

ASSIGNMENT 3

COMPUTATIONAL FLUID DYNAMICS



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Monsoon 2021

1D Linear Hyperbolic Wave Equation

FTCS Scheme computation code (Page 2-12)

```
# include <stdlib.h>
# include <stdio.h>
# include <math.h>
# include <time.h>
# include <string.h>
```

```
int main ();
int i4_modp ( int i, int j );
int i4_wrap ( int ival, int ilo, int ihi );
double *initial_condition ( int nx, double x[] );
double *r8vec_linspace_new ( int n, double a, double b );
void timestamp ( );
```

```
/******
```

```
int main ( )
```

```
/******
```

```
/*
```

Purpose:

FD1D_ADVECTION_FTCS solves the advection equation using the FTCS method.

Discussion:

The FTCS method is unstable for the advection problem.

Given a smooth initial condition, successive FTCS approximations will exhibit erroneous oscillations of increasing magnitude.

```
*/
{
    double a;

    double b;

    double c;

    char command_filename[] = "advection_commands.txt";

    FILE *command_unit;

    char data_filename[] = "advection_data.txt";

    FILE *data_unit;

    double dt;

    double dx;

    int i;

    int j;

    int jm1;

    int jp1;

    int nx;

    int nt;

    int nt_step;

    double t;

    double *u;

    double *unew;

    double *x;

    timestamp ( );

    printf ( "\n" );

    printf ( "FD1D_ADVECTION_FTCS:\n" );

    printf ( " C version\n" );

    printf ( "\n" );

    printf ( " Solve the constant-velocity advection equation in 1D,\n" );

    printf ( "  $du/dt = -c du/dx$ \n" );
```

```

printf ( " over the interval:\n" );

printf ( " 0.0 <= x <= 1.0\n" );

printf ( " with periodic boundary conditions, and\n" );

printf ( " with a given initial condition\n" );

printf ( " u(0,x) = 0.0 for 0.5 <= x\n" );

printf ( " = 1.0 elsewhere.\n" );

printf ( "\n" );

printf ( " We use a method known as FTCS:\n" );


nx = 201;

dx = 1.0 / ( double ) ( nx - 1 );

a = 0.0;

b = 1.0;

x = r8vec_linspace_new ( nx, a, b );

nt = 50;

float lambda[]={0.2,0.8,0.9,1.0,1.1};

float lmb;

dt = 1.0 / ( double ) ( nt );

c = 1.0;


u = initial_condition ( nx, x );

/*

Open data file, and write solutions as they are computed.

*/

data_unit = fopen ( data_filename, "wt" );


t = 0.0;

fprintf ( data_unit, "%10.4f %10.4f %10.4f\n", x[0], t, u[0] );

for ( j = 0; j < nx; j++ )

{

    fprintf ( data_unit, "%10.4f %10.4f %10.4f\n", x[j], t, u[j] );

}

fprintf ( data_unit, "\n" );

```

```

nt_step = 10;

printf ( "\n" );

printf ( " Number of nodes NX = %d\n", nx );

printf ( " Number of time steps NT = %d\n", nt );

printf ( " Constant velocity C = %g\n", c );

unew = ( double * ) malloc ( nx * sizeof ( double ) );

for ( i = 0; i < nt; i++ )
{ lmb=lambda[i];
  for ( j = 0; j < nx; j++ )
  {
    jm1 = i4_wrap ( j - 1, 0, nx - 1 );
    jp1 = i4_wrap ( j + 1, 0, nx - 1 );
    unew[j] = u[j] - lmb / 2.0 * ( u[jp1] - u[jm1] );
  }
  for ( j = 0; j < nx; j++ )
  {
    u[j] = unew[j];
  }
  if ( i == nt_step - 1 )
  {
    t = ( double ) ( i ) * dt;
    for ( j = 0; j < nx; j++ )
    {
      fprintf ( data_unit, "%10.4f %10.4f %10.4f\n", x[j], t, u[j] );
    }
    fprintf ( data_unit, "\n" );
    nt_step = nt_step + 15;
  }
}
/*

```

Close the data file once the computation is done.

```

*/

fclose ( data_unit );

printf ( "\n" );

printf ( " Plot data written to the file \"%s\"\n", data_filename );

return 0;

}

/*****
/

int i4_modp ( int i, int j )

/

/*

```

Purpose:

I4_MODP returns the nonnegative remainder of I4 division.

