Week 1 Exercise Set

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1.

A.

abs(x) Absolute value of a real number; 10magnitude of complex number

acos(x) Arccosine with result in radians

acosh(x) Inverse hyperbolic cosine

angle(x) Phase angle of complex number (in radians)

asin(x) Arcsine with result in radians

asinh(x) Inverse hyperbolic sine

atan(x) Arctangent with result in radians

atan2(x,y) Four quadrant arctangent with result in radians

atanh(x) Inverse hyperbolic tangent

ceil(x) Round toward plus infinity

conj(x) Complex conjugate

cos(x) Cosine with x in radians

cosh(x) Hyperbolic cosine

exp(x) Exponential of x

fix(x) Round toward zero

floor(x) Round toward minus infinite

gcd(x,y) Greatest common divisor of integer x and y

imag(x) Imaginary part of complex number x (i.e. imag(x+iy) = y)

lcm(x,y) Least common multiple of integers x and y

log(x) Natural logarithm of x, i.e.: ln(x) = e log(x)

log10(x) Base-10 logarithm of x, i.e.: 10 log(x)

mod(x,y) x modulo y (i.e. mod(5,2) = 1)

prod(x) Product of elements

real(x) Real part of complex number x (i.e. real(x+iy) = x)

rem(x,y) Remainder after division of x/y (i.e. rem(5,3)=2)

round(x) Round toward nearest integer

sign(x) Signum-function (i.e.: -1 for x<0, 0 for x=0 and 1 for x>0)

sin(x) Sine with x in radians

sinh(x) Hyperbolic sine

sqrt(x) Square root

sum(x) Sum of elements

tan(x) Tangent

tanh(x) Hyperbolic tangent

B.

Syntaxes for

Cosine : y = cos(x)

Natural Logarithm : y = log(x)

Square Root : y = sqrt(x)

2.

```matlab
Hungry = true;
Cookies = 0;
while Hungry == true
    Cookies = Cookies + 1;
    quest = "Still Hungry ?";
    Hungry = questdlg(quest,'Question','Yes','No','Yes');
    switch Hungry
        case 'Yes'
            Hungry = true;
        case 'No'
            Hungry = false;
    end
end
```

```
quest =
"Still Hungry ?"
quest =
"Still Hungry ?"
quest =
"Still Hungry ?"
quest =
"Still Hungry ?"
```

```matlab
disp('')
disp(['Not hungry anymore after:', num2str(Cookies),' cookies.'])
```

```
Not hungry anymore after:4 cookies.
```

3.

```matlab
function area = calcarea(R)
    area = 4*pi*R^2;
end

function vol = calcvol(R)
    vol = (4/3)*pi*R^3;
end
R = input('What is the radius of the Sphere ?')
```

```
R =
10
```

```matlab
area = calcarea(R);
vol = calcvol(R);
fprintf('Sphere with radius of %0.1f units has a volume of %0.2f unit cubed
and a surface area of %0.2f unit squared.',R,vol,area)
```

```
Sphere with radius of 10.0 units has a volume of 4188.79 unit cubed and a surface area of 1256.64 unit squ
```

4.

```matlab
function [x,y]=convert_rectangular(r, phi)
    x = r*cos(phi);
    y = r*sin(phi);
end
prompt ={'Enter the value of R : ', 'Enter the value of Phi : '};
polar = inputdlg(prompt,"Input");
r = str2double(polar{1});
phi = str2double(polar{2});
[x,y]=convert_rectangular(r, phi);
fprintf('The equivalent rectangular coordinates for the polar coordinates
(%0.1f units, %0.1f radians) are (%0.2f units, %0.2f units).\n',r, phi,x,y)
```

```
The equivalent rectangular coordinates for the polar coordinates (10.0 units, 45.0 radians) are (5.25 unit
```

5.

```matlab
N=10;
v = zeros(1,N);
v = changem(v,N);
M = diag(v);
%Change the Main Diagonal
for i = 2:N
    v = zeros(1,N-i+1);
    v = changem(v,N-i+1);
    d1 = diag(v,i-1);%Changing Superdiagonal
    d2 = diag(-v, -(i-1));%Changing Subdiagonal
    M = M + d1+d2;
end
disp(M)
```

3

```
10     9     8     7     6     5     4     3     2     1
-9    10     9     8     7     6     5     4     3     2
-8    -9    10     9     8     7     6     5     4     3
-7    -8    -9    10     9     8     7     6     5     4
-6    -7    -8    -9    10     9     8     7     6     5
-5    -6    -7    -8    -9    10     9     8     7     6
-4    -5    -6    -7    -8    -9    10     9     8     7
-3    -4    -5    -6    -7    -8    -9    10     9     8
-2    -3    -4    -5    -6    -7    -8    -9    10     9
-1    -2    -3    -4    -5    -6    -7    -8    -9    10
```

6.

```matlab
N = input('Enter an Aribtrary uneven Natural Number Larger than 3 : ');
x = zeros(1, N)
```

```
x = 1×7
     0     0     0     0     0     0     0
```

```matlab
for i = 1:N
    x(1,i) = i;
end
x =x*10
```

```
x = 1×7
    10    20    30    40    50    60    70
```

```matlab
x1 = x
```

```
x1 = 1×7
    10    20    30    40    50    60    70
```

```matlab
x1(2) = [];
x1(end) = [];
disp(x1)
```

```
    10    30    40    50    60
```

```matlab
x2 = x;
x2(ceil(N/2))=[]
```

```
x2 = 1×6
    10    20    30    50    60    70
```

```matlab
x3 = zeros(1,ceil(N/2));
count = 1;
for i = 1:N
    if mod(i,2) ~=0
        x3(1,count)= x(1,i);
        count = count +1;
    end
end
disp(x3)
```

```
    10    30    50    70
```

