# Traces, Interpolants and Automata

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- Trace Abstraction
- ► We implemented the paper¹ and tried to understand the approach.
- We'll describe the implementation along with the verification algorithm.

<sup>&</sup>lt;sup>1</sup>Matthias Heizmann, Jochen Hoenicke, and Andreas Podelski. Software model checking for people who love automata. In International Conference on Computer Aided Verification, pages 36–52. Springer, 2013.

# Flow of Algorithm

Program CFG as Automaton

Take an accepting trace

Generate interpolants from the trace

Check for Inclusion

Take an accepting trace

Generate interpolants from the trace

Check for Inclusion

```
\ell_0: assume p != 0;
\ell_1: while(n >= 0)
      assert p != 0;
\ell_2:
         if(n == 0)
\ell_3:
           p := 0;
\ell_4:
    pseudocode
```

 $\ell_0$ p != 0 n >= 0 n != 0 p := 0

control flow graph

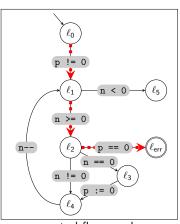
### Take an accepting trace

Generate interpolants from the trace

Check for Inclusion

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assume p != 0;
    while(n >= 0)
         assert p != 0;
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         if(n == 0)
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```

pseudocode



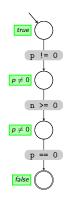
control flow graph

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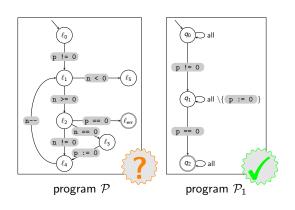
- ► Step 1: Analyze correctness
- ► Step 2: Construct proof
  - ▶ Naive approach: symbolic execution
  - Alternatives:
    - ▶ symbolic execution + unsat cores
    - Craig interpolation



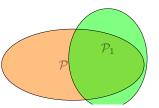
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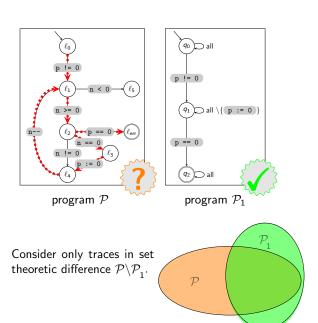
Consider only traces in set theoretic difference  $\mathcal{P} \setminus \mathcal{P}_1$ .



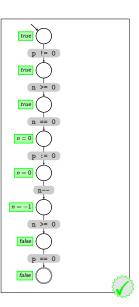
Take an accepting trace

Generate interpolants from the trace

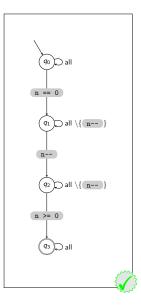
Check for Inclusion

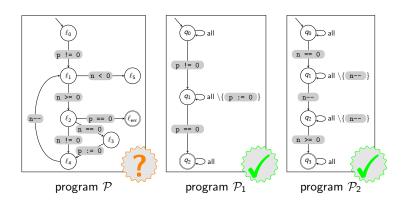


- 1. take trace  $\pi_2$
- 2. consider trace as program  $\mathcal{P}_2$
- 3. analyze correctness of  $\mathcal{P}_2$

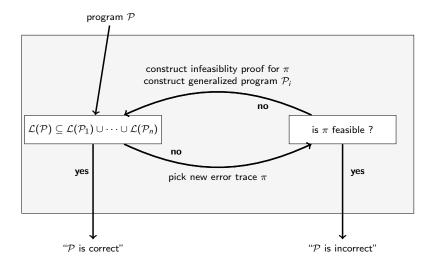


- 1. take trace  $\pi_2$
- 2. consider trace as program  $\mathcal{P}_2$
- 3. analyze correctness or  $\mathcal{P}_2$
- 4. generalize program  $\mathcal{P}_2$ 
  - add transitions
  - merge locations





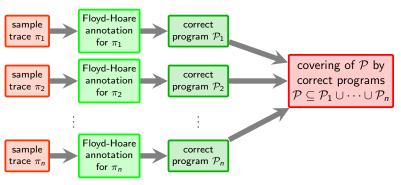
$$\mathcal{P} \subseteq \mathcal{P}_1 \cup \mathcal{P}_2$$



