CPSC-240 Computer Organization and Assembly Language

Chapter 12

Functions

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Outline

- Updated Linking Instructions
- Debugger Commands
- Stack Dynamic Local Variables
- Function Declaration
- Standard Calling Convention
- Linkage
- Argument Transmission
- Calling Convention



Updated Linking Instructions



Updated Linking Instructions

 When writing and debugging functions, it is easier for the C compiler (either GCC or G++) to link the program as the C compiler is aware of the appropriate locations for the various C/C++ libraries.

```
yasm -g dwarf2 -f elf64 example.asm -l example.lst gcc -g -o example example.o
```

 Note, Ubuntu 18 will require the no-pie option on the gcc command as shown:

```
gcc -g -no-pie -o example example.o
```

 This will use the GCC compiler to call the linker, reading the example.o object file and creating the example executable file. The "-g" option includes the debugging information in the executable file in the usual manner.



Debugger Commands



Debugger Command, next

- With respect to a function call, the debugger next command will execute the entire function and go to the next line.
- When debugging functions, this is useful to quickly execute the entire function and then just verify the results. It will not display any of the function code.



Debugger Command, step

- With respect to a function call, the debugger step command will step into the function and go to the first line of the function code.
- It will display the function code. When debugging functions, this is useful to debug the function code.





- In a high-level language, non-static local variables declared in a function are stack dynamic local variables by default.
- Some C++ texts refer to such variables as automatics.
 This means that the local variables are created by allocating space on the stack and assigning these stack locations to the variables.
- When the function completes, the space is recovered and reused for other purposes.



- This requires a small amount of additional run-time overhead, but makes a more efficient overall use of memory.
- If a function with a large number of local variables is never called, the memory for the local variables is never allocated.
- This helps reduce the overall memory footprint of the program which generally helps the overall performance of the program.



- In contrast, statically declared variables are assigned memory locations for the entire execution of the program.
- This uses memory even if the associated function is not being executed. However, no additional run-time overhead is required to allocate the space since the space allocation has already been performed (when the program was initially loaded into memory).



Function Declaration



Function Declaration

A function must be written before it can be used.
 Functions are located in the code segment. The general format is:

```
global cName>

cnocName>:
    ; function body
ret
```

 A function may be defined only once. There is no specific order required for how functions are defined. However, functions cannot be nested.





- To write assembly programs, a standard process for passing parameters, returning values, and allocating registers between functions is needed.
- If each function did these operations differently, things would quickly get very confusing and require programmers to attempt to remember for each function how to handle parameters and which registers were used.



- To address this, a standard process is defined and used which is typically referred to as a standard calling convention.
- There are actually a number of different standard calling conventions.
- The 64-bit C calling convention, called System V AMD64 ABI, is described in the remainder of this document.



- This calling convention is also used for C/C++
 programs by default. This means that interfacing
 assembly language code and C/C++ code is easily
 accomplished since the same calling convention is
 used.
- It must be noted that the standard calling convention presented here applies to Linux based operating systems. The standard calling convention for Microsoft Windows is slightly different and not presented in this text.



Linkage



Linkage

- The linkage is about getting to and returning from a function call correctly. There are two instructions that handle the linkage, call and ret instructions.
- The call transfers control to the named function, and ret returns control back to the calling routine.
 - The call works by saving the address of where to return to when the function completes (referred to as the return address). This is accomplished by placing contents of the rip register on the stack.
 Recall that the rip register points to the next instruction to be executed (which is the instruction immediately after the call).
 - The ret instruction is used in a procedure to return. The ret instruction pops the current top of the stack (rsp) into the rip register. Thus, the appropriate return address is restored.



Linkage

- Since the stack is used to support the linkage, it is important that within the function the stack must not be corrupted.
 Specifically, any items pushed must be popped.
- Pushing a value and not popping would result in that value being popped off the stack and placed in the rip register.
- This would cause the processor to attempt to execute code at that location. Most likely the invalid location will cause the process to crash.



Summary of the function calling or linkage

Instruction		Explanation	
call	<funcname></funcname>	Calls a function. Push the 64-bit rip register and jump to the < funcName >.	
	Examples:	call printString	
ret		Return from a function. Pop the stack into the rip register, effecting a jump to the line after the call.	
	Examples:	ret	



Argument Transmission



Argument Transmission

- The standard terminology for transmitting values to a function is referred to as call-byvalue. The standard terminology for transmitting addresses to a function is referred to as call-by-reference. This should be a familiar topic from a high-level language.
- In general, the calling routine is referred to as the *caller* and the routine being called is referred to as the *callee*.



