

$$Q(s_i) = \frac{w_i}{n_i} + c \sqrt{\frac{\ln F_i}{n_i}}$$

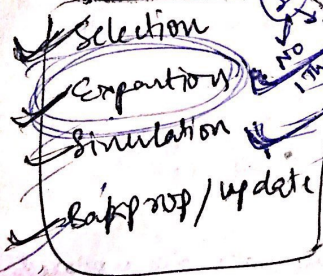
$$V_i = \frac{t_i}{n_i}$$

$$Q(s_i) = V_i + c \sqrt{\frac{\ln t_i}{n_i}}$$

Algorithm for tree traversal and node expansion:

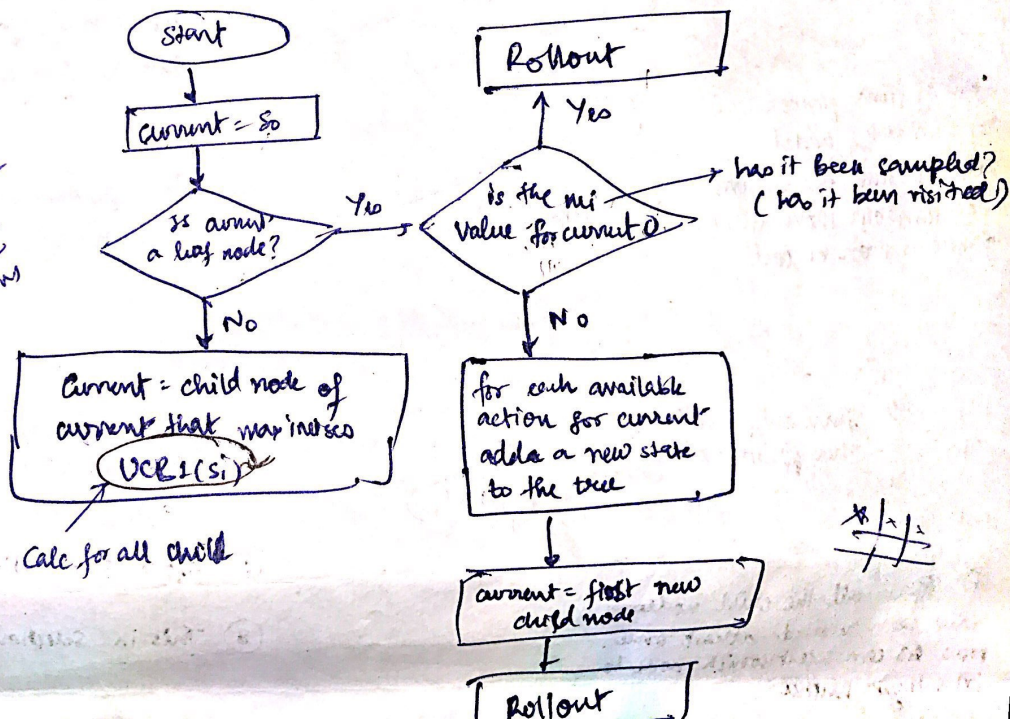
(4)

2 stages



$w$  = no. of wins after the  $i$ th move  
 $n$  = no. of simulations after  $i$ th move  
 $c$  = exploration parameter

$F$  = total no. of simulations for parent node



MCST  
MCTS

MCST  
MCST

Rollout (S) (Simulation)

Loop form

If  $S_i$  is terminal state:

return value( $S_i$ )

$A_i = \text{random}(\text{available actions}(S_i))$

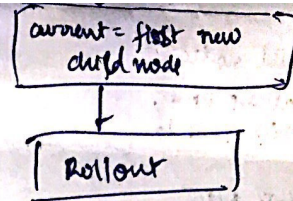
$S_i = \text{simulate}(A_i, S_i)$

Worked example:

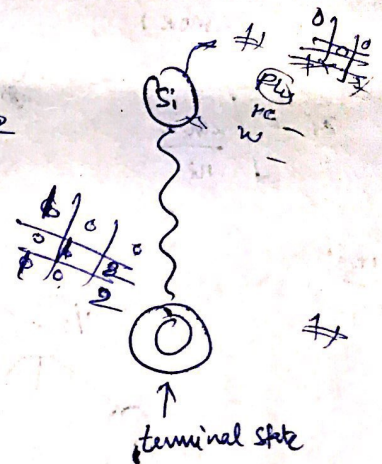
$$UCB1(S_i) = \bar{V}_i + \underbrace{c}_{\text{exploration}} \sqrt{\frac{\ln(N)}{n_i}} \leftarrow \text{exploration}$$

Let  $c = 2$

Significance of  $UCB1(S_i)$ : It depicts the tradeoff b/w exploitation and exploration,  $c$  is used to adjust b/w the two

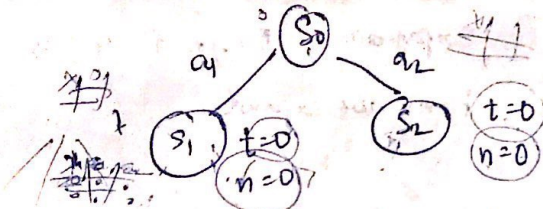


$x_1$

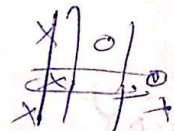
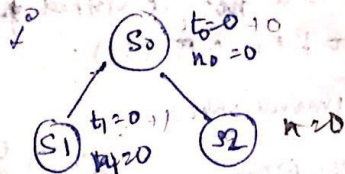


$\frac{1}{n}$

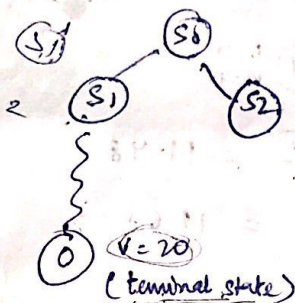




$UCB1(S_i) = \infty$  for both  $S_1$  and  $S_2$  as  $n=0$  for both hence, we can select any.



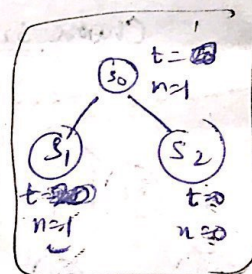
As it is a leaf node, we check, has it been visited or not yet?  
 1.  $S_1$  here hasn't been visited, therefore  $POLL\ OUT(S_1)$



Now, we go to back propagation phase

$S_0, t_1 = 20$   
 $n_1 = 1$  } for  $S_1$

$t_0 = 20$   
 $n = 1$  } for  $S_0$



So, you can run it for any no. of iterations.

After 1st Iter

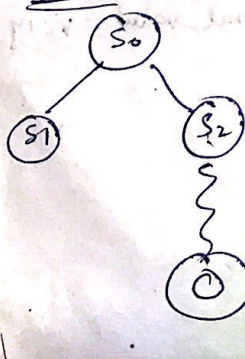
Str 2

$$UCB1(S_1) = 20 + 2 \times \sqrt{\frac{\ln(1)}{1}} = 20$$

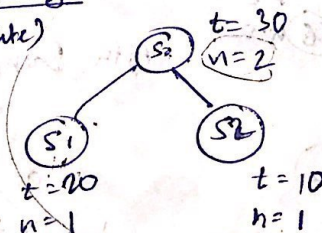
$$UCB1(S_2) = \infty$$

Hence, we visit  $S_2$ , (in general if ~~you~~ you have a sibling with  $n=0$ , then it is chosen first.)

Rollout ( $S_2$ )



After backprop stage:  
 (2nd Iter complete)

