Lesson 17

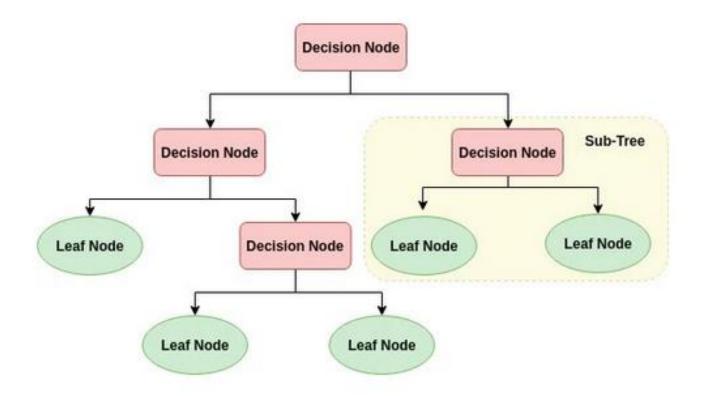
Classification Techniques – Decision Trees

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Decision Tree Algorithm

A decision tree is a flowchart-like tree structure where an internal node represents feature(or attribute), the branch represents a decision rule, and each leaf node represents the outcome.

The topmost node in a decision tree is known as the root node. It learns to partition on the basis of the attribute value. It partitions the tree in recursively manner call recursive partitioning. This flowchart-like structure helps you in decision making.

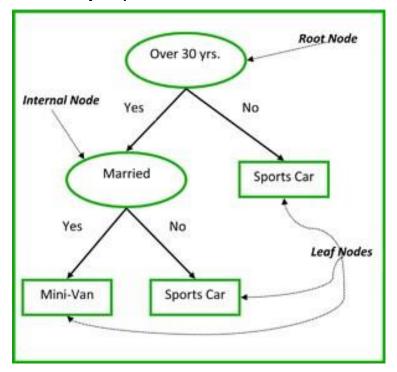


Decision Tree Algorithm

Decision Tree is a white box type of ML algorithm. It shares internal decision-making logic, which makes them one of the most interpretable algorithm in machine learning.

Its training time is faster compared to the neural network algorithm. The decision tree is a distribution-free or non-parametric method, which does not depend upon probability distribution assumptions. Decision trees can handle high dimensional data with good accuracy.

Tree based learning algorithms are considered to be one of the best and mostly used supervised learning methods. Tree based methods empower predictive models with high accuracy, stability and ease of interpretation. Unlike linear models, they map non-linear relationships quite well.



Common Terms

- **Root Node**: It represents entire population or sample and this further gets divided into two or more homogeneous sets.
- Splitting: It is a process of dividing a node into two or more sub-nodes.
- **Decision Node**: When a sub-node splits into further sub-nodes, then it is called decision node.
- Leaf/ Terminal Node: Nodes that do not split are called Leaf or Terminal node.
- **Pruning**: When we remove sub-nodes of a decision node, this process is called pruning. You can say opposite process of splitting.
- Branch / Sub-Tree: A sub section of entire tree is called branch or sub-tree.
- **Parent and Child Node**: A node, which is divided into sub-nodes is called parent node of sub-nodes whereas sub-nodes are the child of parent node.

Working of the Algo

- 1. Select the best attribute using Attribute Selection Measures(ASM) to split the records.
- 2. Make that attribute a decision node and breaks the dataset into smaller subsets.
- 3. Starts tree building by repeating this process recursively for each child until one of the condition will match:
 - 1. All the tuples belong to the same attribute value.
 - 2. There are no more remaining attributes
 - 3. There are no more instances.

Attribute Selection Measures

Attribute selection measure is a heuristic for selecting the splitting criterion that partition data into the best possible manner.

It is also known as splitting rules because it helps us to determine breakpoints for tuples on a given node.

