

## Atsushi Sakai



A Japanese robotics engineer.



## Links

- Twitter  @Atsushi\_twi ([https://twitter.com/atsushi\\_twi](https://twitter.com/atsushi_twi))
- Blog in Japanese  MyEnigma (<https://myenigma.hatenablog.com/>)
- GitHub  AtsushiSakai (<https://github.com/AtsushiSakai>)
- LinkedIn  Atsushi Sakai (<https://www.linkedin.com/in/atsushi-sakai-338a55127/>)
- Youtube  Atsushi Sakai (<https://www.youtube.com/user/MrASakai/>)
- Google Scholar  Atsushi Sakai (<https://scholar.google.com/citations?hl=en&user=oElom3wAAAAA3>)
- Patreon  Atsushi Sakai (<https://www.patreon.com/myenigma>)
- Note.mu  Atsushi\_twi (<https://note.mu/myenigma>)
- Email  [asakaig@gmail.com](mailto:asakaig@gmail.com)

## Open Source Software

- PythonRobotics (<https://github.com/AtsushiSakai/PythonRobotics>) Python sample codes for robotics algorithms.  13k
- SciPy (<https://github.com/scipy/scipy>) An open-source software for mathematics, science, and engineering. I'm a member of SciPy developer organization.  8.4k
- PyAdvancedControl (<https://github.com/AtsushiSakai/PyAdvancedControl>) Python sample codes for advanced control.
- PyOptSamples (<https://github.com/AtsushiSakai/PyOptSamples>) Python sample codes for numerical optimization.
- MATLABRobotics (<https://github.com/AtsushiSakai/MATLABRobotics>) MATLAB sample codes for autonomous navigation in robotics
- SimpleTkGUIkit (<https://pypi.python.org/pypi/SimpleTkGUIkit/>) Simple GUI kit with python Tkinter
- googleearthplot (<https://pypi.python.org/pypi/googleearthplot>) KML file generator for plotting on Google Earth
- pycubicspline (<https://github.com/AtsushiSakai/pycubicspline>) Cubic spline library on python
- rosbag\_to\_csv ([https://github.com/AtsushiSakai/rosbag\\_to\\_csv](https://github.com/AtsushiSakai/rosbag_to_csv)) A GUI tool to convert topics from a rosbag file to csv files
- rosbag\_filter\_gui ([https://github.com/AtsushiSakai/rosbag\\_filter\\_gui](https://github.com/AtsushiSakai/rosbag_filter_gui)) A GUI tool to filter topics in a rosbag file.
- matplotlib-cpp-starter (<https://github.com/AtsushiSakai/matplotlib-cpp-starter>) A header library to use matplotlib from C++ code.
- numpycpp (<https://github.com/AtsushiSakai/numpycpp>) A c++ header library for matrix operation inspired Numpy and Scipy using Eigen.
- julia.vim (<https://github.com/AtsushiSakai/julia.vim>) A Vim plugin for Julia coding.
- PyJSONViewer (<https://github.com/AtsushiSakai/PyJSONViewer>) A JSON file data viewer using pure python.
- PyCoolPlot (<https://github.com/AtsushiSakai/PyCoolPlot>) A cool plotting module on Python
- pyplotjuggler (<https://github.com/AtsushiSakai/pyplotjuggler>) Python plot juggler
- PyRoombaAdapter (<https://github.com/AtsushiSakai/PyRoombaAdapter>) A Python library for Roomba Open Interface
- SciPy.jl (<https://github.com/AtsushiSakai/SciPy.jl>) A Julia interface for SciPy using PyCall.jl.

