Assignment -1

* 1-0 Steady State Conduction

Creneral Transport Equation is;

 $\frac{\partial \phi}{\partial t} + (U \cdot \nabla) \phi = \nabla (\Gamma \cdot \nabla) \phi + S$

Here 20 is time related term,

 $(\upsilon \cdot \nabla) \not \phi$ is conduction term, $\nabla (\Gamma \cdot \nabla) \not \phi$ in Diffusion term, S is bounce term,

For 1-D Steady State Conduction,

V(r.v) & will be not be zero where there is no Source term so it will be zero and conduction will also be zero.

Also we are assuming I as constant.

 $\frac{1}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} = 0$

But as we are taking I-D only, x term is there and y and z are zero.

is T (
$$\frac{3^2T}{33^2}$$
)

as T depends only on x, we can rewrite as,

$$\frac{d^2T}{dx^2} = 0$$

$$\frac{dx^2}{dx^2}$$
Using Finite Difference method,

$$\frac{d^2T}{dx^2} = 0$$

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Using Taylox's Expansion;

$$T(x+h) = T(x) + \frac{dT \cdot h}{dx} + \frac{d^2T \cdot h^2}{dx} + \dots$$

$$\frac{dx}{dx} \frac{dx^2}{2}$$

$$T(x-h) = T(x) - \frac{dT \cdot h}{dx} + \frac{d^2T \cdot h^2}{dx^2} + \dots$$

$$\frac{dx}{dx^2} \frac{dx^2}{2}$$

$$\therefore T(x+h) + T(x-h) = 2T(x) + \frac{d^2T}{dx^2} \cdot h^2$$

$$\frac{dx^2}{dx^2} = T(x+h) - 2T(x) + T(x-h)$$

$$\frac{dx^2}{dx^2} = T(x+h) - 2T(x) + T(x-h) = 0$$

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			T1	T2	Т3	T4	Т5	Т6		
NUMERICAL METHOD			46.1 T1 46.1	44.1 T2 44.34	42.7 T3	40.8 T4 40.81	39.5 T5 39.06	37.3		
								T6 37.3		
TIME	T1	T2	Т3	T4	T5 1	Г6				
7.77	0 46.1		40.000	40.000	The second second	37.3				
	5 46.1		40.000	40.000		37.3				
	10 46.1		41.525	39.325		37.3				
	15 46.1		41.188	40.088		37.3				
	20 46.1		41.950	39.750	190000000000000000000000000000000000000	37.3				
	25 46.1		41.697	40.322	100000000000000000000000000000000000000	37.3				
	30 46.1	The second second second	42.173	40.111	diameter (Control Control Cont	37.3				
	35 46.1		42.005	40.492		37.3				
	40 46.1	100000000000000000000000000000000000000	42.314	40.355		37.3				
	45 46.1		42.204	40.605		37.3				
	50 46.1		42.406	40.516		37.3				
	55 46.1		42.334	40.679		37.3				
	60 46.1	- Control State Control	42.466	40.621	4	37.3				
	65 46.1	100000	42.419	40.728		37.3				
	70 46.1	44.259	42.506	40.690	39.014	37.3				
	75 46.1		42.475	40.760	38.995	37.3				
	80 46.1	44.287	42.531	40.735	39.030	37.3				
	85 46.1	44.316	42.511	40.781	39.017	37.3				
	90 46.1	44.305	42.548	40.764		37.3				
	95 46.1	44.324	42.535	40.794	39.032	37.3				
11	00 46.1	44.317	42.559	40.783	39.047	37.3				
1	05 46.1	44.330	42.550	40.803	39.042	37.3				
1	10 46.1	44.325	42.566	40.796	39.052	37.3				
. 4	15 46.1	44.333	42.561	40.809	39.048	37.3				
1:	20 46.1			40.804		37.3				
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