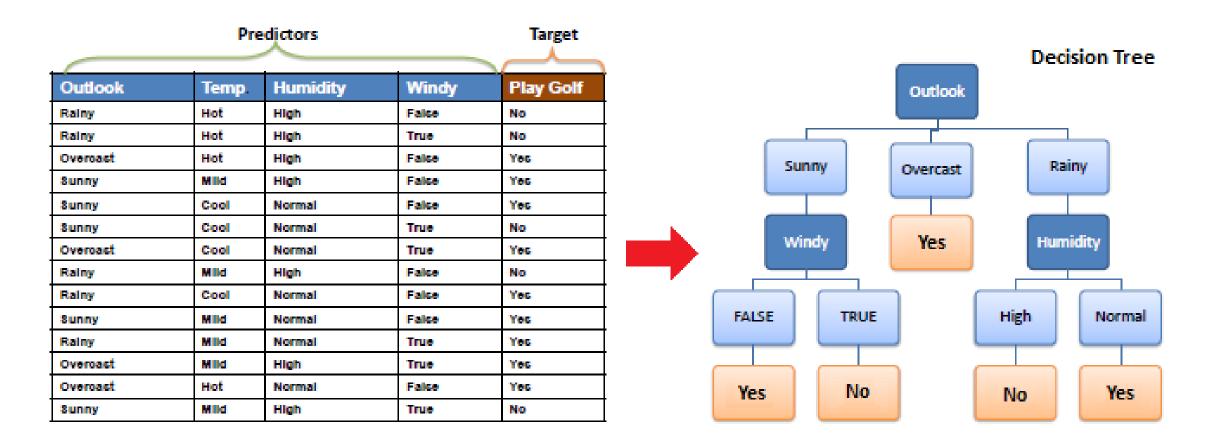
ASM provides a rank to each feature(or attribute) by explaining the given dataset. Best score attribute will be selected as a splitting attribute.

Most popular selection measures are Information Gain, Gini Index.

- Shannon invented the concept of entropy, which measures the impurity of the input set. In physics and mathematics, entropy referred as the randomness or the impurity in the system. In information theory, it refers to the impurity in a group of examples.
- Information gain is the decrease in entropy.
- Information gain computes the difference between entropy before split and average entropy after split of the dataset based on given attribute values.
- ID3 (Iterative Dichotomiser) decision tree algorithm uses information gain.
- Less impure node requires less information to describe it. And, more impure node requires more information. Information theory is a measure to define this degree of disorganization in a system known as Entropy.
- If the sample is completely homogeneous, then the entropy is zero and if the sample is an equally divided (50% 50%), it has entropy of one.
- Entropy can be calculated using formula:- Entropy = -p $\log 2 p q \log 2q$, Where p and q is probability of success and failure respectively in that node.
- Entropy is also used with categorical target variable. It chooses the split which has lowest entropy compared to parent node and other splits. The lesser the entropy, the better it is.

To build a decision tree, we need to calculate two types of entropy using frequency tables as follows:

- 1) Entropy using the frequency table of one attribute
- 2) Entropy using the frequency table of two attributes



1) Entropy using the frequency table of one attribute

$$E(S) = \sum_{i=1}^{c} -p_i \log_2 p_i$$

Play	Golf
Yes	No
9	5

Entropy(PlayGolf) = Entropy (5,9)

= Entropy (0.36, 0.64)

= - (0.36 log₂ 0.36) - (0.64 log₂ 0.64)

= 0.94

2. Entropy using the frequency table of two attributes

$$E(T, X) = \sum_{c \in X} P(c)E(c)$$

		Play	Golf	
		Yes	No	
	Sunny	3	2	5
Outlook	Overcast	4	0	4
	Rainy	2	3	5
				14



$$E(PlayGolf, Outlook) = P(Sunny)*E(3,2) + P(Overcast)*E(4,0) + P(Rainy)*E(2,3)$$

$$= (5/14)*0.971 + (4/14)*0.0 + (5/14)*0.971$$

$$= 0.693$$

The information gain is based on the decrease in entropy after a data-set is split on an attribute. Constructing a decision tree is all about finding attribute that returns the highest information gain (i.e., the most homogeneous branches).

Step 1: Calculate entropy of the target.

Step 2: The dataset is then split on the different attributes. The entropy for each branch is calculated. Then it is added proportionally, to get total entropy for the split. The resulting entropy is subtracted from the entropy before the split. The result is the Information Gain, or decrease in entropy.

$$Gain(T, X) = Entropy(T) - Entropy(T, X)$$

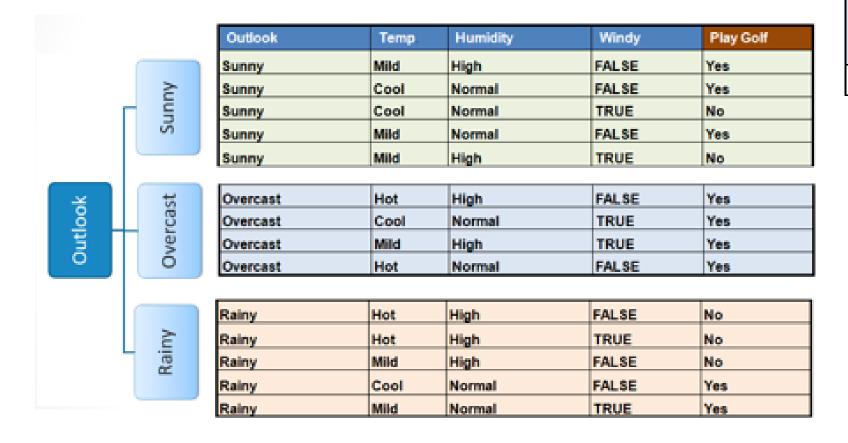
		Play Golf	
		Yes	No
	Sunny	3	2
Outlook	Overcast	4	0
	Rainy	2	3
	Gain = 0).247	