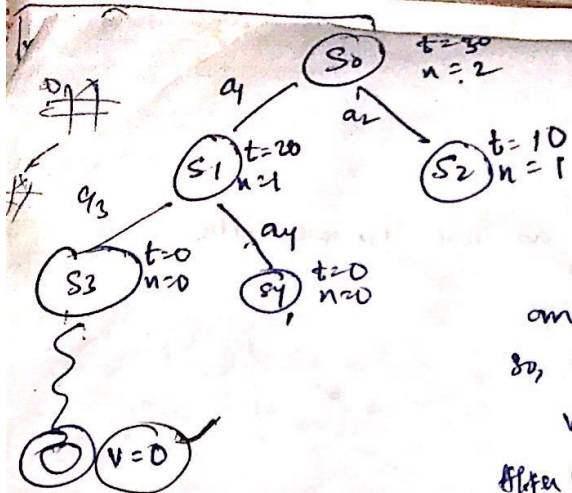


Iter 3

$$UCB1(S_1) = 20 + 2 \sqrt{\frac{\ln(2)}{1}} = 21.67$$

$$UCB1(S_2) = 10 + 2 \sqrt{\frac{\ln(2)}{1}} = 11.67$$



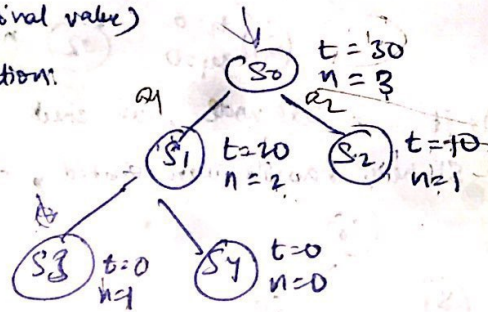


Expansions:  $t=30$  for  $S1$   $n \neq 0$   
 Hence we expand

Choose one of  $S3$  &  $S4$ , but they have same value, hence choose  $S3$   
 and as it is a not yet visited ~~leaf~~ leaf node, so, we do ROLLOUT ( $S3$ ):

$V=0$  (Terminal value)

After Backpropagation:



Str 4 Choose b/w  $S1$ ,  $S2$ :

$$VCB(S1) = 20 + 2 \sqrt{\frac{\ln 2}{2}} = 11.48$$

$$VCB(S2) = 10 + 2 \sqrt{\frac{\ln 1}{1}} = 11.67$$

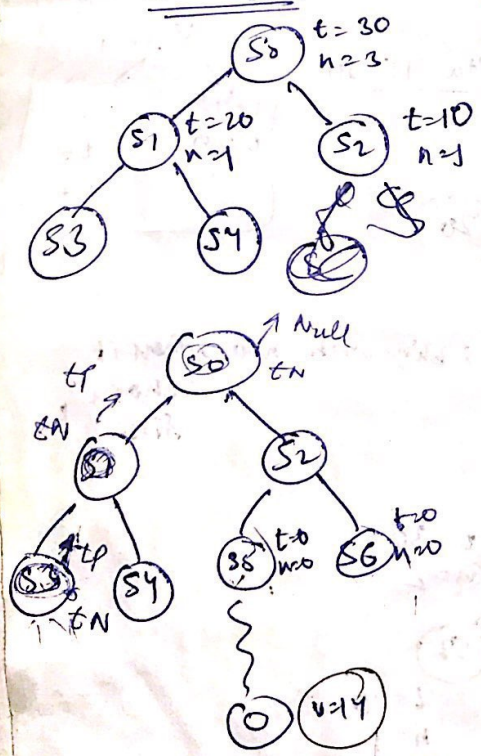
Choose  $S2$ :

$S2$  is a leaf node but it is already explored, hence we look for all actions that can take place, let actions be  $a5, a6$  then

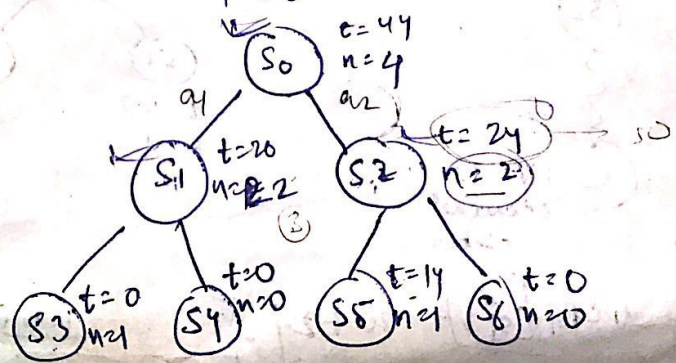
Choose any of  $S5$  and  $S6$ :

Let us choose  $S5$ , as it is unvisited leaf node, hence POLLOUT ( $S5$ ):

let terminal value  $= V=14$



After Backpropagation:



So, after 4 iterations we conclude that  $a2$  is the best action as it has highest value of