#### A classical approach to software model checking:

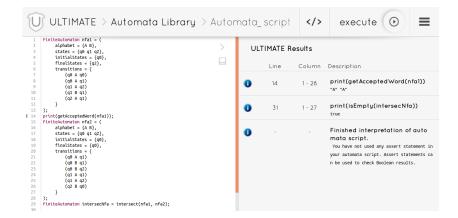


#### Our approach to software model checking:

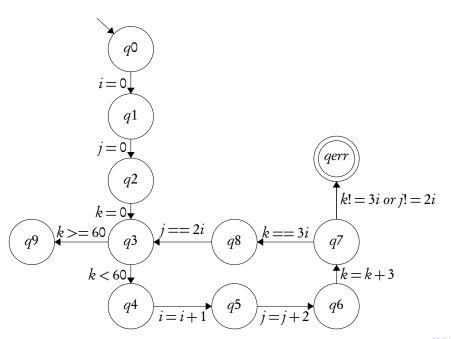


ULTIMATE Automata Library for trace generation.

- ▶ File interface
- ▶ ats file format.



```
FiniteAutomaton nfa \theta = (
int main()
                                                 alphabet = {"i = 0" "j = 0" "k = 0" "k < 16" "i
                                              = i + 1" "j = j + 2" "k = k + 3" "k != 3 * i" "j !=
  unsigned int i = 0;
                                              2 * i"}.
                                                 states = {"q0" "q1" "q2" "q3" "q4" "q5" "q6"
  unsigned int j = 0;
                                              "a7" "aerr"}.
  unsigned int k = 0;
                                                 initialStates = {"q0"},
                                                 finalStates = {"qerr"},
  while (k < 60) {
                                                 transitions = {
     i = i + 1;
                                                     ("q0" "i = 0" "q1")
                                                     ("q1" "j = 0" "q2")
     i = i + 2;
                                                     ("q2" "k = 0" "q3")
     k = k + 3:
                                                     ("q3" "k < 16" "q4")
                                                     ("q4" "i = i + 1" "q5")
                                                     ("q5" "j = j + 2" "q6")
                                                     ("q6" "k = k + 3" "q3")
                                                     ("g3" "k != 3 * i" "gerr")
                                                     ("q3" "j != 2 * i" "qerr")
```



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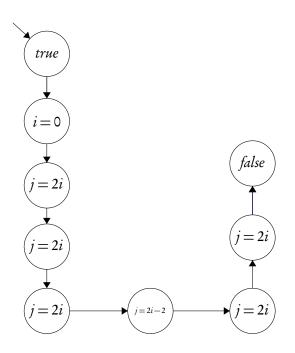
MathSAT for getting interpolants.

