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# Progress Presentation

June 27th - July 19th

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# Agenda

- ❖ small updates to the algorithm
- ❖ experiments
- ❖ revisiting some diagnostic plots
- ❖ paper, schedule, examiner, etc.





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# Updates to Algorithm

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- ❖ Beliefs are now allowed to diverge -> random actions
  - ❖ If the belief in the root node of the top level forest diverges, the run ends
  - ❖ If the target node is initialised with a diverged belief at the start of a single simulation, the simulation fails and we move on to the next one
- ❖ Softargmax for determining actions for a lower forest:
  - ❖ before:  $\mathbb{P}(a_j | b) \propto \exp\left(\frac{N_+(b, a_j)}{\sqrt{N_+(b)}}\right) = \exp\left(\frac{W(b, a_j)}{W(b)} \sqrt{N_+(b)}\right)$
  - ❖ now:  $\mathbb{P}(a_j | b) \propto \exp\left(\frac{\hat{U}(b, a_j)}{c_{\text{sft}} \cdot (1/\sqrt{N_+(b)})}\right)$ 
    - ❖ (Boltzmann distribution with “state energies”  $-\hat{U}(b, a_j)$  and temperature  $1/\sqrt{N_+(b)}$ )
- ❖ Improved memory usage (with 3 agents it was using 20+GB, now around 10-15GB at most)



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# Experiments

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- ❖ Experiment 1

- ❖ goal: investigating the effect of different costs of attacking in a two-agent system

- ❖ independent variable: the cost of attacking (0.01, 0, -0.01, -0.1, -0.9, -1)

- ❖ dependent variables:

- ❖ proportions of different actions over the duration of the simulation

- ❖ distribution of attack streak lengths

- ❖ how to quantify “bounded rationality” / prediction error?

- ❖ number of times a lower forest belief diverges is not a good metric, because the upper forest is exploring different actions

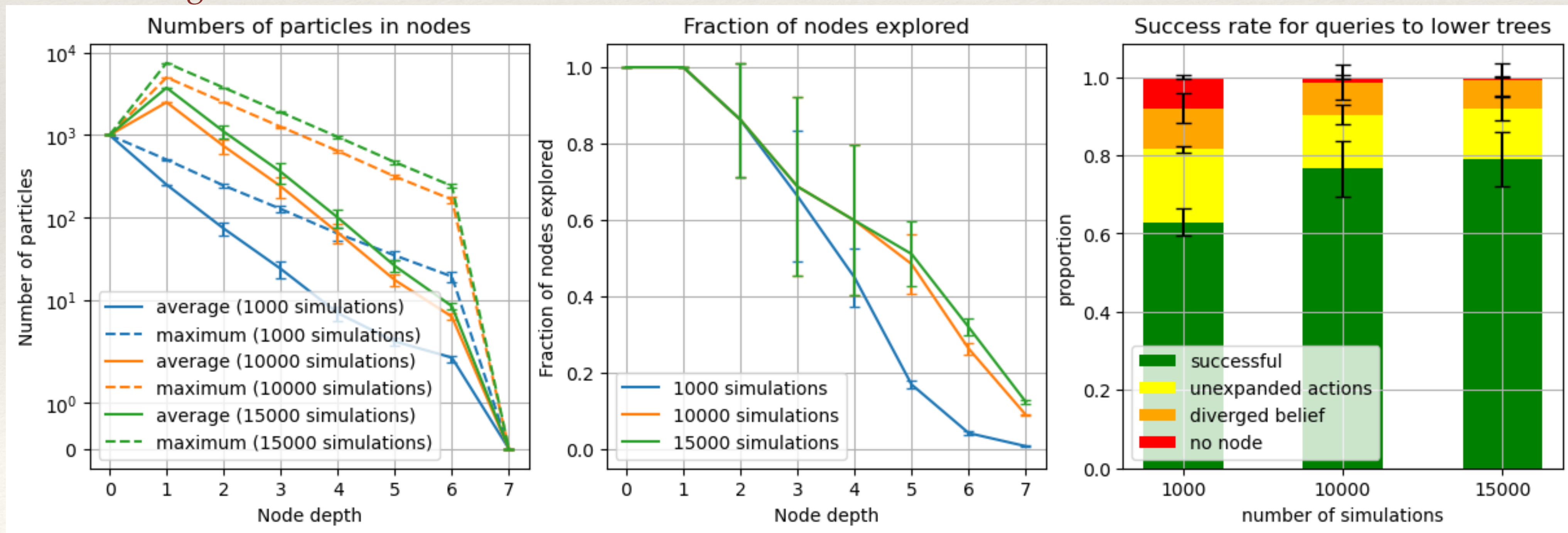
- ❖ instead: at the end of a turn, compare the actions each agent would perform and the actions we think they will perform



