2

September 30, 2023

0.0.1 Importing libraries

```
[1]: import numpy as np
from sklearn.datasets import make_spd_matrix
import matplotlib.pyplot as plt
```

Generating A randomly using $sklearn.datasets.make_spd_matrix, and generate <math>b$ and c using np.random.rand function of numpy.

```
[2]: A = np.matrix(make_spd_matrix(10))
b = np.matrix(np.random.randn(10,1))
c = np.matrix(np.random.randn(1,1))
```

```
f(x) = x^T A x - 2b^T x + c
\Rightarrow \nabla f(x) = 2Ax - 2b
\Rightarrow \nabla^2 f(x) = 2A
\nabla^2 f(x) > 0 \Rightarrow f \text{ is convex}
```

 $2*A>0 \Rightarrow A>0 \Rightarrow A$ is positive definite $\Rightarrow f$ is convex

So we need to check if A is positive definite or not to know if f is convex or not.

```
[3]: def f(x):
    return x.T @ A @ x -2 * b.T @ x + c

def gradient_f(x):
    return 2 * A @ x - 2 * b

def grad_grad_f(x):
    return 2 * A

def is_pos_def(x):
    return np.all(np.linalg.eigvals(x) > 0)
```

0.0.2 Problem 2 (a)

Analytical solution

```
[4]: if is_pos_def(A):
    print("A is positive definite, hence f is convex")
```

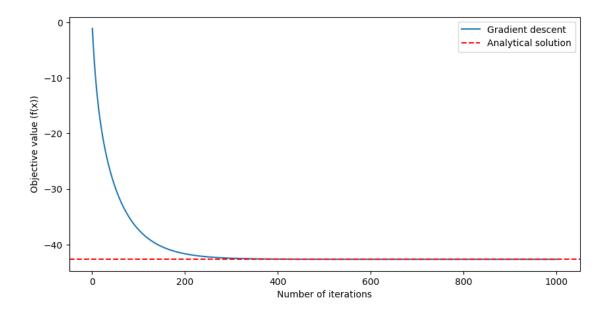
A is positive definite, hence f is convex

```
By setting the gradient of f to zero, we can find the analytical solution \Rightarrow \nabla f(x) = 0
              \Rightarrow 2Ax - 2b = 0
              \Rightarrow x = A^{-1}b
  [5]: result_gradient_zero = np.matrix(A.I @ b)
  [6]: analytical_solution = f(result_gradient_zero)[0,0]
  [7]: print("Minimizer using gradient zero:", result_gradient_zero)
               print("Analytical solution by setting gradient to zero:", analytical_solution)
             Minimizer using gradient zero: [[-1.47773205]
                [ 0.62229752]
                [ 4.27234816]
                [ 2.28670366]
                [ 8.4446222 ]
                [ 1.05823733]
                [-5.28442647]
                [ 6.65035515]
                [-7.22577486]
                [-9.69219262]]
             Analytical solution by setting gradient to zero: -42.65716526724658
             0.0.3 Problem 2 (b)
             Gradient descent Initial point x_0 = [1/10, 1/10, 1/10, 1/10, 1/10, 1/10, 1/10, 1/10, 1/10]^T
             where x_0 \in \mathbb{R}^{10}
  [8]: x0 = np.matrix([[1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10], [1/10],
                  410],[1/10]])
             Step size l_{GD} = \frac{1}{2||A||+||b||_2} where ||A|| is the spectral norm of A and ||b||_2 is the 2-norm of b
  [9]: a_norm = np.linalg.norm(A, ord=2)
               b_norm = np.linalg.norm(b)
               step_size = 1 / ((2*a_norm) + b_norm)
[10]: def gradient_descent(x0, step_size, num_iterations):
                          Gradient descent algorithm
                          :param x0: np.matrix - Initial point
                          :param step_size: float - step size
                          :param num_iterations: int - number of iterations
                          :return: value of x after num_iterations, list of objective values
                          11 11 11
                         x = x0
                         f list = []
                         for i in range(num_iterations):
                                    x = x - step_size * gradient_f(x)
```

```
f_list.append(f(x).tolist()[0][0])
          return x, f_list
[11]: result_gradient_descent, f_list = gradient_descent(x0, step_size, 1000)
[12]: optimal_solution = f(result_gradient_descent)[0,0]
[13]: print("Minimizer using gradient descent:", result_gradient_descent)
      print("Optimal Solution by using gradient descent:", optimal_solution)
     Minimizer using gradient descent: [[-1.47790535]
      [ 0.62156988]
      [ 4.27138982]
      [ 2.28593234]
      [ 8.44167565]
      [ 1.05848769]
      [-5.28260315]
      [ 6.64963057]
      [-7.22392569]
      [-9.69060684]]
     Optimal Solution by using gradient descent: -42.657163232877686
```

In the following plot, the blue line shows the objective value after each iteration and the red dashed line shows the analytical solution.

```
[14]: plt.figure(figsize=(10,5))
   plt.plot(range(1,1001), f_list)
   plt.xlabel("Number of iterations")
   plt.ylabel("Objective value (f(x))")
   plt.axhline(y=analytical_solution, color='r', linestyle='--')
   plt.legend(["Gradient descent", "Analytical solution"])
   plt.show()
```



You can see that the objective value decreases after each iteration and converges to the analytical solution.