Discussion:

If

NREM = I4_MODP (I, J)

NMULT = (I - NREM) / J

then

I = J * NMULT + NREM

where NREM is always nonnegative.

The MOD function computes a result with the same sign as the

quantity being divided. Thus, suppose you had an angle A,

and you wanted to ensure that it was between 0 and 360.

Then mod(A,360) would do, if A was positive, but if A

was negative, your result would be between -360 and 0.

On the other hand, I4_MODP(A,360) is between 0 and 360, always.

Example:

I	J	MOD	I4_MODP	I4_MODP	Factorization
---	---	-----	---------	---------	---------------

107	50	7	7	107 = 2 * 50 + 7
-----	----	---	---	------------------

107	-50	7	7	107 = -2 * -50 + 7
-----	-----	---	---	--------------------

-107	50	-7	43	-107 = -3 * 50 + 43
------	----	----	----	---------------------

-107	-50	-7	43	-107 = 3 * -50 + 43
------	-----	----	----	---------------------

Parameters:

Input, int I, the number to be divided.

Input, int J, the number that divides I.

Output, int I4_MODP, the nonnegative remainder when I is divided by J.

*/

{

int value;

if (j == 0)

{

fprintf (stderr, "\n");

fprintf (stderr, "I4_MODP - Fatal error!\n");

fprintf (stderr, " I4_MODP (I, J) called with J = %d\n", j);

exit (1);

}

value = i % j;

if (value < 0)

{

```

        value = value + abs ( j );
    }

    return value;
}

/*****

```

```

int i4_wrap ( int ival, int ilo, int ihi )

```

```

/*****
/*

```

Purpose:

I4_WRAP forces an **I4** to lie between given limits by wrapping.

Parameters:

Input, int IVAL, an integer value.

Input, int ILO, IHI, the desired bounds for the integer value.

Output, int I4_WRAP, a "wrapped" version of **IVAL**.

```

*/
{
    int jhi;
    int jlo;
    int value;
    int wide;

    if ( ilo < ihi )
    {
        jlo = ilo;
        jhi = ihi;
    }
    else

```



```

{
    jlo = ihi;
    jhi = ilo;
}

wide = jhi + 1 - jlo;

if ( wide == 1 )
{
    value = jlo;
}
else
{
    value = jlo + i4_modp ( ival - jlo, wide );
}

return value;
}

/*****/

double *initial_condition ( int nx, double x[] )

/*****/

/*

```

Purpose:

INITIAL_CONDITION sets the initial condition.

Parameters:

Input, int NX, the number of nodes.

Input, double X[NX], the coordinates of the nodes.

Output, double INITIAL_CONDITION[NX], the value of the initial condition.

```
*/  
  
{  
  
    int i;  
  
    double *u;  
  
  
    u = ( double * ) malloc ( nx * sizeof ( double ) );  
  
  
    for ( i = 0; i < nx; i++ )  
    {  
        if ( 0.5 <= x[i] )  
        {  
            u[i] = 0.0;  
        }  
        else  
        {  
            u[i] = 1.0;  
        }  
    }  
    return u;  
}  
  
/*****
```

double *r8vec_linspace_new (int n, double a, double b)

```
*****/  
  
/*
```

Purpose:

R8VEC_Linspace_NEW creates a vector of linearly spaced values.

Discussion:

An R8VEC is a vector of R8's.

4 points evenly spaced between 0 and 12 will yield 0, 4, 8, 12.

In other words, the interval is divided into $N-1$ even subintervals,
and the endpoints of intervals are used as the points.

Parameters:

Input, int N, the number of entries in the vector.

Input, double A, B, the first and last entries.