## Publications

- X. Zhang, A. Liniger, A. Sakai and F. Borrelli, "Autonomous Parking using Optimization-Based Collision Avoidance", IEEE Conference on Decision and Control (CDC) (<https://cdc2018.ieeeccs.org/>), Dec 2018. Link (<https://ieeexplore.ieee.org/document/8619433>), [open-source code] (<https://github.com/XiaojingGeorgeZhang/H-OBICA>).
- Atsushi Sakai, Daniel Ingram, Joseph Dinius, Karan Chawla, Antonin Raffin: "PythonRobotics: a Python code collection of robotics algorithms", arXiv:1808.10703, (2018); Link (<http://arxiv.org/abs/1808.10703>).
- Atsushi Sakai, and Yoji Kuroda. "Discriminatively Trained Unscented Kalman Filter for Mobile Robot Localization." Journal of Advanced Research in Mechanical Engineering 1.3 (2010). Link (<https://sites.google.com/site/atsushisakaishomepage/paper-list/Discriminatively%20Trained%20Unscented%20Kalman.pdf?attredirects=0&d=1>)
- Y. Kuroda, A. Sakai, Y. Tamura, "Six-Degree-of-Freedom Localization using an Unscented Kalman Filter for Planetary Rovers", Journal of Advanced Robotics 24 (8-9), 1199-1218 (2010). Link (<https://www.tandfonline.com/doi/abs/10.1163/016918610X501273>)
- Atsushi Sakai, Teppei Saitoh, and Yoji Kuroda. "Robust landmark estimation and unscented particle sampling for SLAM in dynamic outdoor environment." Journal of Robotics and Mechatronics 22.2 (2010): 140. Link (<https://www.fujipress.jp/jrm/rb/robot002200020140/>)
- A. Sakai, M. Mitsuhashi, and Y. Kuroda. "Noise model creation for visual odometry with neural-fuzzy model" 2010 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2010), Taipei, Taiwan, 2010, pp. 5190-5195. Link (<https://ieeexplore.ieee.org/abstract/document/5651185>)
- A. Sakai, Y. Tamura and Y. Kuroda, "An efficient solution to 6DOF localization using Unscented Kalman Filter for planetary rovers," 2009 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2009), St. Louis, MO, 2009, pp. 4154-4159. Link (<https://ieeexplore.ieee.org/abstract/document/5354677>)

## Talks

- 『The Full Autonomous Racing System 概説』 ([https://docs.google.com/presentation/d/1PTq1ZTDpa\\_PakXMJO7isR9G-EzYDayarLomScTw3gBs/edit?usp=sharing](https://docs.google.com/presentation/d/1PTq1ZTDpa_PakXMJO7isR9G-EzYDayarLomScTw3gBs/edit?usp=sharing)) 第6回 HarajukuSquare(@Seqsense社) 2019/05/31 (<https://www.seqsense.com/>)
- 『PythonRobotics: a Python code collection of robotics algorithms.』 ([https://docs.google.com/presentation/d/1QhcGvJxO\\_zBzwKxZYbsmWFkct\\_h7eXDz82JqsGVYg/edit?usp=sharing](https://docs.google.com/presentation/d/1QhcGvJxO_zBzwKxZYbsmWFkct_h7eXDz82JqsGVYg/edit?usp=sharing)) ROS Japan UG #27 勉強会 2018/12/17 (<https://rosjp.connpass.com/event/111853/>)
- 『トラレータトラックの自動車計画アルゴリズムの紹介』 ([https://docs.google.com/presentation/d/13tuWC\\_PopDRivYQc34wHeW895TP9278VQjRmRluus4/edit?usp=sharing](https://docs.google.com/presentation/d/13tuWC_PopDRivYQc34wHeW895TP9278VQjRmRluus4/edit?usp=sharing)) ROS Japan UG #24 勉強会 2018/06/20 (<https://rosjp.connpass.com/event/89616/presentation/>)