4

```
x4 = zeros(1,N);
count =0;
for i = 1:N
    if mod(x(1,i),2) ~=0
        count = count +1;
        x4(1,count)= x(1,i);
    end
end
x4 = x4(1:count)
```

```
x4 =

  1×0 empty double row vector
```

```
x5 = fliplr(x(1:N))
```

```
x5 = 1×7
    70    60    50    40    30    20    10
```

```
x6 = zeros(1, N);
for i = 1:N
    if x(1,i)>=mean(x)
        count = count+1;
        x6(1,count) = x(1,i);
    end
end
x6 = x6(1:count)
```

```
x6 = 1×4
    40    50    60    70
```

7.

```
A = [1,2;3,4];
B = ones(size(A));
c = [10, 20]';
disp(A*B);% Matrix Multiplication
```

```
     3     3
     7     7
```

```
disp(A.*B);% Individual element in A is multiplies by the element in the
same position in matrix B
```

```
     1     2
     3     4
```

```
disp(A./B);% Individual element in A gets divided by the element in the
same position in matrix B
```

```
     1     2
     3     4
```

```matlab
disp(A.^B);% Individual element in A is raisded to power of the element in
the same position in matrix B
```

```
     1     2
     3     4
```

```matlab
disp(A*c);% Matrix multiplication operation
```

```
    50
   110
```

```matlab
disp(c'*A);% c is Transposed and matrix multiplied with A
```

```
    70   100
```

8.

```matlab
function f = f(x)
    f = x^2*cos(x);
end
function g = g(x)
    g = x^2*sin(x);
end
x = linspace(-pi,pi);
disp(size(x,2))
```

```
   100
```

```matlab
y_sin = zeros(1,size(x,2));
y_cos = zeros(1, size(x, 2));
for i = 1: size(x,2)
    y_sin(1,i)= f(x(i));
    y_cos(1,i) = g(x(i));
end
p1 = plot(x, y_cos, 'b'); hold on
p2 = plot(x, y_sin, '-.k');
p3 = yline(0, '-.r');

legend([p1 p2],'f(x) = x^2 cos(x)','g(x) = x^2 sin(x)','Location',
'northwest');

title('2D plot of the functions f(x) and g(x) between -\pi abd \pi')
xlabel('-\pi < x < \pi')
```

2D plot of the functions f(x) and g(x) between -π abd π

9.
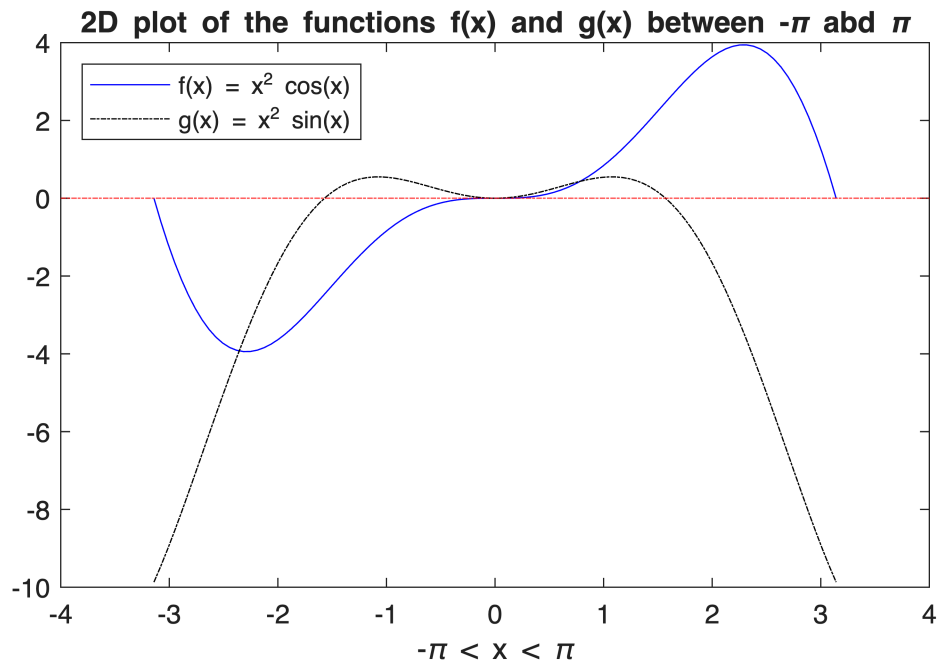
```matlab
deltat =1;
t=0:deltat:60*8;

pmax = 10;
tmax= 4*60;
spread = 120;
p =pmax*exp(-((tmax-t)/spread).^2);

qmax=8;
kr=0.05;
N0=0;
N=zeros(length(t),1); q=zeros(length(t),1); r=zeros(length(t),1);
N(1)=N0;
for it=2:length(t)
    q(it)=min(N(it-1)/deltat,qmax);
    r(it)=kr*N(it-1);
    N(it)= N(it-1)+(p(it)-q(it)-r(it))*deltat;
end
figure;
subplot(2,1,1)
plot(t, p, 'b', 'LineWidth', 1.5); hold on;
plot(t, q, 'r', 'LineWidth', 1.5);
plot(t, r, 'y', 'LineWidth', 1.5);

xlabel('Time [min]');
ylabel('Passenger Fluxes [n/min]');
title('Schiphol Security Queue ');
```

```
legend('Influx', 'Passed', 'Left','Location', 'northwest');

subplot(2,1,2)
plot(t,N,'b','LineWidth',1.5);
xlabel('Time[min]');
ylabel('Number of Passengers in Queue');
```