Output, double R8VEC_Linspace_NEW[N], a vector of linearly spaced data.

```
*/  
{  
    int i;  
    double *x;  
  
    x = ( double * ) malloc ( n * sizeof ( double ) );  
  
    if ( n == 1 )  
    {  
        x[0] = ( a + b ) / 2.0;  
    }  
    else  
    {  
        for ( i = 0; i < n; i++ )  
        {  
            x[i] = ( ( double ) ( n - 1 - i ) * a  
                    + ( double ) ( i ) * b )  
                    / ( double ) ( n - 1 );  
        }  
    }  
    return x;
```

}

/*****

```
# include <stdlib.h>

# include <stdio.h>

# include <math.h>

# include <time.h>

# include <string.h>
```

```
int i4_modp ( int i, int j );
```

```
double *initial_condition ( int nx, double x[] );
```

```
void timestamp ( );
```

```
int main ( )
```

/*

FD1D_ADVECTION_LAX solves the advection equation using the Lax method.

The Lax method is stable for the advection problem, if the time step satisfies the Courant-Friedrichs-Levy (CFL) condition:

$\ast/$

```

{

double a;

double b;

double c;

char command_filename[] = "advection_commands.txt";

FILE *command_unit;

char data_filename[] = "advection_data.txt";

FILE *data_unit;

double dt;

double dx;

int i;

int j;

int jm1;

int jp1;

int nx;

int nt;

int nt_step;

double t;

double *u;

double *unew;

double *x;


printf ( "\n" );

printf ( "FD1D_ADVECTION_LAX:\n" );

printf ( " C version\n" );

printf ( "\n" );

printf ( " Solve the constant-velocity advection equation in 1D,\n" );

printf ( "  du/dt = - c du/dx\n" );

printf ( " over the interval:\n" );

printf ( "  0.0 <= x <= 1.0\n" );

printf ( " with periodic boundary conditions, and\n" );

printf ( " with a given initial condition\n" );

```

```

printf ( "    u(0,x) = 0.0 for 0.5 <= x \n" );

printf ( "        = 1.0 elsewhere.\n" );

printf ( "\n" );

printf ( " We modify the FTCS method using the Lax method:\n" );

```

```

nx = 201;

dx = 1.0 / ( double ) ( nx - 1 );

a = 0.0;

b = 1.0;

x = r8vec_linspace_new ( nx, a, b );

nt = 50;

float lambda[] = {0.2,0.8,0.9,1.0,1.1};

float lmb;

dt = 1.0 / ( double ) ( nt );

c = 1.0;

```

```

u = initial_condition ( nx, x );

data_unit = fopen ( data_filename, "wt" );

```

```

t = 0.0;

fprintf ( data_unit, "%10.4f %10.4f %10.4f\n", x[0], t, u[0] );

for ( j = 0; j < nx; j++ )

{

    fprintf ( data_unit, "%10.4f %10.4f %10.4f\n", x[j], t, u[j] );

}

fprintf ( data_unit, "\n" );

```

```

nt_step = 10;

```

```

printf ( "\n" );

printf ( " Number of nodes NX = %d\n", nx );

printf ( " Number of time steps NT = %d\n", nt );

```

```
printf ( " Constant velocity C = %g\n", c );
```

```
unew = ( double * ) malloc ( nx * sizeof ( double ) );
```

```
for ( i = 0; i < nt; i++ )
```

```
{ lmb=lambda[i];
```

```
for ( j = 0; j < nx; j++ )
```

```
{
```

```
jm1 = i4_wrap ( j - 1, 0, nx - 1 );
```

```
jp1 = i4_wrap ( j + 1, 0, nx - 1 );
```

```
unew[j] = 0.5 * u[jm1] + 0.5 * u[jp1]
```

```
- lmb * ( u[jp1] - u[jm1] ) + (lmb*lmb)/2.0*(u[jp1] -2*u[ceil((jp1+jm1)/2.0)] +u[jm1]);
```

```
}
```

```
for ( j = 0; j < nx; j++ )
```

```
{
```

```
u[j] = unew[j];
```

```
}
```

```
if ( i == nt_step - 1 )
```

```
{
```

```
t = ( double ) ( i ) * dt;
```

```
for ( j = 0; j < nx; j++ )
```

```
{
```

```
fprintf ( data_unit, "%10.4f %10.4f %10.4f\n", x[j], t, u[j] );
```

```
}
```

```
fprintf ( data_unit, "\n" );
```

```
nt_step = nt_step + 15;
```

```
}
```

```
}
```

```
/*
```

```
Close the data file once the computation is done.
```

```
*/
```

```
fclose ( data_unit );
```



```
printf ( "\n" );

printf ( " Plot data written to the file \"%s\\n", data_filename );
```

```
return 0;
```

```
}
```

```
/******
```

```
int i4_modp ( int i, int j )
```

```
/******
```

```
/*
```

Purpose:

I4_MODP returns the nonnegative remainder of I4 division.