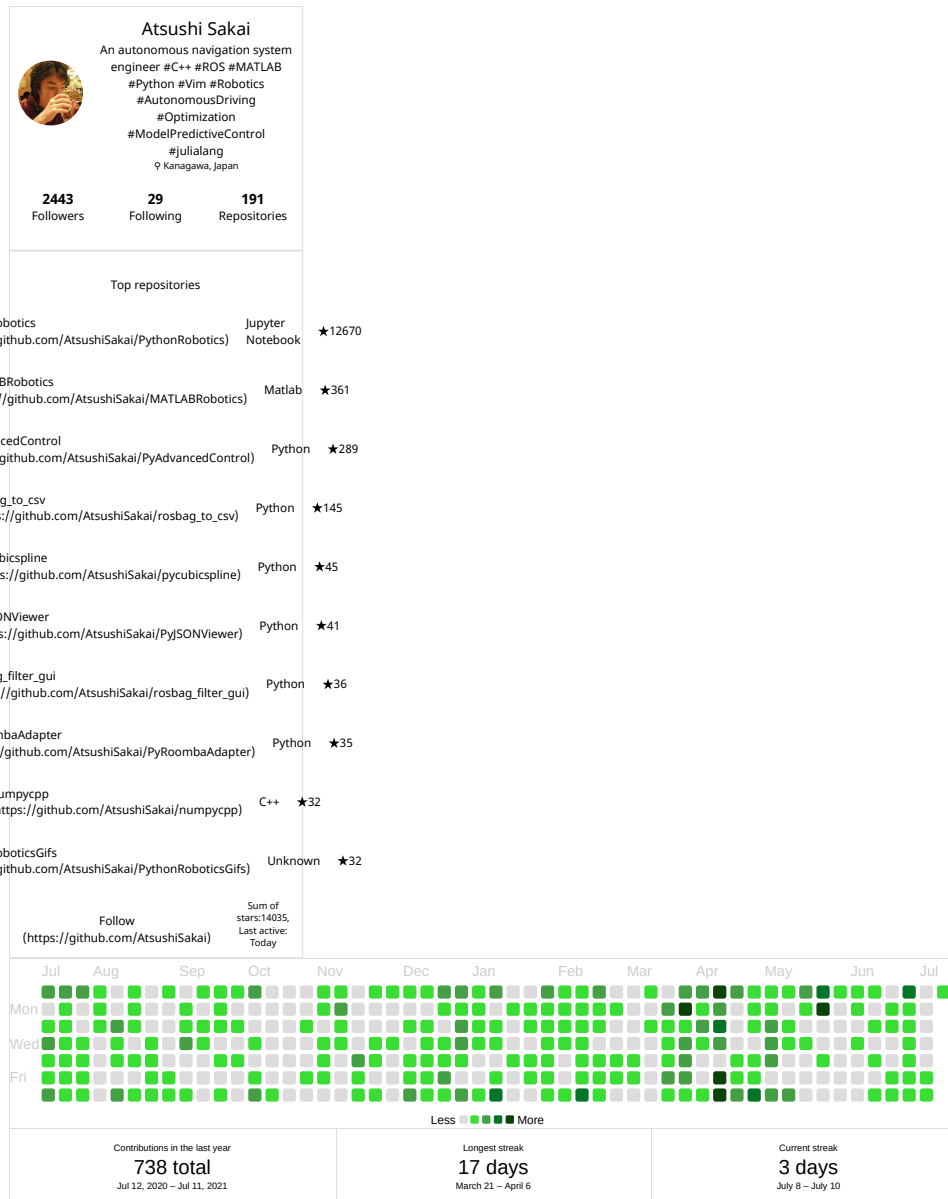
## Web Apps

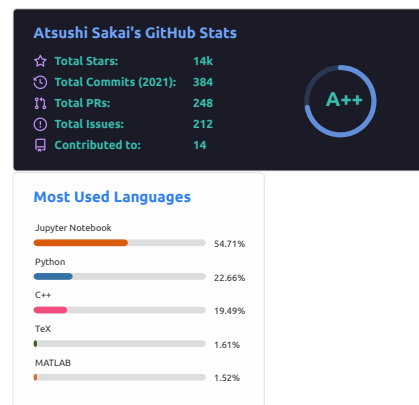
- Today Tool (<https://atsushisakai.github.io/TodayTool/>)
- Tex Converter (<https://atsushisakai.github.io/tex-tool/>)

## 👍 Likes



## 📄 GitHub Widget





## Twitter Widget

@Atsushi\_twiさんのツイート

**Atsushi Sakai**  
@Atsushi\_twi

台湾の研究社の人たちがPythonRoboticsを使って、目が見えない人向けのサポートロボットを研究している🤖。Assistive Navigation Using Deep Reinforcement Learning Guiding Robot With UWB/Voice Beacons and Semantic Feedbacks for Blind and Visually Impaired People [ncbi.nlm.nih.gov/pmc/articles/P...](https://ncbi.nlm.nih.gov/pmc/articles/PMC7111111/)

**Assistive Navigation Using Deep Reinforcement Learning**  
Facilitating navigation in pedestrian environments is critical for enabling people who are blind and visually impaired (BVI) to achieve independent mobility. A deep  
[ncbi.nlm.nih.gov](https://ncbi.nlm.nih.gov/pmc/articles/PMC7111111/)

埋め込む Twitterで表示

## QR code of this page



## Visitor map



ツイート 1

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