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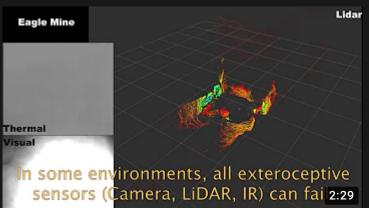
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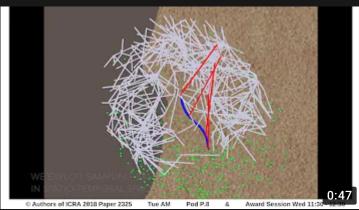
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- Planning for grasping and manipulation tasks with unknown objects Only sensor data and
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32:07

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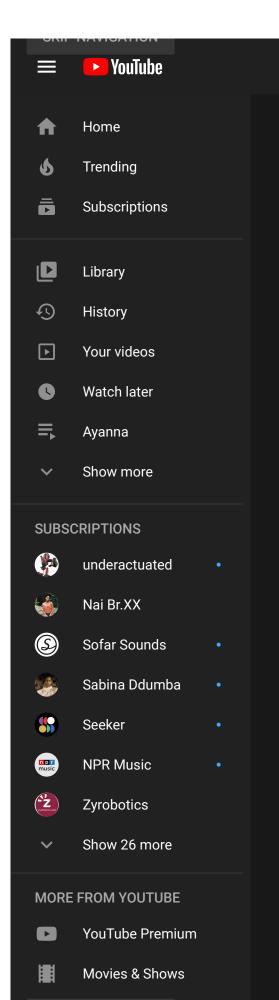
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SKIP NAVIGATION



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Map Building













# 5:02

# 2:32

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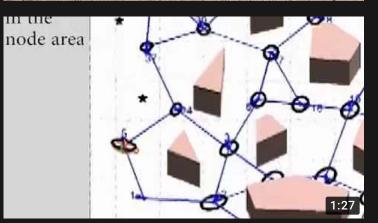
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Fan, D.D., Nguyen, J., Thakker, R., Alatur, N., Agha-mohammadi, A.A. and Theodorou, E.A., 2020, May. Bayesian learning-

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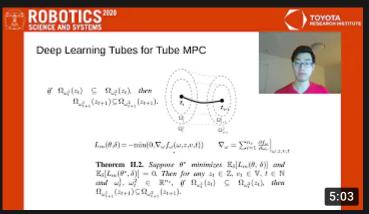
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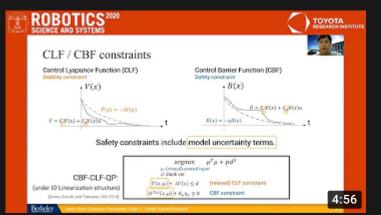
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