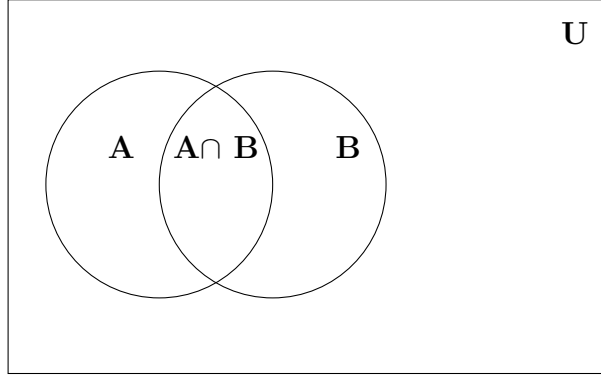


Bayes' Theorem



The probability of finding B is

$$P(B) = \frac{|B|}{|U|}, \quad (1)$$

where $|U|$ is the area of U . Similarly,

$$P(A) = \frac{|A|}{|U|}, \quad (2)$$

while the probability of both A and B is

$$P(AB) = \frac{|A \cap B|}{|U|}, \quad (3)$$

What is the probability of B , given that we know we are in A ?

$$P(B|A) = \frac{|B \cap A|}{|A|}. \quad (4)$$

For future reference

$$P(B|A) = \frac{|B \cap A|}{|A|} = \frac{|B \cap A|}{|U|} \frac{|U|}{|A|} = P(AB) / P(A). \quad (5)$$

Conversely, the probability of A , given that we know we are in B is

$$P(A|B) = \frac{|A \cap B|}{|B|} = P(AB) / P(B). \quad (6)$$

It follows that

$$P(A|B)P(B) = P(B|A)P(A). \quad (7)$$

This is known as Bayes' Theorem.

Bayes's Theorem is often written

$$P(A|B) = P(B|A)P(A)/P(B). \quad (8)$$

Why is this useful? First, it helps counter our usual intuition about probabilities, which are frequency in error. For example, it is believed that about 1 percent of people in Ontario have or have had Covid-19. Tests for Covid-19 are fairly accurate, around 97%, meaning that if they are given to 100 people, only three test will give a positive result in error. Lets also assume that if someone has Covid-19, that the test always returns a positive result (this is not true, but it is not so bad an approximation).

So suppose Ontario starts a random testing program, and tests 1000 people. The tests of some people will be positive. Given that someone has a positive test, what are the odds that they have Covid-19?

Ok, how might this be useful for you this summer? Many of you will be using data to decide if a theory is correct or not. The theory will a number of parameters, conventionally denoted by θ . The data is denoted by d , and has errors σ_d . The theory makes prediction for the values y_i corresponding each of the components of d . One measure of the fit between theory and data is

$$\chi^2 = \sum_i \frac{(y_i - y_{i,obs})^2}{\sigma_i^2}. \quad (9)$$

If the measurement errors are random, they might be described by a Gaussian. In that case the probability that we have the correct value is proportional to

$$L = \prod_i \frac{1}{\sqrt{2\pi\sigma_i^2}} e^{-(y_i - y_{i,obs})^2 / 2\sigma_i^2}, \quad (10)$$

if we also assume that all the measurements are independent.

Now we can use Bayes' Theorem to estimate the probability that our theory is true, given that we have seen the data d :

$$P(\theta|d) = P(\theta)P(d|\theta)/P(d). \quad (11)$$

In practice, the jargon is as follows:

$$P(\theta|d) = \Pi(\theta)L(d|\theta)/Z(d), \quad (12)$$

where $P(\theta|d)$ is called the “posterior probability”, Π is called the “prior”, L is the “likelihood”, and Z is called the “evidence”.