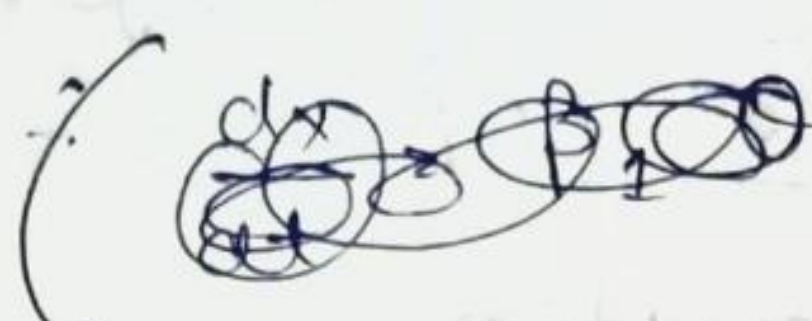
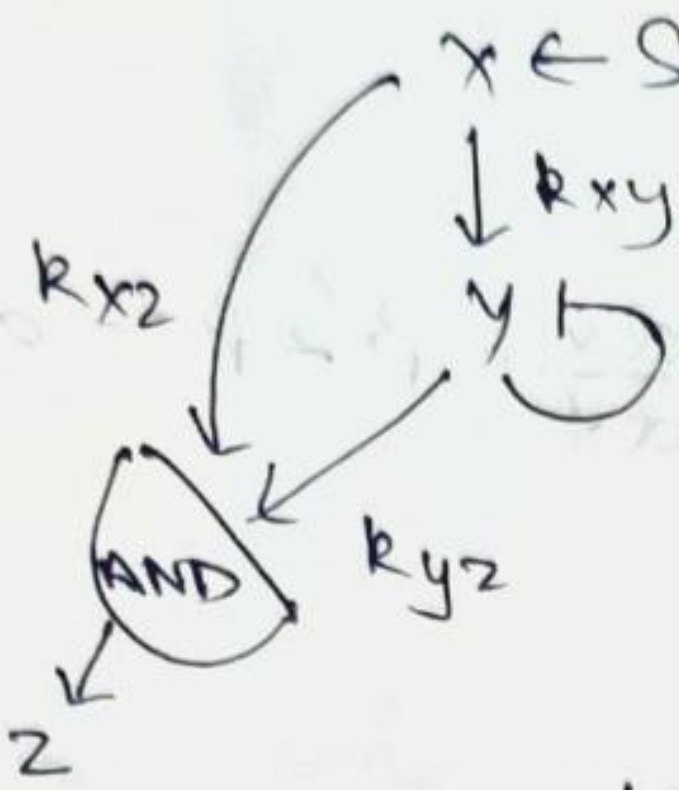


Q1)

$x \in S_x \rightarrow$ we are assuming a step func for x .



2018113012
Kushagra Agrawal

the rate for y will have 3 terms

production due to x
 $(\theta(x > k_{xy}))$
 repression due to itself
 (hill func type)
 $\frac{k_{yy}^n}{\alpha y^n + k_{yy}^n}$
 degradation
 $(-\alpha y)$

$$\frac{dy}{dt} = \beta_1 \theta(x > k_{xy}) \frac{k_{yy}^n}{\alpha y^n + k_{yy}^n} - \alpha y$$