		Play	Golf
		Yes	No
	Hot	2	2
Temp.	Mild	4	2
	Cool	3	1
	Gain = 0	.029	

Play Golf		Golf	
		Yes	No
Hamidta.	High	3	4
Humidity	Normal	6	1
	Gain = 0).152	

		Play Golf	
	_	Yes	No
145-4-	False	6	2
Windy	True	3	3
	Gain = 0	.048	

Step 3: Choose attribute with the largest information gain as the decision node, divide the dataset by its branches and repeat the same process on every branch.

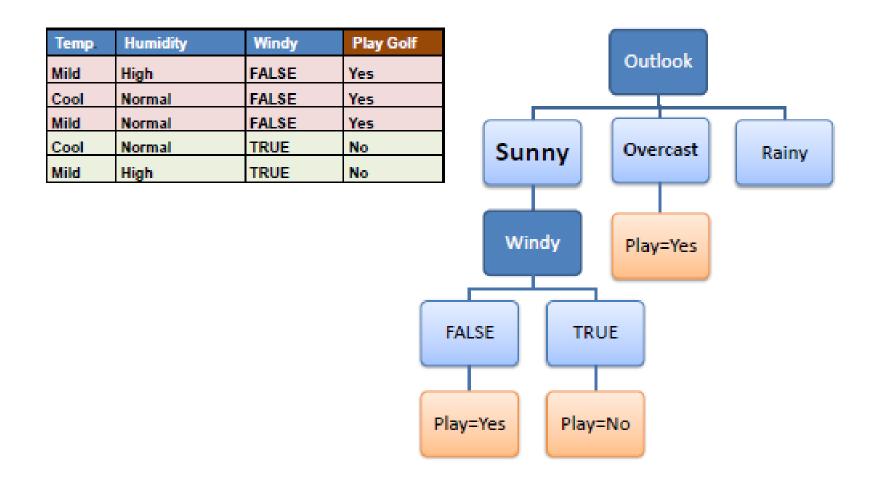


+		Play Golf	
7		Yes	No
	Sunny	3	2
Outlook	Overcast	4	0
	Rainy	2	3
	Gain = 0).247	

Step 4(a): A branch with entropy of 0 is a leaf node.

Temp.	Humidity	Windy	Play Golf	
Hot	High	FALSE	Yes	
Cool	Normal	TRUE	Yes	
Mild	High	TRUE	Yes	
Hot	Normal	FALSE	Yes]
				Sunny

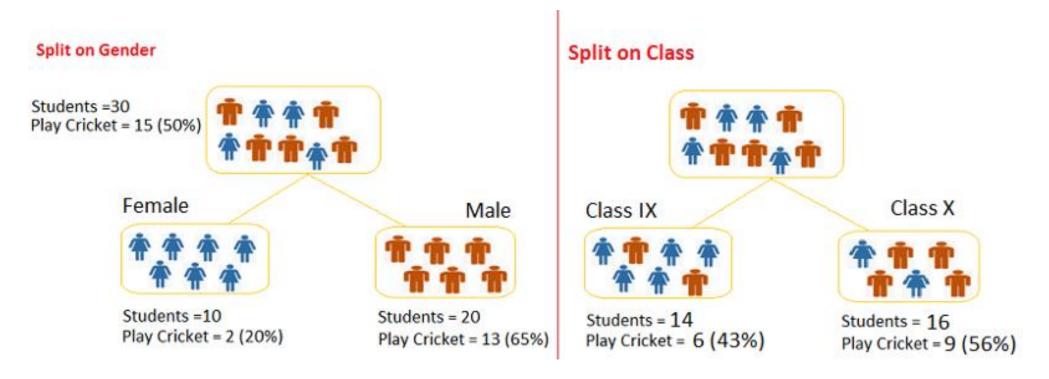
Step 4(b): A branch with entropy more than 0 needs further splitting.