# Revised diagnostic plots

*Number of simulations*

- averages over 5 runs
- two agents
- exploration coefficient 0.1
- reasoning level 1
- only first time step
- results from one agent's forests

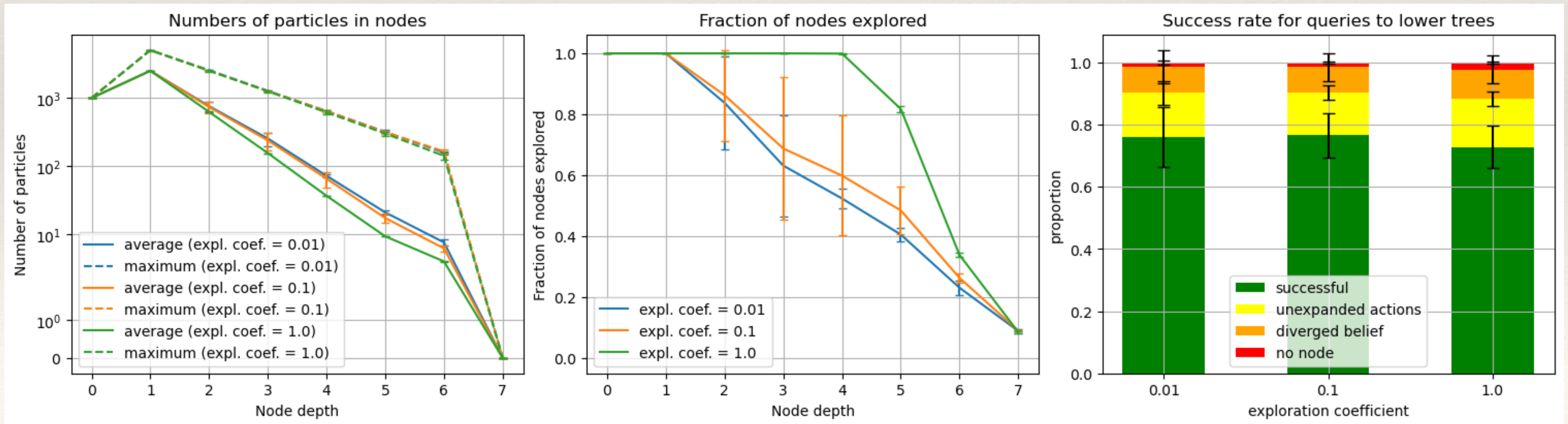




# Revised diagnostic plots

## *Exploration Coefficient*

- averages over 5 runs
- two agents
- 10k simulations
- reasoning level 1
- only first time step
- results from one agent's forests