▶ Python API.

```
rijit@waterfall:~/verification/ApnaAutomizerS time python runner.py -i simple vardep.ats
DEBUG1 iteration count = 0
DEBUG Trace generated : ['i = 0', 'j = 0', 'k = 0', 'k < 300', 'i = i + 1', 'j = j + 2', 'k = k + 3', 'k != 3 * i']
DEBUG1 Found interpolant 0 : true
DEBUG] Found interpolant 1 : (and (<= i 1 0) (<= 0 i 1))
DEBUG| Found interpolant 2 : (and (<= i 1 0) (<= 0 i 1))
DEBUG Found interpolant 3: (and (<= (\frac{1}{4} (* 3 i 1) (\frac{1}{4} (- 1) k 1)) 0) (<= 0 (+ (* 3 i 1) (* (- 1) k 1))))
DEBUG] Found interpolant 4 : (and (<= (+ (* 3 i_1) (* (- 1) k_1)) 0) (<= 0 (+ (* 3 i_1) (* (- 1) k_1))))

DEBUG] Found interpolant 5 : (and (<= (- 3) (+ k_1 (* (- 3) i_2))) (<= (+ k_1 (* (- 3) i_2)) (- 3)))
DEBUG Found interpolant 6: (and (<= (- 3) (+ k_1 (* (- 3) i_2))) (<= (+ k_1 (* (- 3) i_2)) (- 3)))
DEBUG Found interpolant 7: (and (<= (+ (* 3 i \overline{2}) (* (- 1) k \overline{2})) 0) (<= 0 \overline{(+ (* 3 i 2) (* (- 1) k 2))})
DEBUG] Found interpolant 8 : false
DEBUG Trace generated : ['t = 0', 'j = 0', 'k = 0', 'k < 300', 't = t + 1', 'j = j + 2', 'k = k + 3', 'k == 3 * t', 'k < 300'
DEBUG] Found interpolant 0 : true
DEBUGI Found interpolant 1 : (and (<= i 1 0) (<= 0 i 1))
DEBUG| Found interpolant 2 : (and (<= i 1 0) (<= 0 i 1))
DEBUG Found interpolant 3: (and (<= (+ (* 3 i 1) (* (- 1) k 1)) 0) (<= 0 (+ (* 3 i 1) (* (- 1) k 1))))
DEBUG Found interpolant 4 : (and (<= (+ (* 3 t 1) (* (- 1) k 1)) 0) (<= 0 (+ (* 3 t 1) (* (- 1) k 1))))
DEBUG] Found interpolant 5 : (and (<= (-3) (+ k 1 (* (-3) i 2))) (<= (+ k 1 (* (-3) i 2)) (-3)))

DEBUG] Found interpolant 6 : (and (<= (-3) (+ k 1 (* (-3) i 2))) (<= (+ k 1 (* (-3) i 2)) (-3)))
DEBUG] Found interpolant 7: (and (<= (+ (* 3 i_2) (* (- 1) k_2)) 0) (<= 0 (+ (* 3 i_2) (* (- 1) k_2))))
DEBUG] Found interpolant 8 : (and (<= (+ (* 3 i 2) (* (- 1) k 2)) 0) (<= 0 (+ (* 3 i 2) (* (- 1) k 2))))
DEBUG] Found interpolant 9 : (and (<= (+ (* 3 i_2) (* (- 1) k_2)) 0) (<= 0 (+ (* 3 i_2) (* (- 1) k_2))))
DEBUG] Found interpolant 10 : (and (<= (- 3) (+ k 2 (* (- 3) i 3))) (<= (+ k 2 (* (- 3) i 3)) (- 3)))
DEBUG Found interpolant 11: (and (<= (-3) (+ k^2 (* (-3) 13))) (<= (+ k^2 (* (-3) 13)) (-3)))
DEBUG Found interpolant 12: (and (<= (+ (* 3 i 3) (* (- 1) k 3)) 0) (<= 0 (+ (* 3 i 3) (* (- 1) k 3))))
DEBUG1 Found interpolant 13 : false
```



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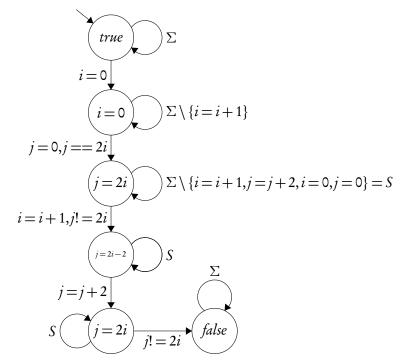
Python API.

Generating Floyd-Hoare Automaton.

- MathSAT API.
- Gets generated as ats file.

