Robotics with ROS

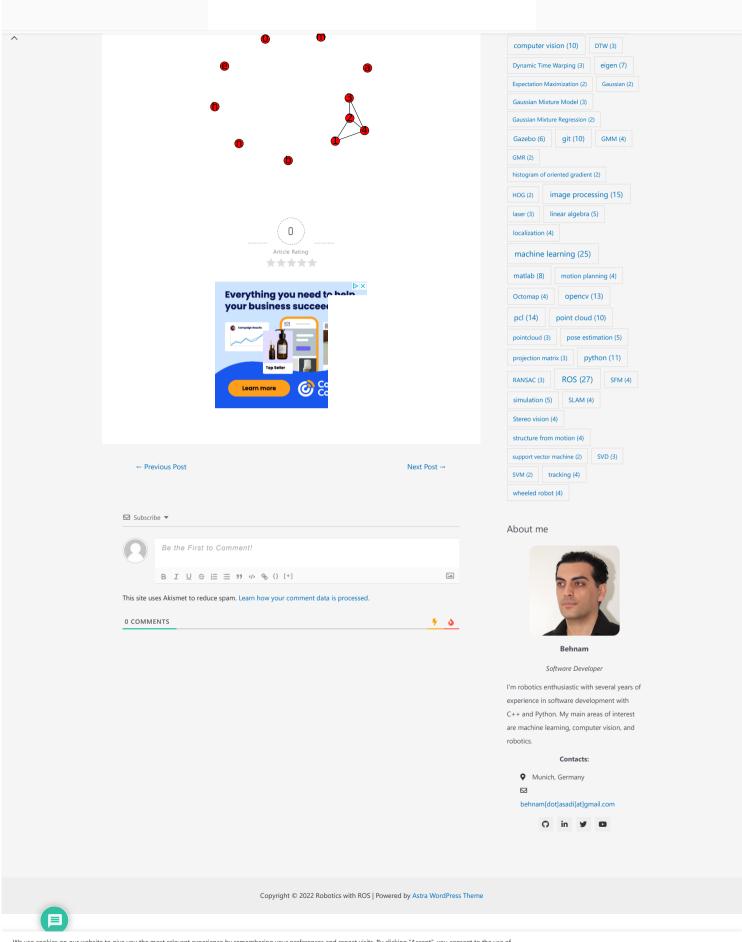


## Drawing graphs in Python with networkx Leave a Comment / Python, Tutorials / By admin 2 import matplotlib.pyplot as plt G=nx.Graph() G.add\_node(1) G.add\_nodes\_from([2,3,4]) #Add an nbunch: iterable container of nodes (e.g. a list, set, graph, file, etc.. H=nx.path\_graph(1) \$\frac{4}{6}\$ now contains the nodes of H as nodes of G. \$\frac{6}{6}\$.add\_nodes\_from(H) \$\frac{4}{6}\$raph of Graph #G.add node(H) #An edge can be associated with any object x using $G.add\_edge(n1,n2,object=x).edge_2_4=(2,4,{'weight':3.1415})$ G.add\_edge(\*edge\_2\_4) G.add\_edge(1, 2, weight=4.7) G.add\_weighted\_edges\_from([(3,4,0.125)]) print G.edges() print 'Neighbors' print G.neighbors(1) #Accessing edges print 'Accessing edges' print G[3] print G[4] print G[4][2]['weight'] for (u,v,d) in G.edges(data='weight'): if d>0.5: print('(%d, %d, %.3f)'%(u,v,d)) G.add\_edges\_from([(1,2,{'color':'blue'}), (2,3,{'weight':8})]) MG=nx.MultiGraph() MG.add\_weighted\_edges\_from([(1,2,.5), (1,2,.75), (2,3,.5)]) MG.degree(weight='weight') GG-nx.Graph() for n,nbrs in MG.adjacency\_iter(): for nbr,edict in nbrs.items(): minvalue=min([d]'weight'] for d in edict.values()]) GG.add\_edge(n,nbr, weight = minvalue) print 'shortest path from 1 to 3' print nx.shortest\_path(GG,1,3) #nx.draw\_spectral(G) #nx.draw\_circular(G) #nx.draw\_random(G) pos=nx.spring\_layout(6) # positions for all nodes 00 nx.draw\_networkx\_labels(G,pos,font\_size=20,font\_family='sans-serif') 01 nx.draw(G,pos)



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