Discussion:

If

$$\text{NREM} = \text{I4_MODP} (I, J)$$

$$\text{NMULT} = (I - \text{NREM}) / J$$

then

$$I = J * \text{NMULT} + \text{NREM}$$

where NREM is always nonnegative.

The MOD function computes a result with the same sign as the

quantity being divided. Thus, suppose you had an angle A,

and you wanted to ensure that it was between 0 and 360.

Then mod(A,360) would do, if A was positive, but if A

was negative, your result would be between -360 and 0.

On the other hand, I4_MODP(A,360) is between 0 and 360, always.

Example:

I J MOD I4_MODP I4_MODP Factorization

$$107 \quad 50 \quad 7 \quad 7 \quad 107 = 2 * 50 + 7$$

$$107 \quad -50 \quad 7 \quad 7 \quad 107 = -2 * -50 + 7$$

$$-107 \quad 50 \quad -7 \quad 43 \quad -107 = -3 * 50 + 43$$

$$-107 \quad -50 \quad -7 \quad 43 \quad -107 = 3 * -50 + 43$$

Parameters:

Input, int I, the number to be divided.

Input, int J, the number that divides I.

Output, int I4_MODP, the nonnegative remainder when I is
divided by J.

*/

{

int value;

if (j == 0)

{

fprintf (stderr, "\n");

fprintf (stderr, "I4_MODP - Fatal error!\n");

fprintf (stderr, " I4_MODP (I, J) called with J = %d\n", j);

exit (1);

}

value = i % j;

```
return value;
}
```

```
int wide;
```

```
if ( ilo < ihi )
```

```
{
```

```
    jlo = ilo;
```

```
    jhi = ihi;
```

```
}
```

```
else
```

```
{
```

```
    jlo = ihi;
```

```
    jhi = ilo;
```

```
}
```

```
wide = jhi + 1 - jlo;
```

```
if ( wide == 1 )
```

```
{
```

```
    value = jlo;
```

```
}
```

```
else
```

```
{
```

```
    value = jlo + i4_modp ( ival - jlo, wide );
```

```
}
```

```
return value;
```

```
}
```

```
/******
```

```
double *initial_condition ( int nx, double x[] )
```

```
/******
```

```
/*
```

Purpose:

INITIAL_CONDITION sets the initial condition.

Parameters:

Input, int NX, the number of nodes.

Input, double X[NX], the coordinates of the nodes.

Output, double INITIAL_CONDITION[NX], the value of the initial condition.

```
*/  
{  
    int i;  
    double *u;  
  
    u = ( double * ) malloc ( nx * sizeof ( double ) );  
  
    for ( i = 0; i < nx; i++ )  
    {  
        if ( 0.5 <= x[i] )  
        {  
            u[i] = 0.0;  
        }  
        else  
        {  
            u[i] = 1.0;  
        }  
    }  
    return u;  
}  
  
/*****/
```

```
double *r8vec_linspace_new ( int n, double a, double b )
```

```
/******
```

```
{
```

```
int i;
```

```
double *x;
```

```
x = ( double * ) malloc ( n * sizeof ( double ) );
```

```
if ( n == 1 )
```

```
{
```

```
  x[0] = ( a + b ) / 2.0;
```

```
}
```

```
else
```

```
{
```

```
  for ( i = 0; i < n; i++ )
```

```
  {
```

```
    x[i] = ( ( double ) ( n - 1 - i ) * a
```

```
            + ( double ) (      i ) * b )
```

```
            / ( double ) ( n - 1 );
```

```
  }
```

```
}
```

```
return x;
```

```
}
```

Plots

FTCS Scheme