### Algorithm 1 Floyd Hoare Automaton Generation

```
    I ← List all distinct interpolants
    Q ← add states q<sub>i</sub> corresponding to I<sub>i</sub> in I
    for two consecutive interpolants I<sub>i</sub> and I<sub>i+1</sub> do
    for each statement st in alphabet do
    if {I<sub>i</sub>}st{I<sub>i+1</sub>} is valid hoare triple then
    add transition (q<sub>i</sub>, st, q<sub>i+1</sub>) in automaton
    end if
    end for
    end for
```



```
FiniteAutomaton fha 1 = (
           alphabet = \{ "k < 300" "j != 2 * i" "j = 0" "k = k + 3" "i = i + 1" "k == 3 * i" "k != 3 * i" "i = 0" "k = 0" "i = i + 2" \}.
           states = \{00 \text{ o1 o2 o3 o4 o5 }\}.
           initialStates = {q0}.
           finalStates = {a5}.
           transitions = {
               (q\theta "i = \theta" q\theta)
8
               (q\theta "j = \theta" q\theta)
               (q\theta "k = \theta" q\theta)
10
               (a\theta "k < 300" a\theta)
               (q\theta "i = i + 1" q\theta)
               (a\theta "i = i + 2" a\theta)
                (a\theta "k = k + 3" a\theta)
               (q0 "k != 3 * i" q0)
               (qθ "i != 2 * i" qθ)
               (q\theta "k == 3 * i" q\theta)
16
               (q1 "i = 0" q1)
               (a\theta "i = \theta" q1)
18
19
                (a1 "i = 0" a1)
20
                (a1 "k = 0" a1)
               (q1 "k < 300" q1)
               (a1 "i = i + 2" a1)
               (q1 "k = k + 3" q1)
               (q1 "k != 3 * i" q1)
                (q1 "j != 2 * i" q1)
26
               (q1 "k == 3 * i" q1)
               (q2 "j = 0" q2)
28
               (a1 "k = 0" a2)
29
               (q2 "k < 300" q2)
30
                (a2 "i = i + 2" a2)
31
               (q2 "k != 3 * i" q2)
32
                (q2 "i != 2 * i" q2)
                (q2 "k == 3 * i" q2)
34
               (a1 "k == 3 * i" q2)
35
               (q3 "j = 0" q3)
36
               (a3 "k < 300" a3)
37
                (a2 "i = i + 1" a3)
38
                (a3 "i = i + 2" a3)
39
                (q3 "k != 3 * i" q3)
48
                (q2 "k != 3 * i" q3)
               (q3 "j != 2 * i" q3)
41
                $75 LP 1 5 L FL 750
```

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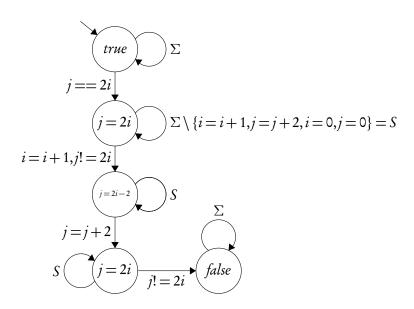
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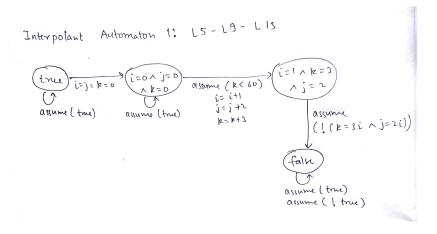
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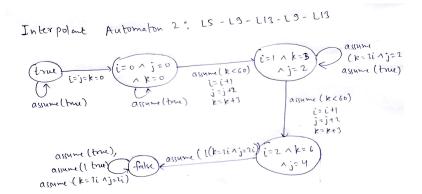
Automata Library for reconstructing Program Automaton.



# Interpolant Automaton by Ultimate



# Interpolant Automaton by Ultimate



# Results and Comparison with Ultimate

Testcode	loop	Iterations		Runtime	
		AA	UA	AA	UA
bhrm.c	5	7	37	111s	37s
nested_loop.c	3x3	8	10	124s	15s
simple_vardep.c	20	10	20	69s	40s
simple_vardep.c	100	10	100	69s	1678s

### Limitations

- ▶ Works only for Linear Integer Arithmetic.
- ► Input must be given in specified format.
- ▶ Program must not contain function calls.

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### Bottlenecks

- ► Time taken by Automata Library is too much.
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### **Bottlenecks**

- ► Time taken by Automata Library is too much.
- ► Time taken to check validity of Hoare triples. For smaller programs too, we are checking a large number of Hoare triples.

## Optimization

- Choose hoare triples to check smartly.
- Manually inserting invariants.

- ► Thank you.
- ► Some of the slides are taken from Matthias' Presentation at EPIT 2018. Thanks to him too.