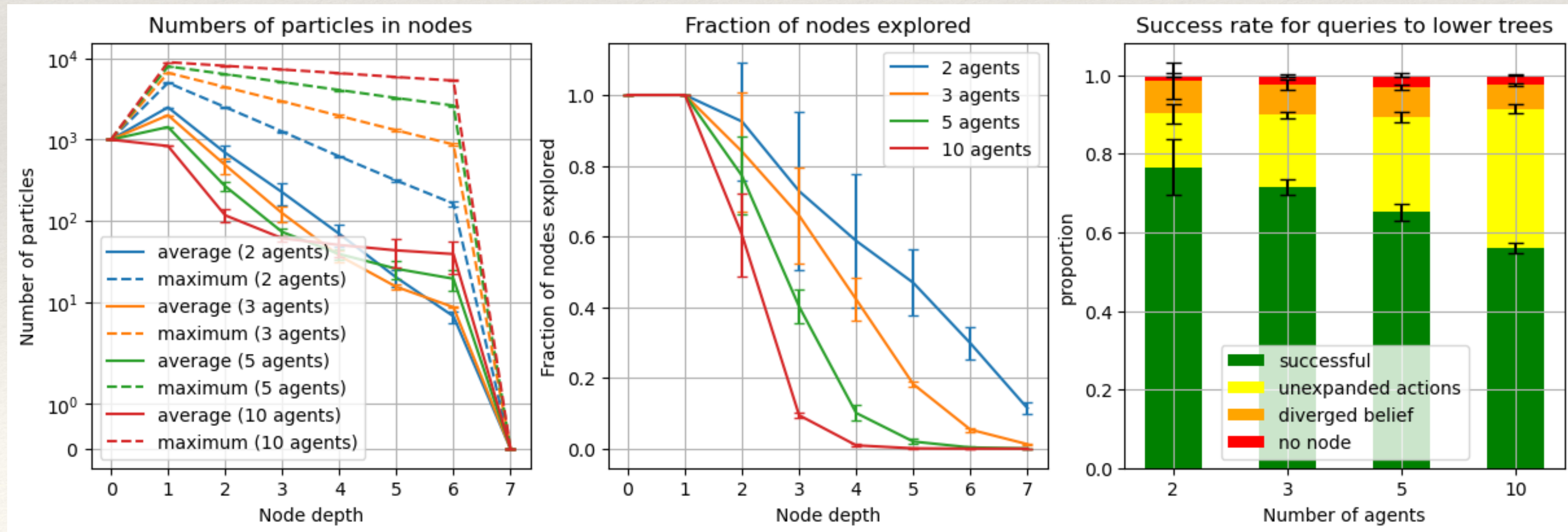




# Revised diagnostic plots

- averages over 5 runs
- 10k simulations
- exploration coefficient 0.1
- reasoning level 1
- only first time step
- results from one agent's forests
  - Note: particle counts (left and middle plots) are from the level 1 forest

*Number of Agents*

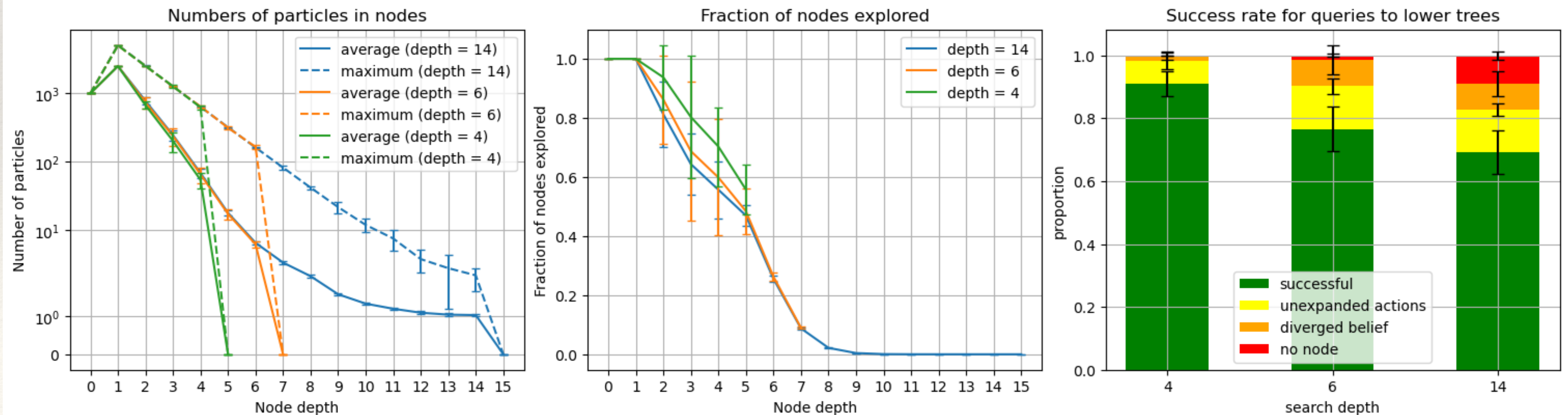




# Revised diagnostic plots

*Search depth*

- averages over 5 runs
- 10k simulations
- exploration coefficient 0.1
- two agents
- reasoning level 1
- only first time step
- results from one agent's forests





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# Practicalities

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- ❖ paper
  - ❖ first draft of methods is done
  - ❖ next: literature review?
- ❖ what is the examiner situation?
- ❖ schedule is looking tight



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# Notes from Meeting

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- ❖ Paper:
  - ❖ finish section 3.1: be as comprehensive as possible
  - ❖ make a figure illustrating the structure of interactive states (similar in style to the “matrix” format used in slides)
  - ❖ literature review: write more in the style of a thesis. Around 5 pages
- ❖ Memory usage:
  - ❖ check global variables, Python is not very good at handling them memory-wise
- ❖ New softargmax approach:
  - ❖ think of an appropriate range for  $c_{\text{sft}}$
  - ❖ similar to quantal response equilibrium
- ❖ Quantifying bounded rationality:
  - ❖ agent-level
  - ❖ system-level: how does payoff received differ from optimal behaviour (which is for everyone to never do anything)