Steps to Calculate Gini for a split:

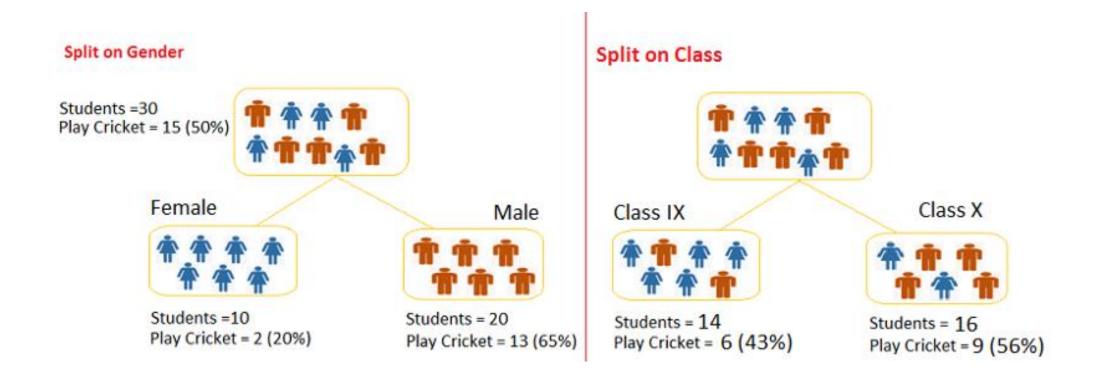
- 1. Calculate Gini for sub-nodes, using formula sum of square of probability for success and failure (p²+q²).
- 2. Calculate Gini for split using weighted Gini score of each node of that split.

Referring to example where we want to segregate the students based on target variable (playing cricket or not). In the snapshot below, we split the population using two input variables Gender and Class. Now, I want to identify which split is producing more homogeneous sub-nodes using Gini index.



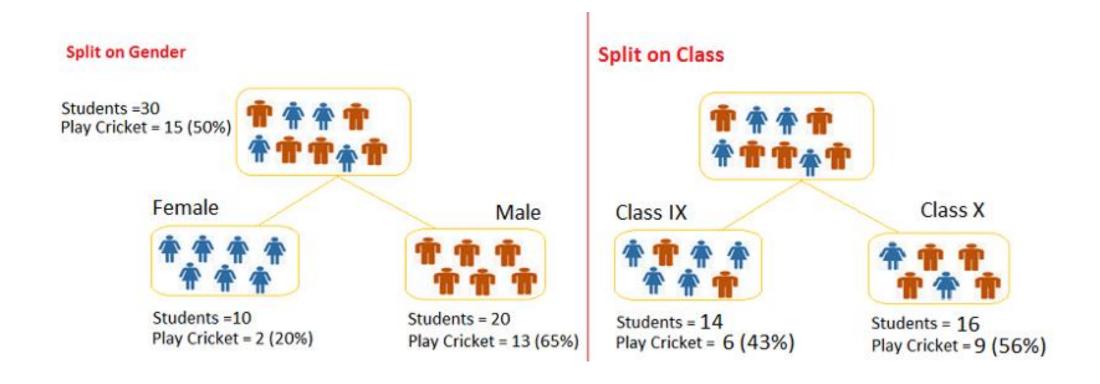
Split on Gender:

- Gini for sub-node Female = (0.2)*(0.2)+(0.8)*(0.8)=0.68
- Gini for sub-node Male = (0.65)*(0.65)+(0.35)*(0.35)=0.55
- Weighted Gini for Split Gender = (10/30)*0.68+(20/30)*0.55 = 0.59



Similar for Split on Class:

- Gini for sub-node Class IX = (0.43)*(0.43)+(0.57)*(0.57)=0.51
- Gini for sub-node Class X = (0.56)*(0.56)+(0.44)*(0.44)=0.51
- Weighted Gini for Split Class = (14/30)*0.51+(16/30)*0.51 = 0.51



Gini score for split on Gender: 0.59

Gini score on the split on Class: 0.51

Above, you can see that Gini score for *Split on Gender* is higher than *Split on Class*, hence, the node split will take place on Gender.

Constraints on Tree Size

1. Minimum samples for a node split

- Defines the minimum number of samples (or observations) which are required in a node to be considered for splitting.
- Used to control over-fitting. Higher values prevent a model from learning relations which might be highly specific to the particular sample selected for a tree.
- Too high values can lead to under-fitting.

2. Minimum samples for a terminal node

- Defines the minimum samples (or observations) required in a terminal node or leaf.
- Used to control over-fitting similar to min_samples_split.
- Generally lower values should be chosen for imbalanced class problems because the regions in which the minority class will be in majority will be very small.

Constraints on Tree Size

3. Maximum depth of tree

- The maximum depth of a tree.
- Used to control over-fitting as higher depth will allow model to learn relations very specific to a particular sample.

4. Maximum number of terminal nodes

- The maximum number of terminal nodes or leaves in a tree.
- Can be defined in place of max_depth. Since binary trees are created, a depth of 'n' would produce a maximum of 2ⁿ leaves.

5. Maximum features to consider for split

- The number of features to consider while searching for a best split. These will be randomly selected.
- As a thumb-rule, square root of the total number of features works great but we should check upto 30–40% of the total number of features.
- Higher values can lead to over-fitting but depends on case to case.