

Menger's Theorem

UTH 303 - Notes for
Tuesday 20150310

(7)

(1)

Recall: $\kappa(x, y) =$ minimum size of an x, y - cut or xy - separator

$\lambda(x, y) =$ maximum no. of internally disjoint xy - paths.

An xy - cut must contain at least one vertex from each xy - path and no vertex can cut two internally disjoint xy - paths.

$\therefore \kappa(x, y) \geq \lambda(x, y)$ is again a dual-type of problem.

Proof is lengthy and will be ~~omitted~~ left for reference only.

Proof of lemma 5.1: If P is an f -augmenting path with tolerance z , then changing flow by $+z$ on edges followed forward on P and by $-z$ on edges followed backward on P produces a feasible flow with $\text{val}(f') = \text{val}(f) + z$.

Proof: ~~We need~~ NB:- we only need to check the edges on P , since other edges are not affected.

First, we need to check the capacity constraints:-

But, if e is a forward edge, then

$$0 \leq f'(e) = f(e) + z = g^+(e) \leq c(e),$$

and if e is backward, then

$$c(e) \geq f'(e) = f(e) - z = g^-(e) \geq 0$$

(*) by definition of z tolerance.

Next, we need to check the z constraint

$$g^+(u) = g^-(v) \text{ on } P.$$

There are four cases. (see diagram)

$$\text{Case 1. } \begin{cases} g^+(u) = f^+(u) + z \\ g^-(v) = f^-(v) + z \end{cases} \Rightarrow g^+(u) = g^-(v)$$

$$\text{Case 2. } \begin{cases} g^+(u) = f^+(u) + z \\ g^-(v) = f^-(v) + z \end{cases} \Rightarrow g^+(u) \neq g^-(v)$$

Simply, the remaining two cases.

$$\begin{aligned} \text{Finally, we have } \text{val}(g) &= g^-(t) - g^+(t) \\ &= \begin{cases} f^-(t) + z - f^+(t) = f^-(t) - f^+(t) + z = \text{val}(f) + z \\ f^-(t) - [f^+(t) - z] = f^-(t) - f^+(t) + z = \text{val}(f) + z, \end{cases} \end{aligned}$$

according as the ~~at~~ final edge on P is forward or backward

Why does the Ford-Fulkerson Algorithm Work?

~~1. NB~~ Every s, t -path uses an edge from $[S, T]$, so intuitively the value of a feasible flow should be bounded (above) by the capacity of the cut $[S, T]$.

For any set of vertices U , we put

$$f^+(U) = \text{Total flow on edges leaving } U$$

$$f^-(U) = \text{Total flow on edges entering } U$$

The net flow out of U is then $f^+(U) - f^-(U)$.

We see: ~~$f^+(U)$~~ net flow out of U
 $=$ sum of net flows ~~in~~ of vertices in U .

In particular, if f is a feasible flow and $[S, T]$ is a source-sink cut, then net flow out of S and net flow into T equal $\text{val}(f)$.

Proof: The claim is $f^+(U) - f^-(U) = \sum_{v \in U} (f^+(v) - f^-(v))$

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We consider the contribution of the flow $f(xy)$ of each edge xy on both sides of U . If ~~edge~~ $x, y \in U$, then $f(xy)$ is not counted on the left, but it contributes $+ve$ via x and $-ve$ via y on right. If $x, y \notin U$, then $f(xy)$ doesn't contribute at all. If $xy \in [U, \bar{U}]$, then it contributes $+ve$ on both sides. If $xy \in [\bar{U}, U]$, then it contributes $-ve$ on both sides.

Summing over all edges, we get the equality (1)

when $[S, T]$ is a source-sink cut and f is a feasible flow, net flow from nodes of S sum to $f^+(S) - f^-(S)$ and net flow from nodes of T equals $f^+(T) - f^-(T) = -\text{val}(f)$, as reqd.