Argument Transmission

- Placing values in register
 - Easiest, but has limitations (i.e., the number of registers).
 - Used for first six integer arguments.
 - Used for system calls.
- Globally defined variables
 - Generally poor practice, potentially confusing, and will not work in many cases.
 - Occasionally useful in limited circumstances.
- Putting values and/or addresses on stack
 - No specific limit to count of arguments that can be passed.
 - Incurs higher run-time overhead.



 The first six integer arguments are passed in registers as follows:

Argument	Argument Size			
Number	64-bits	32-bits	16-bits	8-bits
1	rdi	edi	di	dil
2	rsi	esi	si	sil
3	rdx	edx	dx	dl
4	rcx	ecx	CX	cl
5	r8	r8d	r8w	r8b
6	r9	r9d	r9w	r9b



- The seventh and any additional arguments are passed on the stack. The standard calling convention requires that, when passing arguments (values or addresses) on the stack, the arguments should be pushed in reverse order.
- That is "someFunc (one, two, three, four, five, six, seven, eight, nine)" would imply a push order of: nine, eight, and then seven.



- For floating-point arguments, the floating-point registers xmm0 to xmm7 are used in that order for the first eight float arguments.
- Additionally, when the function is completed, the calling routine is responsible for clearing the arguments from the stack. Instead of doing a series of pop instructions, the stack pointer, rsp, is adjusted as necessary to clear the arguments off the stack. Since each argument is 8 bytes, the adjustment would be adding [(number of arguments) * 8] to the rsp.



 For value returning functions, the result is placed in the A register based on the size of the value being returned.

Return Value Size	Location
byte	al
word	ax
double-word	eax
quadword	rax
floating-point	xmm0



Register Usage

• For value returning functions, the result is placed in the **A** register based on the size of the value being returned.

Return Value Size	Location
byte	al
word	ax
double-word	eax
quadword	rax
floating-point	xmm0



Register Usage

- The standard calling convention specifies the usage of registers when making function calls. Specifically, some registers are expected to be preserved across a function call.
- That means that if a value is placed in a preserved register or saved register, and the function must use that register, the original value must be preserved by placing it on the stack, altered as needed, and then restored to its original value before returning to the calling routine.
- This register preservation is typically performed in the prologue and the restoration is typically performed in the epilogue.



The following table summarizes the register usage.

Register	Usage
rax	Return Value
rbx	Callee Saved
rcx	4 th Argument
rdx	3 rd Argument
rsi	2 nd Argument
rdi	1 st Argument
rbp	Callee Saved
rsp	Stack Pointer
r8	5 th Argument
r9	6 th Argument
r10	Temporary

r11	Temporary
r12	Callee Saved
r13	Callee Saved
r14	Callee Saved
r15	Callee Saved



Call Frame

- The possible items in the call frame include:
 - Return address (required).
 - Preserved registers (if any).
 - Passed arguments (if any).
 - Stack dynamic local variables (if any).



Call Frame

 For example, assuming a function call has eight (8) arguments and assuming the function uses rbx, r12, and r13 registers (and thus must be pushed), the call frame would be as follows:

	-
<8 th Argument>	← rbp + 24
<7 th Argument>	← rbp + 16
rip	(return address)
rbp	← rbp
rbx	
r12	
r13	← rsp



Red Zone

In the Linux standard calling convention, the first 128-bytes after the stack pointer, rsp, are reserved. For example, extending the previous example, the call frame would be as follows:

•••	
<8 th Argument>	
<7 th Argument>	
rip	
rbp	
rbx	
r10	
r12	
128 bytes	
• • • •	

← rbp + 24
← rbp + 16
(return address)
∠ rhn

← rsp

Red Zone

Caller

```
; stats1(arr, len, sum, ave);
mov rcx, ave ; 4th arg, addr of ave
mov rdx, sum ; 3rd arg, addr of sum
mov esi, dword [len] ; 2nd arg, value of len
mov rdi, arr ; 1st arg, addr of arr
call stats1
```

Callee

```
; Simple example function to find and return
; the sum and average of an array.
; HLL call:
; stats1(arr, len, sum, ave);
;----
; Arguments:
; arr, address – rdi
; len, dword value – esi
; sum, address – rdx
; ave, address - rcx
```

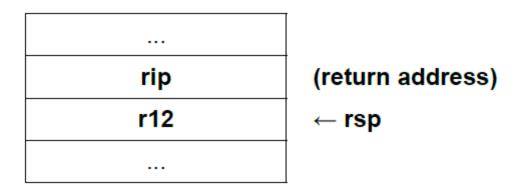


```
global stats1
stats1:
            r12
   push
                                             ; prologue
                                             ; counter/index
            r12, 0
   mov
                                             ; running sum
            rax, 0
   mov
sumLoop:
            eax, dword [rdi+r12*4]
   add
                                             ; sum += arr[i]
   inc
            r12
            r12, rsi
   cmp
   jl
            sumLoop
            dword [rdx], eax
                                             ; return sum
   mov
   cdq
   idiv
            esi
                                             ; compute average
            dword [rcx], eax
                                             ; return ave
   mov
                                             ; epilogue
            r12
   pop
   ret
```