for a simple FFL with no negative autoregulation

$$\frac{dy}{dt} = \beta_2 \theta(x > k_{xy}) - \alpha y$$

the rate of z will have 3 terms

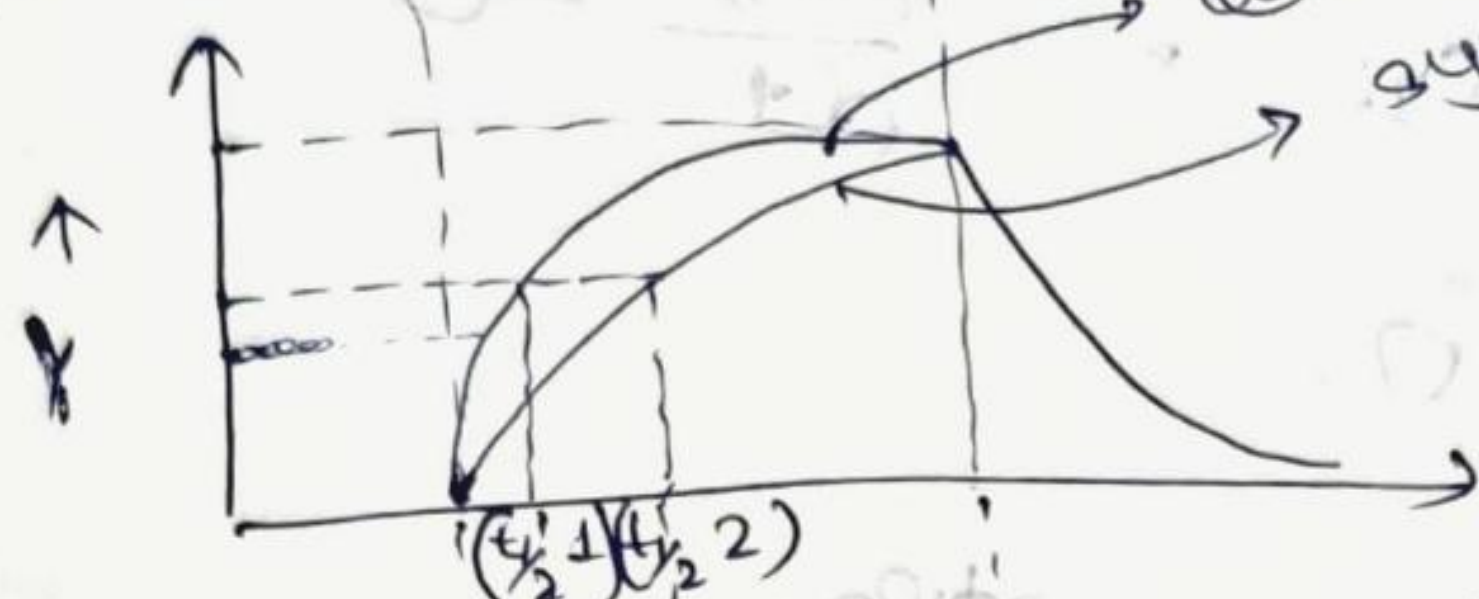
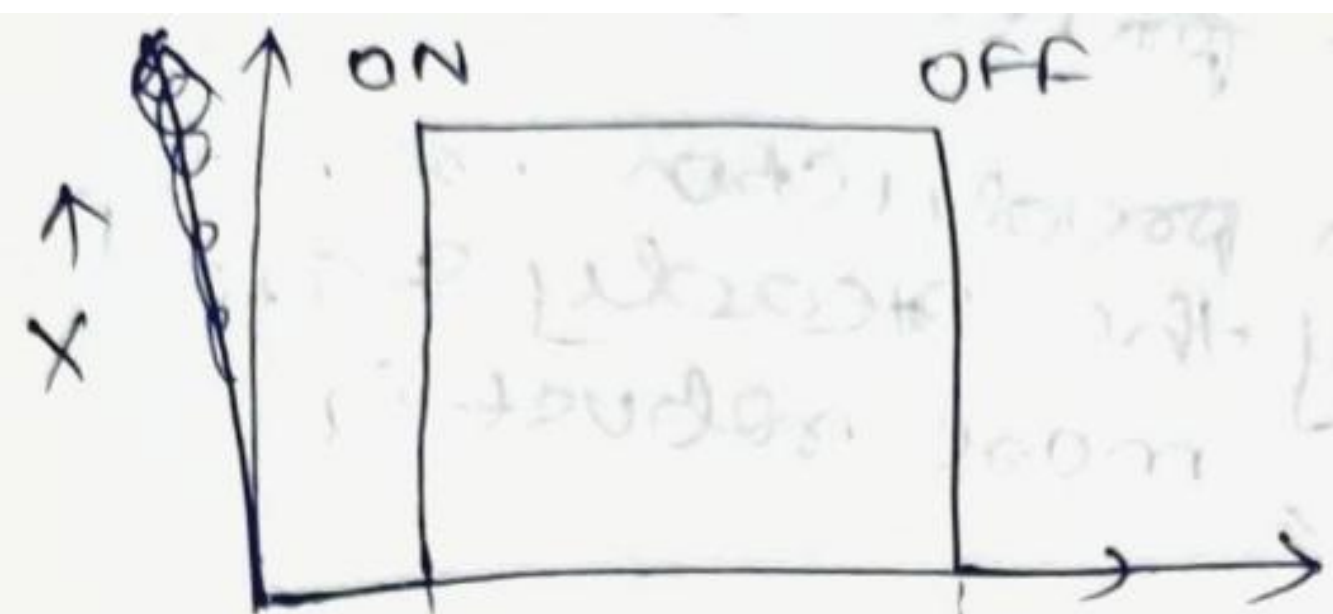
production from x
 $(\theta(x > k_{xz}))$
 production from y
 $(\theta(y > k_{yz}))$
 degradation
 $(-\alpha z)$

as we have an AND gate

$$\frac{dz}{dt} = \beta_3 \theta(x > k_{xz}) \theta(y > k_{yz}) - \alpha z$$

same for one with no NAR on y

now if we draw graphs for them.



