figure(figsize=(8,4))
   plt.plot(range(1,1001), f_list)
   plt.xlabel("Number of iterations")
   plt.ylabel("Objective value (f(x))")
   plt.axhline(y=analytical_solution, color='r', linestyle='--')
   plt.legend(["Gradient descent", "Analytical solution"])
   plt.show()
```



You can see that the objective value decreases after each iteration and converges to the analytical solution.