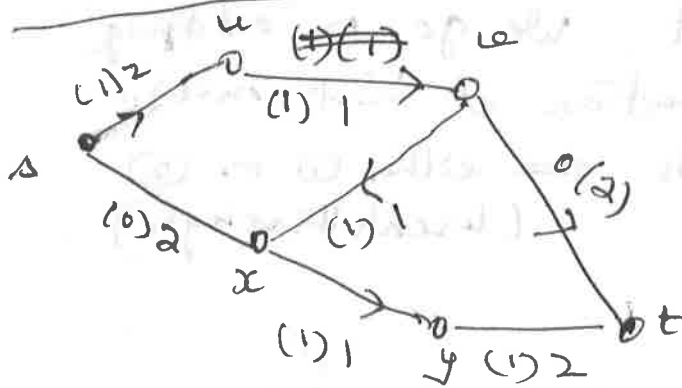
Corollary:- If f is a feasible flow, and $[S, T]$ is a source-sink cut, then $\text{val}(f) \leq \text{cap}[S, T]$.

By above: value of f = net flow out of S ,
 i.e. $\text{val}(f) = f^+(S) - f^-(S) \leq f^+(S)$,
 since the flow into S is not less than 0.
 Since capacity constraints require $f^+(S) \leq \text{cap}(S, T)$, we get the result.

From this we get the following:-
 out of all source-sink cuts, the one with min. capacity gives the best bound for $\text{val}(f)$, i.e. minimization of $\text{cap}[S, T]$ is dual to maximization of $\text{val}(f)$. If we get one with equality, then we have got a solution to the problem.

Illustration of the algorithm

(5)



$$R = \{s\}, S = \emptyset$$

Stage 1:- Start with $s \rightarrow$ we have excess capacity on both u and x , so they are labelled as Reached from s .

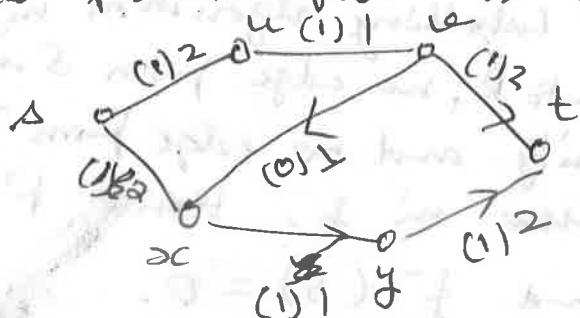
$$\text{So now } R = \{s, u, x\}, S = \emptyset$$

There is no excess capacity on uv or xy :- so we can't get anything from u . But there is ~~excess capacity~~ non-zero flow on $v \rightarrow x$, so v can be added to R .

$$\text{So now } R = \{s, u, x, v\}, S = \{s, u, x\}$$

Now v is the only element of $R - S$, and searching from v reaches t , so we have found an f -augmenting path: s, x, v, t .

The tolerance is 1. So we get a new feasible flow as follows:-



$$R = \{s\}, S = \emptyset$$

In this new flow f' , every edge has unit flow except $f'(ux) = 0$. When we run the labelling algorithm again, we have excess capacity on su and vx , so we can add them to R .

to get $R - S = \{s, u, x\}$. But from these we can label no others, so $R = \{s, u, x\}, S = \{s, u, x\}$, and we terminate. The cut is $[S, \bar{S}]$ with capacity 2.

Proof of Theorem 5:- the zero flow is feasible and allows us to start. We go on adding vertices to S (each vertex at most once),

and terminates with ~~one~~ either ① or ②

① ~~breakthrough~~ :- $t \in R$ (breakthrough)

② ~~breakthrough~~ :- $S = R$

In case ①, we have an f -augmenting path \rightarrow we get a new feasible flow with increased flow - so we repeat.

When the capacities are rational, each augmentation increases the flow by a multiple of $\frac{1}{a}$, where $a = \text{lcd of denominators}$ - so after finitely many iterations, the capacity of some cut is reached, so it terminates with $S = R$.

We now claim that $\text{cap}[S, \bar{S}] = \text{val}(f)$, hence by the earlier remark, this is the maximum possible flow.

It is a cut because $s \in S$ and $t \notin S$. Since applying the labelling algorithm introduces no node of \bar{S} into R , no edge from S into $T = \bar{S}$ has excess capacity and no edge from T into S has non-zero flow in f . Hence, $f^+(S) = \text{cap}[S, T]$ and $f^-(S) = 0$.

But as we showed before

$$\text{val}(f) = f^+(S) - f^-(S) = \text{cap}[S, T]$$