delay for our system

delay for system without NAR

As we can see from the figures, our system (with NAR on y) ~~reaches~~ has a quicker response time hence ~~crosses~~ crosses the limit $O(y > ky_2)$ faster than the one without NAR. As we have a **AND** gate implemented the production of z begins only when both input signals are 1. \therefore There is a delay as it takes some time for y to be produced $> ky_2$. Note that there is no delay for $O(x > kx_2)$ or OFF as if either one $O(x > kx_2)$ or $O(y > ky_2)$ is 0 then the func. switches off. \therefore NAR on y reduces ^{transient} delay in production of z and also allows more z to be produced as they switch off together.

2018113012

Kushagra Agarwal

Q2) Show that the response time can vary with n .

Sol) for a NAR system,

$$\frac{dx}{dt} = \frac{\beta K^n}{x^n + K^n} - \alpha x$$

assumption for strong auto repulsion:

$$\left(\frac{x}{K}\right)^n \gg 1 \quad \text{or} \quad x^n \gg K^n$$

$$\frac{dx}{dt} = \frac{\beta K^n}{x^n} - \alpha x$$

$$\Rightarrow \frac{dx}{dt} = \frac{\beta K^n - \alpha x^{n+1}}{x^n}$$

$$\Rightarrow \int_{x_0}^x \frac{x^n dx}{\beta K^n - \alpha x^{n+1}} = \int_0^t dt$$

$$\text{taking } \beta K^n - \alpha x^{n+1} = a$$

$$\therefore -\alpha(n+1)x^n dx = da$$

~~limits are~~

$$a_2 \int_{a_1}$$

$$- \frac{da}{\alpha(n+1)(a)}$$

$$= \int_0^t dt$$

$$\therefore \ln(a_2/a_1) = -\alpha(n+1)t$$

$$a_2 = a_1 e^{-\alpha(n+1)t}$$

taking $x_0 = 0$

$$a_2 = \beta K^n - \alpha x^{n+1} \quad a_1 = \beta K^n$$

$$\beta K^n - \alpha x^{n+1} = \beta K^n e^{-\alpha(n+1)t}$$

$$x^{n+1} = \frac{\beta K^n}{\alpha} (1 - e^{-\alpha(n+1)t})$$

$$\therefore x = \left(\frac{\beta K^n}{\alpha} \right)^{1/n+1} (1 - e^{-\alpha(n+1)t})^{1/n+1}$$

calculating

$t_{1/2}$

we

$$\text{at } t_{1/2} \quad x = x_{st} = \left(\frac{\beta K^n}{\alpha} \right)^{1/n+1}$$

$$\therefore \text{at } t_{1/2} \quad x = \frac{x_{st}}{2} = \left(\frac{\beta K^n}{\alpha} \right)^{1/n+1} (1 - e^{-\alpha(n+1)t})^{1/n+1}$$

$$\frac{x_{st}}{2} = x_{st} (1 - e^{-\alpha(n+1)t})^{1/n+1}$$

$$\therefore \left(\frac{1}{2} \right)^{1/n+1} = 1 - e^{-\alpha(n+1)t}$$

$$e^{-\alpha(n+1)t} = 1 - \left(\frac{1}{2} \right)^{1/n+1}$$

$$-\alpha(n+1)t = \log_e \left(1 - \frac{1}{2^{1/n+1}} \right)$$

$$t = \frac{1}{\alpha(n+1)} \log_e \left(\frac{2^{1/n+1} - 1}{2^{1/n+1}} \right)$$

$$\therefore t_{1/2} = \frac{1}{(n+1)\alpha} \log_e \left(\frac{2^{1/n+1}}{2^{1/n+1} - 1} \right)$$

response time

we can rewrite as $t_{1/2} = \frac{1}{(n+1)\alpha} \log_e \left(1 - \frac{1}{2^{1/n+1}} \right)$

on increasing $n \uparrow$

this term increases

this term decreases

$\frac{1}{(n+1)\alpha}$ decreases

also $\frac{1}{1 - \frac{1}{2^{1/n+1}}}$ decreases

$\therefore t_{1/2}$ decreases on increasing n

\therefore (response time decreases) with increasing n

Q2 contd) ~~variations in production rates~~
 Robustness to variations in production rates (β)
 depends on the dependence of the steady state (β)
 on β . weaker the dependence, more robust is
 our system.