Call Frame of Example 1

 The choice of the r12 register is arbitrary, however a 'saved register' was selected. The call frame for this function would be as follows:





Caller

```
; stats2(arr, len, min, med1, med2, max, sum, ave);
push
                                   ; 8th arg, add of ave
       ave
                                   ; 7th arg, add of sum
push
       sum
                                   ; 6th arg, add of max
       r9, max
mov
                                   ; 5th arg, add of med2
       r8, med2
mov
                                   ; 4th arg, add of med1
       rcx, med1
mov
       rdx, min
                                   ; 3rd arg, addr of min
mov
       esi, dword [len]
                                   ; 2nd arg, value of len
mov
                                   ; 1st arg, addr of arr
       rdi, arr
mov
call
       stats2
add
       rsp, 16
                                   ; clear passed arguments
```



Callee

```
; Simple example function to find and return the minimum,
; maximum, sum, medians, and average of an array.
; HLL call:
; stats2(arr, len, min, med1, med2, max, sum, ave);
; Arguments:
; arr, address - rdi
; len, dword value – esi
; min, address – rdx
; med1, address - rcx
; med2, address - r8
; max, address - r9
; sum, address – stack (rbp+16)
; ave, address - stack (rbp+24)
```



```
global stats2
stats2:
           rbp
                                            ; prologue
   push
           rbp, rsp
   mov
           r12
   push
   ; Get min and max.
           eax, dword [rdi]
                                            ; get min
   mov
           dword [rdx], eax
                                            ; return min
   mov
           r12, rsi
                                            ; get len
   mov
   dec
           r12
                                            ; set len-1
           eax, dword [rdi+r12*4]
                                            ; get max
   mov
           dword [r9], eax
                                            ; return max
   mov
   ; Get medians
           rax, rsi
   mov
           rdx, 0
   mov
   mov
           r12, 2
   div
           r12
                                            ; rax = length/2
                                            ; even/odd length?
           rdx, 0
   cmp
           evenLength
   je
```



```
r12d, dword [rdi+rax*4]
                                           ; get arr[len/2]
   mov
           dword [rcx], r12d
                                           ; return med1
   mov
           dword [r8], r12d
                                           ; return med2
   mov
           medDone
   jmp
evenLength:
   mov
           r12d, dword [rdi+rax*4]
                                           ; get arr[len/2]
           dword [r8], r12d
                                           ; return med2
   mov
   dec
           rax
           r12d, dword [rdi+rax*4]
                                           ; get arr[len/2-1]
   mov
           dword [rcx], r12d
                                           ; return med1
   mov
medDone:
; Find sum
           r12, 0
                                           ; counter/index
   mov
                                           ; running sum
           rax, 0
   mov
```



```
sumLoop:
   add
           eax, dword [rdi+r12*4]
                                           ; sum += arr[i]
           r12
   inc
           r12, rsi
   cmp
   jl
           sumLoop
           r12, qword [rbp+16]
                                           ; get sum addr
   mov
           dword [r12], eax
                                           ; return sum
   mov
   ; Calculate average.
   cdq
   idiv
           rsi
                                           ; average = sum/len
           r12, qword [rbp+24]
                                           ; get ave addr
   mov
           dword [r12], eax
                                           ; return ave
   mov
           r12
                                           ; epilogue
   pop
           rbp
   pop
   ret
```



Call Frame of Example 2

 The choice of the registers is arbitrary with the bounds of the calling convention. The call frame for this function would be as follows:

	-1
<8 th Argument>	← rbp + 24
<7 th Argument>	← rbp + 16
rip	(return address)
rbp	← rbp
r12	← rsp



Lab Activity



Lab Activity

Given the following variable declarations and code fragment:

```
dq
                        1, 3, 5, 7, 9
      Ist
               rsi, 0
      mov
               rcx, 5
      mov
lp1:
      push
               qword [lst+rsi*8]
      inc
               rsi
               lp1
      loop
               rsi, 0
      mov
               rcx, 5
      mov
               qword [lst+rsi*8]
lp2:
      pop
      inc
               rsi
               lp2
      loop
               rbx, qword [lst]
      mov
```

Explain what would be the **result** of the code (after execution)?



End of Chapter 12