steady state value $X_{st} = \frac{dX}{dt} = 0$

$$\therefore \frac{\beta K^n}{X^n + K^n} - \alpha X = 0.$$

using strong repression assumption.

$$X^n \gg K^n$$

$$\therefore \frac{\beta K^n}{X^n} = \alpha X.$$

$$\Rightarrow X^{n+1} = \frac{\beta K^n}{\alpha}$$

$$\therefore X_{st} = \left(\frac{\beta K^n}{\alpha} \right)^{1/n+1}$$

$$\text{or } X_{st} = \left(\beta^{1/n+1} \right) \left(\frac{K^n}{\alpha} \right)^{1/n+1}$$

as n increases dependence of X_{st} on β reduces
 [for $n = \infty$ X_{st} is independent of β]

\therefore as $n \uparrow$ robustness to variations in production rates (β) \uparrow .

$$Q3) \quad \frac{dx}{dt} = \beta' + \beta x - \alpha x$$

2018/11/30/12
Kushagra
Agarwal

$$\Rightarrow \frac{dx}{dt} = \beta' + (\beta - \alpha)x$$

$$\int_0^x \frac{dx}{\beta' + (\beta - \alpha)x} = \int_0^t dt$$

$$\beta' + (\beta - \alpha)x = a$$

$$(\beta - \alpha) dx = da$$

$$\int_{a_1}^{a_2} \frac{da}{(\beta - \alpha)a} = \int_0^t dt$$

$$\ln(a_2/a_1) = (\beta - \alpha)t \Rightarrow a_2 = a_1 e^{(\beta - \alpha)t}$$

$$a_2 = \beta' + (\beta - \alpha)x$$

$$a_1 = \beta'$$

$$\therefore \beta' + (\beta - \alpha)x = \beta' e^{(\beta - \alpha)t}$$

$$\Rightarrow (\beta' - \beta' e^{-(\alpha - \beta)t}) = (\alpha - \beta)x$$

$$\Rightarrow x = \frac{\beta'}{(\alpha - \beta)} (1 - e^{-(\alpha - \beta)t})$$

for steady state $\frac{dx}{dt} = 0$

$$\therefore \beta' + \beta x_{st} - \alpha x_{st} = 0$$

$$\therefore x_{st} = \frac{\beta'}{(\alpha - \beta)}$$

$$\therefore \text{at } t_{1/2} \Rightarrow x = \frac{x_{st}}{2} = \frac{\beta'}{2(\alpha - \beta)}$$

$$\frac{\beta'}{2(\alpha - \beta)} = \frac{\beta'}{(\alpha - \beta)} (1 - e^{-(\alpha - \beta)t_{1/2}})$$

$$\Rightarrow -(\alpha - \beta) t_{1/2} = \log e/2$$

$$\Rightarrow \boxed{t_{1/2} = \frac{\log e/2}{(\alpha - \beta)}} \rightarrow \text{for } \frac{dx}{dt} = \beta' + \beta x - \alpha x$$

↳ In a simple system

$$\frac{dx}{dt} = b\beta - \alpha x$$

$$x = \frac{b\beta}{\alpha} (1 - e^{-\alpha t})$$

at steady state

$$dx/dt = 0$$

$$x_{st} = \beta/a$$

$$\text{at } t_{1/2} \Rightarrow x = \frac{x_{st}}{2}$$

$$\therefore \frac{1}{2} \frac{\beta}{\alpha} = \frac{\beta}{\alpha} (1 - e^{-\alpha t})$$

$$\Rightarrow \boxed{t_{1/2} = \frac{\log e/2}{\alpha}} \rightarrow \text{for } \frac{dx}{dt} = \beta - \alpha x$$

simple system

↳ so we can say that our system is just like a simple system with $a = \alpha - \beta$ and $b = \beta'$

↳ if we are comparing a simple system response time with $a = \alpha$ then our response time is lesser than a simple system.